

## CSE 143

### Trees

[Chapter 10]

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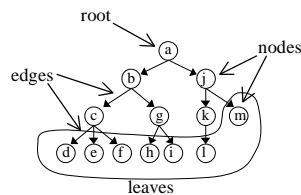
## Everyday Examples of Trees

- Family tree
- Company organization chart
- Table of contents
- Any hierarchical organization of information, representing components in terms of their subcomponents

*NB: Some of these are not true trees in the CS definition of the term*

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## A Tree



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## Tree Terminology

- Empty tree: tree with no nodes
- Child of a node  $u$ 
  - Any node reachable from  $u$  by 1 edge pointing away from  $u$
  - Nodes can have zero, one, or more children
  - Leaves have no children
- If  $b$  is a child of  $a$ , then  $a$  is the *parent* of  $b$ 
  - All nodes except root have exactly one parent
  - Root has no parent

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## Tree Terminology (2)

- **Descendant** of a node (recursive definition)

- $P$  is a descendant of  $P$
- If  $C$  is child of  $P$ , and  $P$  is a descendant of  $A$ , then  $C$  is a descendant of  $A$
- Example:  $k$  and  $m$  are descendants of  $j$ ,  $l$  is descendant of  $j$ ,  $k$ , and  $l$

- **Ancestor** of a node

- If  $D$  is a descendant of  $A$ , then  $A$  is an ancestor of  $D$
- Example:  $j$ ,  $k$ , and  $l$  are ancestors of  $l$

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## Tree Terminology (3)

- **Subtree**

- Any node of a tree, with all of its descendants

- **Depth** (recursive definition)

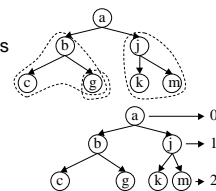
- Depth of root node is 0
- Depth of any node other than root is one greater than depth of its parent

- **Height**

- Height of a tree is maximum of all depths of its leaves

- **Warning:** Definitions vary

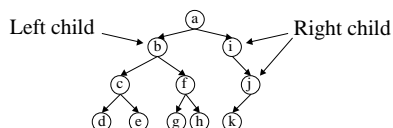
- Some define depth of the root node as 1.



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## Binary Trees

- A *binary tree* is a tree each of whose nodes has exactly zero, one, or two children
- Two children are called the left child and right child



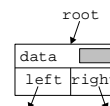
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## Binary Tree Data Structure

- Usually use a variant of a Node:

```

struct BTreeNode {
    int data;
    BTreeNode *left;
    BTreeNode *right;
};
  
```



- Keep a *root* pointer to the root node
  - Empty tree has a *NULL* root
- Note the recursive data structure
- As the data structure is recursive, algorithms often are recursive as well

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## Example: Counting Nodes

- Base case: Empty tree has zero nodes
- Recursive case: Nonempty tree has root + nodes in left subtree + nodes in right subtree

```

int CountNodes(BTreeNode *root)
{
    if ( root == NULL )
        return 0; // base
    else
        return 1 + CountNodes(root->left)
            + CountNodes(root->right);
}
  
```

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## Finding the Height

- Base case: Empty tree has height -1
- Recursive case: Nonempty tree has height 1 more than maximum height of left and right subtrees

```

int Height(BTreeNode *root) {
    if ( root == NULL )
        return -1;
    else
        return 1 + max(Height(root->left),
                       Height(root->right));
}
  
```

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## Analyses

- What is running time of these algorithms?
  - Base case:  $O(1)$  for both
  - Recursive case:  $O(N)$  for both, where  $N$  is the number of nodes in tree
- How to write an iterative version?
  - Try it

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## Recursive Tree Searching

- How to tell if a data item is in a binary tree?

```

bool Find(BTreeNode *root, int item) {
    if ( root == NULL )
        return false;
    else if ( root->data == item )
        return true;
    else
        return ( Find(root->left, item) ||
                Find(root->right, item) );
}
  
```

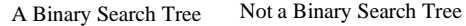
- What is the running time of this algorithm?
  - Worst case: Has to visit every node in the tree,  $O(N)$
  - Can we do better?

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[Section 13.3]

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## Examples and Non-Examples



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## Finding an item in a BST

```
Find(root, 10)
```



## Finding an item in a BST (2)

If we have a binary search tree, then Find can be done as:

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## Running time of Find

- ```

graph TD
    root((root)) --> 9((9))
    9 --> 4((4))
    9 --> 12((12))
    4 --> 2((2))
    4 --> 7((7))
    12 --> 10((10))
    12 --> 15((15))

```

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## Running time of Find (2)

- ```

graph TD
    root((root)) --> 9((9))
    9 --> 12((12))
    12 --> 15((15))
    15 --> 18((18))

```

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## Tables Revisited

- Using a List or Array to implement Table can be inefficient for searching
- Could use binary search trees to implement a table (dictionary)
- Must support Insert and Delete in addition to Find
- Must maintain BST ordering constraint

