

Case Study 4: Collaborative Filtering

Graph-Parallel Problems

Synchronous v. Asynchronous Computation

Machine Learning/Statistics for Big Data
CSE599C1/STAT592, University of Washington

Carlos Guestrin
March 12th, 2013

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Needless to Say, We Need Machine Learning for Big Data

flickr

6 Billion
Flickr Photos



28 Million
Wikipedia Pages

facebook

1 Billion
Facebook Users

You Tube

72 Hours a Minute
YouTube

The New York Times
SundayReview

WORLD U.S. N.Y./REGION BUSINESS TEC

NEWS ANALYSIS
The Age of Big Data

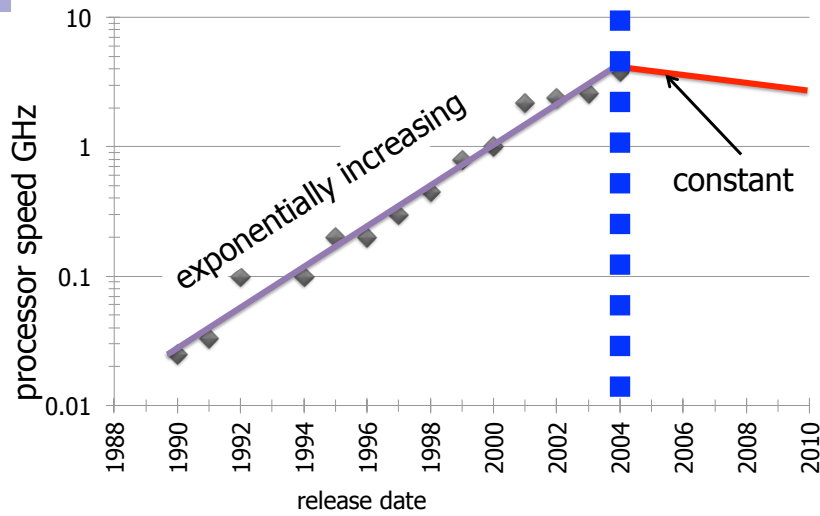
By STEVE LOHR
Published: February 11, 2012

“... data a new class of economic
asset, like currency or gold.”

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CPUs Stopped Getting Faster...



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ML in the Context of Parallel Architectures



■ But scalable ML in these systems is hard, especially in terms of:

1. Programmability ✓
2. Data distribution ✓
3. Failures ✓

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Move Towards Higher-Level Abstraction

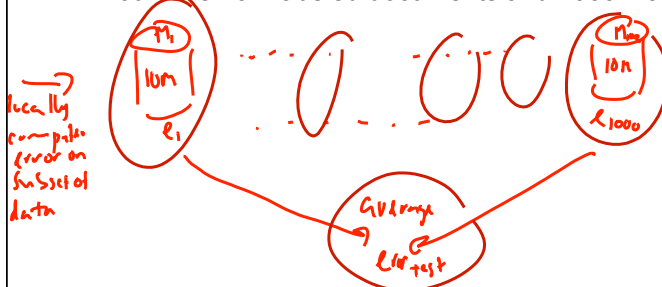
- Distributed computing challenges are hard and annoying!
 1. Programmability ↑
 2. Data distribution ↑
 3. Failures
- High-level abstractions try to simplify distributed programming by hiding challenges:
 - Provide different levels of robustness to failures, optimizing data movement and communication, protect against race conditions...
 - Generally, you are still on your own WRT designing parallel algorithms
- Some common parallel abstractions:
 - Lower-level:
 - Pthreads: abstraction for distributed threads on single machine
 - MPI: abstraction for distributed communication in a cluster of computers
 - Higher-level:
 - Map-Reduce (Hadoop: open-source version): mostly data-parallel problems ✓
 - GraphLab: for graph-structured distributed problems ✓

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Simplest Type of Parallelism: Data Parallel Problems

- You have already learned a classifier w^*
 - What's the test error?
$$err = \frac{1}{N_{test}} \sum_i \frac{1}{2} |y^{(i)} - \text{sign}(w^* \cdot x^{(i)})|$$
- You have 10B labeled documents and 1000 machines

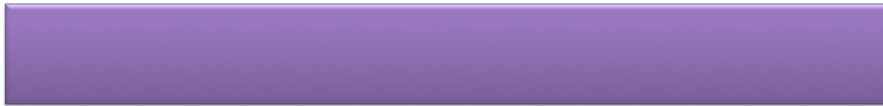


- Problems that can be broken into independent subproblems are called data-parallel (or embarrassingly parallel)
- Map-Reduce is a great tool for this...
 - Focus of today's lecture
 - but first a simple example

