Surfaces of Revolution

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Idea: rotate a 2D **profile curve** around an axis.

What kinds of shapes can you model this way?

Constructing surfaces of revolution



Given: A curve C(v) in the *xy*-plane:

$$C(v) = \begin{bmatrix} C_x(v) \\ C_y(v) \\ 0 \\ 1 \end{bmatrix}$$

Let $R_{y}(\theta)$ be a rotation about the *y*-axis.

Find: A surface S(u, v) which is C(v) rotated about the *y*-axis, where $u, v \in [0, 1]$.

Solution: $\int (u_{jv}) = R_{\gamma}(x_{ij}u) C(v)$

Constructing surfaces of revolution

We can sample in u and v to get a grid of points over the surface.



Suppose we sample:

- in *v*, to give C[j] where $j \in [0..M-1]$
- in *u*, to give rotation angle $\theta[i] = 2\pi i/N$ where $i \in [0..N]$

We can now write the surface as:

 $S[i,j] = R_{\gamma} \left(\frac{2\pi i}{N}\right) C[j]$

How would we turn this into a mesh of triangles? How do we assign per-vertex normals?

Tangent vectors, tangent planes, and normals





Normals on a surface of revolution



We can compute tangents in the *x*-*y* plane:

 $\mathbf{T}_{1}[0,j] \approx \langle [j+1] - \langle [j] \rangle$ $\mathbf{T}_{2}[0,j] = \begin{bmatrix} 0 & 0 & 1 \end{bmatrix}^{\mathsf{T}}$

to get the normal in that plane:

$$\mathbf{N}[0, j] = \mathbf{T}_1[0, j] \times \mathbf{T}_2[0, j] \quad \dots \text{ then normalize}$$

and then rotate it around:

$$N[i_j j] = R_{\gamma} (2) N[o_j j]$$

.

Texture coordinates on a surface of revolution



The simplest assignment of texture coordinates would be:

 $v = \frac{i}{N}$

We can do better for ν to reduce distortion. Define:

$$d[j] = \begin{cases} \|C[j] - C[j-1]\|, & \text{if } j \neq 0\\ 0, & \text{if } j = 0 \end{cases}$$

and set ν to fractional distance along the curve:

"arc length parameterization"

You must do this for ν for the assignment!

Triangle meshes

How should we generally represent triangle meshes?

 $S_{1}, N_{1}, u_{1}, v_{1}$ $S_{2}, N_{2}, u_{2}, v_{2}$ $S_{3}, N_{3}, u_{2}, v_{2}$ $S_{1}, N_{1}, u_{1}, v_{1}$ $S_{3}, N_{3}, u_{3}, v_{3}$ $S_{4}, N_{4}, v_{4}, v_{4}$

$$\frac{Vertices}{S_{1}, N_{1}, M_{1}, V_{1}} = \underbrace{\Delta's}_{(1, 2, 3)}$$

$$S_{2}, N_{2}, M_{2}, M_{2} = \underbrace{(1, 3, 4)}_{1, 3, 4}$$

$$\frac{Vertices}{S_{2}, N_{2}, M_{2}, M_{2}}$$

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