

Learning to Track: Online Multi-Object Tracking by Decision Making

Yu Xiang¹, Alexandre Alahi², and Silvio Savarese²

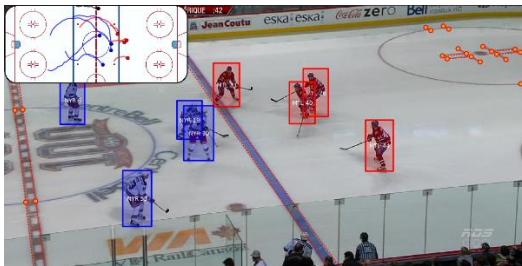
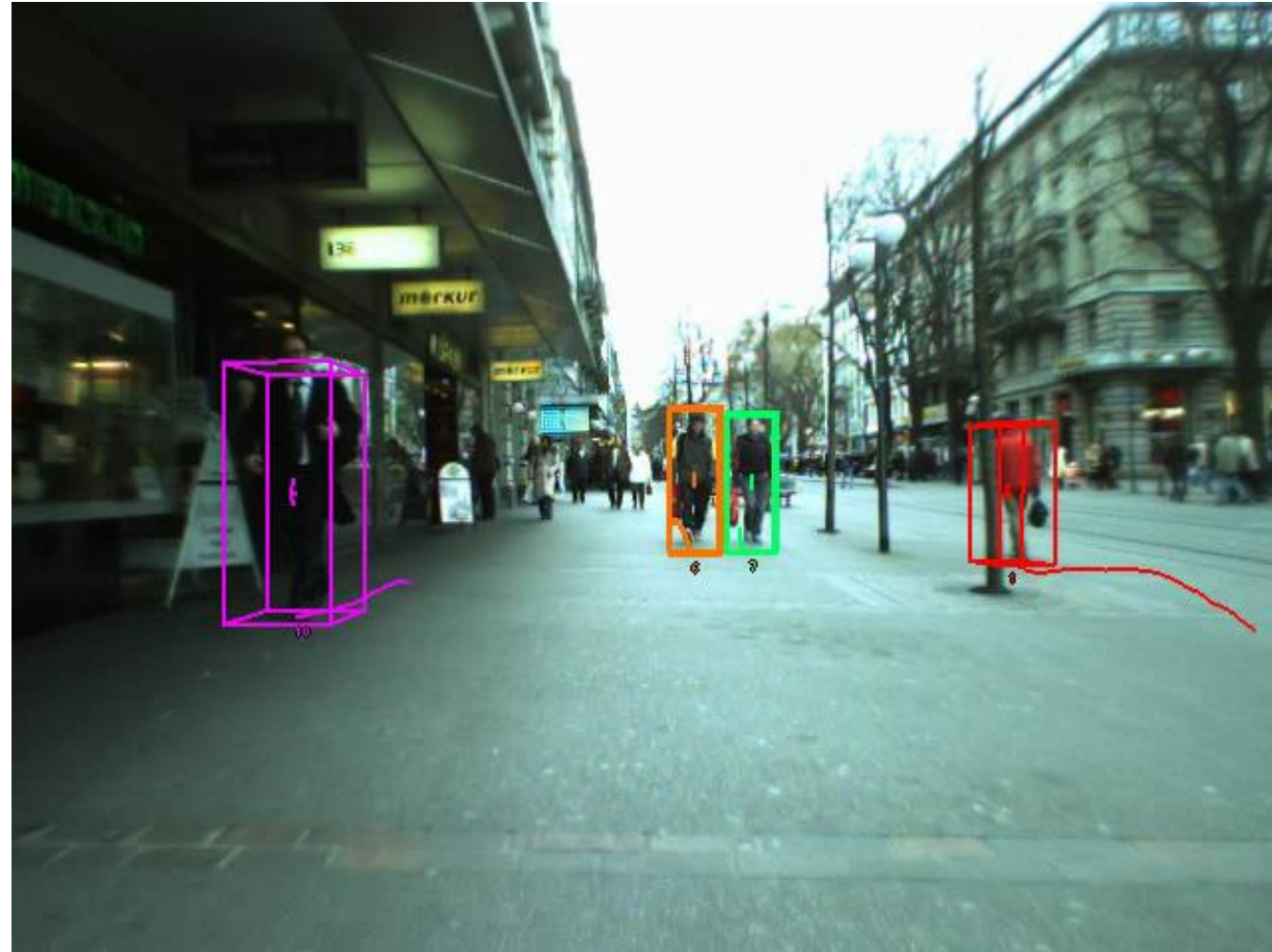
¹University of Washington, ²Stanford University

ICCV 2015

Multi-Object Tracking



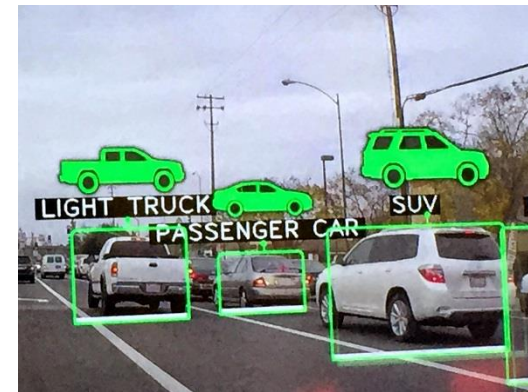
Visual surveillance



Sport Analysis



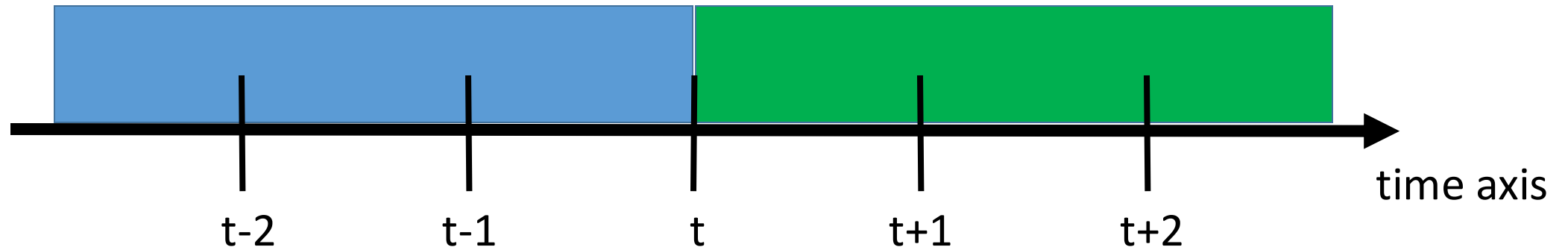
Robot navigation



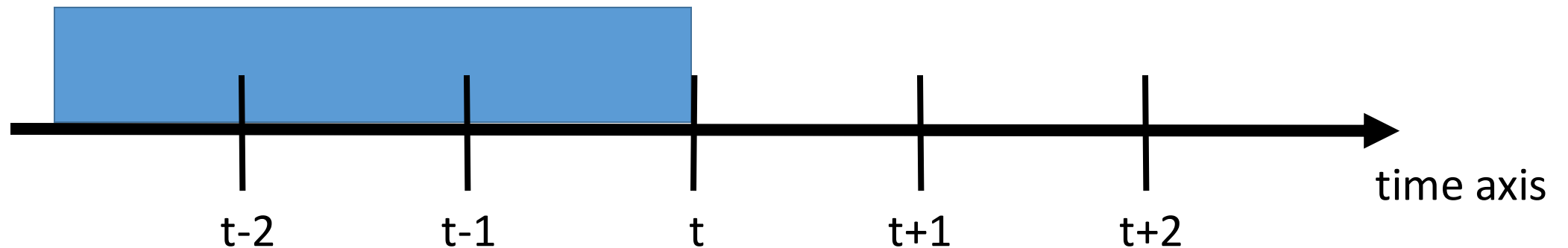
Autonomous driving

Batch Mode vs. Online Mode

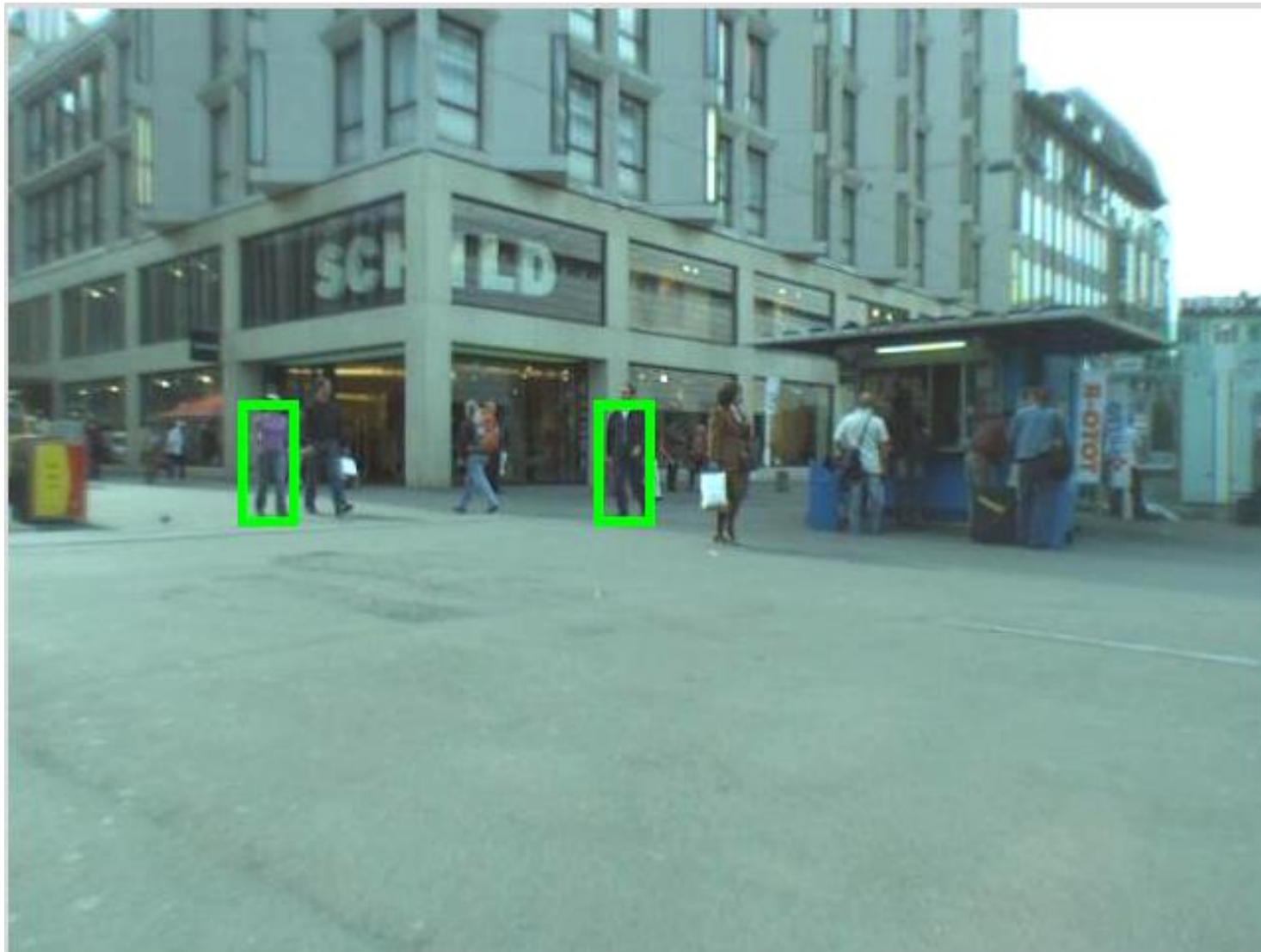
- Batch Mode



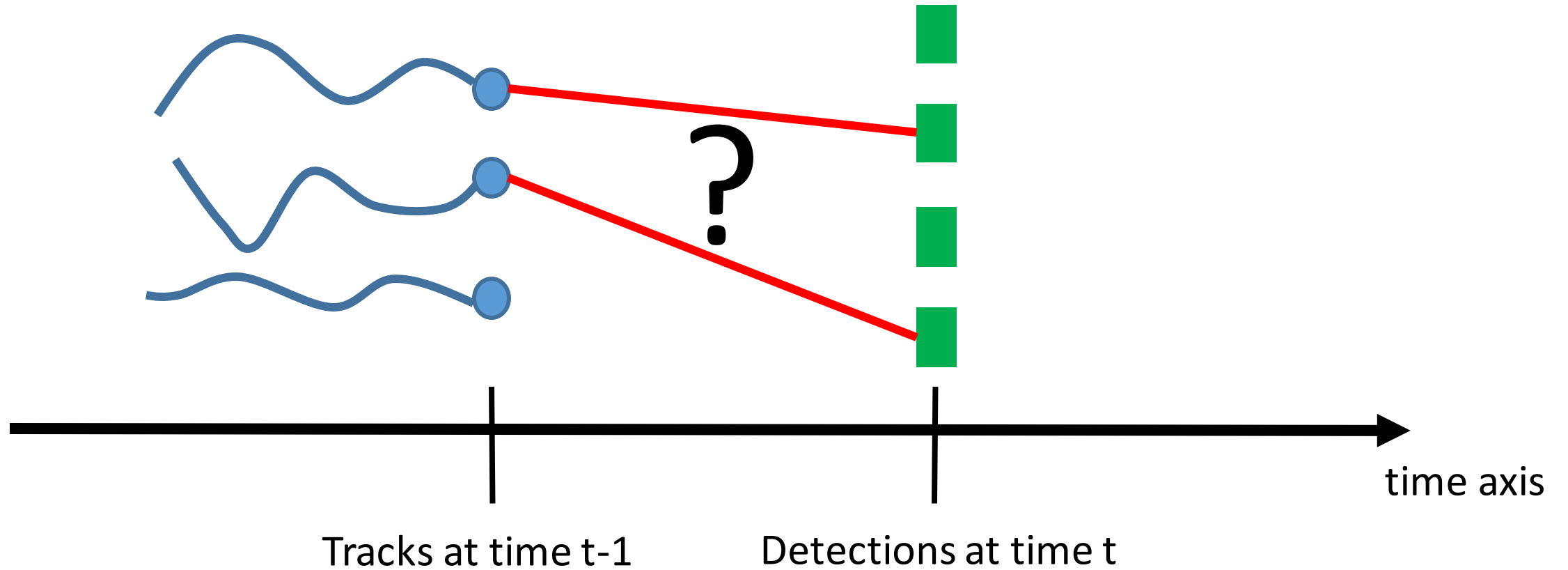
- Online Mode



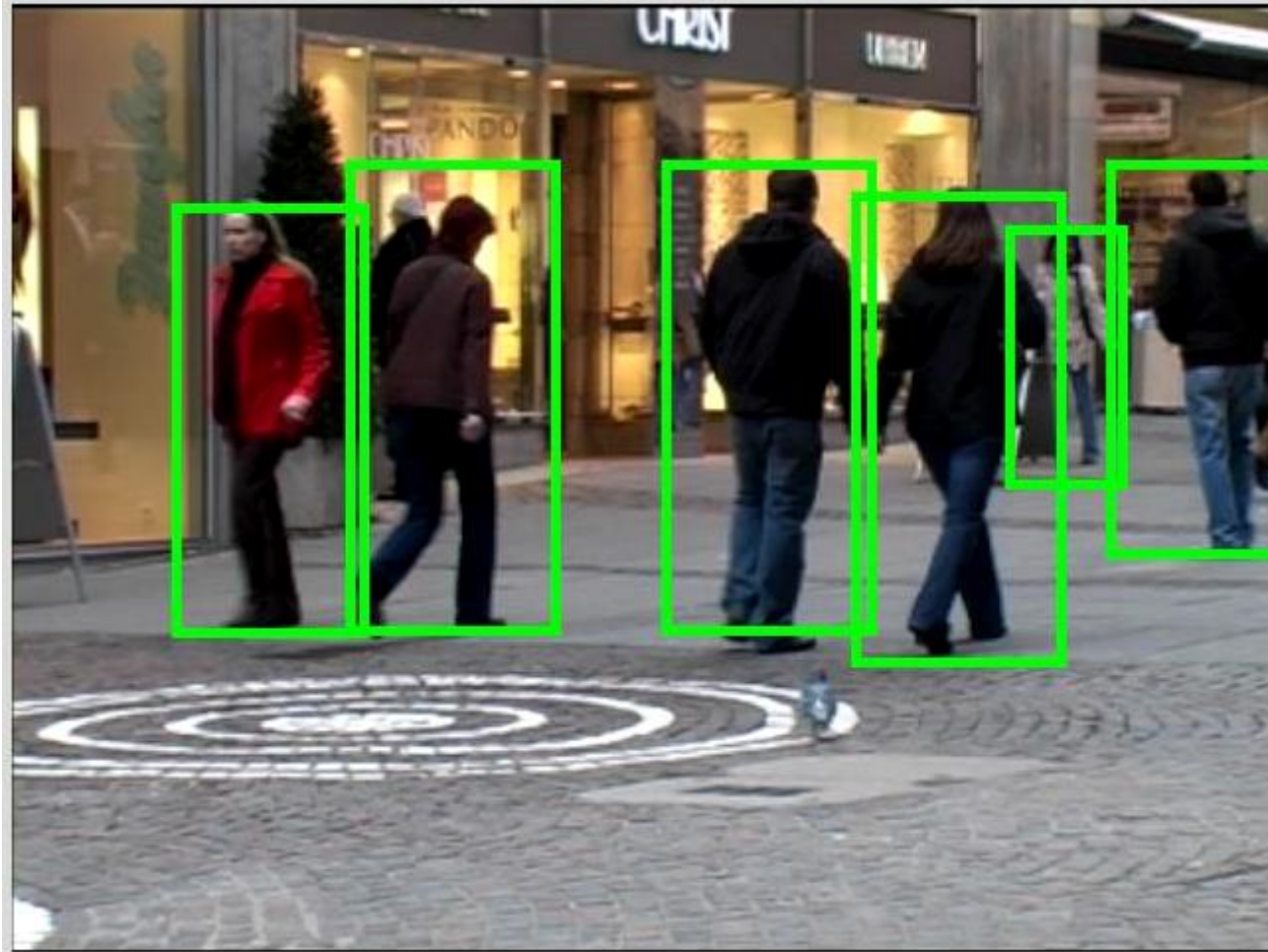
Tracking by Detection



Data Association



Challenges



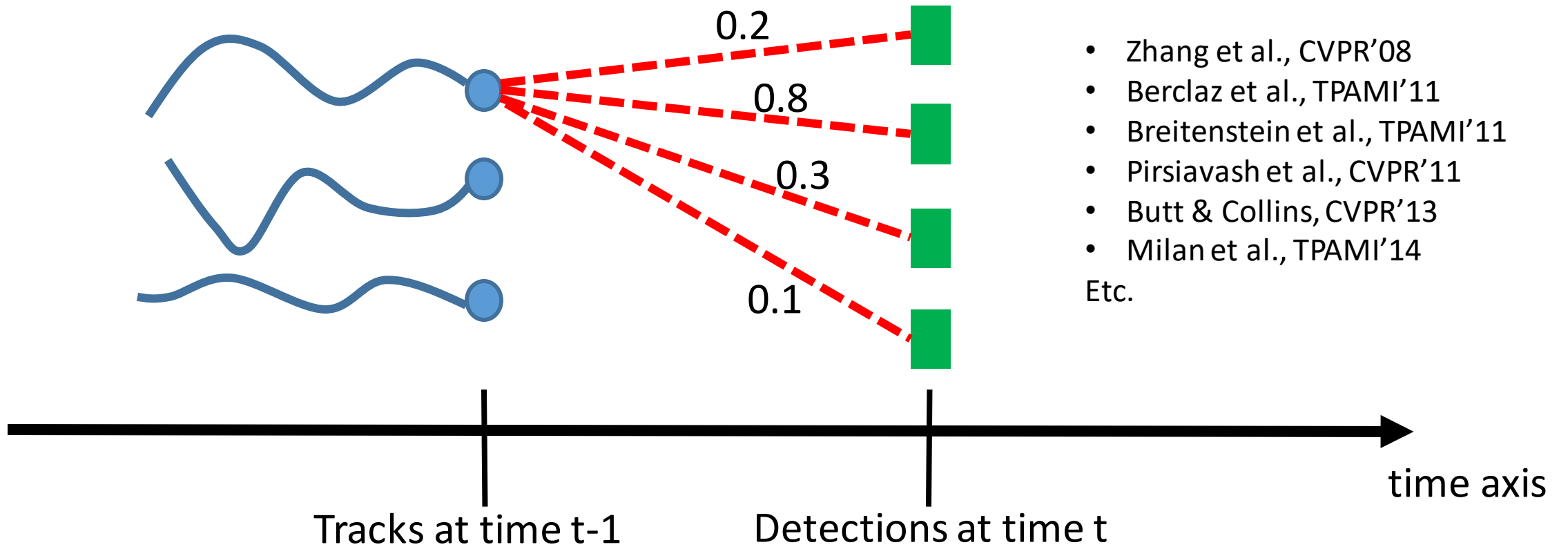
Noisy detection: false alarms and missing detections

Challenges



Occlusion

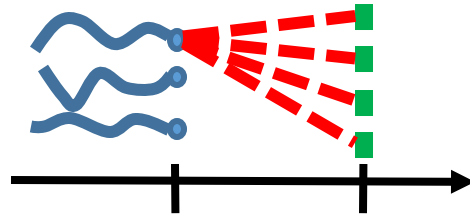
Similarity Function for Data Association



Ours

Simple similarity measure + **Powerful** optimization

Learning to Track



Different features/cues between targets and detections

- Appearance
- Location
- Motion
- Etc.

