## Section 9 - Solutions

## Review

Law of total probability and law of total expectation

1) Law of Total Probability (partition based on value of a r.v.): If $X$ is a discrete random variable, then

$$
\mathbb{P}(A)=\sum_{x \in \Omega_{X}} \mathbb{P}(A \mid X=x) p_{X}(x)
$$

If $X$ is a continuous random variable, then

$$
\mathbb{P}(A)=\int_{-\infty}^{\infty} \mathbb{P}(A \mid X=x) f_{X}(x) d x
$$

2) Conditional Expectation: Let $X$ and $Y$ be random variables. Then, the conditional expectation of $X$ given $Y=y$ is

$$
\mathbb{E}[X \mid Y=y]=\sum_{x \in \Omega_{X}} x \cdot \mathbb{P}(X=x \mid Y=y) \quad X \text { discrete }
$$

and for any event $A$,

$$
\mathbb{E}[X \mid A]=\sum_{x \in \Omega_{X}} x \cdot \mathbb{P}(X=x \mid A) \quad X \text { discrete }
$$

Note that linearity of expectation still applies to conditional expectation: $\mathbb{E}[X+Y \mid A]=\mathbb{E}[X \mid A]+\mathbb{E}[Y \mid A]$
3) Law of Total Expectation (Event Version): Let $X$ be a random variable, and let events $A_{1}, \ldots, A_{n}$ partition the sample space. Then,

$$
\mathbb{E}[X]=\sum_{i=1}^{n} \mathbb{E}\left[X \mid A_{i}\right] \mathbb{P}\left(A_{i}\right)
$$

4) Law of Total Expectation (RV Version): Suppose $X$ and $Y$ are random variables. Then,

$$
\begin{array}{cc}
\mathbb{E}[X]=\sum_{y} \mathbb{E}[X \mid Y=y] p_{Y}(y) & Y \text { discrete r.v.. } \\
\mathbb{E}[X]=\int_{-\infty}^{\infty} \mathbb{E}[X \mid Y=y] f_{Y}(y) d y \quad Y \text { continuous r.v. }
\end{array}
$$

## Maximum Likelihood Estimation

1) Realization/Sample: A realization/sample $x$ of a random variable $X$ is the value that is actually observed.
2) Likelihood: Let $x_{1}, \ldots x_{n}$ be iid realizations from probability mass function $p_{X}(\mathrm{x} ; \theta)$ (if $X$ discrete) or density $f_{X}(\mathrm{x} ; \theta)$ (if $X$ continuous), where $\theta$ is a parameter (or a vector of parameters). We define the likelihood function to be the probability of seeing the data.
If $X$ is discrete:

$$
L\left(x_{1}, \ldots, x_{n} \mid \theta\right)=\prod_{i=1}^{n} p_{X}\left(x_{i} \mid \theta\right)
$$

If $X$ is continuous:

$$
L\left(x_{1}, \ldots, x_{n} \mid \theta\right)=\prod_{i=1}^{n} f_{X}\left(x_{i} \mid \theta\right)
$$

3) Maximum Likelihood Estimator (MLE): We denote the MLE of $\theta$ as $\hat{\theta}_{\text {MLE }}$ or simply $\hat{\theta}$, the parameter (or vector of parameters) that maximizes the likelihood function (probability of seeing the data).

$$
\hat{\theta}_{\mathrm{MLE}}=\arg \max _{\theta} L\left(x_{1}, \ldots, x_{n} \mid \theta\right)=\arg \max _{\theta} \ln L\left(x_{1}, \ldots, x_{n} \mid \theta\right)
$$

4) Log-Likelihood: We define the log-likelihood as the natural logarithm of the likelihood function. Since the logarithm is a strictly increasing function, the value of $\theta$ that maximizes the likelihood will be exactly the same as the value that maximizes the log-likelihood.
If $X$ is discrete:

$$
\ln L\left(x_{1}, \ldots, x_{n} \mid \theta\right)=\sum_{i=1}^{n} \ln p_{X}\left(x_{i} \mid \theta\right)
$$

If $X$ is continuous:

$$
\ln L\left(x_{1}, \ldots, x_{n} \mid \theta\right)=\sum_{i=1}^{n} \ln f_{X}\left(x_{i} \mid \theta\right)
$$

5) Steps to find the maximum likelihood estimator, $\hat{\theta}$ :
(a) Find the likelihood and log-likelihood of the data.
(b) Take the derivative of the log-likelihood and set it to 0 to find a candidate for the MLE, $\hat{\theta}$.
(c) Take the second derivative and show that $\hat{\theta}$ indeed is a maximizer, that $\frac{\partial^{2} L}{\partial \theta^{2}}<0$ at $\hat{\theta}$. Also ensure that it is the global maximizer: check points of non-differentiability and boundary values.
(d) If we are finding the MLE for a set of parameters, then we set up the system of equations obtained by taking the partial derivative of the log-likelihood function with respect to each of the parameters and setting it equal to 0 . We then solve this system to get the MLEs. (And again, second order conditions need to be checked.)
6) An estimator $\hat{\theta}$ for a parameter $\theta$ of a probability distribution is unbiased iff $\mathbb{E}\left[\hat{\theta}\left(X_{1}, \ldots, X_{n}\right)\right]=\theta$

## Task 1 - Trapped Miner

A miner is trapped in a mine containing 3 doors.