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Data Parallelism (MapReduce)



Solve a huge number of independent subproblems, e.g., extract features in images

Map-Reduce Abstraction

- Map: *Transforms a data element*
 - Data-parallel over elements, e.g., documents
 - Generate (key,value) pairs
 - "value" can be any data type

in this example:

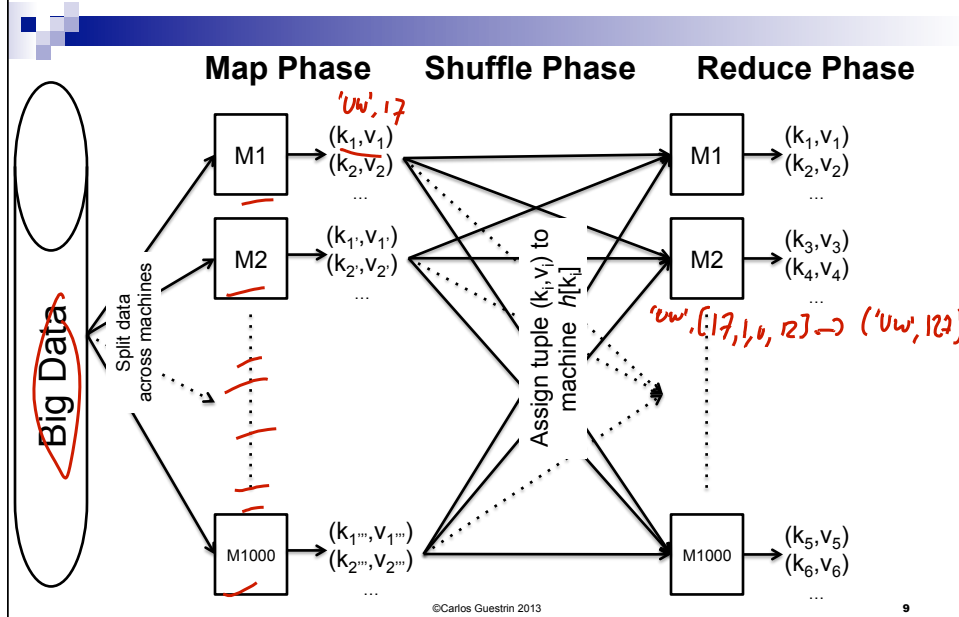
(Uw, 17)
(Mary, 1)
(Uw, 1)
(Mary, 1)
- Reduce: *Take all values associated with a key and aggregate*
 - Aggregate values for each key
 - Must be commutative-associate operation
 - Data-parallel over keys
 - Generate (key,value) pairs

map reduce (Uw, [1, 17, 0, 0, 12])
emit (Uw, 30)

word count
map (document)
for word in doc
emit (word, 1)

Reduce (word, count: list(int))
c = 0
for i in count
c += count[i]
emit (word, c)
- Map-Reduce has long history in functional programming
 - But popularized by Google, and subsequently by open-source Hadoop implementation from Yahoo!

Map-Reduce – Execution Overview



Issues with Map-Reduce Abstraction

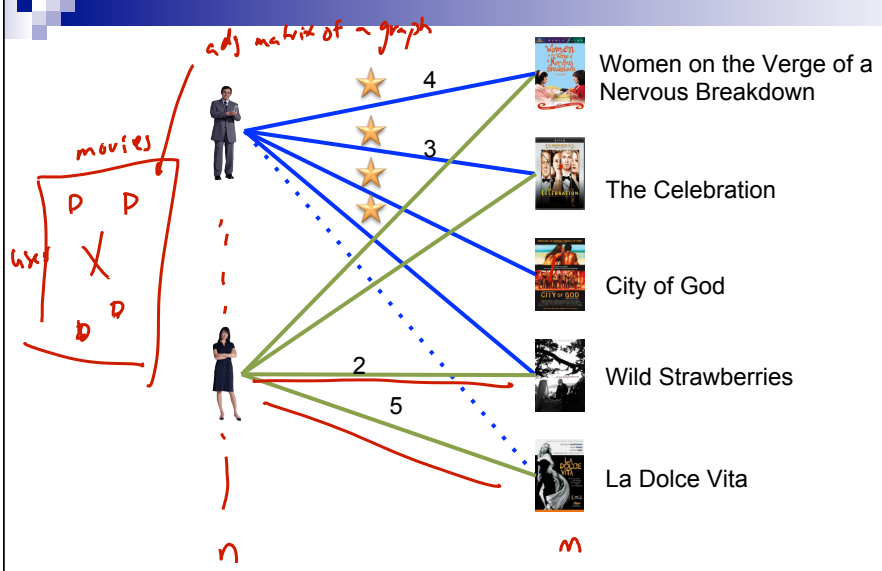
- Often all data gets moved around cluster
 - Very bad for iterative settings
- Definition of Map & Reduce functions can be unintuitive in many apps
 - Graphs are challenging
- Computation is synchronous

