

Case Study 1: Estimating Click Probabilities

Intro Logistic Regression Gradient Descent + SGD

Machine Learning for Big Data
CSE547/STAT548, University of Washington

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Announcements:

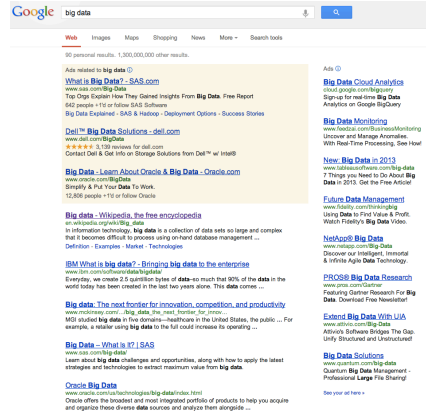
- **Lecture 2 cancelled**
 - **TAs will hold a python recitation**
- HW1 posted today.
- Readings: please do them.
- Project Proposals: please start thinking about it!

- Today:
 - Review: click prediction and logistic regression

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Ad Placement Strategies

- Companies bid on ad prices
- Which ad wins? (many simplifications here)
 - Naively:
 - But:
 - Instead:



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Key Task: Estimating Click Probabilities

- What is the probability that user i will click on ad j
- Not important just for ads:
 - Optimize search results
 - Suggest news articles
 - Recommend products
- Methods much more general, useful for:
 - Classification
 - Regression
 - Density estimation

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Learning Problem for Click Prediction

- Prediction task:
- Features:
- Data:
 - Batch:
 - Online:
- Many approaches (e.g., logistic regression, SVMs, naïve Bayes, decision trees, boosting,...)
 - Focus on logistic regression; captures main concepts, ideas generalize to other approaches

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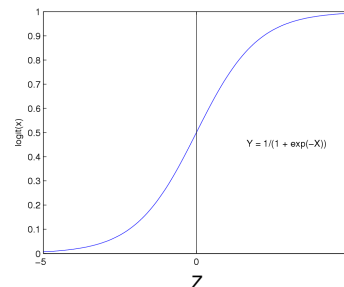
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Logistic Regression

- Learn $P(Y|X)$ directly
 - Assume a particular functional form
 - Sigmoid applied to a linear function of the data:

$$P(Y = 0|X, W) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

Logistic function (or Sigmoid): $\frac{1}{1 + \exp(-z)}$



Features can be discrete or continuous!

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Very convenient!

$$P(Y = 0 | X = \langle X_1, \dots, X_n \rangle) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

implies

$$\ln \frac{P(Y = 1 | X)}{P(Y = 0 | X)} = w_0 + \sum_i w_i X_i$$

linear
classification
rule!

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Digression: Logistic regression more generally

- Logistic regression in more general case, where Y in $\{y_1, \dots, y_R\}$

for $k < R$

$$P(Y = y_k | X) = \frac{\exp(w_{k0} + \sum_{i=1}^n w_{ki} X_i)}{1 + \sum_{j=1}^{R-1} \exp(w_{j0} + \sum_{i=1}^n w_{ji} X_i)}$$

for $k=R$ (normalization, so no weights for this class)

$$P(Y = y_R | X) = \frac{1}{1 + \sum_{j=1}^{R-1} \exp(w_{j0} + \sum_{i=1}^n w_{ji} X_i)}$$

Features can be discrete or continuous!

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Loss function: Conditional Likelihood

- Have a bunch of iid data of the form:
- Discriminative (logistic regression) loss function:
Conditional Data Likelihood

$$\ln P(\mathcal{D}_Y | \mathcal{D}_X, \mathbf{w}) = \sum_{j=1}^N \ln P(y^j | \mathbf{x}^j, \mathbf{w})$$

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Expressing Conditional Log Likelihood

$$\ell(\mathbf{w}) \equiv \sum_j \ln P(y^j | \mathbf{x}^j, \mathbf{w})$$

$$P(Y = 0 | \mathbf{X}, \mathbf{w}) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$
$$P(Y = 1 | \mathbf{X}, \mathbf{w}) = \frac{\exp(w_0 + \sum_i w_i X_i)}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

$$\begin{aligned} \ell(\mathbf{w}) &= \sum_j y^j \ln P(Y = 1 | \mathbf{x}^j, \mathbf{w}) + (1 - y^j) \ln P(Y = 0 | \mathbf{x}^j, \mathbf{w}) \\ &= \sum_j y^j (w_0 + \sum_{i=1}^d w_i x_i^j) - \ln \left(1 + \exp(w_0 + \sum_{i=1}^d w_i x_i^j) \right) \end{aligned}$$