- $D_{1}$ : The $1^{\text {st }}$ door leads to a tunnel that will take him to safety after 3 hours.
- $D_{2}$ : The $2^{\text {nd }}$ door leads to a tunnel that returns him to the mine after 5 hours.
- $D_{3}$ : The $3^{r d}$ door leads to a tunnel that returns him to the mine after a number of hours that is Binomial with parameters $\left(12, \frac{1}{3}\right)$.
At all times, he is equally likely to choose any one of the doors. What is the expected number of hours for this miner to reach safety? Use the law of total expectation.

Let $T=$ number of hours for the miner to reach safety. ( $T$ is a random variable)
Let $D_{i}$ be the event the $i^{t h}$ door is chosen. $i \in\{1,2,3\}$. Finally, let $T_{3}$ be the time it takes to return to the mine in the third case only (a random variable). Note that the expectation of $T_{3}$ is $12 \cdot \frac{1}{3}$
because it is binomially distributed with parameters $n=12, p=\frac{1}{3}$. By Law of Total Expectation, linearity of expectation, and by applying the conditional expectations given by the problem statement:

$$
\begin{aligned}
\mathbb{E}[T] & =\mathbb{E}\left[T \mid D_{1}\right] \cdot \mathbb{P}\left(D_{1}\right)+\mathbb{E}\left[T \mid D_{2}\right] \cdot \mathbb{P}\left(D_{2}\right)+\mathbb{E}\left[T \mid D_{3}\right] \cdot \mathbb{P}\left(D_{3}\right) \\
& =3 \cdot \frac{1}{3}+(5+\mathbb{E}[T]) \cdot \frac{1}{3}+\left(\mathbb{E}\left[T_{3}+T\right]\right) \cdot \frac{1}{3} \\
& =3 \cdot \frac{1}{3}+(5+\mathbb{E}[T]) \cdot \frac{1}{3}+\left(\mathbb{E}\left[T_{3}\right]+\mathbb{E}[T]\right) \cdot \frac{1}{3} \\
& =3 \cdot \frac{1}{3}+(5+\mathbb{E}[T]) \cdot \frac{1}{3}+(4+\mathbb{E}[T]) \cdot \frac{1}{3}
\end{aligned}
$$

Solving this equation for $\mathbb{E}[T]$, we get

$$
\mathbb{E}[T]=12
$$

Therefore, the expected number of hours for this miner to reach safety is 12 .

## Task 2 - Lemonade Stand

Suppose I run a lemonade stand, which costs me $\$ 100$ a day to operate. I sell a drink of lemonade for $\$ 20$. Every person who walks by my stand either buys a drink or doesn't (no one buys more than one). If it is raining, $n_{1}$ people walk by my stand, and each buys a drink independently with probability $p_{1}$. If it isn't raining, $n_{2}$ people walk by my stand, and each buys a drink independently with probability $p_{2}$. It rains each day with probability $p_{3}$, independently of every other day. Let $X$ be my profit over the next week. In terms of $n_{1}, n_{2}, p_{1}, p_{2}$ and $p_{3}$, what is $\mathbb{E}[X]$ ? Use the law of total expectation.

Let $R$ be the event it rains. Let $X_{i}$ be how many drinks I sell on day $i$ for $i=1, \ldots, 7$. We are interested in $X=\sum_{i=1}^{7}\left(20 X_{i}-100\right)$. We have $X_{i} \mid R \sim \operatorname{Binomial}\left(n_{1}, p_{1}\right)$, so $\mathbb{E}\left[X_{i} \mid R\right]=n_{1} p_{1}$. Similarly, $X_{i} \mid R^{C} \sim \operatorname{Binomial}\left(n_{2}, p_{2}\right)$, so $\mathbb{E}\left[X_{i} \mid R^{C}\right]=n_{2} p_{2}$. By the law of total expectation,

$$
\mu=\mathbb{E}\left[X_{i}\right]=\mathbb{E}\left[X_{i} \mid R\right] \mathbb{P}(R)+\mathbb{E}\left[X_{i} \mid R^{C}\right] \mathbb{P}\left(R^{C}\right)=n_{1} p_{1} p_{3}+n_{2} p_{2}\left(1-p_{3}\right)
$$

Hence, by linearity of expectation,

$$
\begin{gathered}
\mathbb{E}[X]=\mathbb{E}\left[\sum_{i=1}^{7}\left(20 X_{i}-100\right)\right]=20 \sum_{i=1}^{7} \mathbb{E}\left[X_{i}\right]-700=140 \mu-700 \\
=140 \cdot\left(n_{1} p_{1} p_{3}+n_{2} p_{2}\left(1-p_{3}\right)\right)-700
\end{gathered}
$$

## Task 3 - Mystery Dish!

A fancy new restaurant has opened up that features only 4 dishes. The unique feature of dining here is that they will serve you any of the four dishes randomly according to the following probability distribution: give dish A with probability 0.5 , dish B with probability $\theta$, dish C with probability $2 \theta$, and dish D with probability $0.5-3 \theta$. Each diner is served a dish independently. Let $x_{A}$ be the number of people who received dish $\mathrm{A}, x_{B}$ the number of people who received dish B , etc, where $x_{A}+x_{B}+x_{C}+x_{D}=n$. Find the MLE $\hat{\theta}$ for $\theta$.