SGD for Matrix Factorization in Map-Reduce?

$$\epsilon_t = L_u^{(t)} \cdot R_v^{(t)} - r_{uv} \quad \begin{bmatrix} L_u^{(t+1)} \\ R_v^{(t+1)} \end{bmatrix} \leftarrow \begin{bmatrix} (1 - \eta_t \lambda_u) L_u^{(t)} - \eta_t \epsilon_t R_v^{(t)} \\ (1 - \eta_t \lambda_v) R_v^{(t)} - \eta_t \epsilon_t L_u^{(t)} \end{bmatrix}$$

- Map and Reduce functions???
- Map-Reduce:
 - Data-parallel over all mappers
 - Data-parallel over reducers with same key
- Here, one update at a time!

Matrix Factorization as a Graph



Flashback to 1998

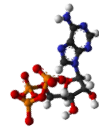


First Google advantage:
a **Graph Algorithm** & a **System to Support it!**

Social Media



Science



Advertising



Web



- **Graphs** encode the **relationships** between:

People

Facts

Products

Interests

Ideas

- **Big**: 100 billions of **vertices** and **edges** and rich metadata

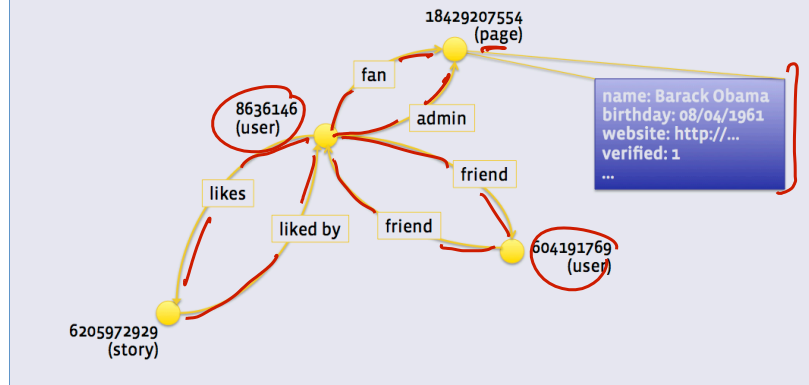
- Facebook (10/2012): 1B users, 144B friendships
- Twitter (2011): 15B follower edges

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Facebook Graph

Data model Objects & Associations



Slide from Facebook Engineering presentation 15

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Label a Face and Propagate



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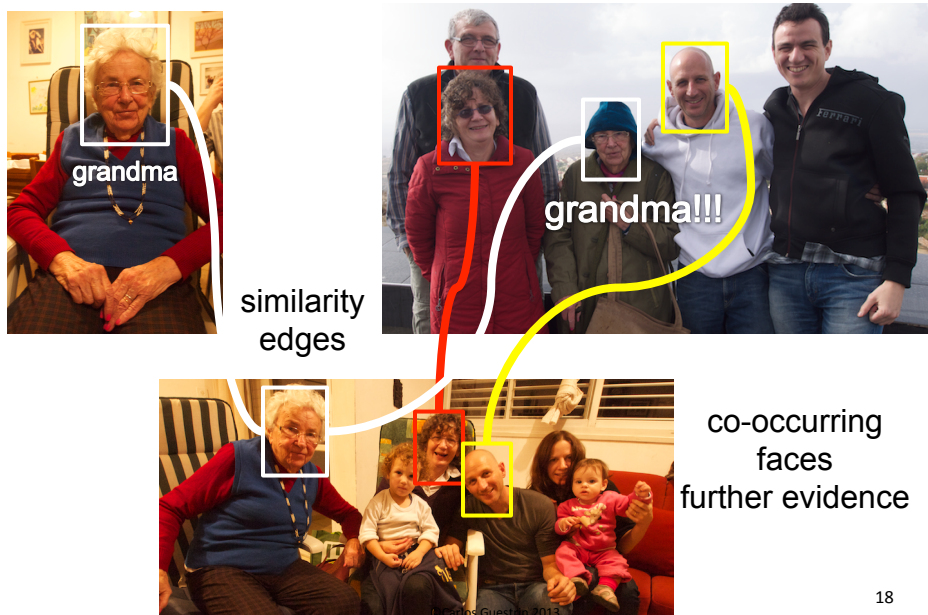
Pairwise similarity not enough...



