



Searching and Sorting [Sections 12.4, 12.7-12.8]

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Searching and Sorting

- ◆ Two very common problems in Computer Science
- ◆ Searching
 - ◆ Given a collection and an element, find the element in the collection
 - ◆ Useful for both Table and Set ADTs
 - ◆ Elements must be comparable using ==
- ◆ Sorting
 - ◆ Given a collection, rearrange elements into some order
 - ◆ Elements must be comparable using <= (or <)

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Searching Arrays

- ◆ We can search any sequential collection using the supplied navigation methods
- ◆ But we'll focus on searching arrays
 - ◆ Direct access makes searching potentially faster
 - ◆ Indices allow us to return location of element in array

```
int search( int data[], int size, int item ) {  
    // Return the index of item in the array  
    // or -1 if the item isn't in the array  
}
```

- ◆ Size of problem is length of the array

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Linear Search

- ◆ Look at every array element in order

```
// Linear search  
int search( int data[], int size, int item ) {  
    for( int idx = 0; idx < size; idx++ ) {  
        if( data[ idx ] == item ) {  
            return idx;  
        }  
    }  
    return -1;  
}
```

- ◆ What's the complexity of linear searching?

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Searching a Sorted Array

- ◆ If the array is already in sorted order, we can do a lot better
- ◆ Idea: for any chunk of the array, the item we're searching for is either <, == or > the element at the middle of the chunk
 - ◆ If ==, we're done
 - ◆ If <, we don't have to look at anything right of the middle
 - ◆ If >, we don't have to look at anything left of the middle

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Binary Search

- ◆ Jump to the middle and discard the half we don't care about

```
// Binary search  
int search( int data[], int size, int item ) {  
    return findInRange( data, item, 0, size - 1 );  
}  
  
int findInRange( int data[], int item, int lo, int hi ) {  
    if( lo > hi ) return -1;  
    int mid = (lo+hi) / 2;  
    if( item == data[ mid ] ) {  
        return mid;  
    } else if( item < data[ mid ] )  
        return findInRange( data, item, lo, mid - 1 );  
    } else {  
        return findInRange( data, item, mid + 1, hi );  
    }  
}
```

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Performance Analysis

- ◆ How much work is done at each recursive call?
- ◆ How many recursive calls are there?
- ◆ On a sorted array, would you rather use linear search or binary search?

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Other Searching Methods

- ◆ Interpolation Search
 - ◆ If the array contains numeric data, can "guess" how far into array to jump instead of middle
 - ◆ Works well on uniformly distributed data
 - ◆ Worst case is $O(n)$, average case is better than $O(\log_2 n)$
- ◆ Hashing (maybe later)
 - ◆ Relies on constructing a "hash function"
 - ◆ Average case is $O(1)$!!

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Sorting Arrays

- ◆ Given an array, move elements around until the array is sorted according to some \leq relation
 - ◆ If $idx \leq jdx$, then $data[idx] \leq data[jdx]$
- ◆ Size of problem is length of array
- ◆ Two facets to amount of work done
 - ◆ Number of element comparisons
 - ◆ Number of data movements

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Selection Sort

```
void selectionSort( int* data, int size )
{
    if( size > 1 ) {
        int mi = 0;
        for( int idx = 1; idx < size; ++idx ) {
            if( data[ idx ] < data[ mi ] ) {
                mi = idx;
            }
        }
        swap( data[ 0 ], data[ mi ] );
        selectionSort( data + 1, size - 1 );
    }
}
```

- ◆ How many recursive calls are there?
- ◆ How much work done at each recursive call?