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## Inserting in a BST

To insert a new key:

- Base case:
  - If tree is empty, create new node for item
  - If root holds key, return (no duplicate keys allowed)
- Recursive case: If key < root's value, recursively add to left subtree, otherwise to right subtree

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## Example

Add 8, 10, 5, 1, 7, 11 to an empty BST, in that order:

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## Inserting in a BST (2)

```
// Add data to tree root and return ptr to tree
BTreeNode * Insert(BTreeNode *root, int data) {
    if ( root == NULL ) {
        BTreeNode *tmp = new BTreeNode;
        tmp->left = tmp->right = NULL;
        tmp->data = data;
        return tmp;
    }
    if (data < root->data )
        root->left = Insert(root->left, data);
    else if (data > root->data )
        root->right = Insert(root->right, data);
    return root;
}
```

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## Example (2)

- What if we change the order in which the numbers are added?
- Add 1, 5, 7, 8, 10, 11 to a BST, in that order (following the algorithm):

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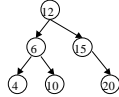
## Complexity of Insert

- Base case:  $O(1)$
- How many recursive calls?
  - For each node added, takes  $O(H)$ , where  $H$  is the height of the tree
- Again, what is height of tree?
  - Balanced trees yields best-case height of  $O(\log N)$  for  $N$  nodes
  - Degenerate trees yield worst-case height of  $O(N)$  for  $N$  nodes
  - For random insertions, expected height is  $O(\log N)$  -- true, but not simple to prove

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## Deleting an Item from a BST

- Simple strategy: lazy deletion (just mark the node as “deleted”)
- The hard way. Must deal with 3 cases
  - 1. The deleted item has no children (easy)
  - 2. The deleted item has 1 child (harder)
  - 3. The deleted item has 2 children (hardest)



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## Deletion (2): Algorithm

- First find the node (call it N) to delete.
- If N is a leaf, just delete it.
- If N has just one child, have N's parent bypass it and point to N's child.
- If N has two children:
  - Replace N's key with the smallest key K of the right subtree
  - (Recursively) delete the node that had key K (this node is now useless)
  - Note: The smallest key always lives at the leftmost “corner” of a subtree (why?)

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## Deletion (3): Finding the Node

- This is the “easy” part:

```
BTreeNode* delItem(int item, BTreeNode* t) {
    if (t != NULL) {
        if (item == t->data)
            t = delNode(t);
        else if (item > t->data)
            t->right = delItem(item, t->right);
        else
            t->left = delItem(item, t->left);
    }
    return t;
}
```

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## Deletion (4): Deleting the Node

```
BTreeNode* delNode(BTreeNode* t) {
    if (t->left && t->right) { // 2 children
        t->data = findMin(t->right);
        t->right = delItem(t->data, t->right);
        return t;
    }
    else { // 0 or 1 child
        BTreeNode* rval = NULL;
        if (t->left) // left child only
            rval = t->left;
        else if (t->right) // right child only
            rval = t->right;
        delete t;
        return rval;
    }
}
```

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## Deletion (5): Finding Min

- All that remains is to figure out how to find the minimum value in a BST
- Remember, the minimum element lives at the leftmost “corner” of a BST

```
// PRECONDITION: must be called on non-NULL pointer

int findMin(BTreeNode* t)
{
    assert(t != NULL);
    while (t->left != NULL)
        t = t->left;
    return t->data;
}
```

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## Balanced Search Trees

- BST operations are dependent on tree height
  - $O(\log N)$  for N nodes if tree is balanced
  - $O(N)$  if tree is not
- Can we ensure tree is always balanced?
  - Yes: Insert and Delete can be modified to reorganize tree if it gets unbalanced
  - Exact details more complicated
  - Results in  $O(\log N)$  dictionary operations, even in worst case

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## Tree Traversal

- As with lists, would like to be able to iterate through all nodes in a tree
  - How to have equivalent to `Start()`, `IsEnd()`, `NextElement()`?
- What order should nodes be visited in?
  - Top-down?
  - Left-to-right?
  - Bottom-up?
  - How to deal with recursive nature of trees?
- Visiting nodes of a tree is called *tree traversal*

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## Types of Traversal

- Preorder** traversal:
  - Visit the node *first*
  - Recursively do preorder traversal on its children, in some order
- Postorder** traversal:
  - Recursively do postorder traversals of children, in some order
  - Visit the node *last*

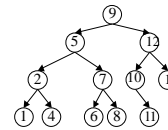
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## Inorder (for Binary Trees)

- With a binary tree, each node has at most two children, called *left* and *right*
- Inorder** traversal:
  - Recursively do inorder traversal of left child
  - Then visit the node
  - Then recursively do inorder traversal of right child
- For preorder and postorder traversals, typically traverse left child before right one

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## Example of Tree Traversal



Preorder:

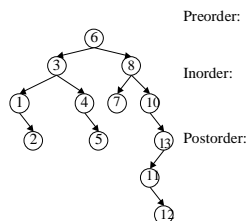
Inorder:

Postorder:

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## Another Example

What about this tree?