The data tells us, for each diner in the restaurant, what their dish was. We begin by computing the likelihood of seeing the given data given our parameter $\theta$. Because each diner is assigned a dish independently, the likelihood is equal to the product over diners of the chance they got the particular dish they got, which gives us:

$$
\mathcal{L}(x \mid \theta)=0.5^{x_{A}} \theta^{x_{B}}(2 \theta)^{x_{C}}(0.5-3 \theta)^{x_{D}}
$$

From there, we just use the MLE process to get the log-likelihood, take the first derivative, set it equal to 0 , and solve for $\hat{\theta}$.

$$
\begin{gathered}
\ln \mathcal{L}(x \mid \theta)=x_{A} \ln (0.5)+x_{B} \ln (\theta)+x_{C} \ln (2 \theta)+x_{D} \ln (0.5-3 \theta) \\
\frac{\mathrm{d}}{\mathrm{~d} \theta} \ln \mathcal{L}(x \mid \theta)=\frac{x_{B}}{\theta}+\frac{x_{C}}{\theta}-\frac{3 x_{D}}{0.5-3 \theta} \\
\frac{x_{B}}{\hat{\theta}}+\frac{x_{C}}{\hat{\theta}}-\frac{3 x_{D}}{0.5-3 \hat{\theta}}=0
\end{gathered}
$$

Solving yields $\hat{\theta}=\frac{x_{B}+x_{C}}{6\left(x_{B}+x_{C}+x_{D}\right)}$.

## Task 4 - A Red Poisson

Suppose that $x_{1}, \ldots, x_{n}$ are i.i.d. samples from a Poisson $(\theta)$ random variable, where $\theta$ is unknown. In other words, they follow the distributions $\mathbb{P}(k ; \theta)=\theta^{k} e^{-\theta} / k!$, where $k \in \mathbb{N}$ and $\theta>0$ is a positive real number.
Find the MLE of $\theta$.
We follow the recipe given in class:

$$
\begin{aligned}
\mathcal{L}\left(x_{1}, \ldots, x_{n} \mid \theta\right) & =\prod_{i=1}^{n} e^{-\theta} \frac{\theta^{x_{i}}}{x_{i}!} \\
\ln \mathcal{L}\left(x_{1}, \ldots, x_{n} \mid \theta\right) & =\sum_{i=1}^{n}\left[-\theta-\ln \left(x_{i}!\right)+x_{i} \ln (\theta)\right] \\
\frac{\mathrm{d}}{\mathrm{~d} \theta} \ln \mathcal{L}\left(x_{1}, \ldots, x_{n} \mid \theta\right) & =\sum_{i=1}^{n}\left[-1+\frac{x_{i}}{\theta}\right] \\
-n+\frac{\sum_{i=1}^{n} x_{i}}{\hat{\theta}} & =0 \\
\hat{\theta}=\frac{\sum_{i=1}^{n} x_{i}}{n} &
\end{aligned}
$$

## Task 5 - A biased estimator

In class, we showed that the maximum likelihood estimate of the variance $\theta_{2}$ of a normal distribution (when both the true mean $\mu$ and true variance $\sigma^{2}$ are unknown) is what's called the population variance. That is

$$
\left.\hat{\theta}_{2}=\left(\frac{1}{n} \sum_{i=1}^{n}\left(x_{i}-\hat{\theta}_{1}\right)^{2}\right)\right)
$$

where $\hat{\theta}_{1}=\frac{1}{n} \sum_{i=1}^{n} x_{i}$ is the MLE of the mean. Is $\hat{\theta}_{2}$ unbiased?
Let $\bar{X}=\frac{1}{n} \sum_{i=1}^{n} X_{i}$. Then

$$
\mathbb{E}\left[\hat{\theta}_{2}\right]=\mathbb{E}\left[\frac{1}{n} \sum_{i=1}^{n}\left(X_{i}-\bar{X}\right)^{2}\right]=\mathbb{E}\left[\frac{1}{n} \sum_{i=1}^{n}\left(X_{i}^{2}-2 X_{i} \bar{X}+\bar{X}^{2}\right)\right]
$$

which by linearity of expectation (and distributing the sum) is

$$
\begin{aligned}
& =\frac{1}{n} \sum_{i=1}^{n} \mathbb{E}\left[X_{i}^{2}\right]-\mathbb{E}\left[\frac{2}{n} \bar{X} \sum_{i=1}^{n} X_{i}\right]+\mathbb{E}\left[\bar{X}^{2}\right] \\
& =\frac{1}{n} \sum_{i=1}^{n} \mathbb{E}\left[X_{i}^{2}\right]-2 \mathbb{E}\left[\bar{X}^{2}\right]+\mathbb{E}\left[\bar{X}^{2}\right] \\
& =\frac{1}{n} \sum_{i=1}^{n} \mathbb{E}\left[X_{i}^{2}\right]-\mathbb{E}\left[\bar{X}^{2}\right] .
\end{aligned}
$$