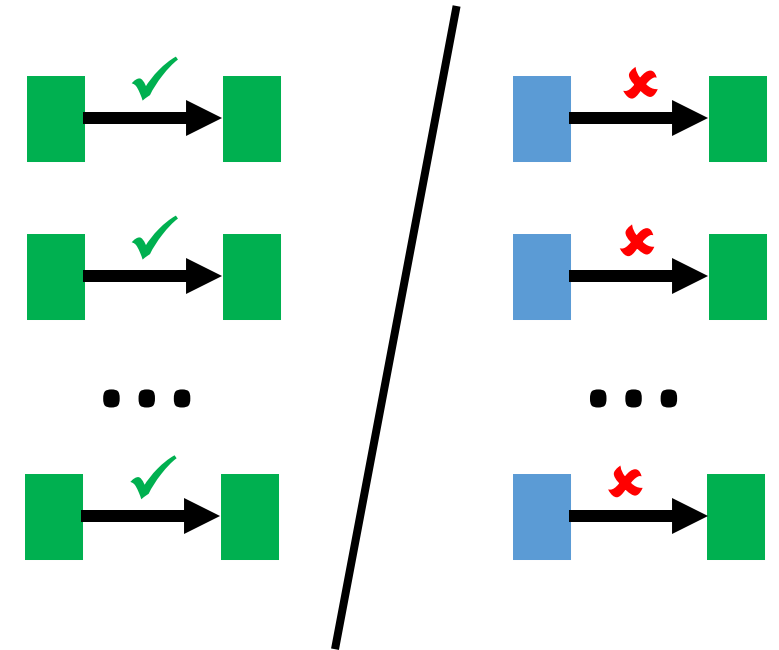
$$\text{Similarity} = w_1 \phi_1(\text{blue wavy line}, \text{green square}) + \dots + w_n \phi_n(\text{blue wavy line}, \text{green square})$$

Weights to combine different cues
(to be learned)

Offline-learning vs. Online-learning

Offline-learning vs. Online-learning

	Offline-learning
Training time	Before Tracking
With supervision	✓
Use history of the target	✗



- Li et al., CVPR'09
 - Kim et al., ACCV'12
- Etc.

Offline-learning vs. Online-learning

	Offline-learning	Online-learning
Training time	Before Tracking	During Tracking
With supervision	✓	✗
Use history of the target	✗	✓

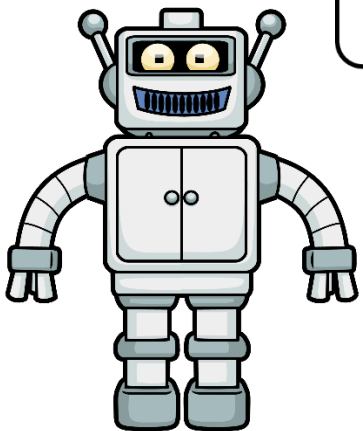


- Song et al., ECCV'08
 - Kuo et al., CVPR'10
 - Bae et al., CVPR'14
- Etc.

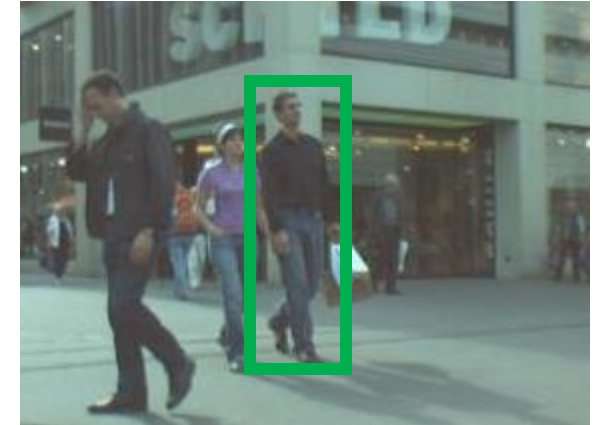
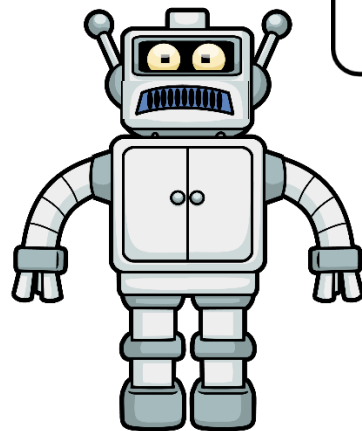
Our Solution: Tracking by Decision Making



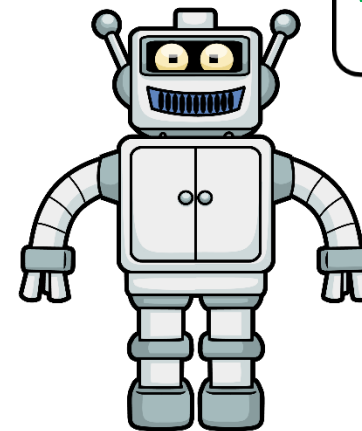
The target is tracked



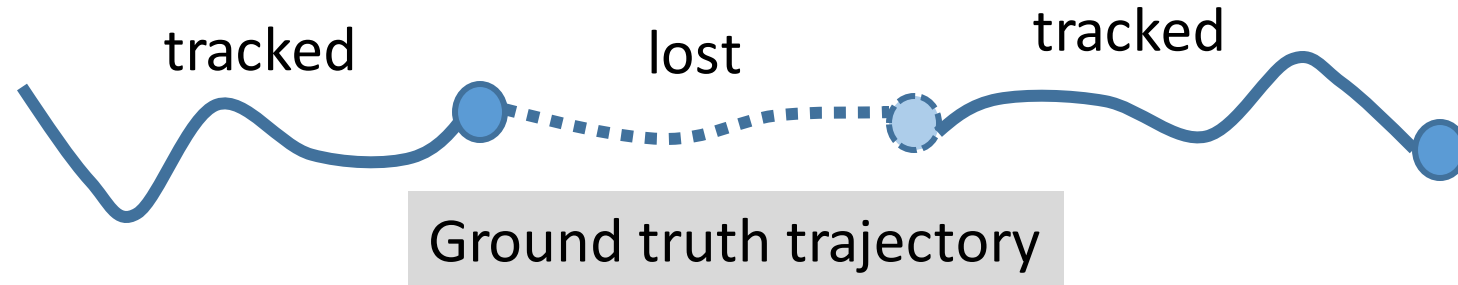
The target is occluded



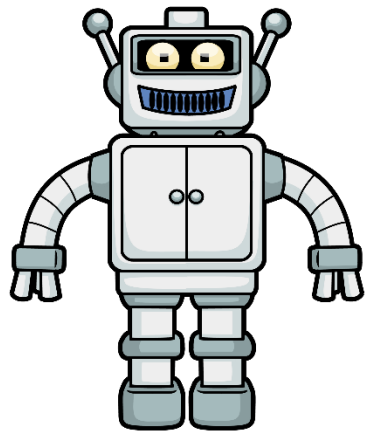
The target is tracked again



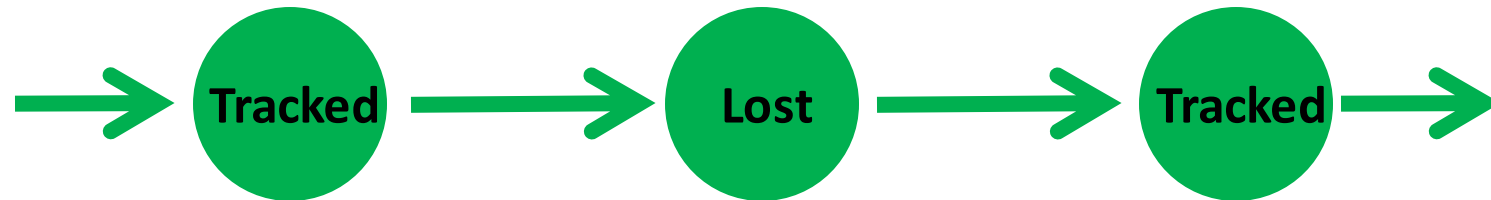
Inverse Reinforcement Learning



Supervision



Markov
Decision
Process
(MDP)

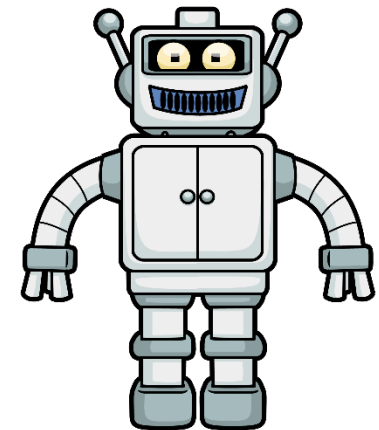


Comparison between Different Learning Strategies

	Offline-learning	Online-learning
Training time	Before Tracking	During Tracking
With supervision	✓	✗
Use history of the target	✗	✓

Comparison between Different Learning Strategies

	Offline-learning	Online-learning	Ours
Training time	Before Tracking	During Tracking	Before Tracking
With supervision	✓	✗	✓
Use history of the target	✗	✓	✓



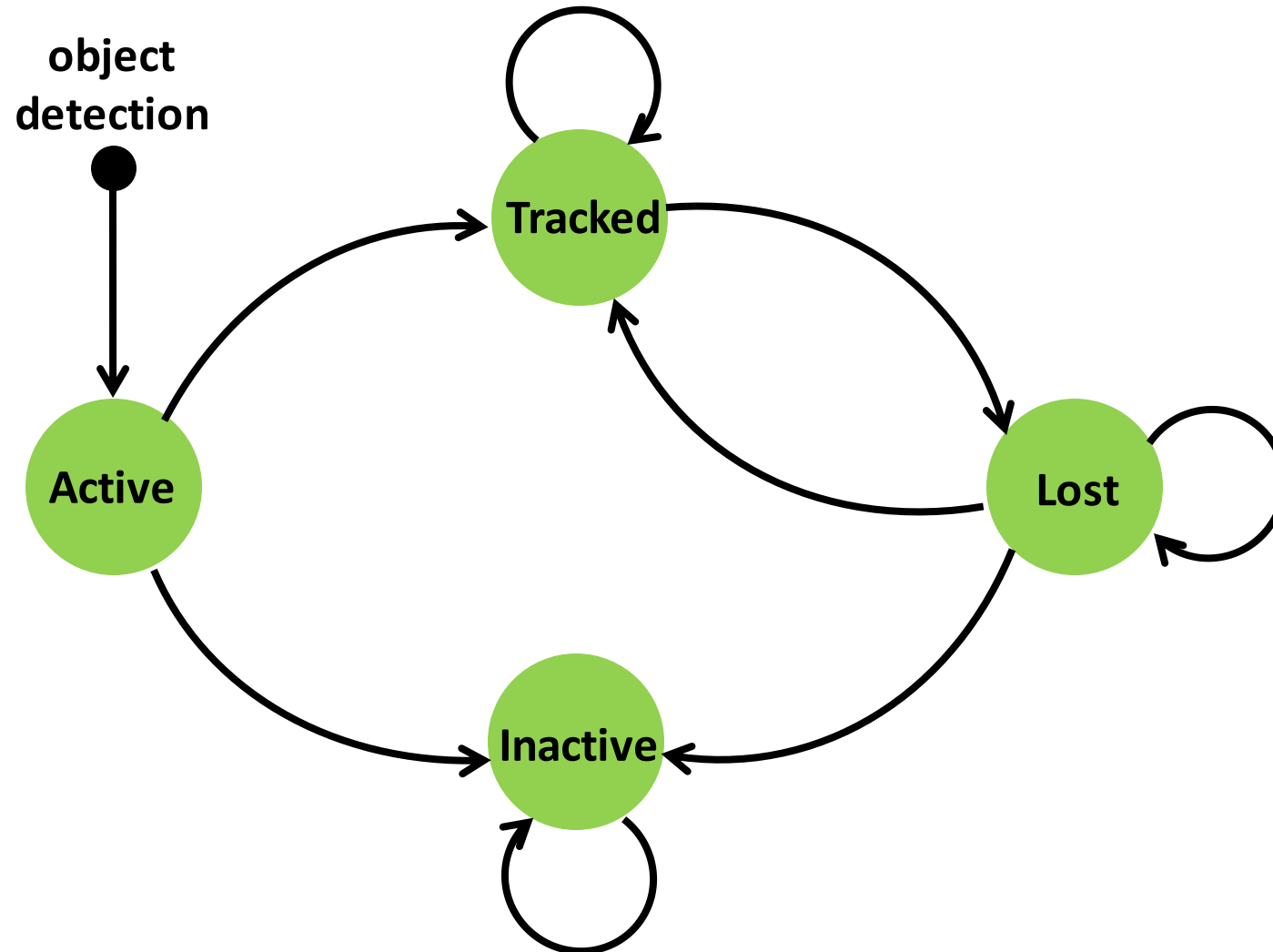
Outline

- Markov Decision Process (MDP) for a Single Target
- Online Multi-Object Tracking with MDPs
- Experiments
- Conclusion

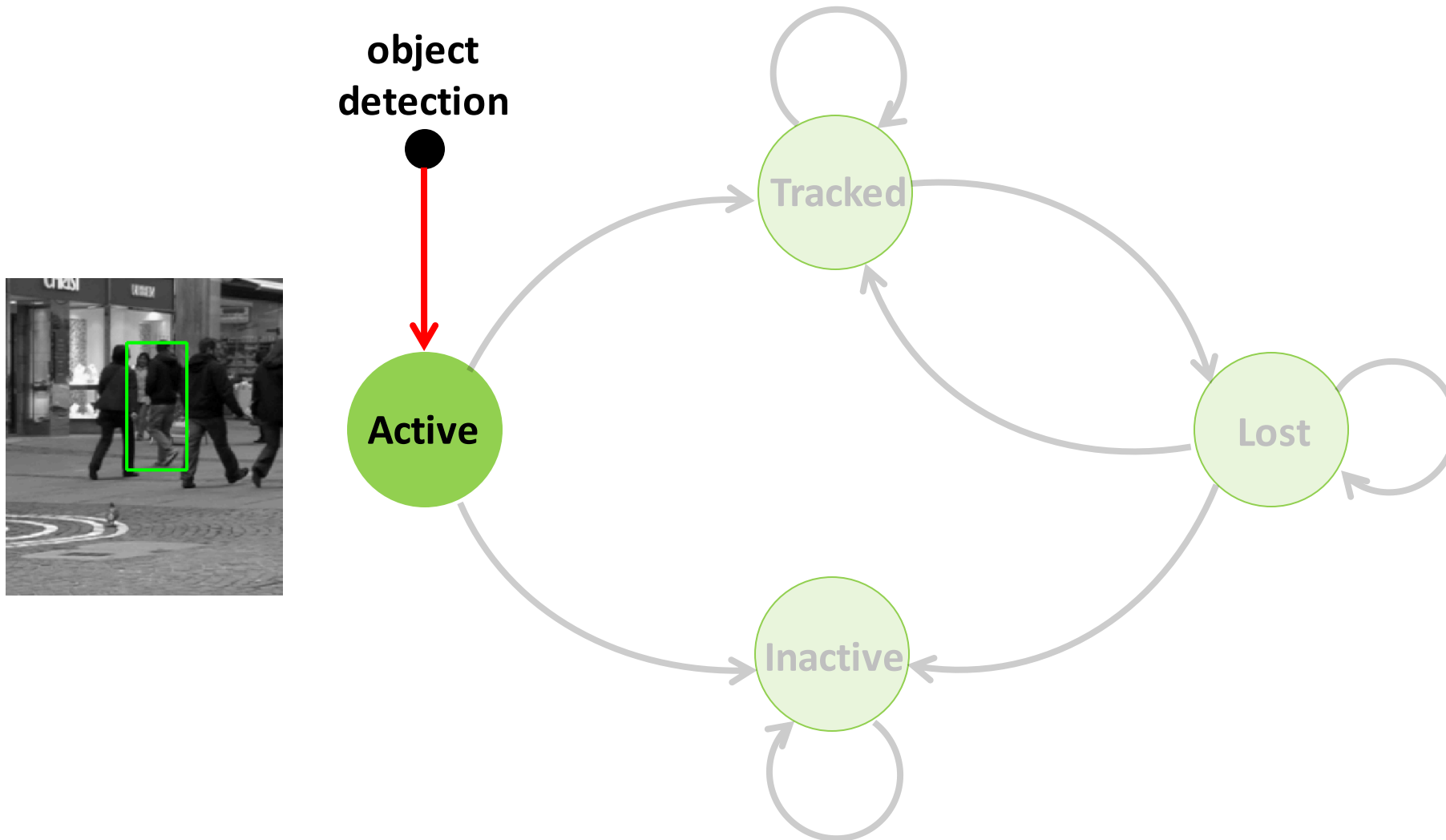
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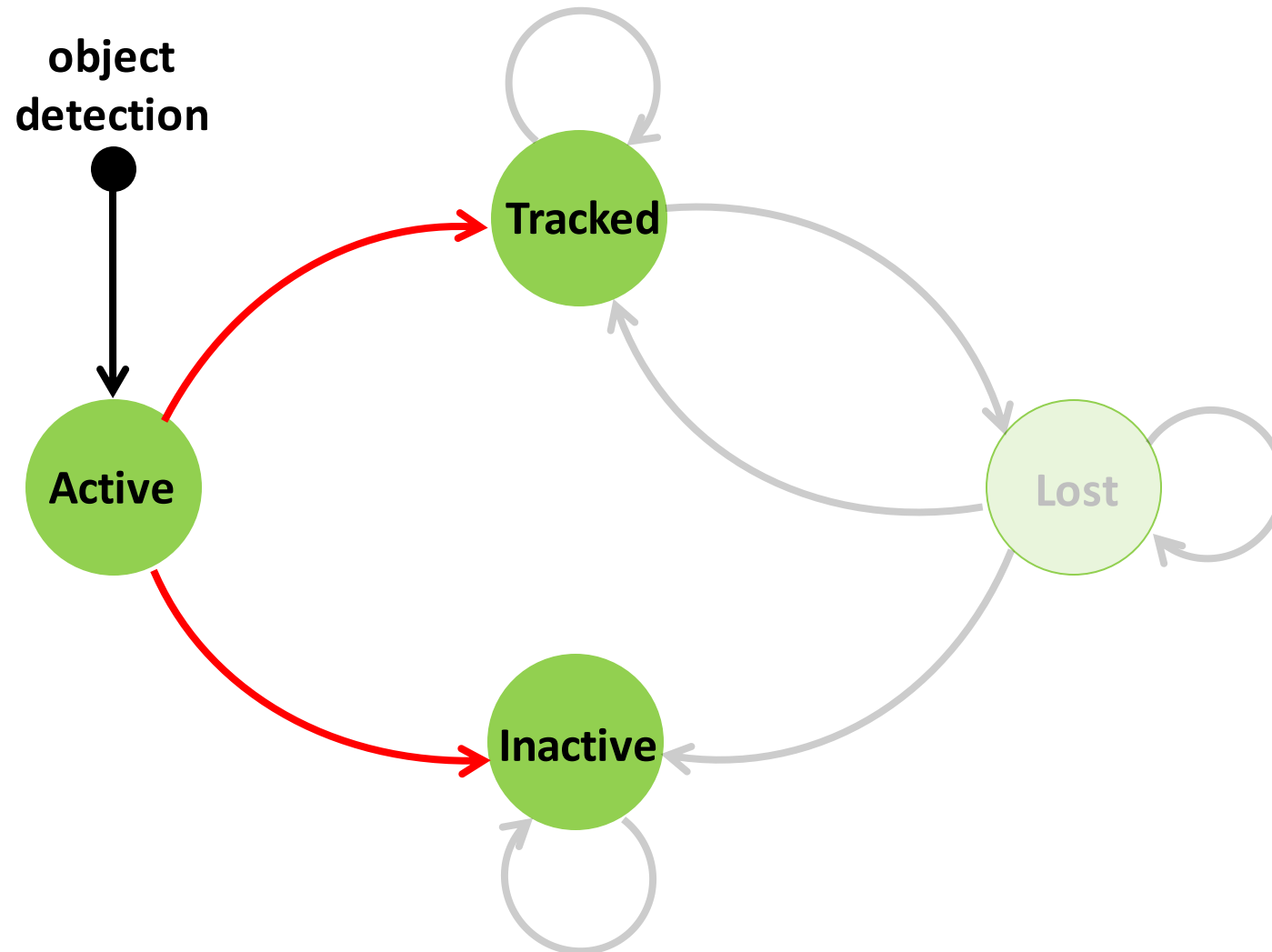
Markov Decision Process for a Single Target