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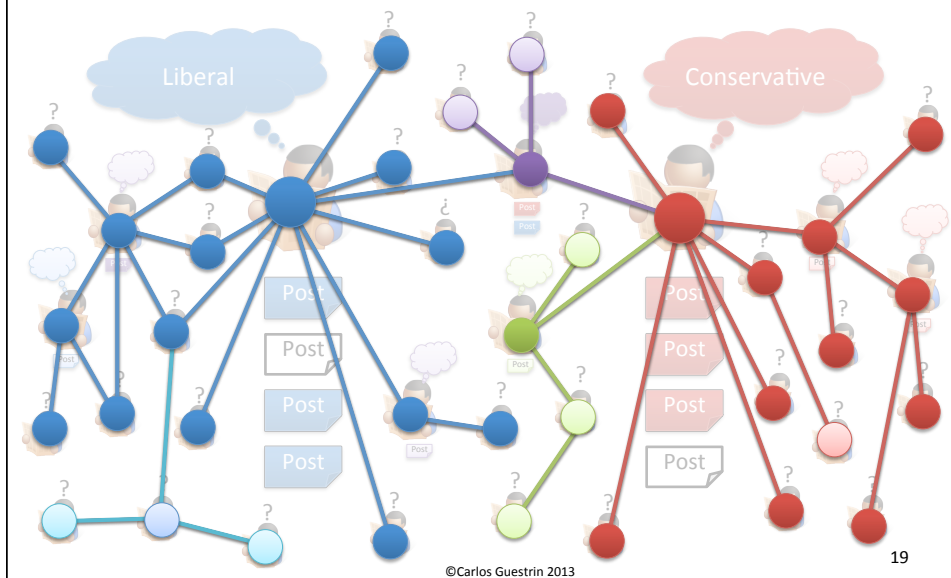
Propagate Similarities & Co-occurrences for Accurate Predictions



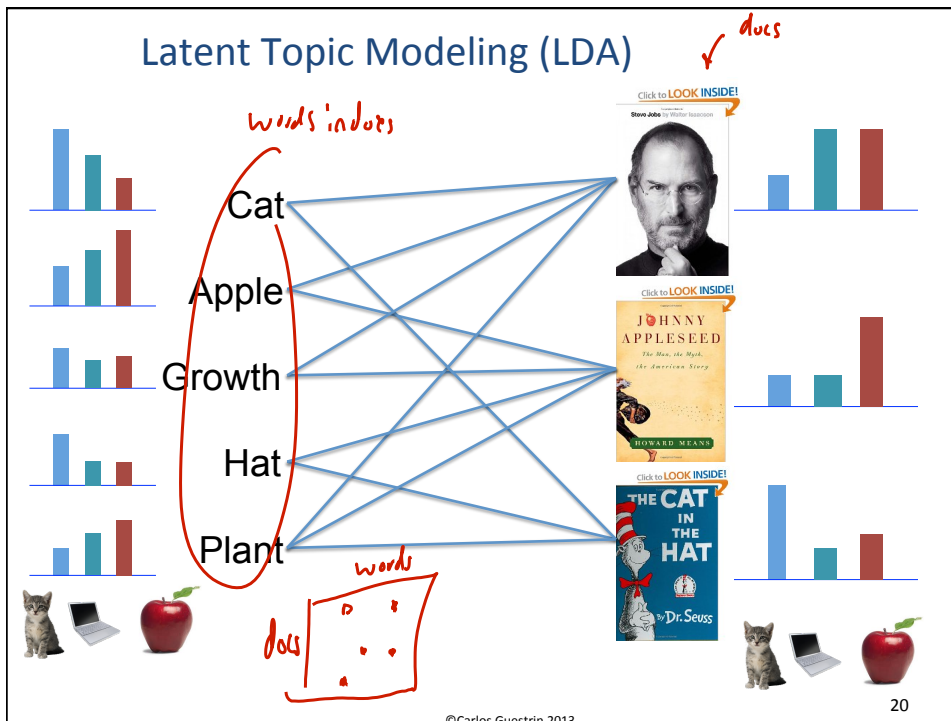
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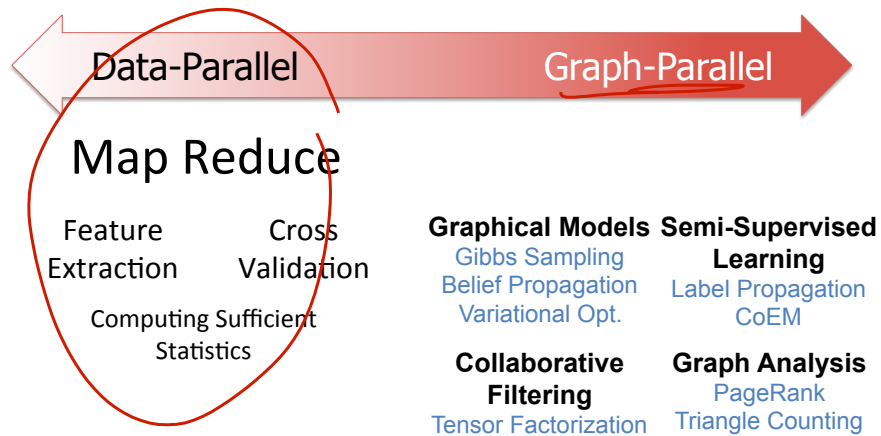
Example: Estimate Political Bias



