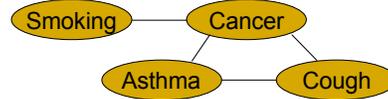


# Markov Networks



## Markov Networks

- **Undirected** graphical models



- Potential functions defined over cliques

$$P(x) = \frac{1}{Z} \prod_c \Phi_c(x_c)$$

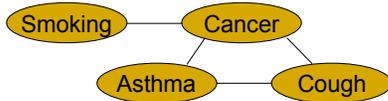
$$Z = \sum_x \prod_c \Phi_c(x_c)$$

Smoking	Cancer	$\Phi(S,C)$
False	False	4.5
False	True	4.5
True	False	2.7
True	True	4.5



## Markov Networks

- **Undirected** graphical models



- Log-linear model:

$$P(x) = \frac{1}{Z} \exp\left(\sum_i w_i f_i(x)\right)$$

Weight of Feature  $i$       Feature  $i$

$$f_i(\text{Smoking}, \text{Cancer}) = \begin{cases} 1 & \text{if } \neg \text{Smoking} \vee \text{Cancer} \\ 0 & \text{otherwise} \end{cases}$$

$w_1 = 1.5$



## Hammersley-Clifford Theorem

If Distribution is strictly positive ( $P(x) > 0$ )  
**And** Graph encodes conditional independences  
**Then** Distribution is product of potentials over cliques of graph

Inverse is also true.  
 ("Markov network = Gibbs distribution")



## Markov Nets vs. Bayes Nets

Property	Markov Nets	Bayes Nets
Form	Prod. potentials	Prod. potentials
Potentials	Arbitrary	Cond. probabilities
Cycles	Allowed	Forbidden
Partition func.	$Z = ?$	$Z = 1$
Indep. check	Graph separation	D-separation
Indep. props.	Some	Some
Inference	MCMC, BP, etc.	Convert to Markov

## Inference in Markov Networks

- **Goal:** compute marginals & conditionals of

$$P(X) = \frac{1}{Z} \exp\left(\sum_{\tau} w_{\tau} f_{\tau}(X)\right) \quad Z = \sum_X \exp\left(\sum_{\tau} w_{\tau} f_{\tau}(X)\right)$$

- Exact inference is #P-complete
- Conditioning on Markov blanket is easy:

$$P(x | MB(x)) = \frac{\exp\left(\sum_i w_i f_i(x)\right)}{\exp\left(\sum_i w_i f_i(x=0)\right) + \exp\left(\sum_i w_i f_i(x=1)\right)}$$

- Gibbs sampling exploits this

## MCMC: Gibbs Sampling

```

state ← random truth assignment
for i ← 1 to num-samples do
  for each variable x
    sample x according to P(x|neighbors(x))
    state ← state with new value of x
P(F) ← fraction of states in which F is true
    
```

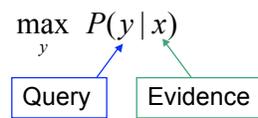
## Other Inference Methods

- Belief propagation (sum-product)
- Mean field / Variational approximations

## MAP/MPE Inference



- **Goal:** Find most likely state of world given evidence



## MAP Inference Algorithms



- Iterated conditional modes
- Simulated annealing
- Graph cuts
- Belief propagation (max-product)