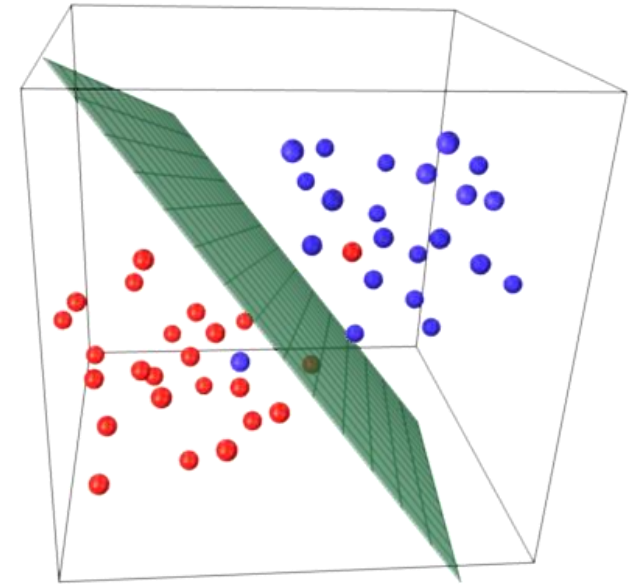
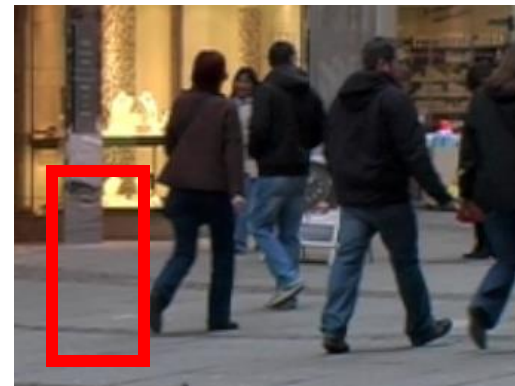
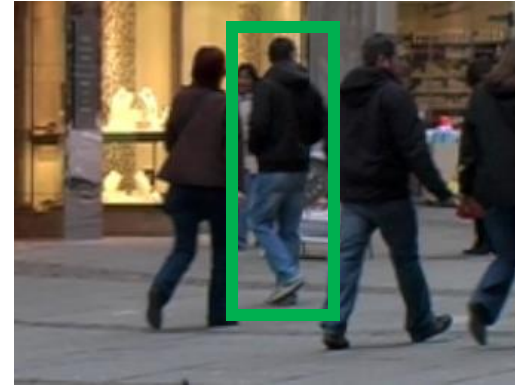
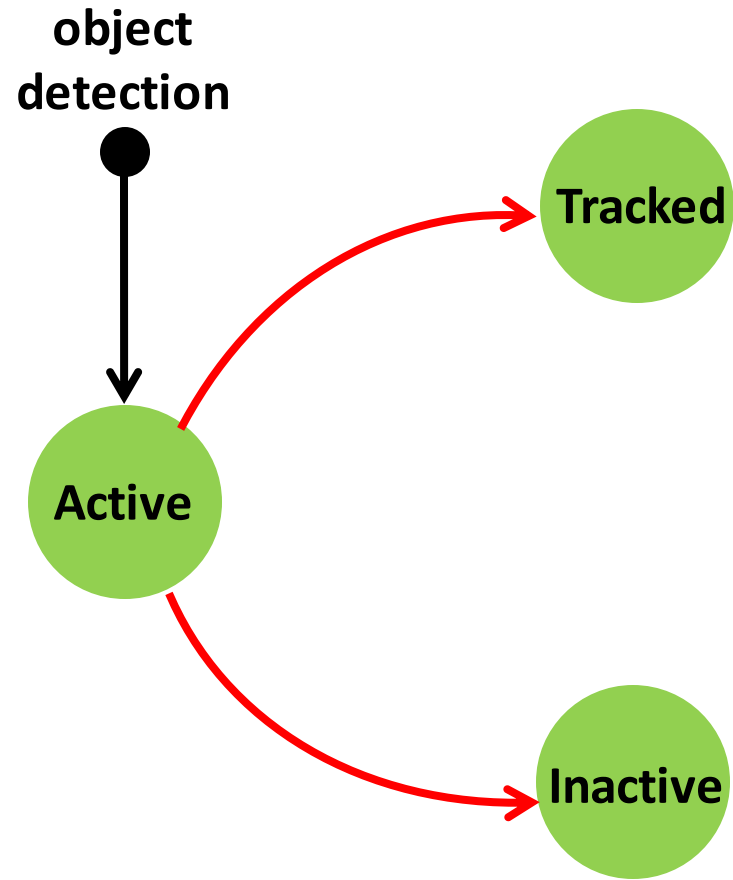
Markov Decision Process for a Single Target



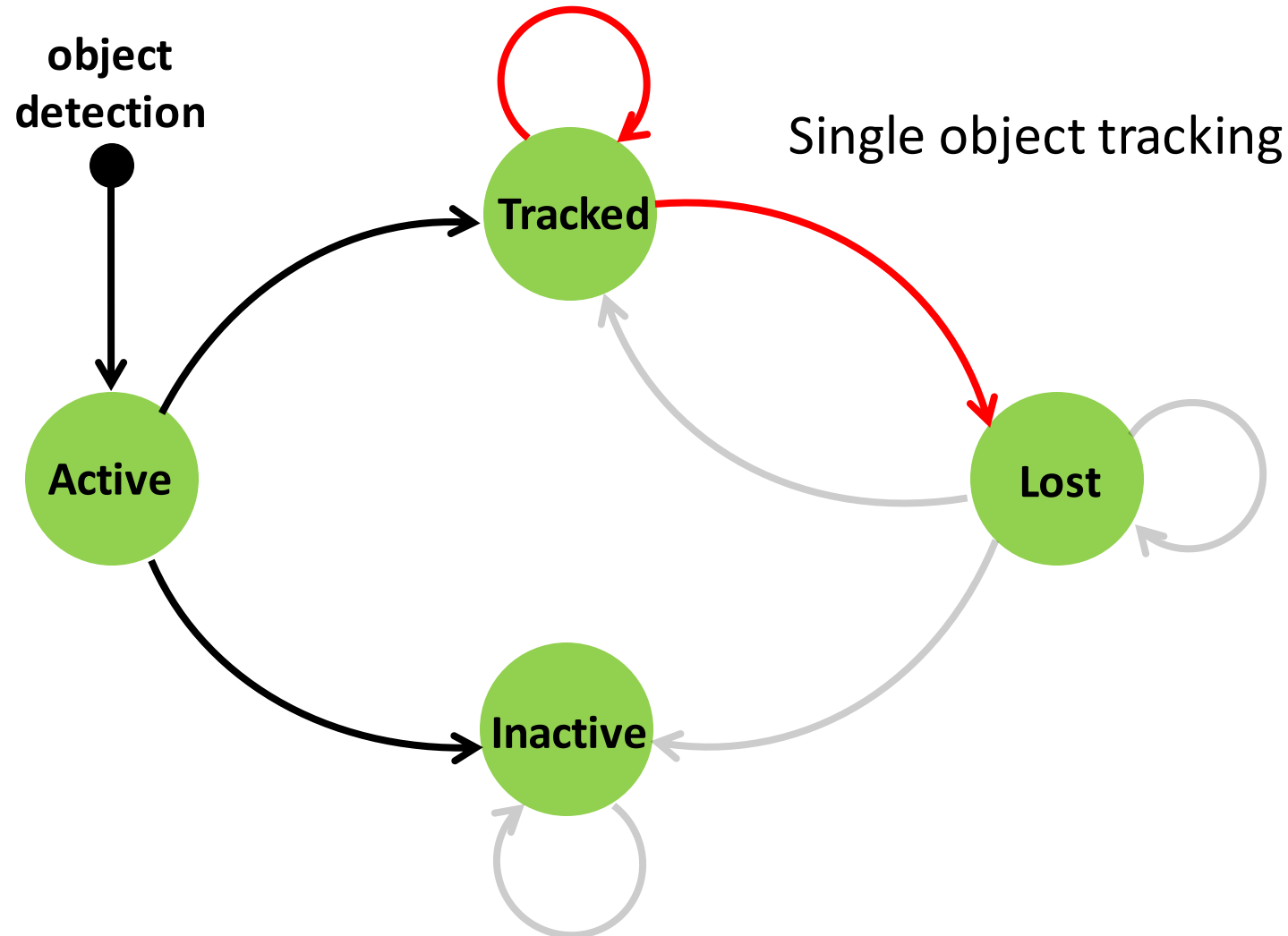
Markov Decision Process for a Single Target