Latent Topic Modeling (LDA)



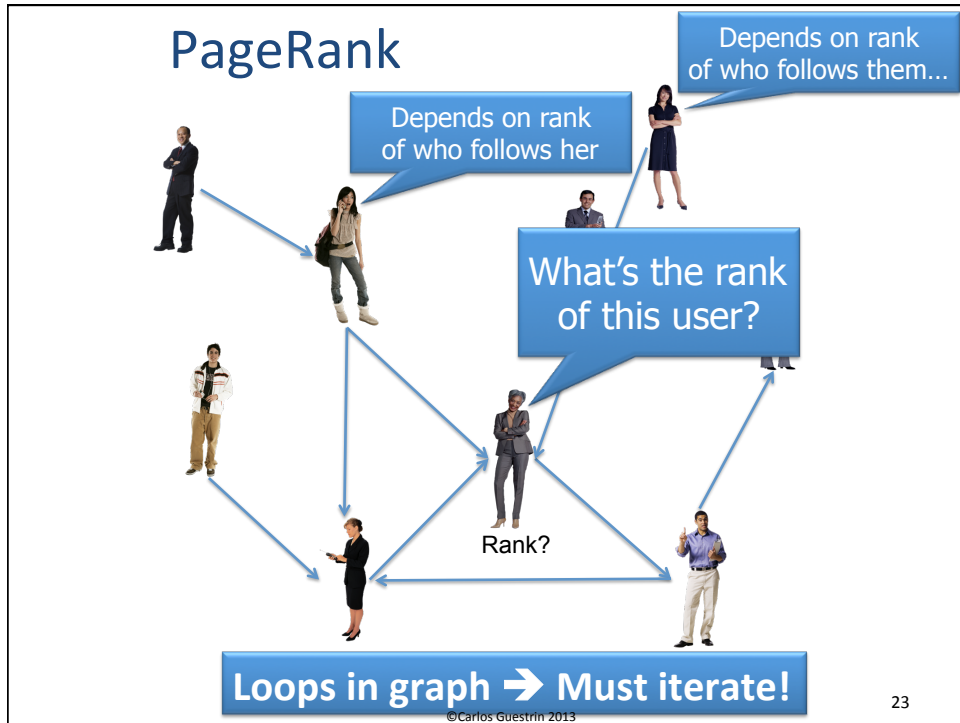
ML Tasks Beyond Data-Parallelism



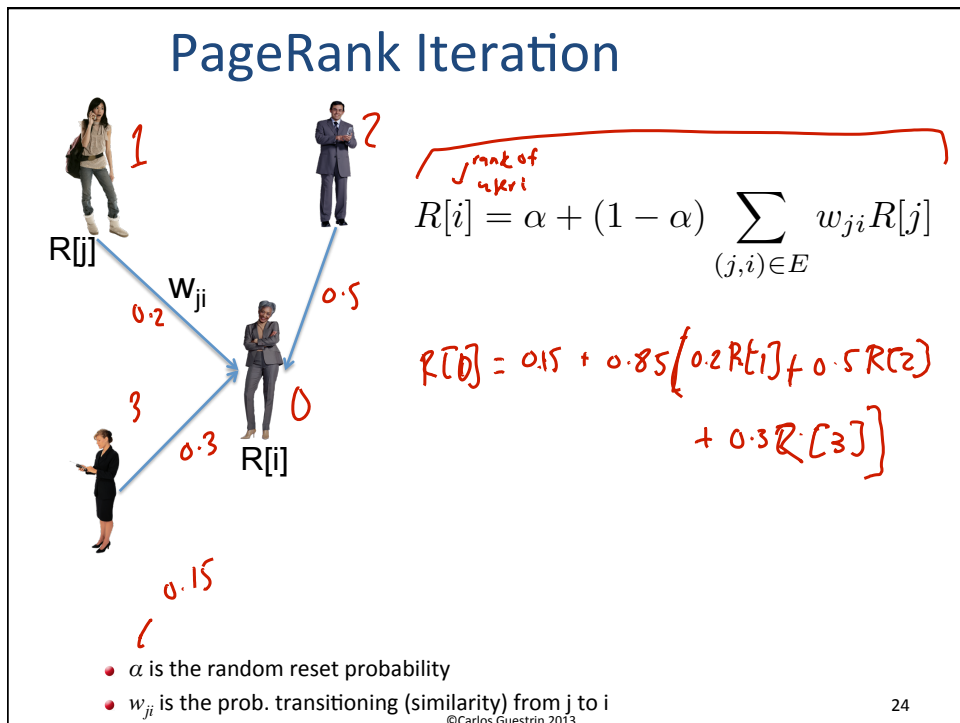
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Example of a Graph-Parallel Algorithm



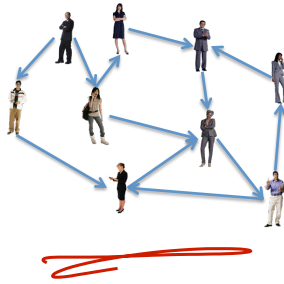
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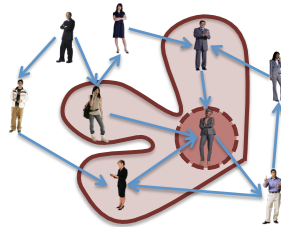
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Properties of Graph Parallel Algorithms

Dependency Graph



Local Updates



Iterative Computation



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Addressing Graph-Parallel ML