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Maximizing Conditional Log Likelihood

$$l(\mathbf{w}) \equiv \ln \prod_j P(y^j | \mathbf{x}^j, \mathbf{w})$$

$$= \sum_j y^j (w_0 + \sum_{i=1}^d w_i x_i^j) - \ln \left(1 + \exp(w_0 + \sum_{i=1}^d w_i x_i^j) \right)$$

Good news: $l(\mathbf{w})$ is concave function of \mathbf{w} ,
no local optima problems

Bad news: no closed-form solution to maximize $l(\mathbf{w})$

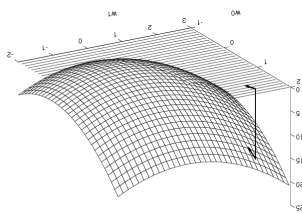
Good news: concave functions easy to optimize

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Optimizing concave function – Gradient ascent

- Conditional likelihood for logistic regression is *concave*
- Find optimum with *gradient ascent*



Gradient: $\nabla_{\mathbf{w}} l(\mathbf{w}) = \left[\frac{\partial l(\mathbf{w})}{\partial w_0}, \dots, \frac{\partial l(\mathbf{w})}{\partial w_n} \right]^T$

Update rule: $\Delta \mathbf{w} = \eta \nabla_{\mathbf{w}} l(\mathbf{w})$

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \frac{\partial l(\mathbf{w})}{\partial w_i}$$

Step size, $\eta=0$

- Gradient ascent is simplest of optimization approaches
 - e.g., Conjugate gradient ascent much better (see reading)

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Gradient Ascent for LR

Gradient ascent algorithm: iterate until change $< \epsilon$

$$w_0^{(t+1)} \leftarrow w_0^{(t)} + \eta \sum_j [y^j - \hat{P}(Y^j = 1 | \mathbf{x}^j, \mathbf{w}^{(t)})]$$

For $i = 1, \dots, d$,

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \sum_j x_i^j [y^j - \hat{P}(Y^j = 1 | \mathbf{x}^j, \mathbf{w}^{(t)})]$$

repeat

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Regularized Conditional Log Likelihood

- If data are linearly separable, weights go to infinity
- Leads to overfitting \rightarrow Penalize large weights
- Add regularization penalty, e.g., L_2 :

$$\ell(\mathbf{w}) = \ln \prod_j P(y^j | \mathbf{x}^j, \mathbf{w}) - \frac{\lambda}{2} \|\mathbf{w}\|_2^2$$

- Practical note about w_0 :

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Standard v. Regularized Updates

- Maximum conditional likelihood estimate

$$\mathbf{w}^* = \arg \max_{\mathbf{w}} \ln \left[\prod_{j=1}^N P(y^j | \mathbf{x}^j, \mathbf{w}) \right]$$

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \sum_j x_i^j [y^j - \hat{P}(Y^j = 1 | \mathbf{x}^j, \mathbf{w})]$$

- Regularized maximum conditional likelihood estimate

$$\mathbf{w}^* = \arg \max_{\mathbf{w}} \ln \left[\prod_j P(y^j | \mathbf{x}^j, \mathbf{w}) \right] - \frac{\lambda}{2} \sum_{i>0} w_i^2$$

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \left\{ -\lambda w_i^{(t)} + \sum_j x_i^j [y^j - \hat{P}(Y^j = 1 | \mathbf{x}^j, \mathbf{w}^{(t)})] \right\}$$

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Stopping criterion

$$\ell(\mathbf{w}) = \ln \prod_j P(y^j | \mathbf{x}^j, \mathbf{w}) - \frac{\lambda}{2} \|\mathbf{w}\|_2^2$$

- Regularized logistic regression is strongly concave
 - Negative second derivative bounded away from zero:

- Strong concavity (convexity) is super helpful!!
- For example, for strongly concave $\ell(\mathbf{w})$:

$$\ell(\mathbf{w}^*) - \ell(\mathbf{w}) \leq \frac{1}{2\lambda} \|\nabla \ell(\mathbf{w})\|_2^2$$

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Convergence rates for gradient descent/ascent

- Number of iterations to get to accuracy

$$\ell(\mathbf{w}^*) - \ell(\mathbf{w}) \leq \epsilon$$

- If func $\ell(\mathbf{w})$ Lipschitz: $O(1/\epsilon^2)$
- If gradient of func Lipschitz: $O(1/\epsilon)$
- If func is strongly convex: $O(\ln(1/\epsilon))$

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Challenge 1: Complexity of computing gradients

- What's the cost of a gradient update step for LR???