We know that for any random variable $Y$, since $\operatorname{Var}(Y)=\mathbb{E}\left[Y^{2}\right]-(\mathbb{E}[Y])^{2}$ it holds that

$$
\mathbb{E}\left[Y^{2}\right]=\operatorname{Var}(Y)+(\mathbb{E}[Y])^{2}
$$

Also, we have $\mathbb{E}\left[X_{i}\right]=\mu, \operatorname{Var}\left(X_{i}\right)=\sigma^{2} \forall i$ and $\mathbb{E}[\bar{X}]=\mu, \operatorname{Var}(\bar{X})=\frac{\sigma^{2}}{n}$. Combining these facts, we get

$$
\mathbb{E}\left[X_{i}^{2}\right]=\sigma^{2}+\mu^{2} \quad \forall i \quad \text { and } \quad \mathbb{E}\left[\bar{X}^{2}\right]=\frac{\sigma^{2}}{n}+\mu^{2}
$$

Substituting these equations into $\left({ }^{* *}\right)$ we get

$$
\begin{aligned}
\left.\mathbb{E}\left[\frac{1}{n} \sum_{i=1}^{n}\left(X_{i}-\bar{X}\right)^{2}\right)\right] & =\frac{1}{n} \sum_{i=1}^{n} \mathbb{E}\left[X_{i}^{2}\right]-\mathbb{E}\left[\bar{X}^{2}\right]=\sigma^{2}+\mu^{2}-\left(\frac{\sigma^{2}}{n}+\mu^{2}\right) \\
& =\left(1-\frac{1}{n}\right) \sigma^{2} .
\end{aligned}
$$

Thus $\hat{\theta}_{2}$ is not unbiased.

## Task 6 - Weather Forecast

A weather forecaster predicts sun with probability $\theta_{1}$, clouds with probability $\theta_{2}-\theta_{1}$, rain with probability $\frac{1}{2}$ and snow with probability $\frac{1}{2}-\theta_{2}$. This year, there have been 55 sunny days, 100 cloudy days, 160 rainy days and 50 snowy days. What is the maximum likelihood estimator for $\theta_{1}$ and $\theta_{2}$ ?

We want to find the likelihood of the data samples given the parameter $\theta$. To do this, we take the following product over all the data points.

$$
\mathcal{L}\left(x_{1}, \ldots, x_{365} \mid \theta_{1}, \theta_{2}\right)=\theta_{1}^{55}\left(\theta_{2}-\theta_{1}\right)^{100}\left(\frac{1}{2}\right)^{160}\left(\frac{1}{2}-\theta_{2}\right)^{50}
$$

Then, we use this to determine the log likelihood.

$$
\begin{aligned}
\ln \mathcal{L}\left(x_{1}, \ldots, x_{365} \mid \theta_{1}, \theta_{2}\right) & =\ln \theta_{1}^{55}\left(\theta_{2}-\theta_{1}\right)^{100}\left(\frac{1}{2}\right)^{160}\left(\frac{1}{2}-\theta_{2}\right)^{50} \\
& =\ln \theta_{1}^{55}+\ln \left(\theta_{2}-\theta_{1}\right)^{100}+\ln \left(\frac{1}{2}\right)^{160}+\ln \left(\frac{1}{2}-\theta_{2}\right)^{50} \\
& =55 \ln \theta_{1}+100 \ln \left(\theta_{2}-\theta_{1}\right)+160 \ln \left(\frac{1}{2}\right)+50 \ln \left(\frac{1}{2}-\theta_{2}\right)
\end{aligned}
$$

Then, we take the derivative of the log likelihood with respect to $\theta_{1}$.

$$
\frac{\partial}{\partial \theta_{1}} \ln \mathcal{L}\left(x_{1}, \ldots, x_{365} \mid \theta_{1}, \theta_{2}\right)=\frac{55}{\theta_{1}}-\frac{100}{\theta_{2}-\theta_{1}}
$$

Setting this equal to 0 , we solve for $\hat{\theta_{1}}$ :

$$
\begin{gathered}
\frac{55}{\hat{\theta_{1}}}-\frac{100}{\hat{\theta_{2}}-\hat{\theta_{1}}}=0 \\
55\left(\hat{\theta_{2}}-\hat{\theta_{1}}\right)-100 \hat{\theta_{1}}=0 \\
55 \hat{\theta_{2}}=155 \hat{\theta_{1}} \\
\hat{\theta_{1}}=\frac{11}{31} \hat{\theta_{2}}
\end{gathered}
$$

Then, we take the derivative of the log likelihood with respect to $\theta_{2}$.

$$
\frac{\partial}{\partial \theta_{2}} \ln \mathcal{L}\left(x_{1}, \ldots, x_{365} \mid \theta_{1}, \theta_{2}\right)=\frac{100}{\theta_{2}-\theta_{1}}-\frac{50}{\frac{1}{2}-\theta_{2}}
$$

Setting this equal to 0 , we solve for $\hat{\theta_{2}}$ :

$$
\begin{gathered}
\frac{100}{\hat{\theta_{2}}-\hat{\theta_{1}}}-\frac{50}{\frac{1}{2}-\hat{\theta_{2}}}=0 \\
100\left(\frac{1}{2}-\hat{\theta_{2}}\right)-50\left(\hat{\theta_{2}}-\hat{\theta_{1}}\right)=0 \\
50-150 \hat{\theta_{2}}+50 \hat{\theta_{1}}=0 \\
\hat{\theta_{2}}=\frac{\hat{\theta_{1}}+1}{3}
\end{gathered}
$$