Map Reduce

Feature Extraction Cross Validation
 Computing Sufficient Statistics

Graph-Parallel Abstraction

Graphical Models Semi-Supervised Learning

Gibbs Sampling Belief Propagation Variational Opt. Label Propagation CoEM

Collaborative Filtering Tensor Factorization **Data-Mining** PageRank Triangle Counting

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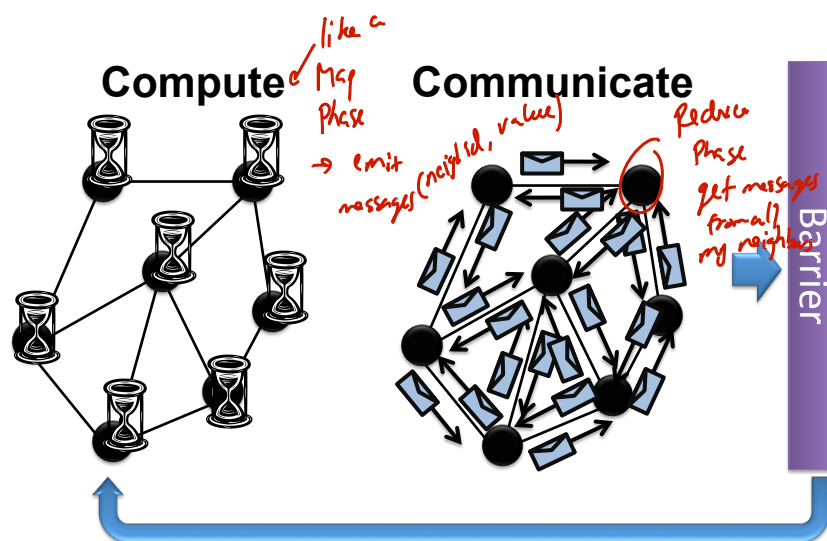
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Graph Computation:

Synchronous
v.
Asynchronous

Bulk Synchronous Parallel Model: Pregel (Giraph)