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Insertion Sort

- ◆ Idea: build a new list that's always sorted and return that
- ◆ Better for linked lists
- ◆ Can be faster than selection sort
- ◆ Can use as basis for new ADT: SortedList

```
IntList insertionSort( IntList list )
{
    IntList result;
    list.start();
    while( !list.isEmpty() ) {
        int item = list.getData();
        list.deleteItem();
        insert( result, item );
    }
    return result;
}

void insert( IntList list, int item )
{
    for( list.start(); !list.atEnd(); list.advance() ) {
        if( item < list.getData() ) {
            break;
        }
    }
    list.insertBefore( item );
}
```

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Fast Sorting Algorithms

- ◆ Even $O(n^2)$ can get expensive when n is really big
- ◆ There are sorting algorithms that run closer to $O(n \log n)$
- ◆ These algorithms tend to be elegantly recursive: break the problem down, sort subproblems, reassemble (**divide and conquer**)
 - ◆ Quicksort
 - ◆ Mergesort

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Mergesort

- ◆ Idea:
 - ◆ Break the list down into two roughly equal-sized sublists
 - ◆ Recursively sort each sublist
 - ◆ "Merge" the sublists together to get solution

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How To Merge

- ◆ Start with two **sorted** lists of integers, which act like two queues
- ◆ Until both lists are empty, remove the front element which is smaller and add to result list
- ◆ Result will be sorted!

```

IntList merge( IntList& l1, IntList& l2 ) {
    IntList result;
    l1.start();
    l2.start();
    while( true ) {
        if( l1.isEmpty() && l2.isEmpty() ) {
            return result;
        } else if( l1.isEmpty() ) {
            result.insertAfter( l2.getData() );
            l2.deleteItem();
        } else if( l2.isEmpty() ) {
            result.insertAfter( l1.getData() );
            l1.deleteItem();
        } else {
            if( l1.getData() < l2.getData() ) {
                result.insertAfter( l1.getData() );
                l1.deleteItem();
            } else {
                result.insertAfter( l2.getData() );
                l2.deleteItem();
            }
        }
    }
}
    
```

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Writing Mergesort

```

void split( IntList& from, IntList& t1, IntList& t2 ) {
    from.start();
    while( true ) {
        if( from.isEmpty() ) break;
        t1.insertAfter( from.getData() );
        from.deleteItem();
        if( from.isEmpty() ) break;
        t2.insertAfter( from.getData() );
        from.deleteItem();
    }
}

IntList mergesort( IntList& list ) {
    if( list.getSize() <= 1 ) {
        return list;
    } else {
        IntList sub1, sub2;
        split( list, sub1, sub2 );
        sub1 = mergesort( sub1 );
        sub2 = mergesort( sub2 );
        return merge( sub1, sub2 );
    }
}
    
```

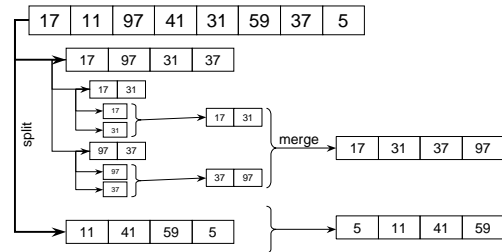
- ◆ Break the list down into two roughly equal-sized sublists
- ◆ Recursively sort each sublist
- ◆ "Merge" the sublists together to get solution

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Example of Mergesort



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Analysis of Mergesort

- ◆ Initial questions:
 - ◆ What's the complexity of `merge()`?
 - ◆ What's the complexity of `split()`?
- ◆ Complete analysis is rather difficult
 - ◆ Each "level" of recursion involves 2^k calls to mergesort, each of size $n/2^k$
 - ◆ So we're doing a total of $O(n)$ work at each level
 - ◆ There are $O(\log n)$ levels, so total complexity is $O(n \log n)$
- ◆ But mergesort is not used very often!

