# SECTION EIGHT

Tail bounds + other stuff :D



## **CONDITIONAL DISTRIBUTIONS**

Sometimes we want to define a distribution for something like X|Y - the random variable X given we know the value of the RV Y

	Discrete	Continuous
	$p_{X Y}(x y) = \frac{p_{X,Y}(x,y)}{p_Y(y)}$	$f_{X Y}(x y) = \frac{f_{X,Y}(x,y)}{f_Y(y)}$
Conditional Expectation	$\mathbb{E}\left[X Y=y\right] = \sum_{x}^{\infty} x p_{X Y}(x y)$	$\mathbb{E}\left[X Y=y\right] = \int_{-\infty}^{\infty} x f_{X Y}(x y) dx$

## **CONDITIONAL DISTRIBUTIONS**

Sometimes we want to define a distribution for something like X|Y - the random variable X given we know the value of the RV Y

	Discrete	Continuous
Conditional PMF/PDF	$p_{X Y}(x y) = \frac{p_{X,Y}(x,y)}{p_Y(y)}$	$f_{X Y}(x y) = \frac{f_{X,Y}(x,y)}{f_Y(y)}$
Conditional Expectation	$\mathbb{E}\left[X Y=y\right] = \sum_{x} x p_{X Y}(x y)$	$\mathbb{E}\left[X Y=y\right] = \int_{-\infty}^{\infty} x f_{X Y}(x y) dx$

A lot of this is similar to what you've seen already :)

## **CONDITIONAL DISTRIBUTIONS**

Sometimes we want to define a distribution for something like X|Y - the random variable X given we know the value of the RV Y

Linearity of expectation still applies to conditional distributions!

## $\mathbb{E}\left[X+Y|A\right] = \mathbb{E}\left[X|A\right] + \mathbb{E}\left[Y|A\right]$



## **CONTINUOUS LOTP**

This is the law of total probability for continuous random variables!

Instead of conditioning on a set of discrete events, and finding the probability of a discrete random variable, we might want to find the probability of <u>continuous</u> random variables, partitioning on the values in the range of a different <u>continuous</u> random variable.

$$\mathbb{P}(A) = \int_{x \in \Omega_X} \mathbb{P}(A|X=x) f_X(x) dx$$

## LAW OF TOTAL EXPECTATION

Computed the expected value by partitioning on a set of events.

This is very similar in idea to law of total probability except that we're doing it for expectation.

$$\mathbb{E}[X] = \sum_{i=1}^{n} \mathbb{E}[X|A_i] \mathbb{P}(A_i) \qquad \mathbb{E}[X] = \sum_{y} \mathbb{E}[X|Y=y] p_Y(y)$$

# **CONTINUOÚS** LÓTE

$$\mathbb{E}\left[X\right] = \int_{y \in \Omega_Y} \mathbb{E}\left[X|Y=y\right] f_Y(y) dy$$

Same thing as above, but for continuous RVs!

Markov + Chebyshev + Chernoff

## If we find something like P(..) <= ..

### If we find something like P(..) >= ..

## -LOWER BOUND

-UPPER BOUND

## TAIL BOUNDS MARKOV CHEBYSHE

Gives an *upper bound* for P(X >= t):

$$\mathbb{P}\left(X \ge \alpha\right) \le \frac{\mathbb{E}\left[X\right]}{\alpha}$$

#### **Requirements**

- X must be non-negative
- Must know E[X]

### CHERNOFF

Gives upper bound for either tail:  $\mathbb{P}\left(X \ge (1+\delta)\,\mu\right) \le e^{-\frac{\delta^2\mu}{3}} - right \, tail$   $\mathbb{P}\left(X \le (1-\delta)\,\mu\right) \le e^{-\frac{\delta^2\mu}{2}} - left \, tail$ 

#### <u>Requirements</u>

- X is sum of independent Bernoulli

- Must know E[X]

Gives an upper bound for:

$$\mathbb{P}\left(|Y-\mu| \ge \alpha\right) \le \frac{\sigma}{\alpha}$$

<u>Requirements</u> - Y can be *any* RV - Must know E[X] *and Var(X)* 

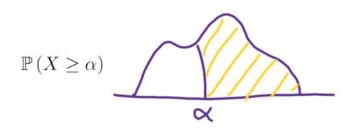
## UNION

Gives *upper bound* for union of events: "bound P of at least one...." "bound P of even one urn having a ball"

$$P\left(\bigcup_{i=1}^{N} A_i\right) \le \sum_{i=1}^{N} P(A_i)$$



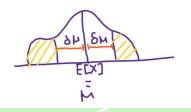
## TAIL BOUNDS MARKOV CHEBYSHEV



 $\mathbb{P}\left(|Y-\mu| \ge \alpha\right)$ 

 $\mathbb{P}\left(X \ge (1+\delta)\,\mu\right) \le e^{-\frac{\delta^2\mu}{3}} - right \ tail$  $\mathbb{P}\left(X \le (1-\delta)\,\mu\right) \le e^{-\frac{\delta^2\mu}{2}} - left \ tail$ 

CHERNOFF





ECXI

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