

## Spanning Tree

Spanning tree: a subset of the edges from a connected graph that...
...touches all vertices in the graph (spans the graph)


Minimum spanning tree: the spanning tree with the least total edge cost.

## Two Different Algorithms



Prim's Algorithm Almost identical to Dijkstra's


Kruskals's Algorithm Completely different!

## Prim's Algorithm for

 Minimum Spanning TreesA node-oriented greedy algorithm (builds an MST by greedily adding nodes)

Select a node to be the "root" and mark it as known While there are unknown nodes left in the graph

Select the unknown node $n$ with the smallest cost from some known node $m$
Mark $n$ as known
Add $(m, n)$ to our MST
Runtime:

## Prim's Algorithm In Action



## Kruskal's Algorithm for Minimum Spanning Trees

An edge-oriented greedy algorithm (builds an MST by greedily adding edges)

Initialize all vertices to unconnected
While there are still unmarked edges
Pick the lowest cost edge $\mathbf{e}=(\mathbf{u}, \mathrm{v})$ and mark it
If $\mathbf{u}$ and $\mathbf{v}$ are not already connected, add $\mathbf{e}$ to the minimum spanning tree and connect $\mathbf{u}$ and $\mathbf{v}$

Sound familiar? (Think maze generation.)

## Kruskal's Algorithm In Action



## Proof of Correctness

We already showed this finds a spanning tree:
That was part of our definition of a good maze.
Proof by contradiction that Kruskal's finds the minimum: Assume another spanning tree has lower cost than Kruskal's Pick an edge $\mathbf{e}_{1}=(\mathbf{u}, \mathbf{v})$ in that tree that's not in Kruskal's Kruskal's tree connects $\mathbf{u}$ 's and $\mathbf{v}$ 's sets with another edge $\mathbf{e}_{\mathbf{2}}$
But, $\mathbf{e}_{2}$ must have at most the same cost as $\mathbf{e}_{1}$ !
So, swap $\mathbf{e}_{2}$ for $\mathbf{e}_{1}$ (at worst keeping the cost the same)
Repeat until the tree is identical to Kruskal's: contradiction!
QED: Kruskal's algorithm finds a minimum spanning tree.