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \left\{ -\lambda w_i^{(t)} + \sum_j x_i^j [y^j - \hat{P}(Y^j = 1 | \mathbf{x}^j, \mathbf{w}^{(t)})] \right\}$$

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Challenge 2: Data is streaming

- Assumption thus far: **Batch data**
- But, click prediction is a streaming data task:
 - User enters query, and ad must be selected:
 - Observe \mathbf{x}^j , and must predict y^j
 - User either clicks or doesn't click on ad:
 - Label y^j is revealed afterwards
 - Google gets a reward if user clicks on ad
 - Weights must be updated for next time:

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Learning Problems as Expectations

- Minimizing loss in training data:
 - Given dataset:
 - Sampled iid from some distribution $p(\mathbf{x})$ on features:
 - Loss function, e.g., hinge loss, logistic loss,...
 - We often minimize loss in training data:

$$\ell_{\mathcal{D}}(\mathbf{w}) = \frac{1}{N} \sum_{j=1}^N \ell(\mathbf{w}, \mathbf{x}^j)$$

- However, we should really minimize expected loss on all data:

$$\ell(\mathbf{w}) = E_{\mathbf{x}} [\ell(\mathbf{w}, \mathbf{x})] = \int p(\mathbf{x}) \ell(\mathbf{w}, \mathbf{x}) d\mathbf{x}$$

- So, we are approximating the integral by the average on the training data

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Gradient Ascent in Terms of Expectations

- “True” objective function:

$$\ell(\mathbf{w}) = E_{\mathbf{x}} [\ell(\mathbf{w}, \mathbf{x})] = \int p(\mathbf{x}) \ell(\mathbf{w}, \mathbf{x}) d\mathbf{x}$$

- Taking the gradient:
- “True” gradient ascent rule:
- How do we estimate expected gradient?

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SGD: Stochastic Gradient Ascent (or Descent)

- “True” gradient: $\nabla \ell(\mathbf{w}) = E_{\mathbf{x}} [\nabla \ell(\mathbf{w}, \mathbf{x})]$
- Sample based approximation:
- What if we estimate gradient with just one sample???
 - Unbiased estimate of gradient
 - Very noisy!
 - Called stochastic gradient ascent (or descent)
 - Among many other names
 - VERY useful in practice!!!

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Stochastic Gradient Ascent: General Case

- Given a stochastic function of parameters:
 - Want to find maximum
- Start from $\mathbf{w}^{(0)}$
- Repeat until convergence:
 - Get a sample data point \mathbf{x}^t
 - Update parameters:
- Works in the online learning setting!
- Complexity of each gradient step is constant in number of examples!
- In general, step size changes with iterations

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Stochastic Gradient Ascent for Logistic Regression

- Logistic loss as a stochastic function:

$$E_{\mathbf{x}} [\ell(\mathbf{w}, \mathbf{x})] = E_{\mathbf{x}} \left[\ln P(y|\mathbf{x}, \mathbf{w}) - \frac{\lambda}{2} \|\mathbf{w}\|_2^2 \right]$$

- Batch gradient ascent updates:

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \left\{ -\lambda w_i^{(t)} + \frac{1}{N} \sum_{j=1}^N x_i^{(j)} [y^{(j)} - P(Y = 1 | \mathbf{x}^{(j)}, \mathbf{w}^{(t)})] \right\}$$

- Stochastic gradient ascent updates:

- Online setting:

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta_t \left\{ -\lambda w_i^{(t)} + x_i^{(t)} [y^{(t)} - P(Y = 1 | \mathbf{x}^{(t)}, \mathbf{w}^{(t)})] \right\}$$

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Convergence Rate of SGD

- **Theorem:**
 - (see Nemirovski et al '09 from readings)
 - Let f be a strongly convex stochastic function
 - Assume gradient of f is Lipschitz continuous and bounded

 - Then, for step sizes:

 - The expected loss decreases as $O(1/t)$:

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Convergence Rates for Gradient Descent/Ascent vs. SGD

- Number of Iterations to get to accuracy
$$\ell(\mathbf{w}^*) - \ell(\mathbf{w}) \leq \epsilon$$
- Gradient descent:
 - If func is strongly convex: $O(\ln(1/\epsilon))$ iterations
- Stochastic gradient descent:
 - If func is strongly convex: $O(1/\epsilon)$ iterations
- Seems exponentially worse, but much more subtle:
 - Total running time, e.g., for logistic regression:
 - Gradient descent:
 - SGD:
 - SGD can win when we have a lot of data
 - See readings for more details

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What you should know about Logistic Regression (LR) and Click Prediction

- Click prediction problem:
 - Estimate probability of clicking
 - Can be modeled as logistic regression
- Logistic regression model: Linear model
- Gradient ascent to optimize conditional likelihood
- Overfitting + regularization
- Regularized optimization
 - Convergence rates and stopping criterion
- Stochastic gradient ascent for large/streaming data
 - Convergence rates of SGD