We can now solve the simultaneous equations we have for $\theta_{1}$ and $\theta_{2}$ to obtain the maximum likelihood estimators for each parameter.

$$
\hat{\theta_{2}}=\frac{\hat{\theta_{1}}+1}{3}
$$

Plugging in the equation for $\theta_{1}$, we find

$$
\begin{gathered}
\hat{\theta_{2}}=\frac{\frac{11}{31} \hat{\theta_{2}}+1}{3} \\
3 \hat{\theta_{2}}=\frac{11}{31} \hat{\theta_{2}}+1 \\
93 \hat{\theta_{2}}=11 \hat{\theta_{2}}+31 \\
\hat{\theta_{2}}=\frac{31}{82}
\end{gathered}
$$

Plugging in the value for $\theta_{2}$ into the equation for $\theta_{1}$,

$$
\hat{\theta_{1}}=\frac{11}{31} \cdot \frac{31}{82}=\frac{11}{82}
$$

To confirm that this is in fact a maximum, we could do a second derivative test. We won't ask you do this for this multivariate case, but it would still be good to check!

## Task 7 - Faulty Machines

You are trying to use a machine that only works on some days. If on a given day, the machine is working it will break down the next day with probability $0<b<1$, and works on the next day with probability $1-b$. If it is not working on a given day, it will work on the next day with probability $0<r<1$ and not work the next day with probability $1-r$.
a) In this problem we will formulate this process as a Markov chain. First, let $X^{(t)}$ be a variable that denotes the state of the machine at time $t$. Then, define a state space $\mathcal{S}$ that includes all the possible states that the machine can be in. Lastly, for all $A, B \in \mathcal{S}$ find $\mathbb{P}\left(X^{(t+1)}=A \mid X^{(t)}=B\right)$ ( $A$ and $B$ can be the same state).

Formally, a Markov chain is defined by a state space $\mathcal{S}$ and a transition probability matrix. The two possible states of the machine are "working" and "broken". So, $\mathcal{S}=\{W, B\}$. Let $X_{t}$ be the state of the process at time $t$. Then we can define the following transition probabilities:

$$
\begin{array}{cc}
\mathbb{P}\left(X^{(t+1)}=W \mid X^{(t)}=W\right)=1-b & \mathbb{P}\left(X^{(t+1)}=B \mid X^{(t)}=W\right)=b \\
\mathbb{P}\left(X^{(t+1)}=W \mid X^{(t)}=B\right)=r & \mathbb{P}\left(X^{t+1}=B \mid X^{(t)}=B\right)=1-r
\end{array}
$$

We can also represent the transition probabilities with the following matrix:

$$
M=\left[\begin{array}{cc}
1-b & b \\
r & 1-r
\end{array}\right]
$$

where the $i j$-th entry is probability that the machine is in the $j$-th state at time $t+1$ given it was in state $i$ at time $t$. (Here state 1 is working and state 2 is broken.)
b) Suppose that on day 1 , the machine is working. What is the probability that it is working on day 3?

We are trying to find $\mathbb{P}\left(X^{(3)}=W \mid X^{(1)}=W\right)$. From the law of total probability, and then plugging in the values from our transition matrix:

$$
\begin{aligned}
& \mathbb{P}\left(X^{(3)}=W \mid X^{(1)}=W\right) \\
& \quad=\sum_{i \in \mathcal{S}} \mathbb{P}\left(X^{(3)}=W \mid X^{(1)}=W, X^{(2)}=i\right) \cdot \mathbb{P}\left(X^{(2)}=i \mid X^{(1)}=W\right) \\
& \quad=\mathbb{P}\left(X^{(3)}=W \mid X^{(2)}=W\right) \cdot \mathbb{P}\left(X^{(2)}=W \mid X^{(1)}=W\right) \\
& \quad+\mathbb{P}\left(X^{(3)}=W \mid X^{(2)}=B\right) \cdot \mathbb{P}\left(X^{(2)}=B \mid X^{(1)}=W\right) \\
& \quad=\mathbb{P}\left(X^{(3)}=W \mid X^{(2)}=W\right) \cdot(1-b)+\mathbb{P}\left(X^{(3)}=W \mid X^{(2)}=B\right) \cdot b \\
& \quad=(1-b)(1-b)+r b \\
& \quad=(1-b)^{2}+r b
\end{aligned}
$$

Alternative solution using matrix operations: Let $q^{(t)}$ be the probability vector at time $t$ associated with this Markov chain. The assumption that the machine is working on day 1 is the same as saying that the probability vector $q^{(1)}=[1,0]$. Then

$$
q^{(2)}=q^{(1)} \cdot M=\left[\begin{array}{ll}
1 & 0
\end{array}\right]\left[\begin{array}{cc}
1-b & b \\
r & 1-r
\end{array}\right]=\left[\begin{array}{ll}
1-b & b
\end{array}\right] .
$$

The probability we want to compute is the 1st entry of

$$
q^{(3)}=q^{(2)} \cdot M=\left[\begin{array}{ll}
1-b & b
\end{array}\right]\left[\begin{array}{cc}
1-b & b \\
r & 1-r
\end{array}\right]
$$

which equals $(1-b) \cdot(1-b)+b \cdot r=(1-b)^{2}+b r$.
c) As $n \rightarrow \infty$, what does the probability that the machine is working on day $n$ converge to? To get the answer, solve for the stationary distribution.

