Natural Language Processing (CSE 517): Featurized Language Models

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Quick Review

A language model is a probability distribution over \mathcal{V}^{\dagger} .

Typically p decomposes into probabilities $p(x_i | h_i)$.

- n-gram: h_i is (n-1) previous symbols
- ► class-based: further decomposition $p(x_i | cl(x_i)) \cdot p(cl(x_i) | h_i)$
 - previous (n 1) symbols' *classes* predict class of x_i
 - class of x_i predicts x_i
- Probabilities are estimated from data.

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 - Why?

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Today: log-linear language models

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Central idea today: teach histories and words how to share.

Log-Linear Models: Definitions

We define a conditional log-linear model $p(Y \mid X)$ as:

- \mathcal{Y} is the set of events (\odot for language modeling, \mathcal{V})
- ▶ \mathcal{X} is the set of contexts (\odot for n-gram language modeling, \mathcal{V}^{n-1})
- $\boldsymbol{\phi}: \mathcal{X} imes \mathcal{Y}
 ightarrow \mathbb{R}^d$ is a feature vector function
- $\mathbf{w} \in \mathbb{R}^d$ are the model parameters

$$p_{\mathbf{w}}(Y = y \mid X = x) = \frac{\exp \mathbf{w} \cdot \boldsymbol{\phi}(x, y)}{\sum_{y' \in \mathcal{Y}} \exp \mathbf{w} \cdot \boldsymbol{\phi}(x, y')}$$

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"Log-linear" comes from the fact that:

$$\log p_{\mathbf{w}}(Y = y \mid X = x) = \mathbf{w} \cdot \boldsymbol{\phi}(x, y) - \underbrace{Z_{\mathbf{w}}(x)}_{\text{constant in } y}$$

This is an instance of the family of generalized linear models.

Consider the case where $\mathcal{Y} = \{+1, -1\}$.

$$p_{\mathbf{w}}(Y = +1 \mid x) = \frac{\exp \mathbf{w} \cdot \boldsymbol{\phi}(x, +1)}{\exp \mathbf{w} \cdot \boldsymbol{\phi}(x, +1) + \exp \mathbf{w} \cdot \boldsymbol{\phi}(x, -1)}$$

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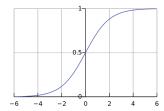
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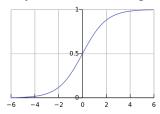
Should be familiar, if you know about logistic regression.



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When 𝔅 = {1, 2, ..., k}, log-linear models are often called multinomial logistic regression.

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Special Case: n-Gram Language Model

Consider an n-gram language model, where $\mathcal{X} = \mathcal{V}^{n-1}$ and $\mathcal{Y} = \mathcal{V}$. Let:

• d = 1• $\phi_1(\mathbf{h}, v) = \log c(\mathbf{h}v)$ • $w_1 = 1$ • $Z(\mathbf{h}) = \sum_{v' \in \mathcal{V}} \exp \log c(\mathbf{h}v') = \sum_{v' \in \mathcal{V}} c(\mathbf{h}v') = c(\mathbf{h})$

Special Case: n-Gram Language Model

Consider an n-gram language model, where $\mathcal{X} = \mathcal{V}^{n-1}$ and $\mathcal{Y} = \mathcal{V}$. Let:

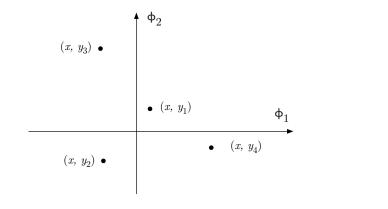
- ► *d* = 1
- $\phi_1(\boldsymbol{h}, v) = \log c(\boldsymbol{h}v)$
- ▶ $w_1 = 1$

$$\blacktriangleright Z(h) = \sum_{v' \in \mathcal{V}} \exp \log c(hv') = \sum_{v' \in \mathcal{V}} c(hv') = c(h)$$

Alternately:

$$\begin{array}{l} \bullet \quad d = |\mathcal{V}|^{\mathsf{n}} \\ \bullet \quad \phi_{\tilde{\boldsymbol{h}}, \tilde{v}}(\boldsymbol{h}, v) = \begin{cases} 1 & \text{if } \boldsymbol{h} = \tilde{\boldsymbol{h}} \wedge v = \tilde{v} \\ 0 & \text{otherwise} \end{cases} \\ \bullet \quad w_{\tilde{\boldsymbol{h}}, \tilde{v}} = \log \frac{c(\tilde{\boldsymbol{h}}\tilde{v})}{c(\tilde{\boldsymbol{h}})} \\ \bullet \quad Z(\boldsymbol{h}) = 1 \end{cases}$$

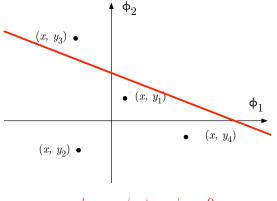
Suppose we have instance x, $\mathcal{Y} = \{y_1, y_2, y_3, y_4\}$, and there are only two features, ϕ_1 and ϕ_2 .