Markov Decision Process for a Single Target



Markov Decision Process for a Single Target



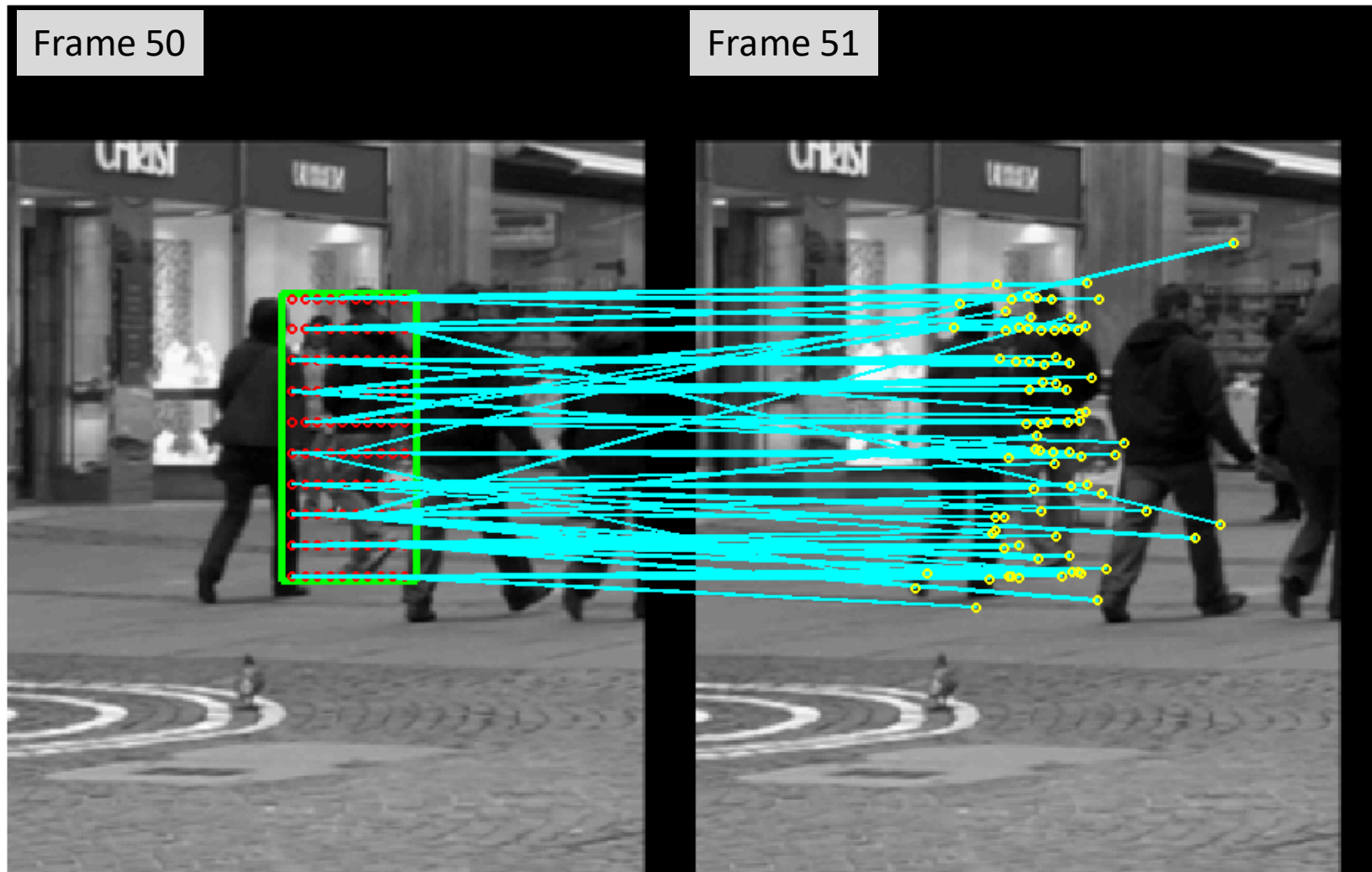
Template Tracking in Tracked States



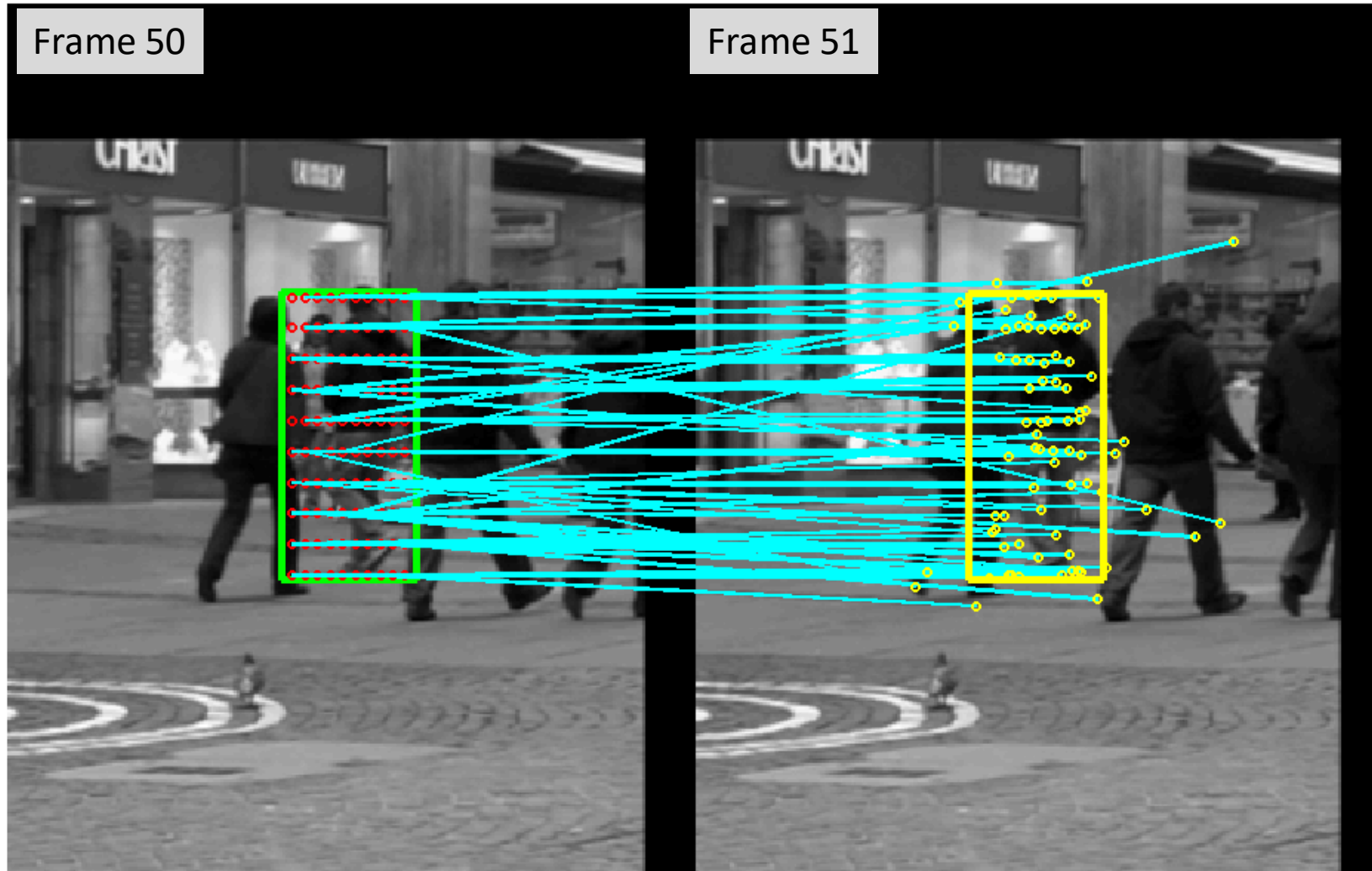
Template Tracking in Tracked States



Template Tracking in Tracked States



Template Tracking in Tracked States



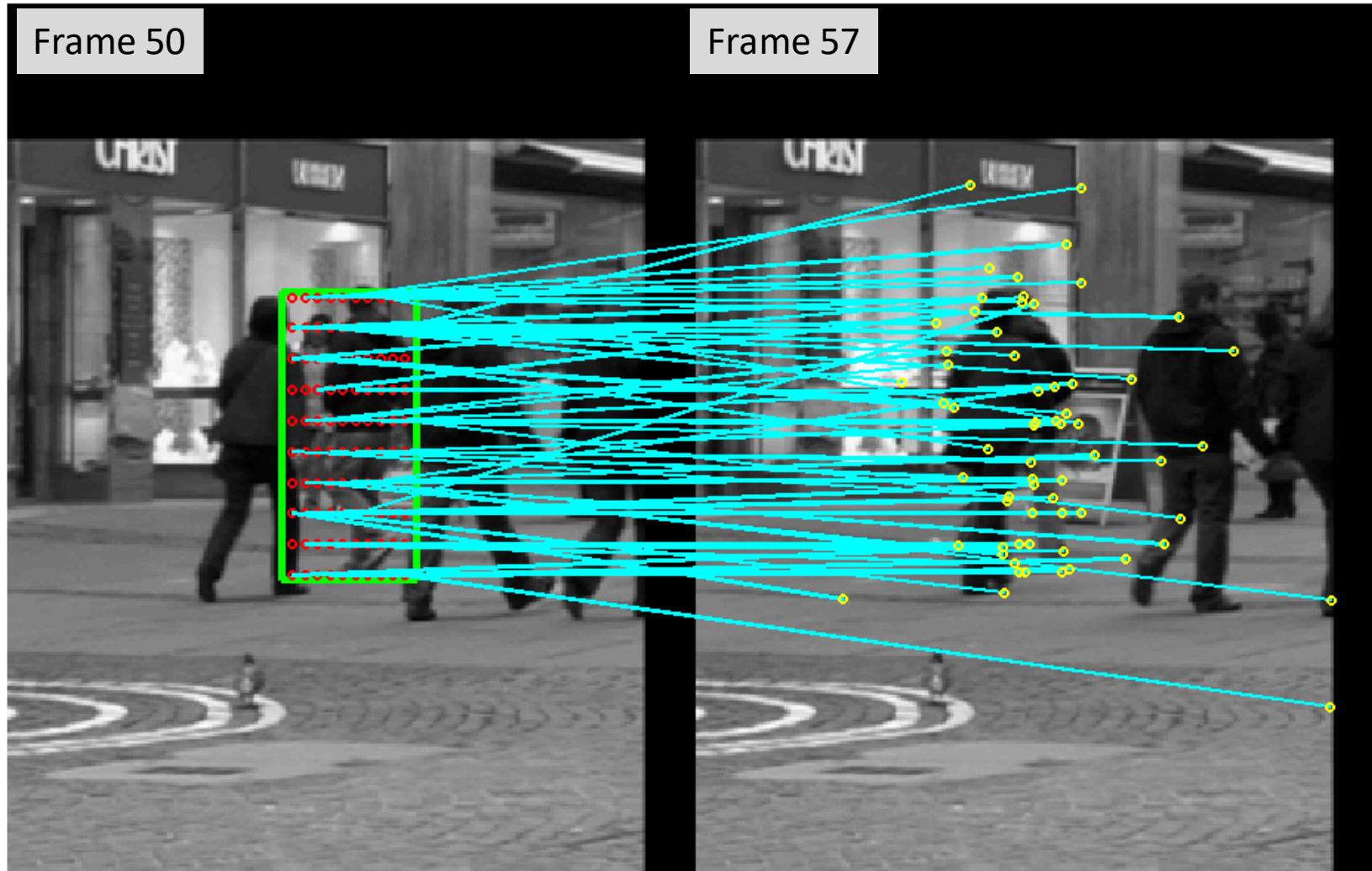
Template Tracking in Tracked States



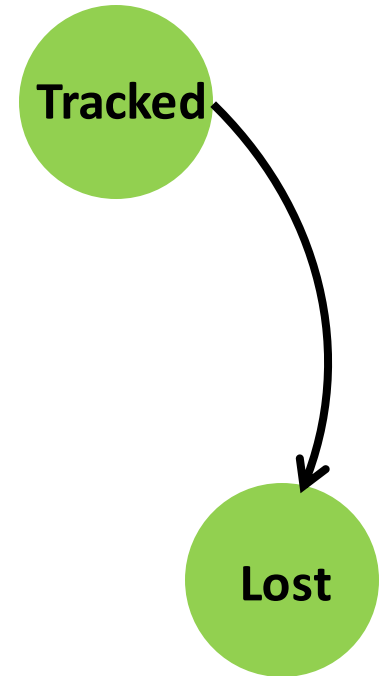
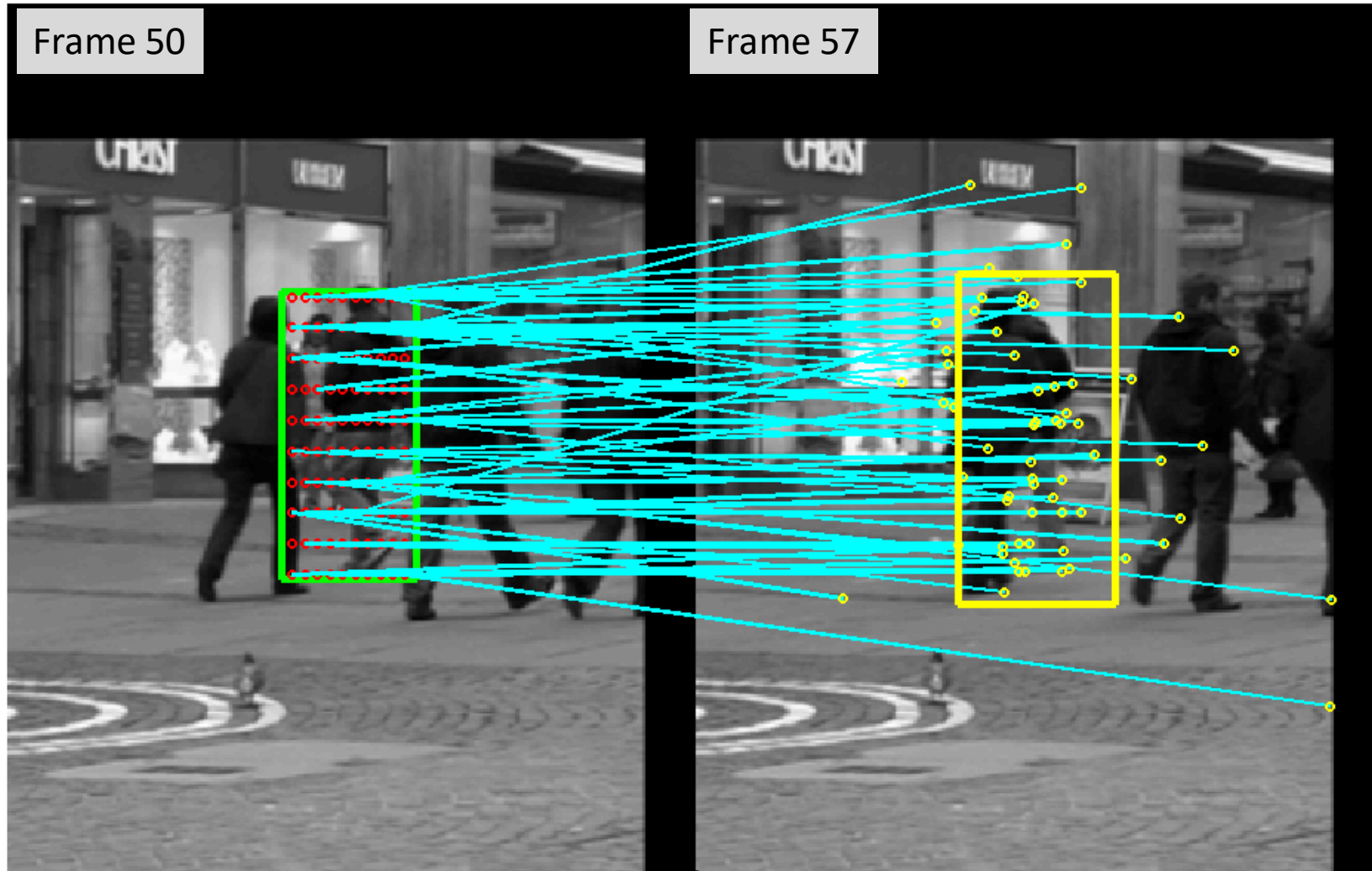
Template Tracking in Tracked States



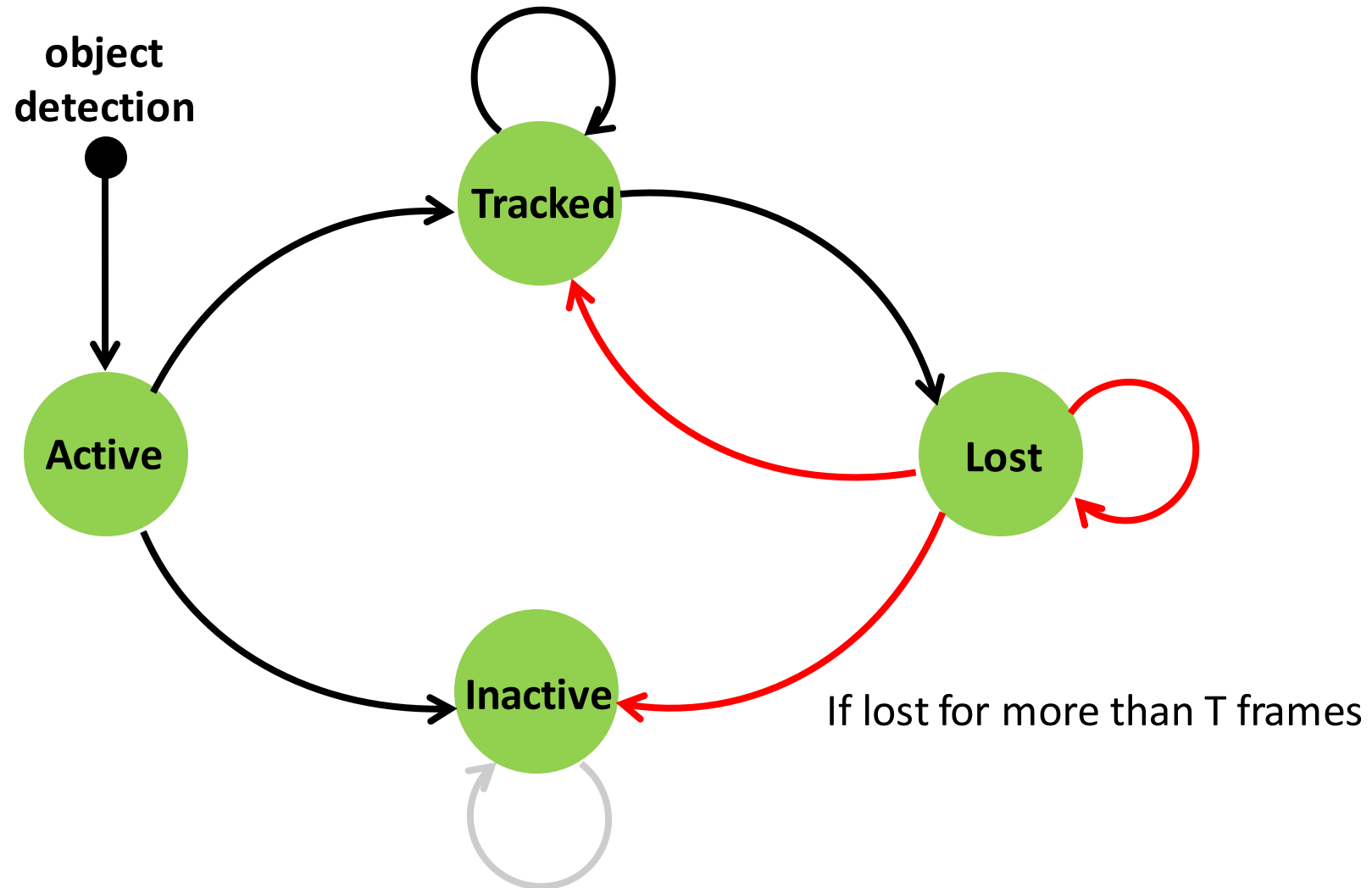
Template Tracking in Tracked States



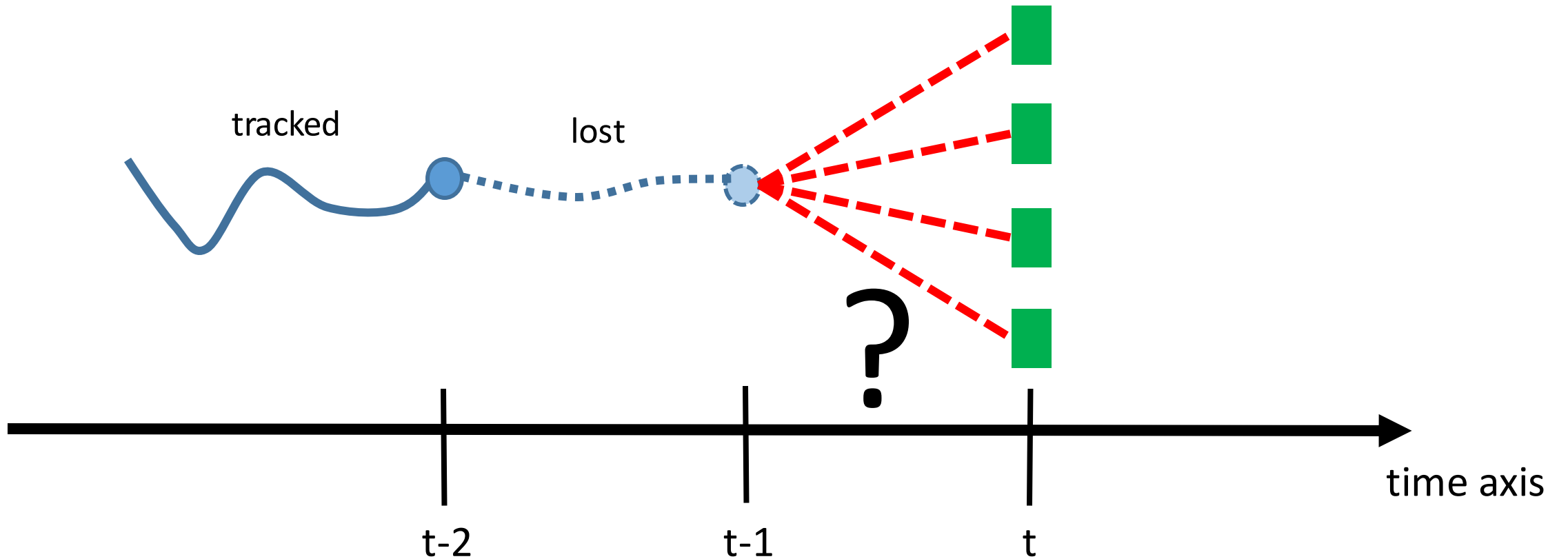
Template Tracking in Tracked States



Markov Decision Process for a Single Target



Data Association in Lost States



Learning the Similarity Function

$$\text{Similarity} = w_1 \phi_1(\text{moo}, \blacksquare) + \dots + w_n \phi_n(\text{moo}, \blacksquare) + b$$

Inverse reinforcement learning: tracking objects in training videos!

(moo , 1)

(moo , 2)

...

(moo , M)

Hard positive examples

(moo , 1)

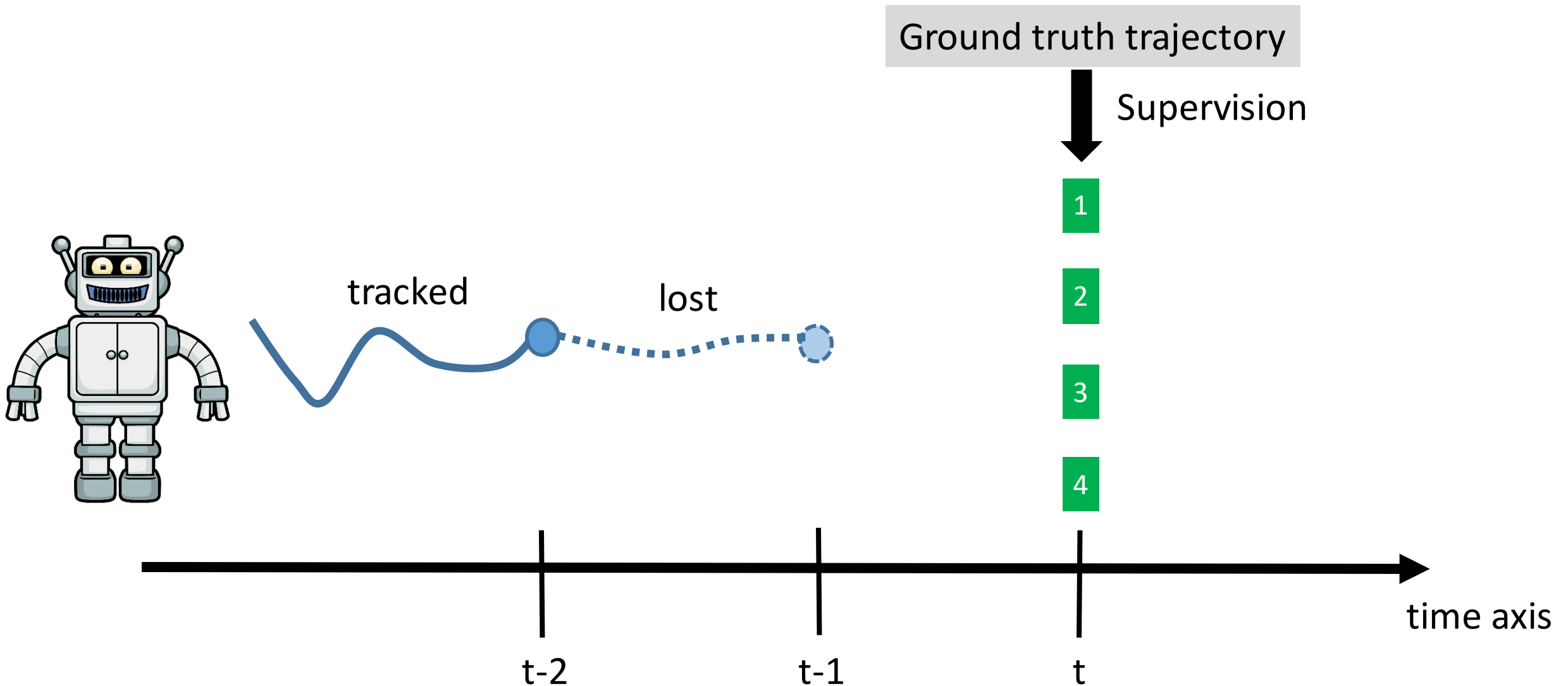
(moo , 2)

...

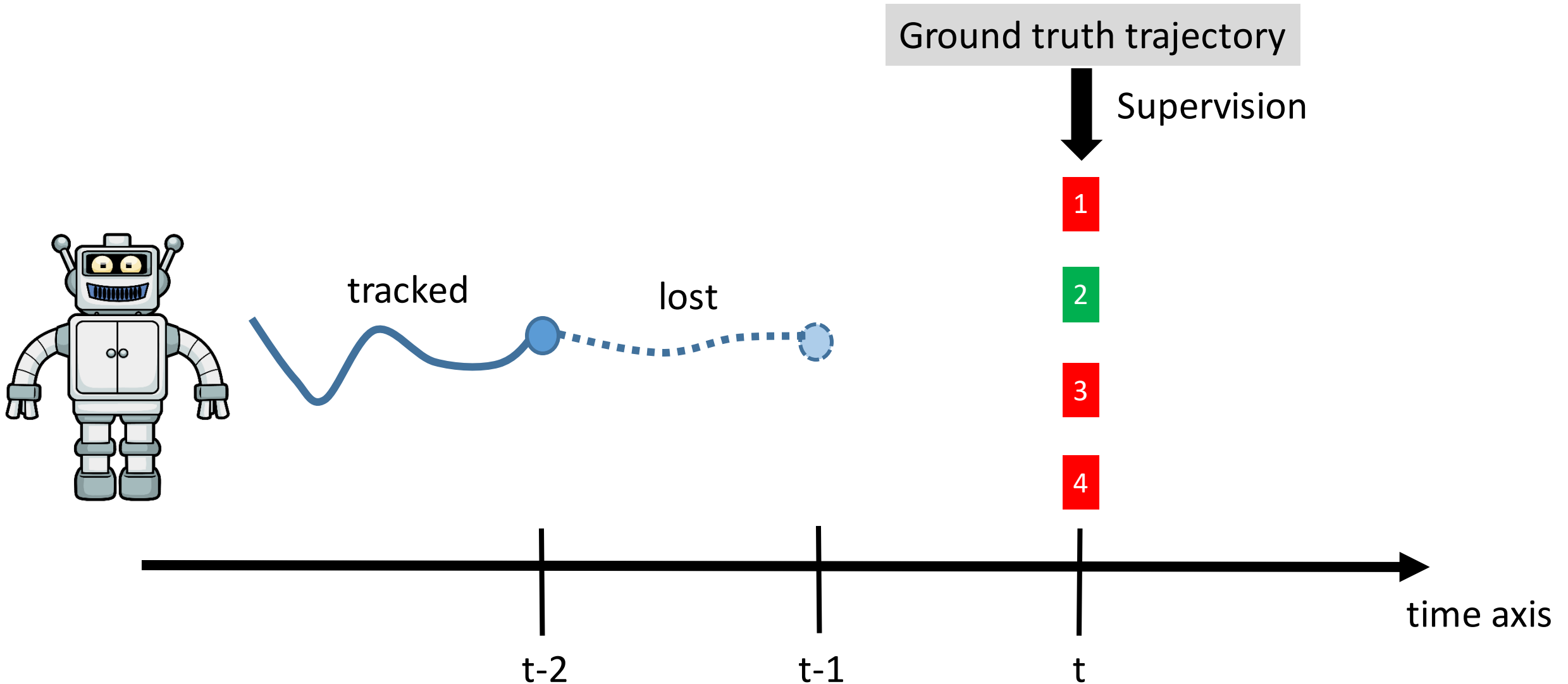
(moo , N)