Preorder:

Inorder:

Postorder:

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## Example Traversal: Printing

```

// print the nodes of tree with given root
void Preorder (BTreeNode *root)
{
    if ( root == NULL )
        return;

    // Visit the node first
    cout << root->data << " ";
    Preorder (root->left);
    Preorder (root->right);
}
    
```

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## Example Traversal: Printing

```
void printInOrder(BTreeNode* t) {
    if (t != NULL) {
        printInOrder(t->left);
        cout << t->data << " ";
        printInOrder(t->right);
    }
}

void printPreOrder(BTreeNode* t) {
    if (t != NULL) {
        cout << t->data << " ";
        printInOrder(t->left);
        printInOrder(t->right);
    }
}
```

- Why might these traversals be useful?

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## Another Example

- Use a postorder traversal to return a whole tree to the heap.

```
void deleteTree(BTreeNode* t) {
    if (t != NULL) {
        deleteTree(t->left);
        deleteTree(t->right);
        delete t;
    }
}
```

- Would inorder or preorder work as well?

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## Analysis of Tree Traversal

- How many recursive calls?
  - Two for every node in tree (plus one initial call);
  - $O(N)$  in total for  $N$  nodes
- How much time per call?
  - Depends on complexity  $O(V)$  of the visit
  - For printing and most other types of traversal, visit is  $O(1)$  time
- Multiply to get total
  - $O(N) * O(V) = O(N * V)$
- Does tree shape matter?

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## Expression Trees [Section 13.5]

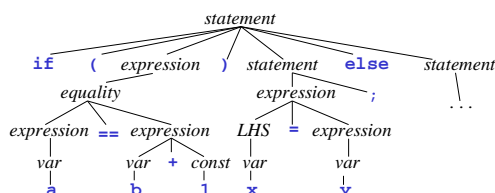
- Programs have a hierarchical structure
  - All statements have a fixed form
  - Statements can be ordered and nested almost arbitrarily (nested if-then-else)
- Can use a structure known as a *syntax tree* to represent programs
  - Trees capture hierarchical structure

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## A Syntax Tree

Consider the C++ statement:

```
if ( a == b + 1 ) x = y; else ...
```



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## Syntax Trees

- Compilers usually use syntax trees when compiling programs
  - Can apply simple rules to check program for syntax errors (the "grammar" in Appendix K of textbook)
  - Easier for compiler to translate and optimize than text file
- Process of building a syntax tree is called *parsing*

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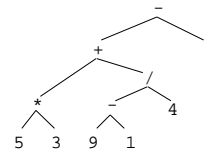
## Binary Expression Trees

- A *binary expression tree* is a syntax tree used to represent meaning of a mathematical expression
  - Normal mathematical operators like +, -, \*, /
- Structure of tree defines result
- Easy to evaluate expressions from their binary expression tree

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## Example

$5 * 3 + (9 - 1) / 4 - 1$



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## Traversing Expression Trees

- Traverse in preorder for prefix notation  
- + \* 5 3 / - 9 1 4 1
- Traverse in inorder for infix notation  
5 \* 3 + 9 - 1 / 4 - 1
  - Note that operator precedence may be wrong without adding parentheses at every step  
 $((5 * 3) + ((9 - 1) / 4)) - 1$
- Traverse in postorder for postfix notation  
5 3 \* 9 1 - 4 / + 1 -

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## Evaluating Expressions

- Easy to evaluate an expression from its binary expression tree
  - Use a postorder traversal
  - Recursively evaluate the left and right subtrees and store those values
  - Apply operator at root to stored values
- Much like using a stack to evaluate postfix notation

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## Trees Summary

- Tree as new hierarchical data structure
  - Recursive definition and recursive data structure
- Tree parts and terminology
  - Made up of nodes
  - Root node, leaf nodes
  - Children, parents, ancestors, descendants
  - Depth of node, height of tree
  - Subtrees

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## Trees Summary (2)

- Binary Trees
  - Either 0, 1, or 2 children at any node
  - Recursive functions to manipulate them
- Binary Search Trees
  - Binary Trees with ordering invariant
  - Recursive BST search
  - Recursive Insert, Delete functions
  - $O(H)$  operations, where  $H$  is height of tree
  - $O(\log N)$  for  $N$  nodes in balanced case
  - $O(N)$  in worst case

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## Trees Summary (3)

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- Tree Traversals
  - Preorder traversal
  - Postorder traversal
- Binary Tree Traversals
  - Inorder traversal
- Expression and Syntax Trees

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