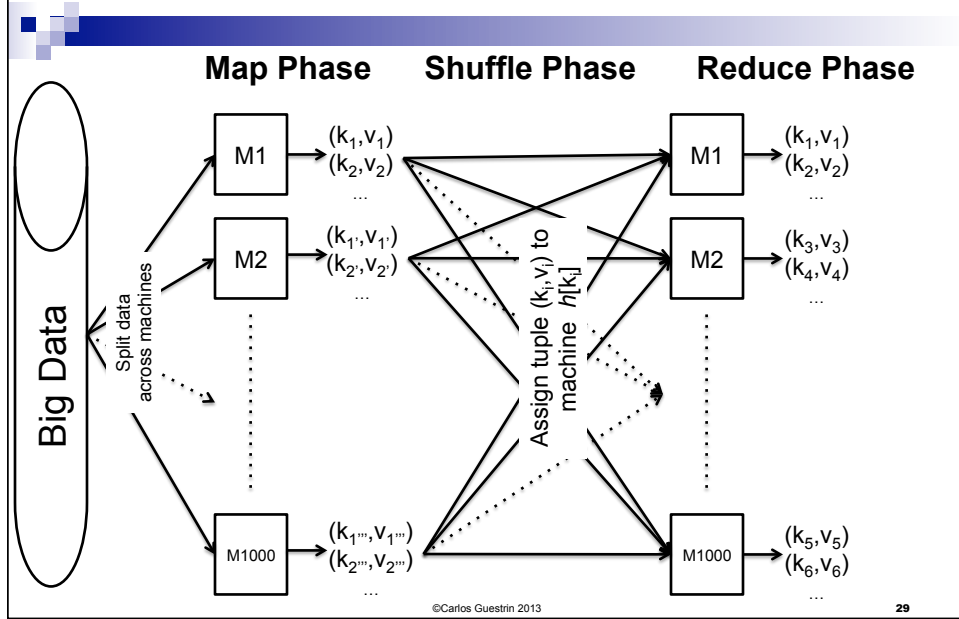
[Valiant '90]



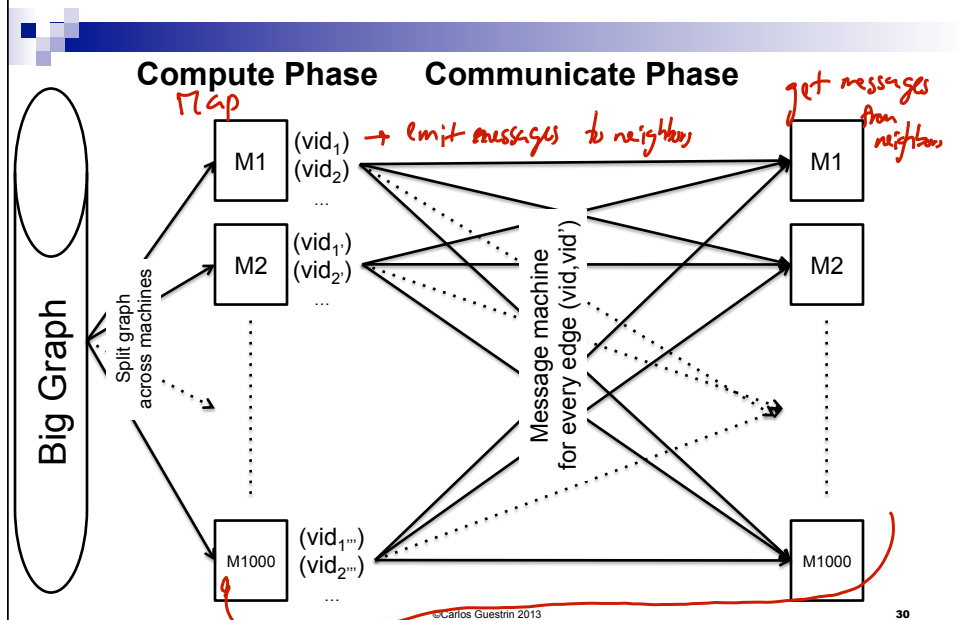
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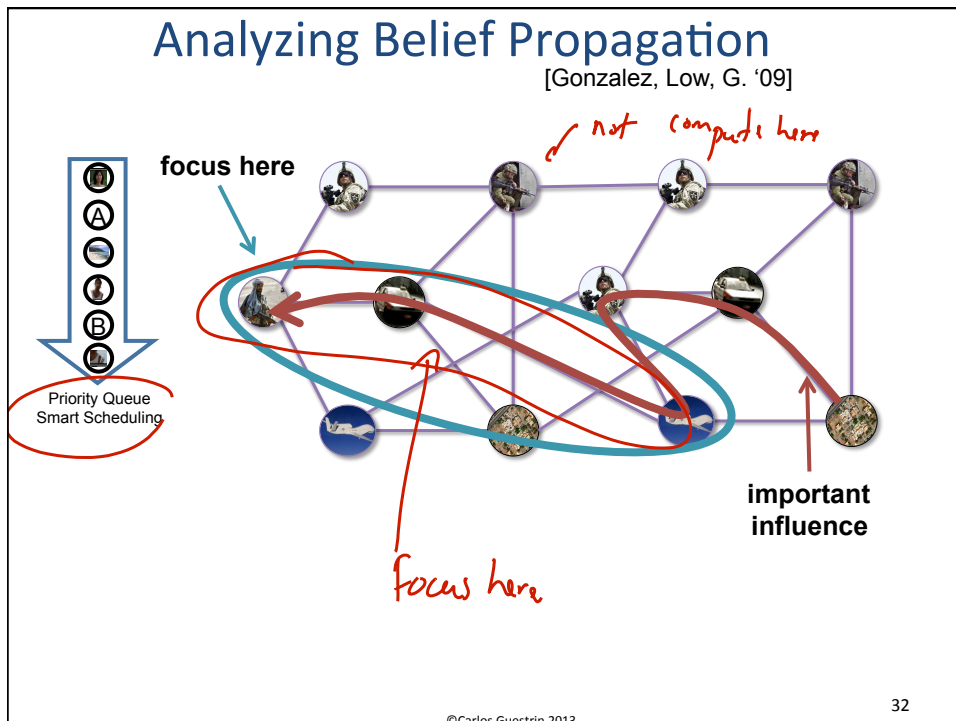
Map-Reduce – Execution Overview