Hard negative examples

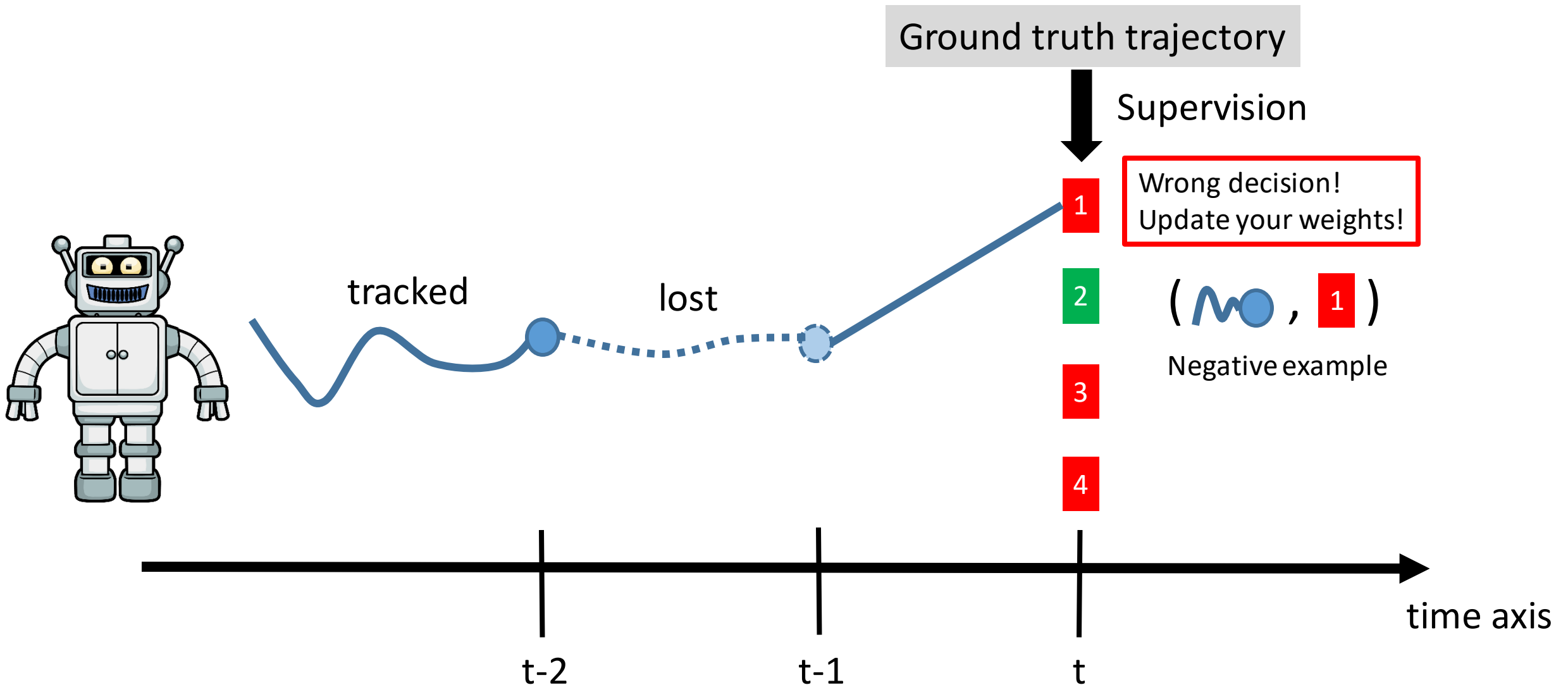
Inverse Reinforcement Learning



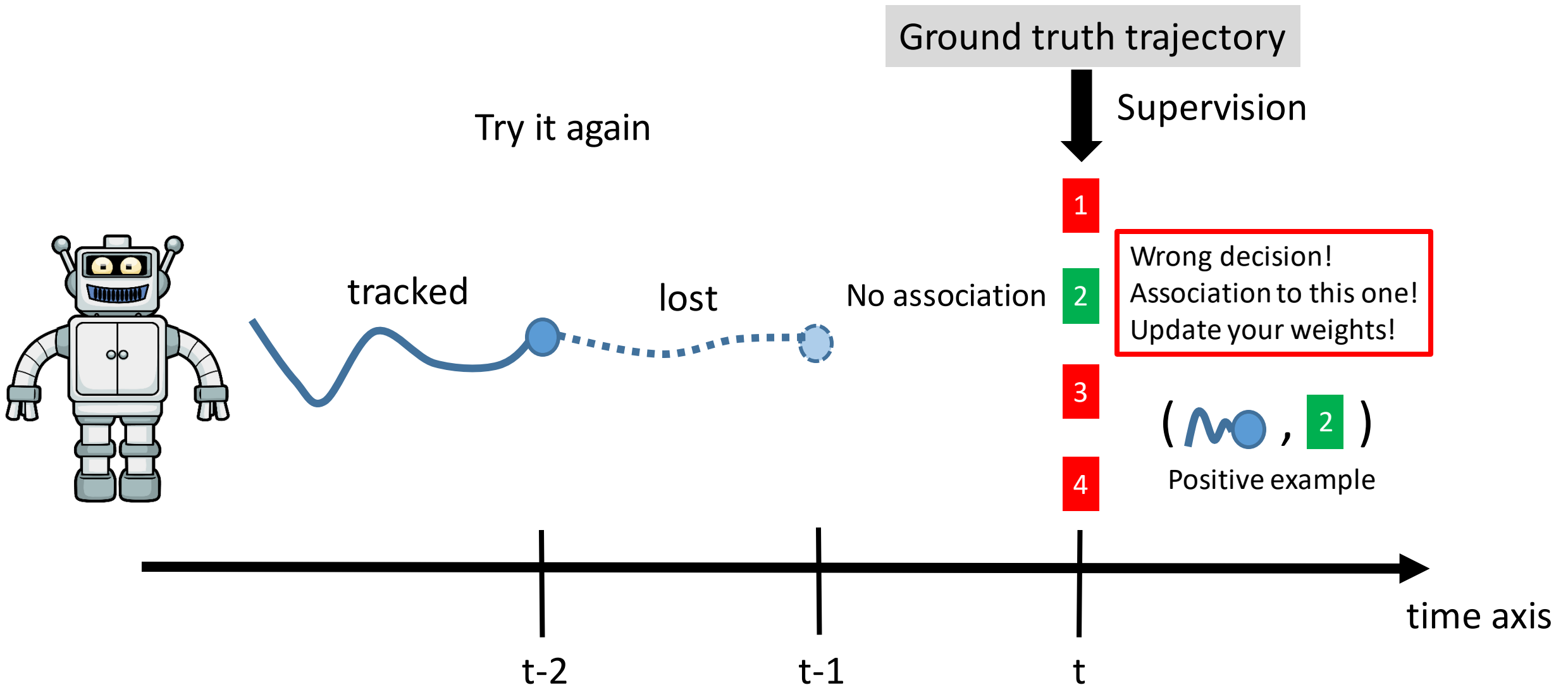
Inverse Reinforcement Learning



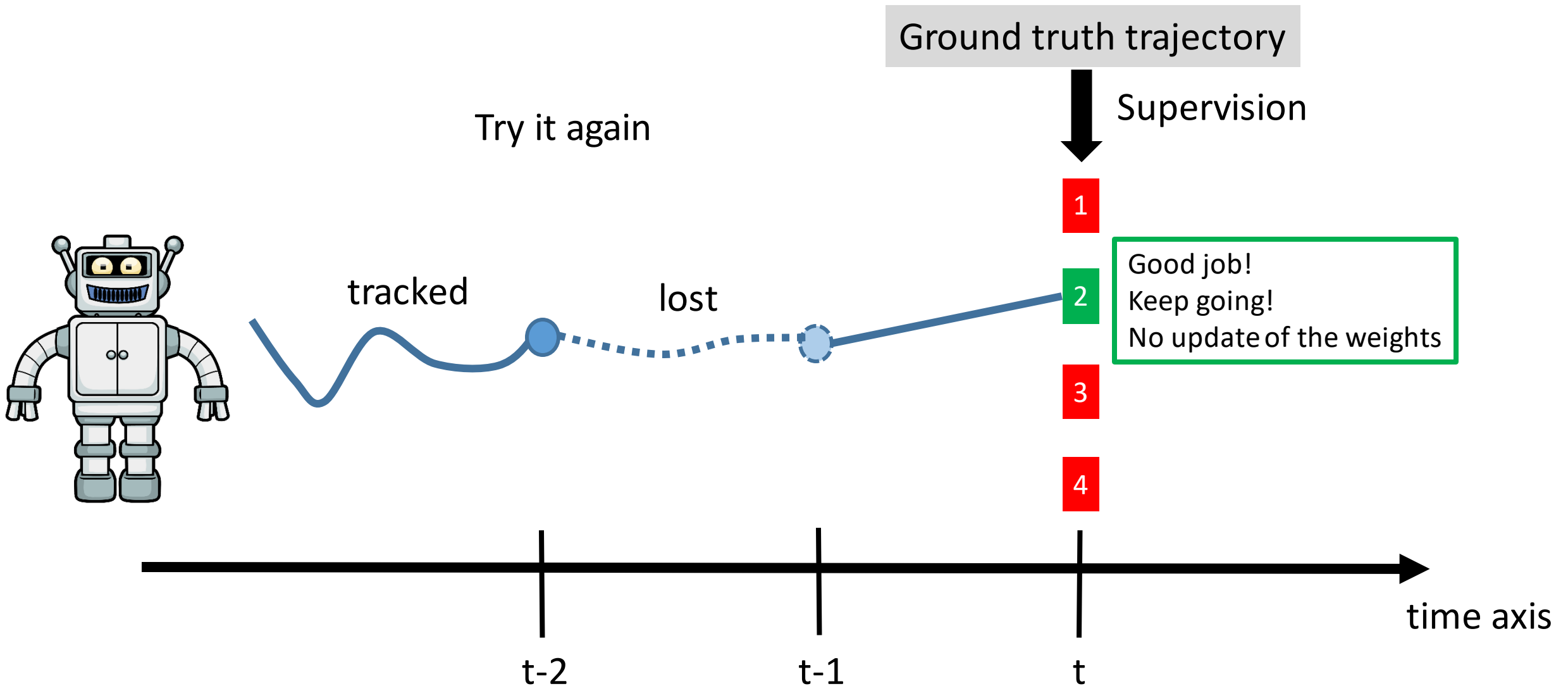
Inverse Reinforcement Learning



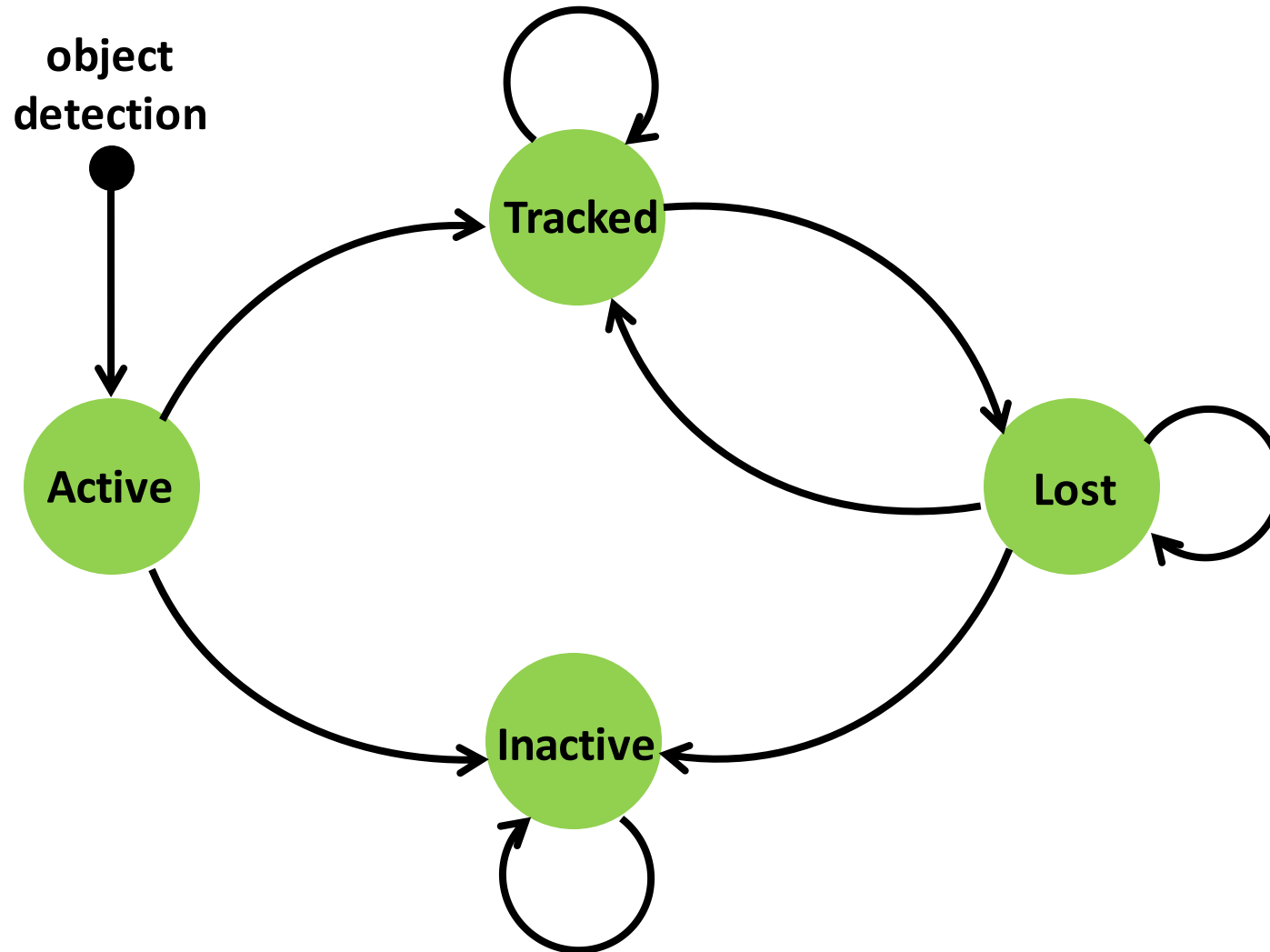
Inverse Reinforcement Learning



Inverse Reinforcement Learning



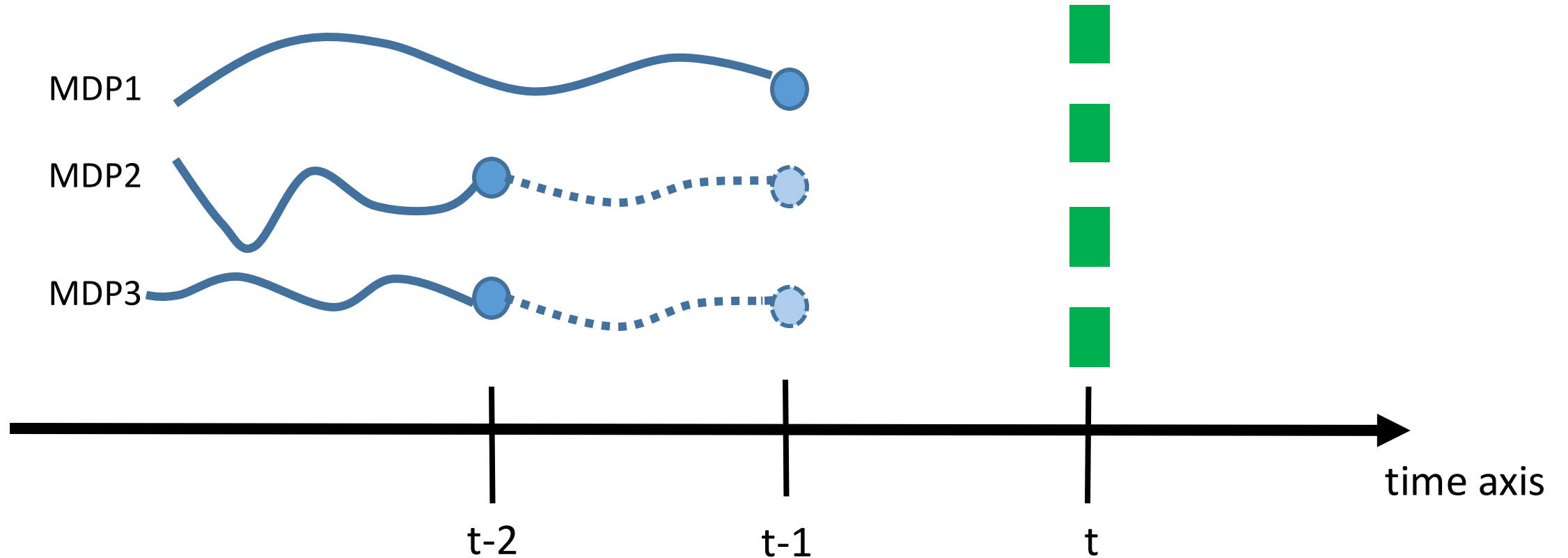
Markov Decision Process for a Single Target



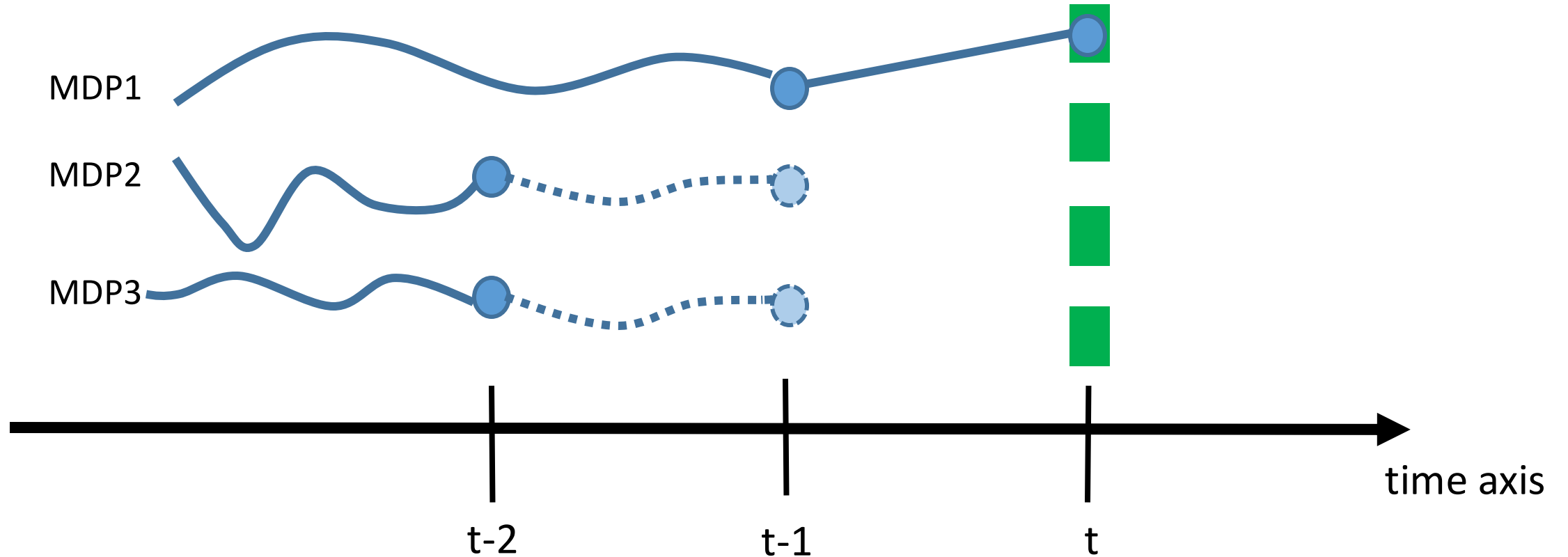
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- **Online Multi-Object Tracking with MDPs**
- Experiments
- Conclusion

