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Distributed State

- We want to have a consistent view of state across a distributed system
- Need some way for multiple "agents" to agree on such a state
- Made harder by the presence of failure:
 - **Byzantine faults:** machines can do the "wrong" thing
 - Paxos assumes non-Byzantine
 - Agents can stop or restart arbitrarily
 - Requires that some information is remembered "stable storage"
 - Messages have no upper bound on delivery time and can be dropped or duplicated
 - Paxos assumes that messages are not corrupted

Consensus Algorithm

Goal: A set of processes agree on a value

Safety:

- Only a value that has been proposed may be chosen
- Only a single value is chosen
- A process never learns that a value has been chosen unless it actually has been.

Liveness:

- Some value is eventually chosen
- If a value has been chosen, any process can eventually learn the value

Three Agent Classes



First Attempt: Single Acceptor



First Attempt: Single Acceptor



First Attempt: Single Acceptor







What goes wrong?



Second Attempt: Multiple Acceptors





Second Attempt: Multiple Acceptors





What goes wrong?

Δ 3



Phase 1

• Proposer sends PREPARE(n) to a majority of acceptors

If acceptor receives PREPARE(n) with *n* greater than any previous PREPARE requests, it responds PROMISE(n, p) indicating it will not accept any proposals <*n* and *p* is the highest-numbered proposal it has previously accepted

Phase 2

 If the proposer receives a response to its PREPARE(n) requests from a majority of acceptors, then it sends ACCEPT(n, v) to each acceptor, where n is the proposal number and v is the value of the highest-numbered proposal among the responses (or any value if none of the acceptors had previous proposals)

- If an acceptor receives an ACCEPT(n, v) request, it accepts the proposal unless it has already responded to a PREPARE request with a number greater than n
 - *chosen* only if a majority of acceptors accept











What happens if a proposer fails?

- 1. Before PREPARE
- 2. After PREPARE but before ACCEPT
- 3. After ACCEPT

What happens if an acceptor fails?

- 1. Before PREPARE
- 2. After PREPARE but before ACCEPT
- 3. After ACCEPT

Learners

- Each acceptor could send a message to each learner when it accepts a proposal
 - Requires |A| * |L| responses
- Each acceptor could send a message to a single learner when it accepts a proposal, who then informs the other learners when a value is chosen
 - Requires an extra round for all the learners to discover the chosen value
 - If the distinguished learner fails, the rest of the learners will not learn the message
 - Requires |A| + |L| responses
- Acceptors could send messages to a set of learners
- Learners could ask acceptors what proposal have been accepted
- Learners can have proposers issue a proposal to determine whether a value has already been chosen

Using Paxos to Implement a State Machine

- The server is a deterministic state machine
- Clients can issue commands
- An implementation with a single central server would fail if that server ever failed, so use a collection of servers that independently implement the state machine
- All the servers will produce the same sequences of states/outputs if they execute the same sequence of commands, so we just need to guarantee that the servers all agree on the command sequence
- Use Paxos repeatedly to choose the next command to execute
 - i.e. 1 Paxos instance per command "slot"
- Each server is a proposer, acceptor, and learner
- Usually elect a single leader for efficiency, but it is not strictly required for safety

Progress in Paxos

- Everything before this guarantees safety
- But it doesn't guarantee progress:
 - Two proposers could have an interleaving where they keep proposing higher numbers
- How do we fix this?
 - Can use a *distinguished proposer* this is the only proposer that tries to make proposals.
 - Need an election process to determine this distinguished proposer
 - In their implementation, same process is the *distinguished proposer* and *distinguished learner*.













Raft



Chain Replication

- Queries go straight to the tail, updates to the head
- *master* detects failures and updates configurations
 - Actually implemented via Paxos
- Assumes fail-stop

What does this do well? What does this not do well?



Fault-Tolerant Virtual Machines

- If a VM fails, we want to be able to transition to a backup without the client noticing
- How might we keep a backup up to date?

Two possibilities:

- Send all state (CPU, memory, etc.) to backup too much bandwidth!
- Send only input requests
 - But then must deal with non-deterministic operations
 - ...but this can be dealt with via the hypervisor

- Less than 10% overhead and less than 20 Mb/s bandwidth required
- Limited to uniprocessors

SMART

- **Byzantine Fault Tolerant State Machine Replication** (BFT SMR): state system that can tolerate Byzantine faults
- SMART: Java implementation, can prevent non-malicious Byzantine faults
 - Corrupted messages, abnormal processes
- Three steps:



- PROPOSE proposes a batch of requests
- WRITE and ACCEPT use cryptographic hash of batch
- When certain faults occur, begins *synchronization phase* (leader election, state transfer, etc.)

SMART (cont.)

- Can enable "crash fault-tolerant" (CFT) mode
 - No longer protects against Byzantine faults
 - Removes the *WRITE* step from before



 BFT mode increases latency, but less than you might think

2 Phase Commit

- Coordinator and cohorts
- First Phase:
 - Coordinator sends "prepare" message to each cohort
 - Cohorts respond with either "commit-vote" or "abort-vote"
- Second Phase:
 - If all cohorts responded with "commit-vote", the coordinator sends "commit". If any cohorts responded with "abort-vote", the coordinator sends "abort"
 - Cohorts respond with acknowledgement
- Blocking protocol: low availability, no progress if a cohort is down