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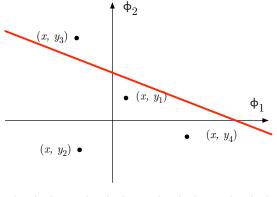
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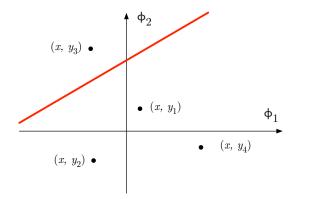
 $\mathbf{w} \cdot \boldsymbol{\phi} = w_1 \phi_1 + w_2 \phi_2 = 0$

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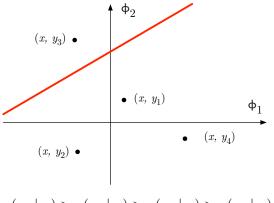


 $p(y_3 \mid x) > p(y_1 \mid x) > p(y_4 \mid x) > p(y_2 \mid x)$

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Why Build Language Models This Way?

- Exploit features of histories for sharing of statistical strength and better smoothing (Lau et al., 1993)
- Condition the whole text on more interesting things (Eisenstein et al., 2011)
- Interpretability!
 - ► Each feature φ_k controls a factor to the probability (e^{w_k}); w_k is the *ceteris parebis* log-odds.

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- If $w_k < 0$ then ϕ_k makes the event less likely.
- If $w_k > 0$ then ϕ_k makes the event more likely.
- If $w_k = 0$ then ϕ_k has no effect.

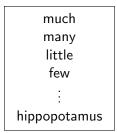
Log-Linear n-Gram Models

$$p_{\mathbf{w}}(\mathbf{X} = \mathbf{x}) = \prod_{j=1}^{\ell} p_{\mathbf{w}}(X_j = x_j \mid \mathbf{X}_{1:j-1} = \mathbf{x}_{1:j-1})$$
$$= \prod_{j=1}^{\ell} \frac{\exp \mathbf{w} \cdot \boldsymbol{\phi}(\mathbf{x}_{1:j-1}, x_j)}{Z_{\mathbf{w}}(\mathbf{x}_{1:j-1})}$$
$$\xrightarrow{\text{assumption}} \prod_{j=1}^{\ell} \frac{\exp \mathbf{w} \cdot \boldsymbol{\phi}(\mathbf{x}_{j-n+1:j-1}, x_j)}{Z_{\mathbf{w}}(\mathbf{x}_{j-n+1:j-1})}$$
$$= \prod_{j=1}^{\ell} \frac{\exp \mathbf{w} \cdot \boldsymbol{\phi}(\mathbf{h}_j, x_j)}{Z_{\mathbf{w}}(\mathbf{h}_j)}$$

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Example

The man who knew too



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► Too few (good) features, and your model will not learn ☺

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- \blacktriangleright Too many features, and your model will overfit \circledast
 - "Feature selection" methods, e.g., ignoring features with very low counts, can help.
- ► Too few (good) features, and your model will not learn ☺

"Feature Engineering"

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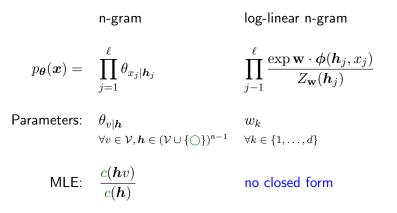
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 - Some people would rather not spend their time on it!
- There is some work on automatically inducing features (Della Pietra et al., 1997).
- More recent work in neural networks can be seen as discovering features (instead of engineering them).
- But in NLP, there's a strong preference for *interpretable* features.

How to Estimate w?



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- ► This is *concave* in **w**.
- $Z_{\mathbf{w}}(\mathbf{h}_i)$ involves a sum over V terms.
 - ▶ Neat trick (Goodman, 2001): class-based model!

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Hope/fear view: for each instance i,

- increase the score of the correct output x_i , $score(x_i) = \mathbf{w} \cdot \phi(\mathbf{h}_i, x_i)$
- ▶ decrease the "average" score overall, $\log \sum_{v \in \mathcal{V}} \exp score(v)$

$$\max_{\mathbf{w} \in \mathbb{R}^d} \sum_{i=1}^N \mathbf{w} \cdot \phi(\boldsymbol{h}_i, x_i) - \log Z_{\mathbf{w}}(\boldsymbol{h}_i)$$

Gradient view:

$$\sum_{i=1}^{N} \phi(\boldsymbol{h}_{i}, x_{i}) - \mathbb{E}_{p_{\mathbf{w}}(X|\boldsymbol{h}_{i})}[\phi(\boldsymbol{h}_{i}, X)]$$

Setting this to zero means getting model's expectations to match empirical expectations.