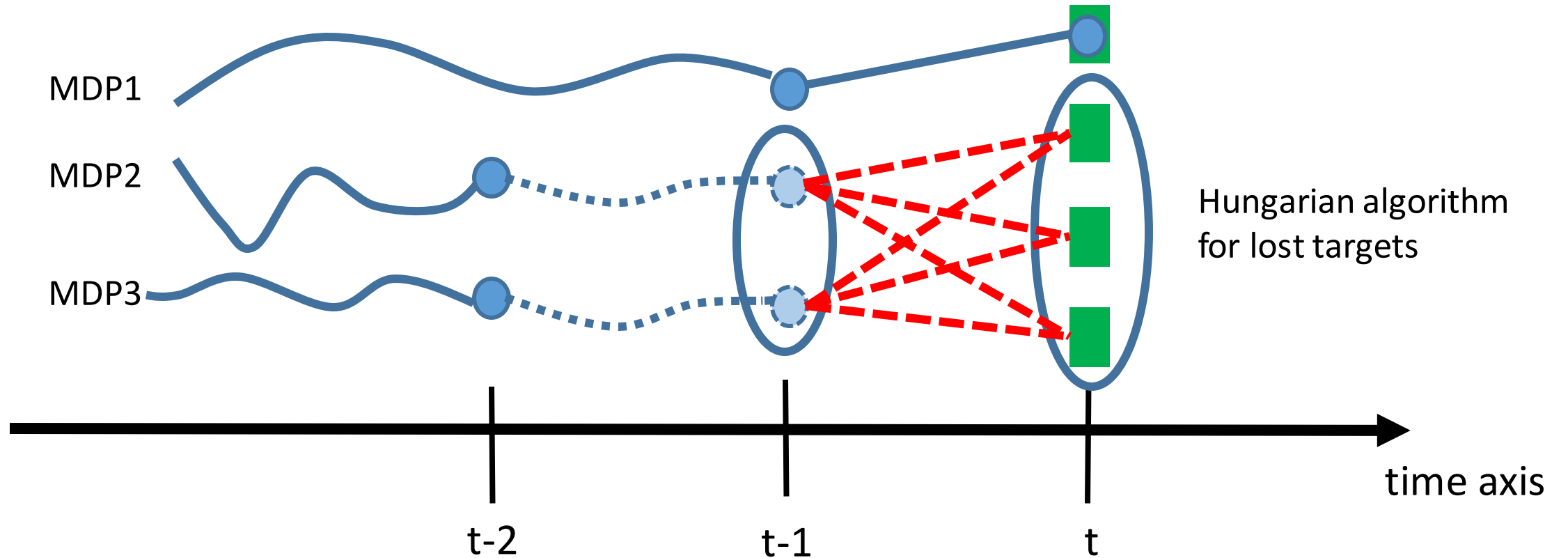
Ensemble MDPs for Online Multi-Object Tracking



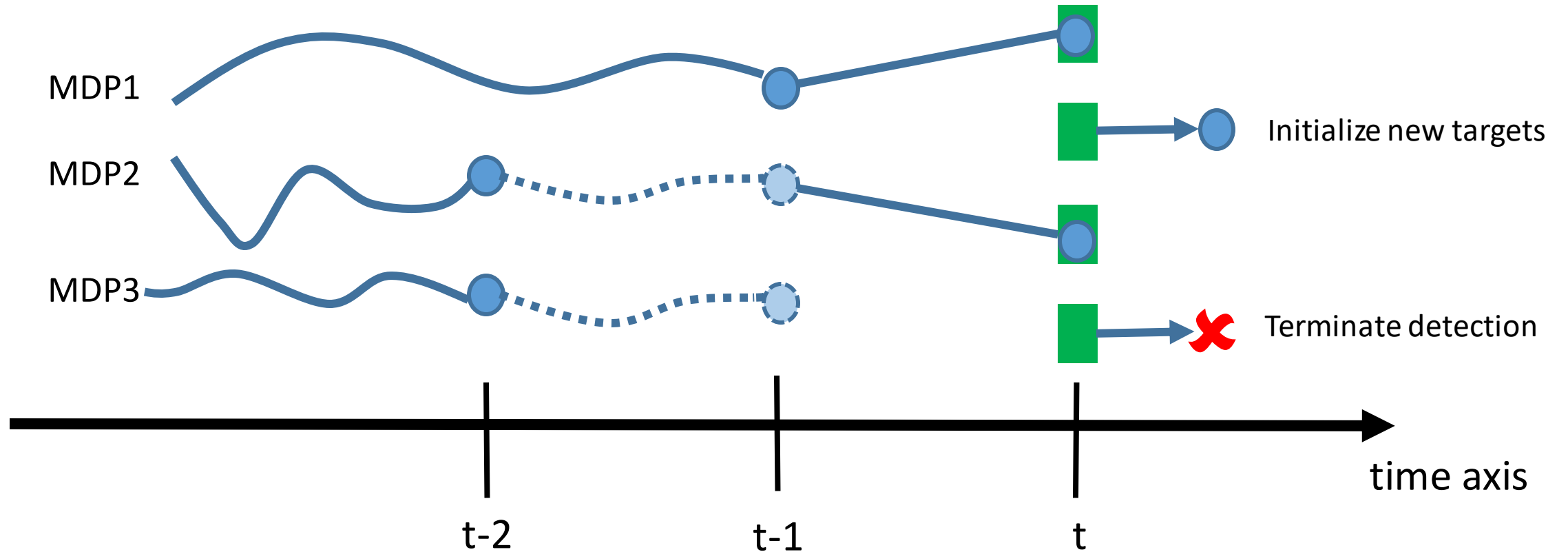
Step 1: Process tracked targets



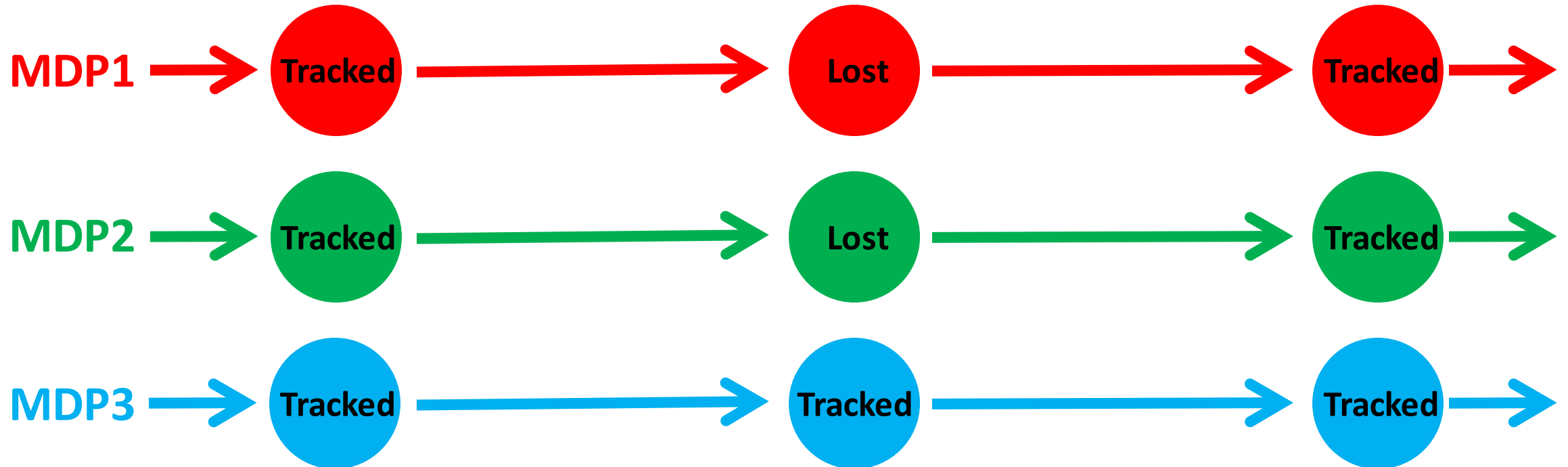
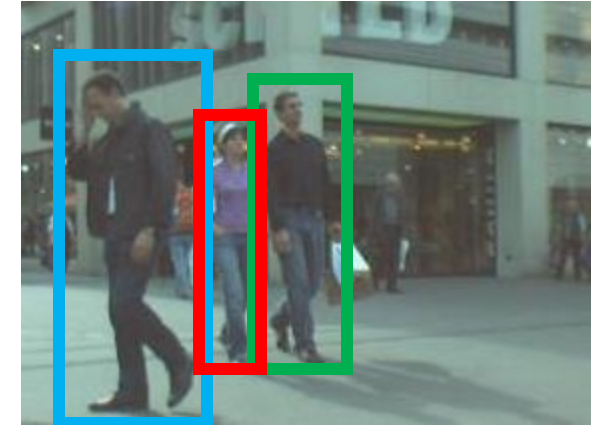
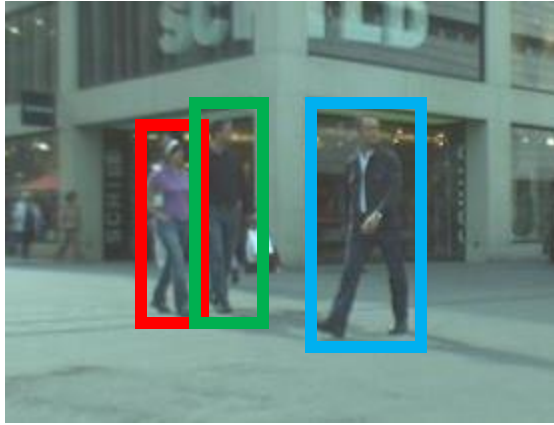
Step 2: Process lost targets



Step 3: Initialize new targets



Online Multi-Object Tracking with MDPs



Outline

- Markov Decision Process (MDP) for a Single Target
- Online Multi-Object Tracking with MDPs
- **Experiments**
- Conclusion

Experiments: Dataset

- Multiple Object Tracking Benchmark [1]
 - 11 training sequences
 - 11 test sequences
 - Object detections from the ACF detector [2]



[1] L. Leal-Taixé, A. Milan, I. Reid, S. Roth, and K. Schindler. MOTChallenge 2015: Towards a Benchmark for Multi-Target Tracking. arXiv:1504.01942 [cs], 2015.

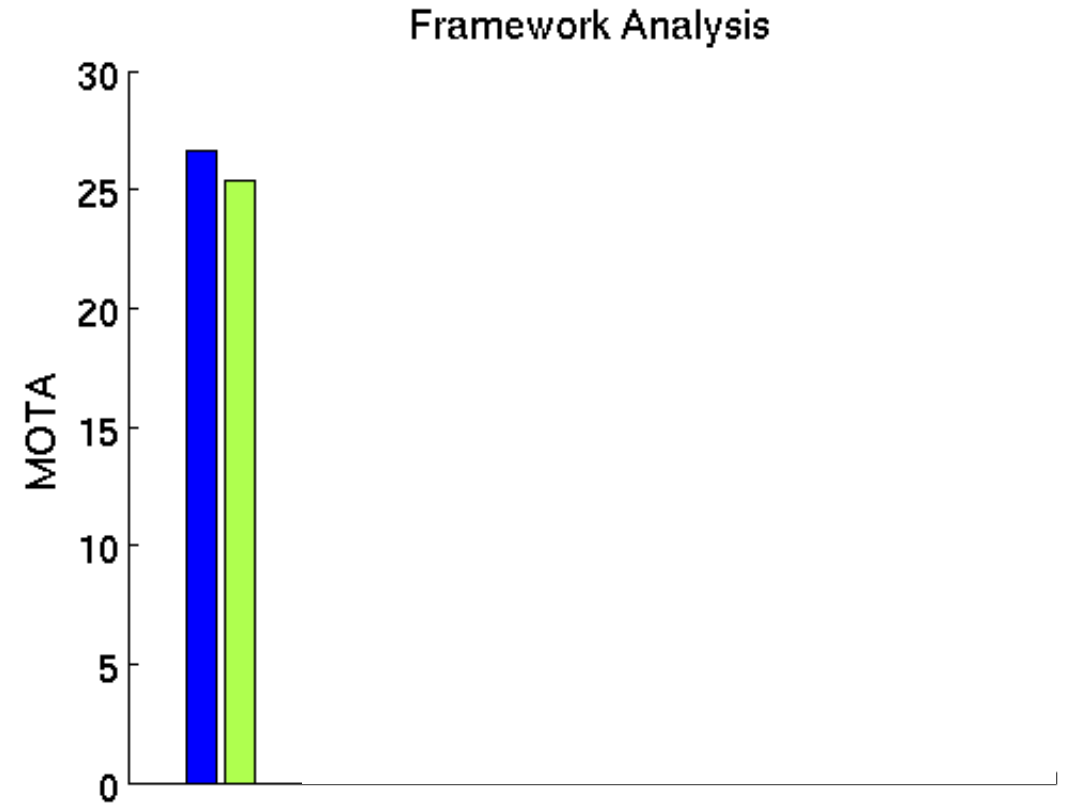
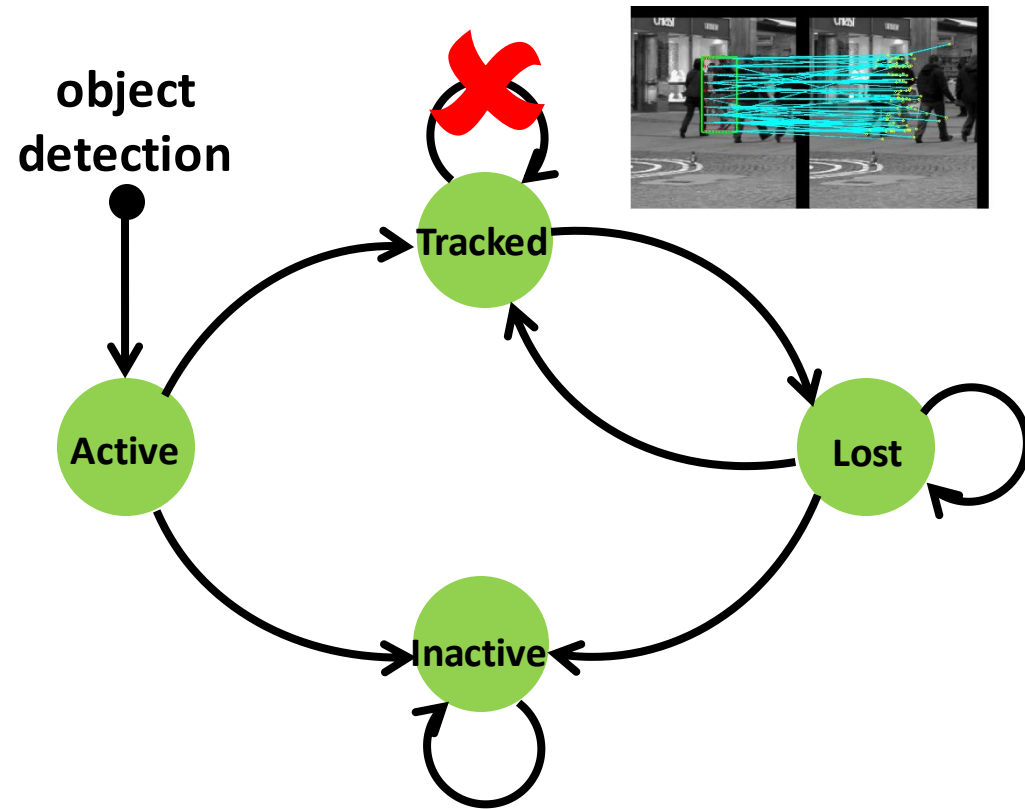
[2] P. Dollár, R. Appel, S. Belongie, and P. Perona. Fast feature pyramids for object detection. TPAMI, 36(8):1532–1545, 2014.

Experiments: Analysis on Validation Set

- Contribution of different components

Experiments: Analysis on Validation Set

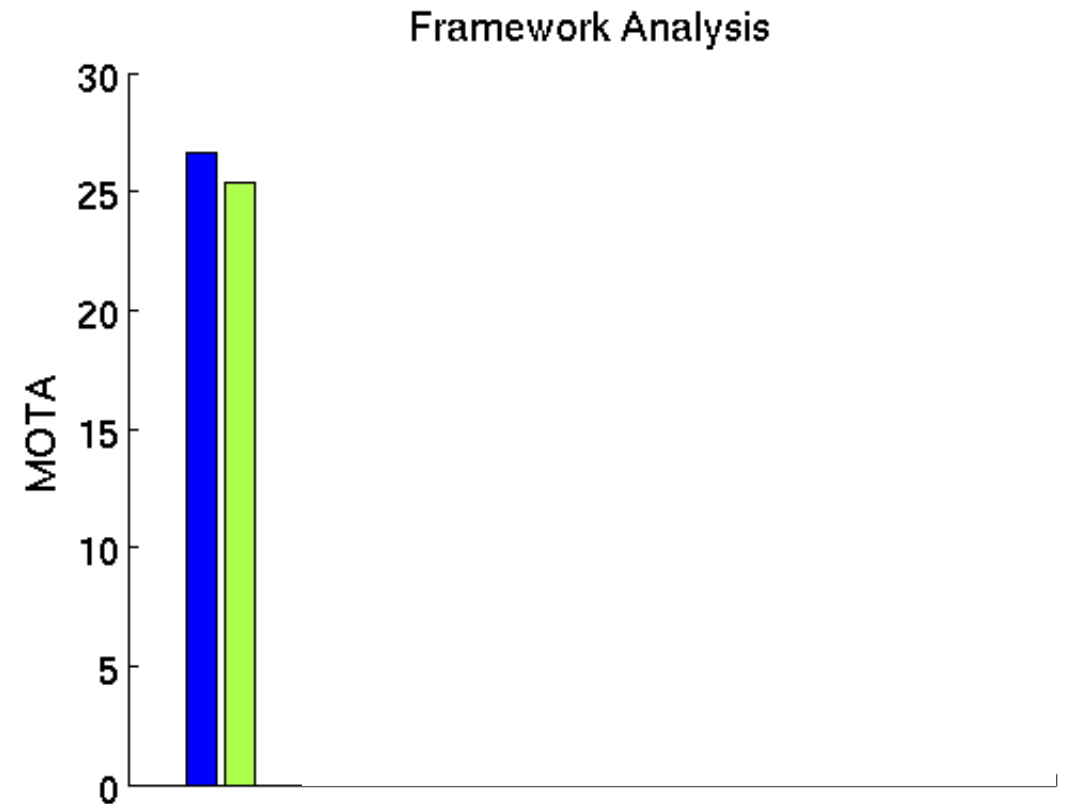
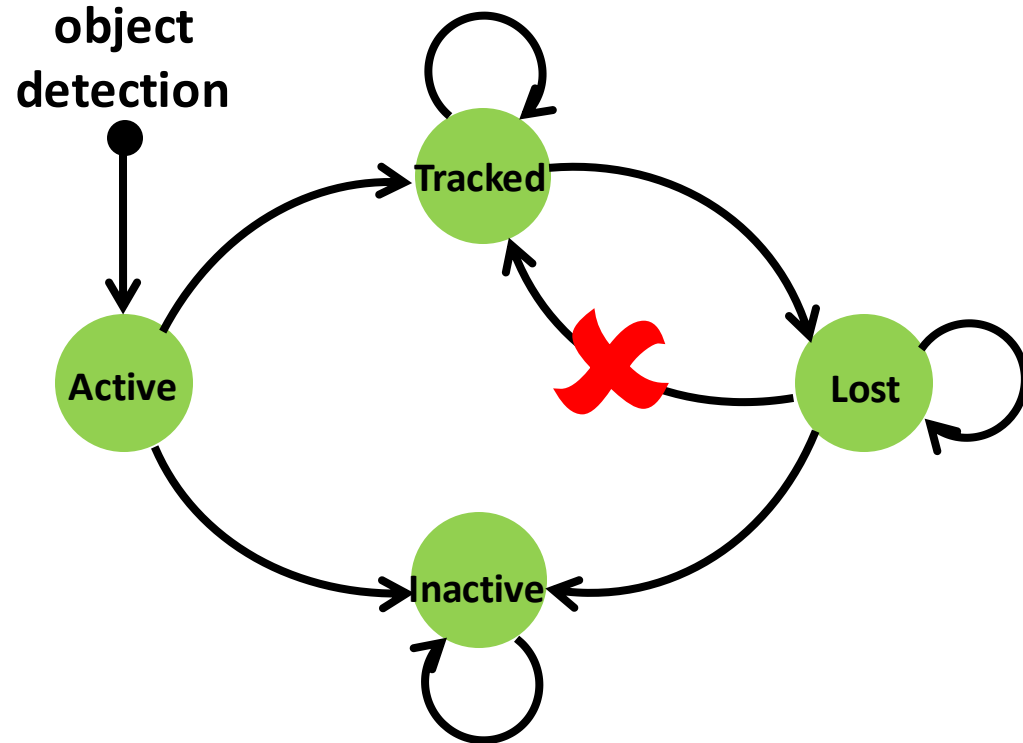
- Contribution of different components