The stationary distribution is the row vector $\pi=\left[\pi_{W} \pi_{B}\right]$ such that $\pi P=\pi$. The entries in the vector $\pi_{W}$ and $\pi_{B}$ can be interpreted as the probabilities that the machine works or is broken converge to. As such, $\pi_{W}+\pi_{B}=1$. Additionally, multiplying the stationary distribution by the TPM gives us the following two equations (one per column of $M$ ):

$$
\pi_{W}=\pi_{W}(1-b)+\pi_{B} r \quad \pi_{B}=\pi_{W} b+\pi_{B}(1-r)
$$

Solving these 3 equations for $\pi_{W}$ and $\pi_{B}$ gives us the following solutions for the stationary distribution:

$$
\pi_{W}=\frac{r}{b+r} \quad \pi_{B}=\frac{b}{b+r}
$$

So, as $n \rightarrow \infty$ the probability that the machine works on day $n$ is $\pi_{W}=\frac{r}{b+r}$

## Task 8 - Another Markov Chain

Suppose that the following is the transition probability matrix for a 4 state Markov chain (states $1,2,3,4$ ).

$$
M=\left[\begin{array}{cccc}
0 & 1 / 2 & 1 / 2 & 0 \\
1 / 3 & 0 & 0 & 2 / 3 \\
1 / 3 & 1 / 3 & 0 & 1 / 3 \\
1 / 5 & 2 / 5 & 2 / 5 & 0
\end{array}\right]
$$

a) What is the probability that $X^{(2)}=4$ given that $X^{(0)}=4$ ?

Let's denote the state space $\mathcal{S}=\{1,2,3,4\}$. Using the law of total probability we can determine that

$$
\begin{aligned}
\mathbb{P}\left(X^{(2)}=4 \mid X^{(0)}=4\right) & =\sum_{i \in \mathcal{S}} \mathbb{P}\left(X^{(2)}=4 \mid X^{(0)}=4, X^{(1)}=i\right) \mathbb{P}\left(X^{(1)}=i \mid X^{(0)}=4\right) \\
& =\sum_{i \in \mathcal{S}} \mathbb{P}\left(X^{(2)}=4 \mid X^{(1)}=i\right) \mathbb{P}\left(X^{(1)}=i \mid X^{(0)}=4\right) \\
& =0+\frac{2}{5} \cdot \frac{2}{3}+\frac{2}{5} \cdot \frac{1}{3}+0 \\
& =\frac{2}{5}
\end{aligned}
$$

Alternative solution using matrix operations: Let $q^{(t)}$ be the probability vector at time $t$ associated with this Markov chain. The statement that $X^{(0)}=4$ is equivalent to saying that the probability vector $q^{(0)}=[0,0,0,1]$. Therefore

$$
q^{(1)}=q^{(0)} \cdot M=\left[\begin{array}{llll}
0 & 0 & 0 & 1
\end{array}\right] \cdot\left[\begin{array}{cccc}
0 & 1 / 2 & 1 / 2 & 0 \\
1 / 3 & 0 & 0 & 2 / 3 \\
1 / 3 & 1 / 3 & 0 & 1 / 3 \\
1 / 5 & 2 / 5 & 2 / 5 & 0
\end{array}\right]=\left[\begin{array}{llll}
1 / 5 & 2 / 5 & 2 / 5 & 0
\end{array}\right]
$$

What we want is the 4-th entry of

$$
q^{(2)}=q^{(1)} \cdot M=\left[\begin{array}{llll}
1 / 5 & 2 / 5 & 2 / 5 & 0
\end{array}\right] \cdot\left[\begin{array}{cccc}
0 & 1 / 2 & 1 / 2 & 0 \\
1 / 3 & 0 & 0 & 2 / 3 \\
1 / 3 & 1 / 3 & 0 & 1 / 3 \\
1 / 5 & 2 / 5 & 2 / 5 & 0
\end{array}\right]
$$

This is $0+\frac{2}{5} \cdot \frac{2}{3}+\frac{2}{5} \cdot \frac{1}{3}+0=2 / 5$.
b) Write down the system of equations that the stationary distribution must satisfy and solve them.

The stationary distribution is the row vector $\pi=\left[\pi_{1} \pi_{2} \pi_{3} \pi_{4}\right]$ such that $\pi P=\pi$. We know that $\pi_{1}+\pi_{2}+\pi_{3}+\pi_{4}=1$. Additionally, multiplying the stationary distribution by the TPM gives us the following equations:

$$
\begin{aligned}
\pi_{1} & =\frac{1}{3} \pi_{2}+\frac{1}{3} \pi_{3}+\frac{1}{5} \pi_{4} \\
\pi_{2} & =\frac{1}{2} \pi_{1}+\frac{1}{3} \pi_{3}+\frac{2}{5} \pi_{4} \\
\pi_{3} & =\frac{1}{2} \pi_{1}+\frac{2}{5} \pi_{4} \\
\pi_{4} & =\frac{2}{3} \pi_{2}+\frac{1}{3} \pi_{3}
\end{aligned}
$$