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Quicksort

- ◆ The most widely-accepted fast sorting algorithm
 - ◆ "Easy" to implement
 - ◆ Good performance
 - ◆ Operates "in place": no need to create temporary data structures
- ◆ Idea: given an array of integers...
 - ◆ Choose an element of the array to act as the **pivot**
 - ◆ Move everything \leq pivot to the left, everything $>$ pivot to the right (**partition** the array)
 - ◆ Recursively sort left and right halves

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Writing Quicksort

```
void quicksort( int data[], int size )
{
    quicksortRange( data, 0, size - 1 );
}

void quicksortRange( int data[], int lo, int hi )
{
    if( lo >= hi ) {
        return;
    }

    int midindex = partition( data, lo, hi );
    quicksortRange( data, lo, midindex - 1 );
    quicksortRange( data, midindex + 1, hi );
}
```

- ◆ Partitioning is the hard part...

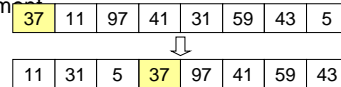
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How to Partition

- ◆ (Arbitrarily) choose the first element of the range as the pivot
- ◆ Swap array elements around until everything \leq pivot is left of pivot, everything $>$ pivot is right of pivot
- ◆ Return the final resting place of the pivot element



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Implementing Partitioning

```
void partition( int data[], int lo, int hi )
{
    int midval = data[ lo ];
    int j = lo;
    int k = hi;

    while( j < k ) {
        while( j <= hi && (data[j] <= midval) ) ++j;
        while( k >= lo && (data[k] > midval) ) --k;
        if( j < k ) {
            swap( data[j], data[k] );
        }
    }

    swap( data[ lo ], data[ k ] );
    return k;
}
```

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Complexity of Partition

- ◆ Don't be fooled by the nested while loops
 - ◆ j starts at lo and only increases
 - ◆ k starts at hi and only decreases
 - ◆ j is incremented at least once for each iteration of outer loop
 - ◆ Stops when j and k cross
- ◆ At most $hi - lo + 1$ iterations of inner loops, so $O(n)$ time

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Complexity of Quicksort

- ◆ Similar to mergesort
 - ◆ Linear work for each recursive call
 - ◆ At every level of recursion, roughly 2^k calls on arrays of size $n/2^k$
 - ◆ So $O(n)$ work at each level of recursion
 - ◆ About $O(\log n)$ levels, so total complexity is $O(n \log n)$
- ◆ But there's a big assumption here!
 - ◆ This analysis depends on how evenly partition divides arrays

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Best Case For Quicksort

- ◆ The best case is when partition breaks every array exactly in half
- ◆ Then our assumptions are valid: every level does $O(n)$, $O(\log n)$ levels, so $O(n \log n)$ total

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Worst Case For Quicksort

- ◆ Worst case is when partition breaks array into subarrays of size 1 and $n-1$
- ◆ In this case, there are n levels of recursion, and we still do $O(n)$ work at each level, so $O(n^2)$ total!
- ◆ This can happen when the chosen pivot is the smallest or largest element of the array
- ◆ We want to avoid that!

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Average Case For Quicksort

- ◆ It turns out that the average case is still pretty good
- ◆ For "most" arrays, quicksort will run in $O(n \log n)$ time
- ◆ Average case analysis based on probability that pivot is bad in a random array

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Building A Better Quicksort

- ◆ Don't have to choose `data[10]` as pivot every time
 - ◆ Can do some small (linear) amount of work to choose a better pivot
- ◆ Choosing a pivot at random yields $O(n \log n)$!!
- ◆ Other techniques involve computing the median of some elements in the array and work fairly well in practice
- ◆ Quicksort is usually the best choice for sorting

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Summary

- ◆ Searching: find an element in a collection
 - ◆ Linear search: $O(n)$
 - ◆ Binary search: $O(\log n)$
- ◆ Sorting: rearrange a collection according to some ordering relation
 - ◆ Selection sort, insertion sort: $O(n^2)$
 - ◆ Mergesort: $O(n \log n)$ but inefficient
 - ◆ Quicksort: $O(n \log n)$ average, $O(n^2)$ worst, but a good choice in practice

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