MOTA: multiple object tracking accuracy

Experiments: Analysis on Validation Set

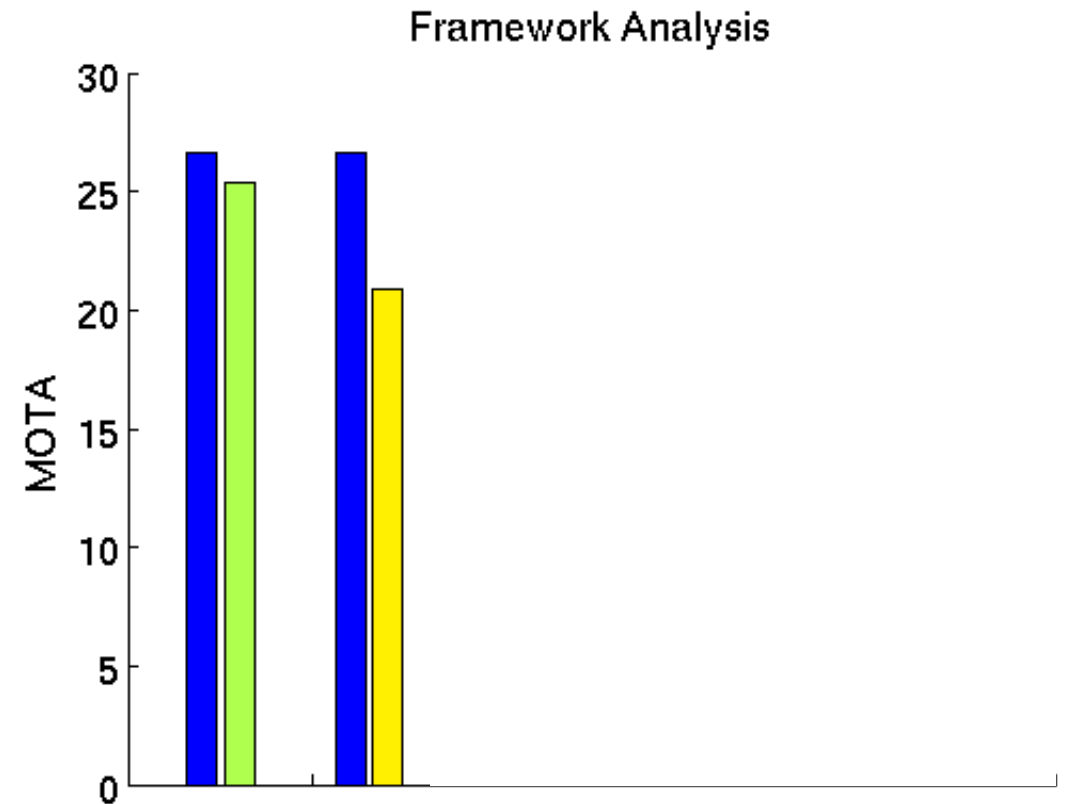
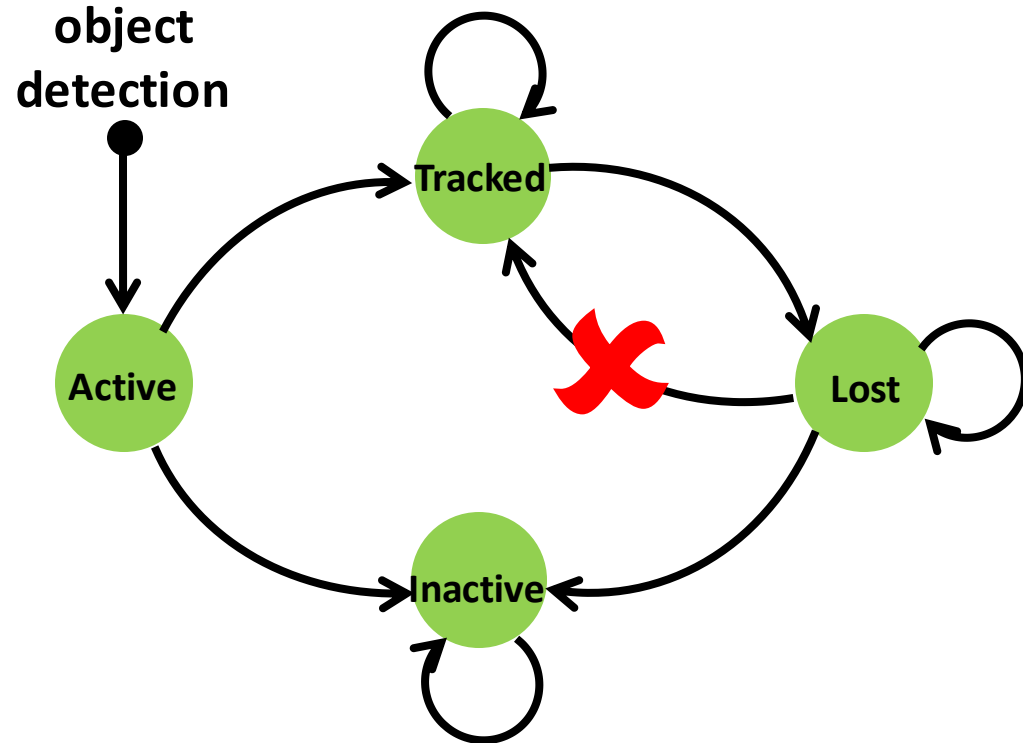
- Contribution of different components



MOTA: multiple object tracking accuracy

Experiments: Analysis on Validation Set

- Contribution of different components

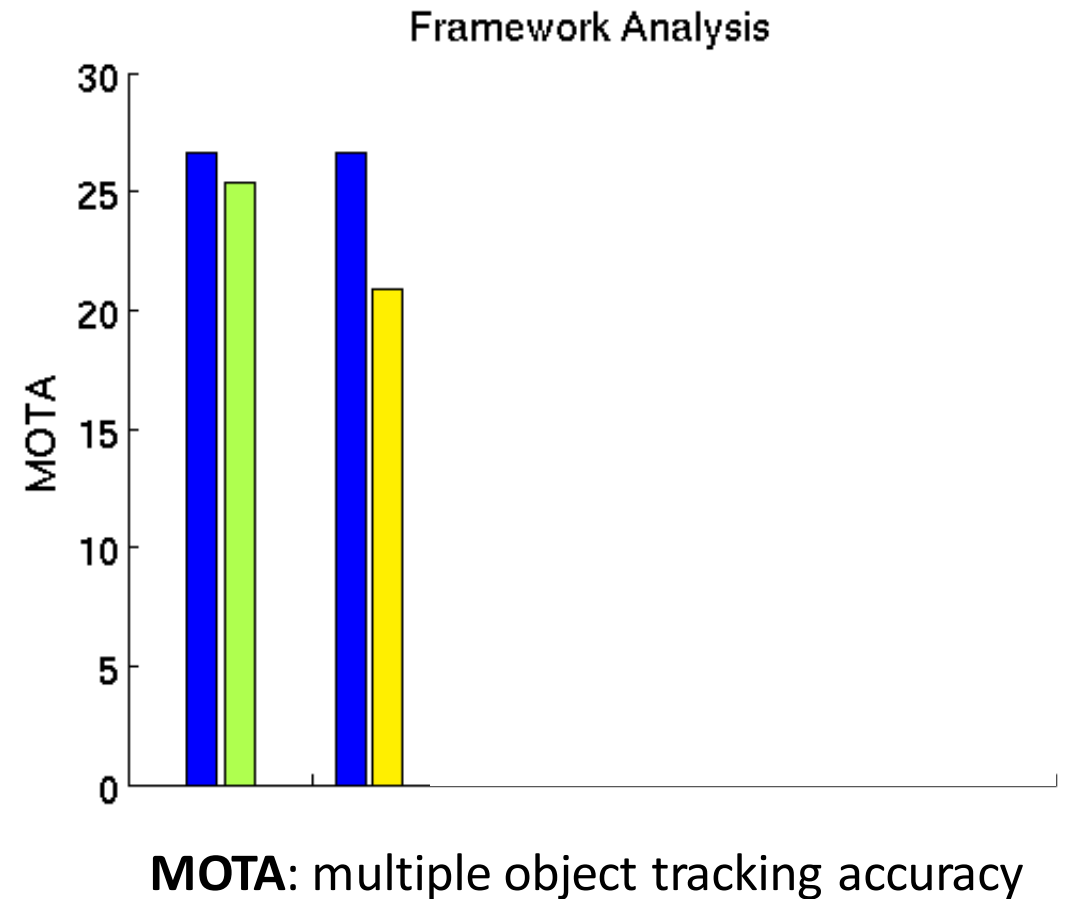


MOTA: multiple object tracking accuracy

Experiments: Analysis on Validation Set

- Contribution of different components

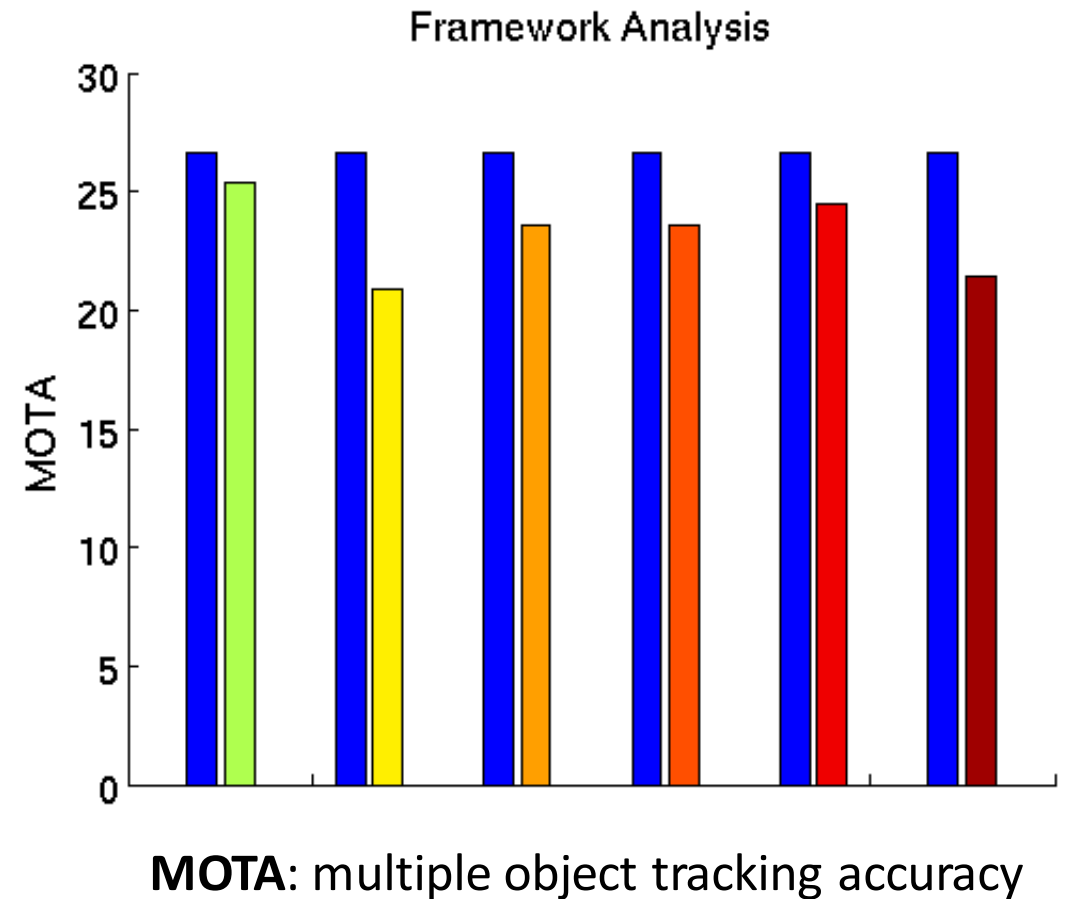
$$\text{Similarity} = w_1 \phi_1(\text{blue wavy line}, \text{green square}) \\ + \dots + w_n \phi_n(\text{blue wavy line}, \text{green square}) \\ + b$$



Experiments: Analysis on Validation Set

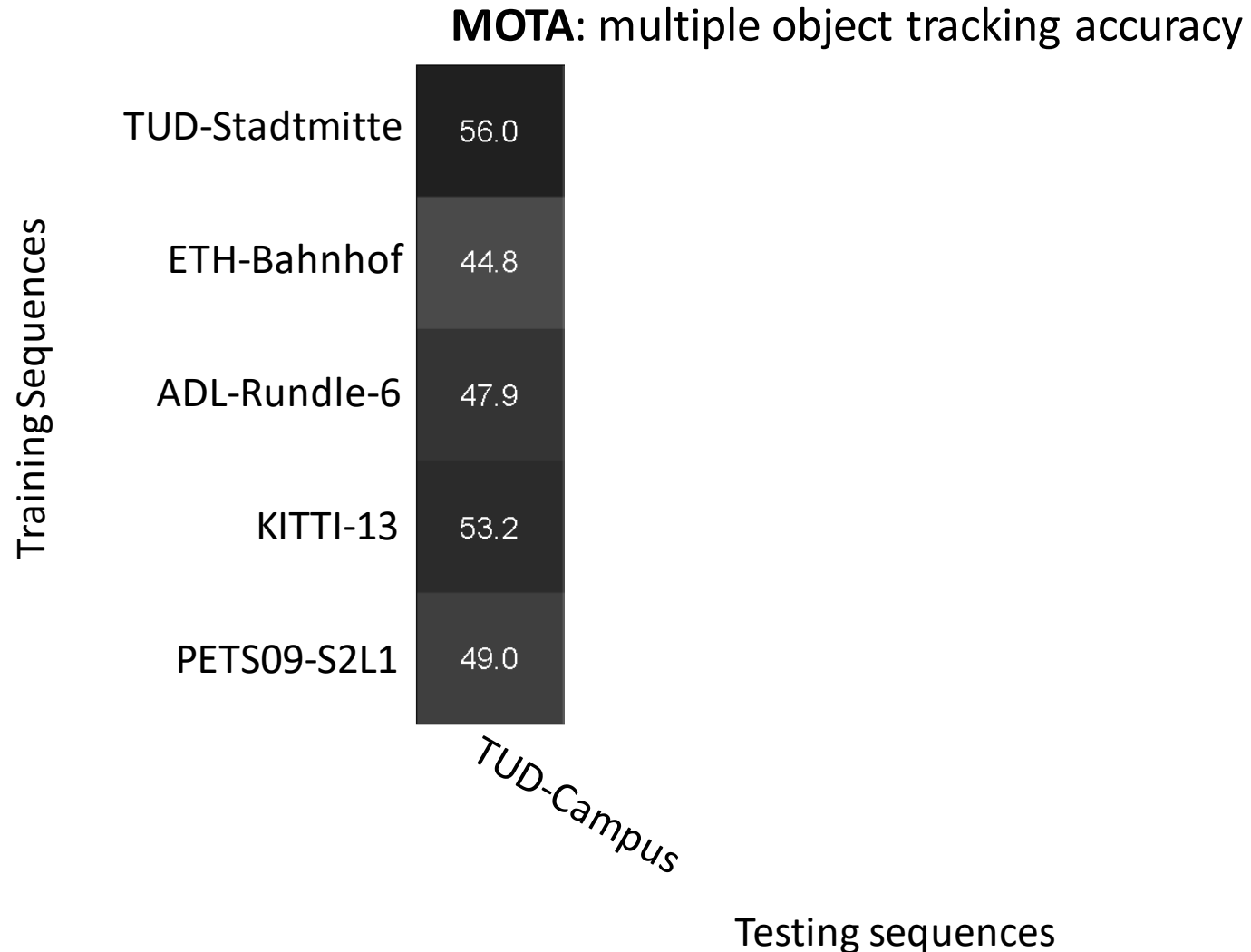
- Contribution of different components

$$\begin{aligned} \text{Similarity} = & w_1 \phi_1(\text{blue circle}, \text{green square}) \\ & + \\ & \vdots \\ & + \\ & w_n \phi_n(\text{blue circle}, \text{green square}) \\ & + \\ & b \end{aligned}$$



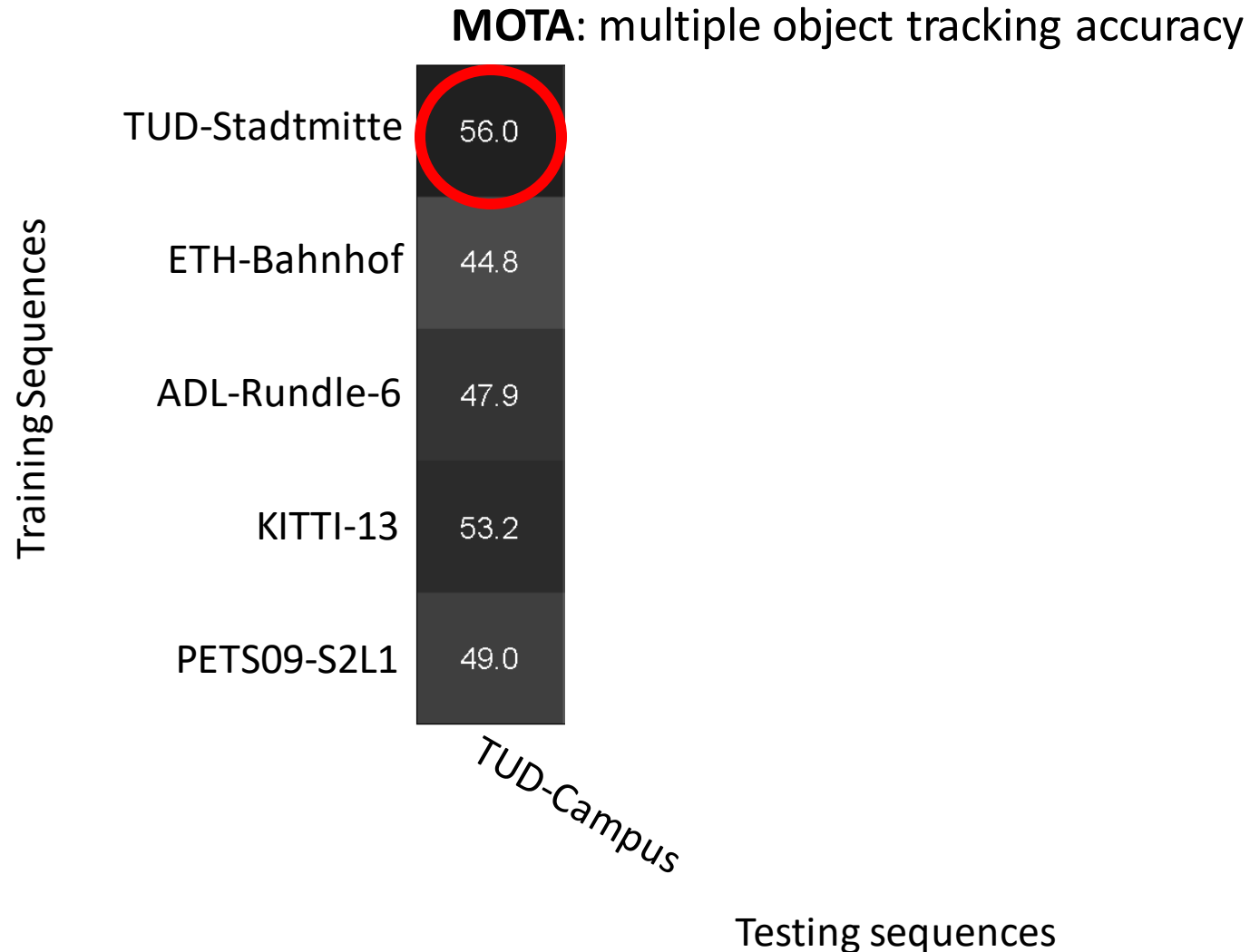
Experiments: Analysis on Validation Set

- Cross-domain tracking



Experiments: Analysis on Validation Set

- Cross-domain tracking



Experiments: Analysis on Validation Set

- Cross-domain tracking

MOTA: multiple object tracking accuracy

Training Sequences	TUD-Campus	ETH-Sunnyday	ETH-Pedcross2	ADL-Rundle-8	Venice-2	KITTI-17
TUD-Stadtmitte	56.0	46.8	14.0	20.0	30.8	60.8
ETH-Bahnhof	44.8	43.4	13.3	22.6	30.8	60.3
ADL-Rundle-6	47.9	48.2	11.5	26.1	29.8	57.8
KITTI-13	53.2	47.5	13.9	20.9	32.1	59.9
PETS09-S2L1	49.0	42.1	11.5	22.1	29.4	61.2