Solving these 5 equations for each $\pi_{i}$ gives us the following solutions for the stationary distribution:

$$
\pi_{1}=\frac{46}{206} \quad \pi_{2}=\frac{60}{206} \quad \pi_{3}=\frac{45}{206} \quad \pi_{4}=\frac{55}{206}
$$

## Task 9 - Three Tails

You flip a fair coin until you see three tails in a row. Model this as a Markov chain with the following states:

- $S$ : start state, which we are only in before flipping any coins.
- $H$ : We see a heads, which means no streak of tails currently exists.
- $T$ : We've seen exactly one tail in a row so far.
- TT: We've seen exactly two tails in a row so far.
- TTT: We've accomplished our goal of seeing three tails in a row, stop flipping, and stay there.
a) Write down the transition probability matrix.

$$
M=\left[\begin{array}{ccccc}
0 & 1 / 2 & 1 / 2 & 0 & 0 \\
0 & 1 / 2 & 1 / 2 & 0 & 0 \\
0 & 1 / 2 & 0 & 1 / 2 & 0 \\
0 & 1 / 2 & 0 & 0 & 1 / 2 \\
0 & 0 & 0 & 0 & 1
\end{array}\right]
$$

b) Write down the system of equations whose variables are $D(s)$ for each state $s \in\{S, H, T, T T, T T T\}$, where $D(s)$ is the expected number of steps until state $T T T$ is reached starting from state $s$. Solve this system of equations to find $D(S)$.

Using the law of total expectation and the transition probability matrix above we can set up and solve the following system of equations:

$$
\begin{aligned}
D(T T T) & =0 \\
D(T T) & =1+\frac{1}{2} D(H)+\frac{1}{2} D(T T T)=\frac{1}{2} D(H)+1 \\
D(T) & =1+\frac{1}{2} D(H)+\frac{1}{2} D(T T)=\frac{3}{4} D(H)+\frac{3}{2} \\
D(H) & =1+\frac{1}{2} D(H)+\frac{1}{2} D(T)=\frac{7}{8} D(H)+\frac{7}{4} \\
D(S) & =1+\frac{1}{2} D(H)+\frac{1}{2} D(T)=\frac{7}{8} D(H)+\frac{7}{4}
\end{aligned}
$$

Solving for $D(H)$ gives us that $D(H)=14$, which allows as to solve for the rest of the expected number of steps, $D(T T)=8, D(T)=12, D(S)=14$. So, we expect to flip 14 coins before we flip three tails in a row.
c) Write down the system of equations whose variables are $\gamma(s)$ for each state $s \in\{S, H, T, T T, T T T\}$, where $\gamma(s)$ is the expected number of heads seen before state $T T T$ is reached. Solve this system to find $\gamma(S)$, the expected number of heads seen overall until getting three tails in a row.

Like in the previous part we can use the LoTE and the Transition Probability Matrix to set up and solve the following system of equations. We get one equation for each column of $M$ :

$$
\begin{aligned}
\gamma(T T T) & =0 \\
\gamma(T T) & =0.5 \gamma(H)+0.5 \gamma(T T T)=0.5 \gamma(H) \\
\gamma(T) & =0.5 \gamma(H)+0.5 \gamma(T T)=0.75 \gamma(H) \\
\gamma(H) & =1+0.5 \gamma(H)+0.5 \gamma(T)=0.875 \gamma(H)+1 \\
\gamma(S) & =0.5 \gamma(H)+0.5 \gamma(T)=0.875 \gamma(H)
\end{aligned}
$$

Solving for $\gamma(H)$ gives us $\gamma(H)=8$. This allows us to solve for the other expected values which are $\gamma(T T)=4, \gamma(T)=6, \gamma(S)=7$. So, we expect to see 7 heads before we flip three tails in a row.

## Task 10 - Use of Law of Total Probability

Suppose that the time until server 1 crashes is $X \sim \operatorname{Exp}(\lambda)$ and the time until server 2 crashes is independent, with $Y \sim \operatorname{Exp}(\mu)$.
What is the probability that server 1 crashes before server 2 ?
We have $X \sim \operatorname{Exp}(\lambda)$ and $Y \sim \operatorname{Exp}(\mu)$, and want to find $\mathrm{P}(X ; Y)$. Let $A$ be the event that $X$ ¡ $Y$. By the Law of Total Probability for Continuous Variables, using $A$ as the event and $Y$ as the continuous random variable, we have

$$
\mathbb{P}(A)=\int_{-\infty}^{\infty} \mathbb{P}(A \mid Y=y) f_{Y}(y) d y
$$

As $Y \sim \operatorname{Exp}(\mu), f_{Y}(y)=0$ for all $y<0$, so the integral is only nonzero over the range from 0 to $\infty$, so we have

$$
\mathbb{P}(A)=\int_{0}^{\infty} \mathbb{P}(A \mid Y=y) f_{Y}(y) d y
$$

As $A$ is the event that $X<Y$, we know

$$
\mathbb{P}(A \mid Y=y)=\mathbb{P}(X<Y \mid Y=y)=\mathbb{P}(X<y \mid Y=y)=\mathbb{P}(X<y)
$$