BSP – Execution Overview

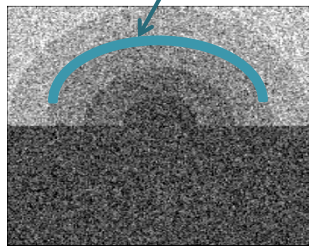


*Bulk synchronous
parallel model
provably inefficient
for some ML tasks*

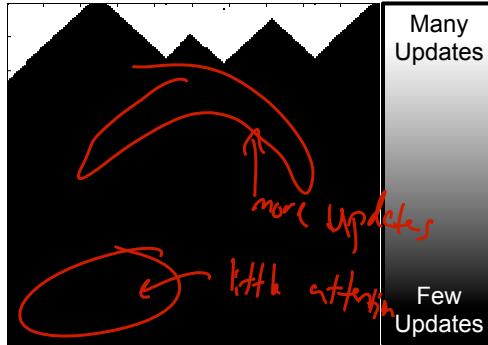


Asynchronous Belief Propagation

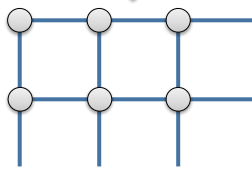
Challenge = Boundaries



Synthetic Noisy Image



Cumulative Vertex Updates



Graphical Model

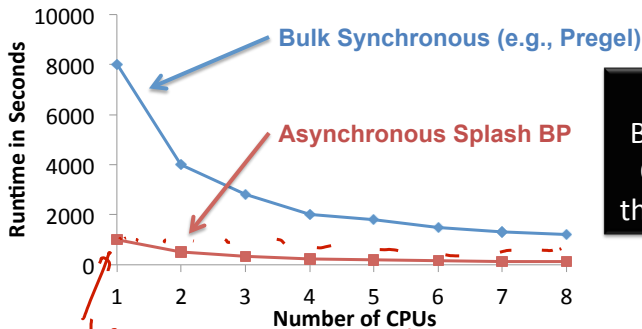
Algorithm identifies and focuses on hidden sequential structure

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BSP ML Problem: *BP on real data*

Synchronous Algorithms can be **Inefficient**



Theorem:
Bulk Synchronous BP
 $O(\#vertices)$ slower
than Asynchronous BP

1 proc async faster than 8 proc of sync

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Synchronous v. Asynchronous

- Bulk synchronous processing:
 - Computation in phases
 - All vertices participate in a phase
 - Though OK to say no-op
 - All messages are sent
 - Simpler to build, like Map-Reduce
 - No worries about race conditions, barrier guarantees data consistency
 - Simpler to make fault-tolerant, save data on barrier
 - Slower convergence for many ML problems
 - In matrix-land, called Jacobi Iteration
 - Implemented by Google Pregel 2010
- Asynchronous processing:
 - Vertices see latest information from neighbors
 - Most closely related to sequential execution
 - Harder to build:
 - Race conditions can happen all the time
 - Must protect against this issue
 - More complex fault tolerance
 - When are you done?
 - Must implement scheduler over vertices
 - Faster convergence for many ML problems
 - In matrix-land, called Gauss-Seidel Iteration
 - Implemented by GraphLab 2010, 2012