Experiments: Evaluation on Test Set

Tracker	Tracking	Learning	MOTA
DP_NMS [1]	Batch	N/A	14.5
TC_ODAL [2]	Online	Online	15.1
TBD [3]	Batch	Offline	15.9
SMOT [4]	Batch	N/A	18.2
RMOT [5]	Online	N/A	18.6
CEM [6]	Online	N/A	19.3
SegTrack [7]	Batch	Offline	22.5
MotiCon [8]	Batch	Offline	23.1
MDP (Ours)	Online	Online	30.3

MOTA: multiple object tracking accuracy

[1] Pirsiavash et al., CVPR' 11

[2] Bae et al., CVPR'14

[3] Geiger et al., TPAMI'14

[4] Dicle et al., ICCV'13

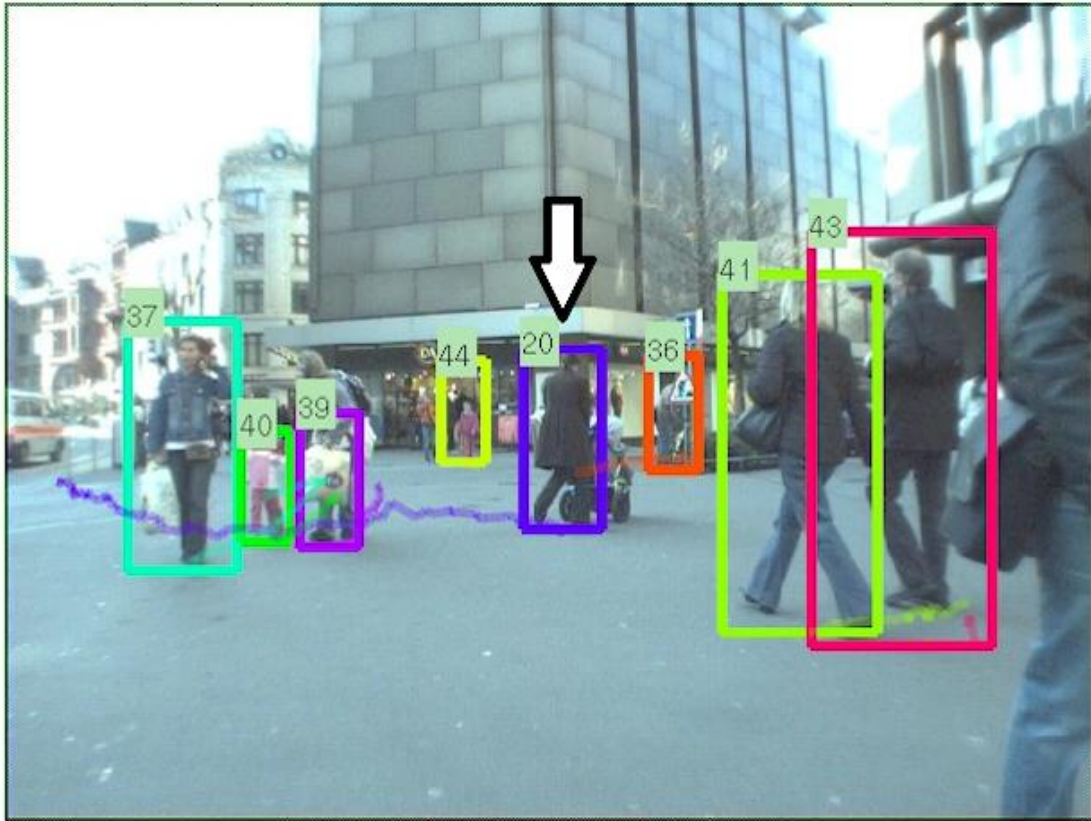
[5] Yoon et al., WACV'15

[6] Milan et al., TPAMI'14

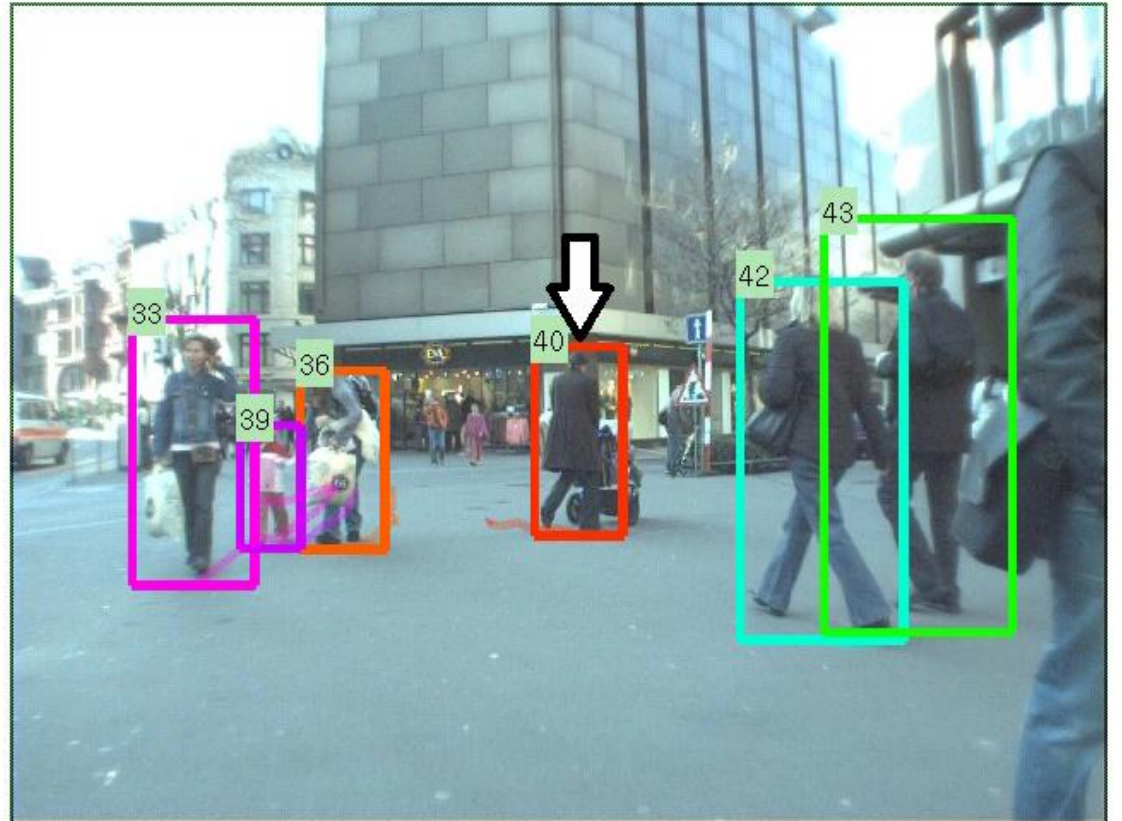
[7] Milan et al., CVPR'15

[8] Leal-Taixé et al., CVPR'14

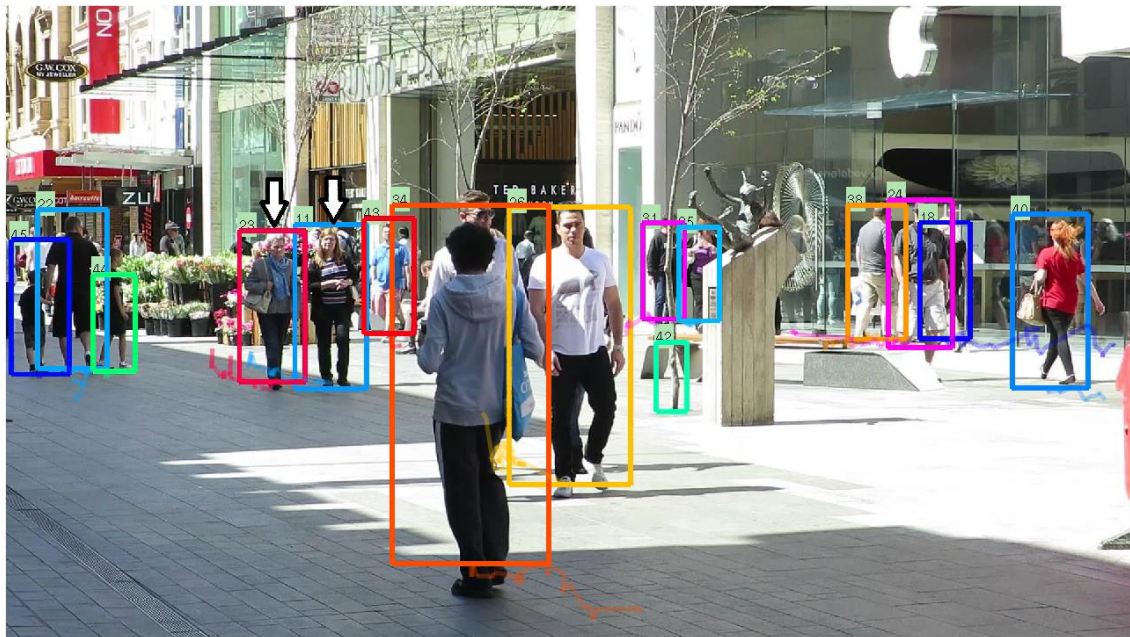
Tracking Results



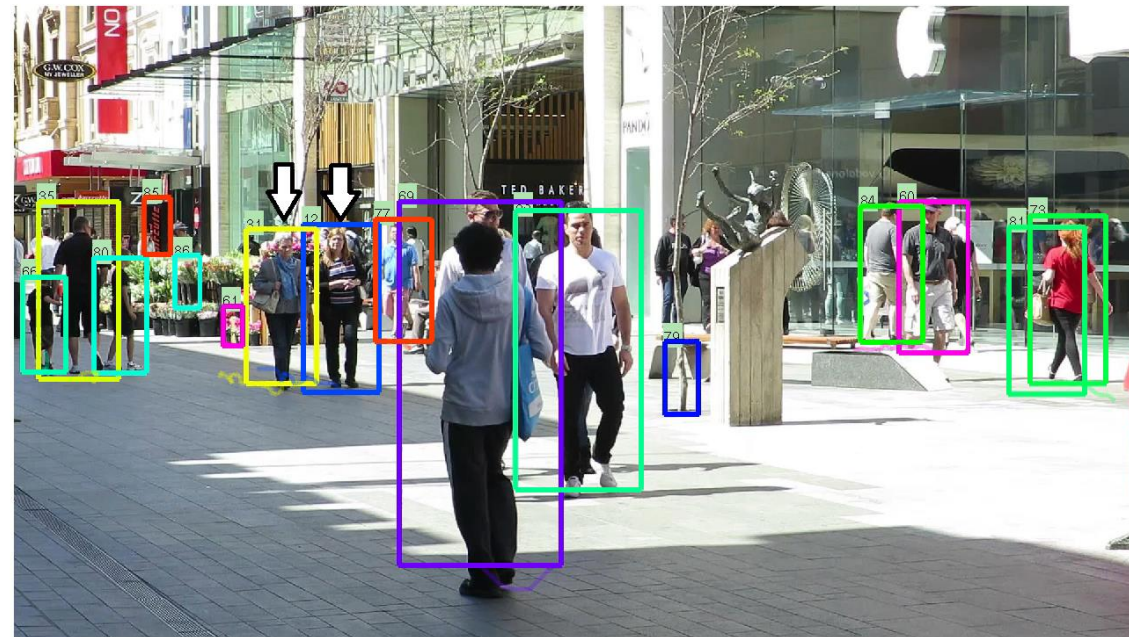
MDP [Ours]



MotiCon [Leal-Taixé et al., CVPR'14]



MDP [Ours]



MotiCon [Leal-Taixé et al., CVPR'14]



MDP [Ours]



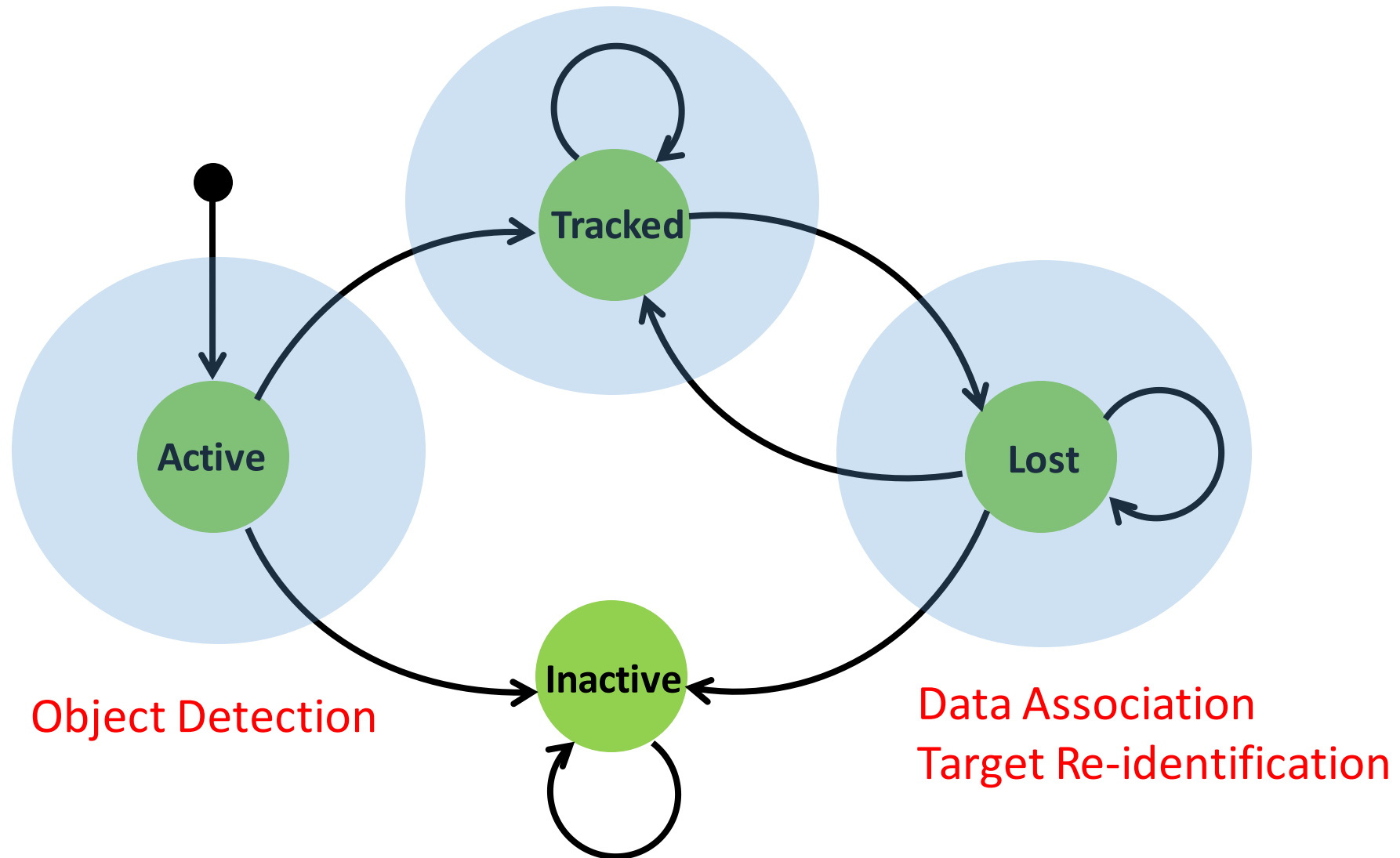
MotiCon [Leal-Taixé et al., CVPR'14]

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- Markov Decision Process (MDP) for a Single Target
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- Experiments
- **Conclusion**


Conclusion

Single Object Tracking



Code











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Learning to Track: Online Multi-Object Tracking by Decision Making

112 commits 1 branch 0 releases 1 contributor

Branch: master ▾ **MDP_Tracking** / +

 Yu Xiang make video 1 to N	Latest commit 744796b on Oct 6
 3rd_party	hungarian 7 months ago
 qsub	qsub 8 months ago
 .gitignore	remove files 2 months ago
 LICENSE	Initial commit 10 months ago
 LICENSE_TLD	add TLD license 2 months ago
 LK.m	clean up 8 months ago
 LK_associate.m	add comments 2 months ago
 LK_crop_image_box.m	add comments 2 months ago
 LK_initialize.m	add comments 2 months ago

Code


Issues 0

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Pulse

Graphs

HTTPS clone URL

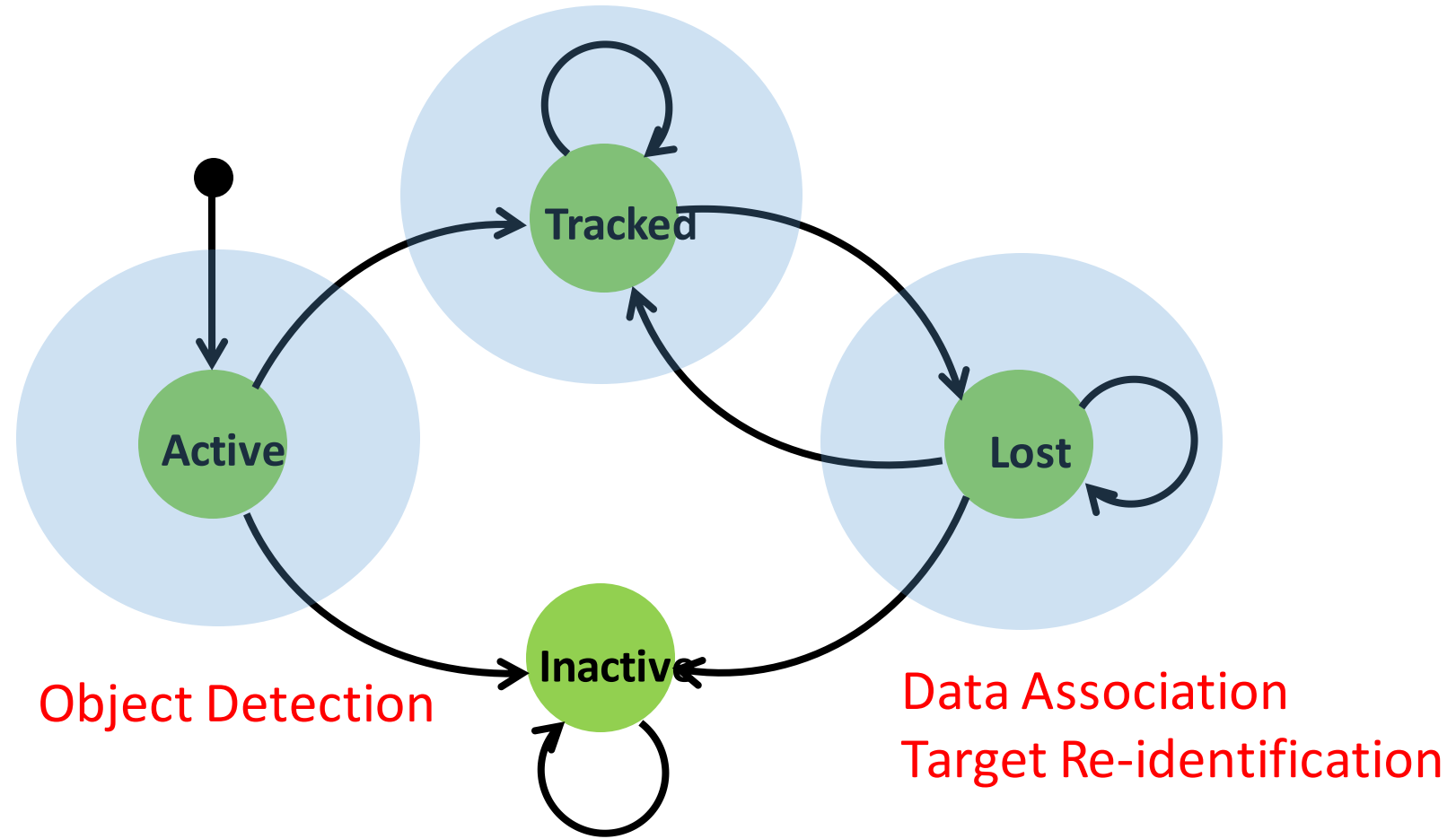
<https://github.com> 

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Single Object Tracking



Thank you!