Note the last equality above is true since $X, Y$ are independent so $P(X<y \mid Y=y)=P(X<y)$ for any $y$. Also note $\mathbb{P}(X<y)=\mathbb{P}(X \leqslant y)$ as $X$ is continuous. So,

$$
\mathbb{P}(A)=\int_{0}^{\infty} \mathbb{P}(A \mid Y=y) f_{Y}(y) d y=\int_{0}^{\infty} \mathbb{P}(X \leqslant y) f_{Y}(y) d y
$$

Here, as $X \sim \operatorname{Exp}(\lambda)$, we can plug in the $\operatorname{CDF}$ of $\operatorname{Exp}(\lambda)$ to get $\mathbb{P}(X \leqslant y)$, and as $Y \sim \operatorname{Exp}(\mu)$, we can plug in the PDF of $\operatorname{Exp}(\mu)$ to get $f_{Y}(y)$ as follows:

$$
\mathbb{P}(A)=\int_{0}^{\infty} \mathbb{P}(X \leqslant y) f_{Y}(y) d y=\int_{0}^{\infty}\left(1-e^{-\lambda y}\right) f_{Y}(y) d y=\int_{0}^{\infty}\left(1-e^{-\lambda y}\right) \mu e^{-\mu y} d y
$$

We can simply evaluate the integral to finish the problem as follows:

$$
\mathbb{P}(A)=\int_{0}^{\infty}\left(1-e^{-\lambda y}\right) \mu e^{-\mu y} d y=\int_{0}^{\infty} \mu e^{-\mu y} d y+\int_{0}^{\infty}\left(-e^{-\lambda y}\right) \mu e^{-\mu y} d y
$$

Let's now evaluate each of the above integrals:

$$
\begin{gathered}
\int_{0}^{\infty} \mu e^{-\mu y} d y=\left[-e^{-\mu y}\right]_{0}^{\infty}=0-(-1)=1 \\
\int_{0}^{\infty}\left(-e^{-\lambda y}\right) \mu e^{-\mu y} d y=-\mu \int_{0}^{\infty}\left(e^{-(\lambda+\mu) y}\right) d y=\frac{-\mu}{\lambda+\mu}\left[-e^{-(\lambda+\mu) y}\right]_{0}^{\infty}=\frac{-\mu}{\lambda+\mu}(0-(-1))=\frac{-\mu}{\lambda+\mu}
\end{gathered}
$$

So, we can combine these results to get:

$$
\mathbb{P}(A)=\int_{0}^{\infty} \mu e^{-\mu y} d y+\int_{0}^{\infty}\left(-e^{-\lambda y}\right) \mu e^{-\mu y} d y=1-\frac{\mu}{\lambda+\mu}=\frac{\lambda}{\lambda+\mu}
$$

So, as $A$ is the event that $X<Y$, our final answer is that the probability that server 1 crashes before server 2 is $\frac{\lambda}{\lambda+\mu}$.

## Task 11 - Elevator rides

The number $X$ of people who enter an elevator on the ground floor is a Poisson random variable with mean 10. If there are N floors above the ground floor, and if each person is equally likely to get off at any one of the $N$ floors, independently of where others get off, compute the expected number of stops the elevator will make before discharging all the passengers.

Let $S$ be the number of stops the elevator makes, and $X \sim \operatorname{Poi}(10)$. We shall calculate $E[S]$. By the law of total expectation, partitioning on the value of $X$, we have

$$
E[S]=\sum_{i=0}^{\infty} E[S \mid X=i] P(X=i)
$$

By the definition of Poison distribution, we know

$$
P(X=i)=e^{-10} \frac{10^{i}}{i!}
$$

To calculate $E[S \mid X=i]$, let $S=y_{1}+y_{2}+\ldots+y_{N}$, where

$$
y_{j}= \begin{cases}1 & \text { if someone gets off at the } j^{\text {th }} \text { floor } \\ 0 & \text { otherwise }\end{cases}
$$

Then, by the linearity of conditional expectation, we have

$$
E[S \mid X=i]=E\left[y_{1}+y_{2}+\ldots+y_{N} \mid X=i\right]=\sum_{j=1}^{N} E\left[y_{j} \mid X=i\right]=\sum_{j=1}^{N} \mathbb{P}\left(y_{j}=1 \mid X=i\right)
$$

To figure out $\mathbb{P}\left(y_{j}=1 \mid X=i\right)$, it would be more convenient to find its complement, $\mathbb{P}\left(y_{j}=0 \mid X=i\right)$, which represents the probability that nobody gets off at $j^{\text {th }}$ floor. Since each person is equally likely to get off at any one of $N$ floor, we know $\mathbb{P}\left(y_{j}=0 \mid X=i\right)=\left(\frac{N-1}{N}\right)^{i}$. Thus, we have

$$
E[S \mid X=i]=\sum_{j=1}^{N} \mathbb{P}\left(y_{j}=1 \mid X=i\right)=\sum_{j=1}^{N} 1-\mathbb{P}\left(y_{j}=0 \mid X=i\right)=\sum_{j=1}^{N} 1-\left(\frac{N-1}{N}\right)^{i}
$$

Finally, we find

$$
E[S]=\sum_{i=0}^{\infty} E[S \mid X=i] P(X=i)=\sum_{i=0}^{\infty}\left(\sum_{j=1}^{N} 1-\left(\frac{N-1}{N}\right)^{i}\right) e^{-10} \frac{10^{i}}{i!}
$$