MLE for \mathbf{w} : Algorithms

- Batch methods (L-BFGS is popular)
- Stochastic gradient descent more common today, especially with special tricks for adapting the step size over time
- Many specialized methods (e.g., "iterative scaling")

Maximum likelihood estimation:

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If φ_j(h, x) is (almost) always positive, we can always increase the objective (a little bit) by increasing w_j toward +∞.

Avoiding Overfitting

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 If φ_j(h, x) is (almost) always positive, we can always increase the objective (a little bit) by increasing w_j toward +∞.
 Standard solution is to add a regularization term:

$$\max_{\mathbf{w} \in \mathbb{R}^d} \sum_{i=1}^N \mathbf{w} \cdot \boldsymbol{\phi}(\boldsymbol{h}_i, x_i) - \log \sum_{v \in \mathcal{V}} \exp \mathbf{w} \cdot \boldsymbol{\phi}(\boldsymbol{h}_i, v) - \lambda \|\mathbf{w}\|_p^p$$

where $\lambda > 0$ is a hyperparameter and p = 2 or 1.

This case warrants a little more discussion:

$$\max_{\mathbf{w} \in \mathbb{R}^d} \sum_{i=1}^N \mathbf{w} \cdot \boldsymbol{\phi}(\boldsymbol{h}_i, x_i) - \log \sum_{v \in \mathcal{V}} \exp \mathbf{w} \cdot \boldsymbol{\phi}(\boldsymbol{h}_i, v) - \lambda \|\mathbf{w}\|_1$$

Note that:

$$\|\mathbf{w}\|_1 = \sum_{j=1}^d |w_j|$$

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 - Many have argued that this is a good thing (Tibshirani, 1996); it's a kind of feature selection.
 - Do not confuse it with data sparseness (a problem to be overcome)!
- This is not differentiable at $w_j = 0$.

This case warrants a little more discussion:

$$\max_{\mathbf{w} \in \mathbb{R}^d} \sum_{i=1}^N \mathbf{w} \cdot \boldsymbol{\phi}(\boldsymbol{h}_i, x_i) - \log \sum_{v \in \mathcal{V}} \exp \mathbf{w} \cdot \boldsymbol{\phi}(\boldsymbol{h}_i, v) - \lambda \|\mathbf{w}\|_1$$

$$\|\mathbf{w}\|_1 = \sum_{j=1}^d |w_j|$$

- This results in **sparsity** (i.e., many $w_j = 0$).
 - Many have argued that this is a good thing (Tibshirani, 1996); it's a kind of feature selection.
 - Do not confuse it with data sparseness (a problem to be overcome)!
- This is not differentiable at $w_j = 0$.
- Optimization: special solutions for batch (e.g., Andrew and Gao, 2007) and stochastic (e.g., Langford et al., 2009) settings.

If we had five more weeks, we'd study this problem more carefully!

Here's what you must remember:

- There is no closed form; you must use a numerical optimization algorithm.
- Log-linear models are powerful but expensive $(Z_{\mathbf{w}}(\mathbf{h}_i))$.
- ► Regularization is very important; we don't actually do MLE.
 - Just like for n-gram models! Only even more so, since log-linear models are even more expressive.

Maximum Entropy

Consider a distribution p over events in \mathcal{X} . The Shannon entropy (in bits) of p is defined as:

$$H(p) = -\sum_{x \in \mathcal{X}} p(X = x) \begin{cases} 0 & \text{if } p(X = x) = 0\\ \log_2 p(X = x) & \text{otherwise} \end{cases}$$

This is a measure of "randomness"; entropy is zero when p is deterministic and $\log |\mathcal{X}|$ when p is uniform.

Maximum entropy principle: among distributions that fit the data, pick the one with the greatest entropy.

Maximum Entropy

If "fit the data" is taken to mean

$$\forall k \in \{1, \ldots, d\}, \mathbb{E}_p[\phi_k] = \tilde{\mathbb{E}}[\phi_k]$$

then the MLE of the log-linear family with features ϕ is the maximum entropy solution.

This is why log-linear models are sometimes called "maxent" models (e.g., Berger et al., 1996)

"Whole Sentence" Log-Linear Models (Rosenfeld, 1994)

Instead of a log-linear model for each word-given-history, define a single log-linear model over event space \mathcal{V}^{\dagger} :

$$p_{\mathbf{w}}(\boldsymbol{x}) = \frac{\exp \boldsymbol{w} \cdot \boldsymbol{\phi}(\boldsymbol{x})}{Z_{\mathbf{w}}}$$

- Any feature of the sentence could be included in this model!
- Z_w is deceptively simple-looking!

$$Z_{\mathbf{w}} = \sum_{oldsymbol{x} \in \mathcal{V}^{\dagger}} \exp{\mathbf{w} \cdot oldsymbol{\phi}(oldsymbol{x})}$$

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Readings and Reminders

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