Types

Major new topic worthy of several lectures: Type systems

- Continue to use (CBV) Lambda Calculus as our core model
- But will soon enrich with other common primitives

This lecture:

- Motivation for type systems
- What a type system is designed to do and not do
  - Definition of stuckness, soundness, completeness, etc.
- The Simply-Typed Lambda Calculus
  - A basic and natural type system
  - Starting point for more expressiveness later

Next lecture:

- Prove Simply-Typed Lambda Calculus is sound
Review: L-R CBV Lambda Calculus

\[ e ::= \lambda x. e \mid x \mid e \ e \]
\[ v ::= \lambda x. e \]

Implicit systematic renaming of bound variables

- \( \alpha \)-equivalence on expressions (“the same term”)

\[
\begin{align*}
  e & \rightarrow e' \\
  (\lambda x. e) \ v & \rightarrow e[v/x] \\
  e_1 \ e_2 & \rightarrow e'_1 \ e_2 \\
  v \ e_2 & \rightarrow v \ e'_2
\end{align*}
\]

\[
\begin{align*}
  e_1[e_2/x] & = e_3 \\
  x[e/x] & = e \\
  y[e/x] & = y \\
  e_1[e/x] & = e'_1 \\
  e_2[e/x] & = e'_2 \\
  (e_1 \ e_2)[e/x] & = e'_1 \ e'_2 \quad y \neq x \quad y \not\in FV(e)
\end{align*}
\]

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  e_1[e/x] & = e'_1 \\
  y & \neq x \\
  y & \not\in FV(e)
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\[
(\lambda y. e_1)[e/x] = \lambda y. e'_1
\]
Introduction to Types

Naive thought: More powerful PLs are always better
  ▶ Be Turing Complete (e.g., Lambda Calculus or x86 Assembly)
  ▶ Have really flexible features (e.g., lambdas)
  ▶ Have conveniences to keep programs short

If this is the only metric, types are a step backward
  ▶ Whole point is to allow fewer programs
  ▶ A “filter” between abstract syntax and compiler/interpreter
    ▶ Fewer programs in language means less for a correct implementation
  ▶ So if types are a great idea, they must help with other desirable properties for a PL...
Why types? (Part 1)

1. Catch “simple” mistakes early, even for untested code
   ▶ Example: “if” applied to “mkpair”
   ▶ Even if some too-clever programmer meant to do it
   ▶ Even though decidable type systems must be conservative
Why types? (Part 1)

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2. (Safety) Prevent getting stuck (e.g., \( x \ v \))
   ▶ Ensure execution never gets to a “meaningless” state
   ▶ But “meaningless” depends on the semantics
   ▶ Each PL typically makes some things type errors (again being conservative) and others run-time errors
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3. Enforce encapsulation (an abstract type)
   - Clients can’t break invariants
   - Clients can’t assume an implementation
   - requires safety, meaning no “stuck” states that corrupt run-time (e.g., C/C++)
   - Can enforce encapsulation without static types, but types are a particularly nice way
4. Assuming well-typedness allows faster implementations
   ▶ Smaller interfaces enable optimizations
   ▶ Don’t have to check for impossible states
   ▶ Orthogonal to safety (e.g., C/C++)
Why types? (Part 2)

4. Assuming well-typedness allows faster implementations
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5. Syntactic overloading
   - Have symbol lookup depend on operands’ types
   - Only modestly interesting semantically
   - Late binding (lookup via run-time types) more interesting

We’ll focus on (1), (2), and (3) and maybe (6)
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6. Detect other errors via extensions
   - Often via a “type-and-effect” system
   - Deep similarities in analyses suggest type systems a good way to think-about/define/prove what you’re checking
   - Uncaught exceptions, tainted data, non-termination, IO performed, data races, dangling pointers, ...
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What is a type system?

Er, uh, you know it when you see it. Some clues:

▶ A decidable (?) judgment for classifying programs
  ▶ E.g., \( e_1 + e_2 \) has type int if \( e_1, e_2 \) have type int (else no type)

▶ A sound (?) abstraction of computation
  ▶ E.g., if \( e_1 + e_2 \) has type int, then evaluation produces an int (with caveats!)

▶ Fairly syntax directed
  ▶ Non-example (?): \( e \) terminates within 100 steps

▶ Particularly fuzzy distinctions with abstract interpretation
  ▶ Possible topic for a later lecture
  ▶ Often a more natural framework for flow-sensitive properties
  ▶ Types often more natural for higher-order programs

This is a CS-centric, PL-centric view. Foundational type theory has more rigorous answers

▶ Later lecture: Typed PLs are like proof systems for logics
Plan for 3ish weeks

- Simply typed $\lambda$ calculus
- (Syntactic) Type Soundness (i.e., safety)
- Extensions (pairs, sums, lists, recursion)

Break for the Curry-Howard isomorphism; continuations; midterm

- Subtyping
- Polymorphic types (generics)
- Recursive types
- Abstract types
- Effect systems

Homework: Adding back mutation
Omitted: Type inference
Adding constants

Enrich the Lambda Calculus with integer constants:

- Not strictly necessary, but makes types seem more natural

\[ e ::= \lambda x. \ e \mid x \mid e\ e \mid c \]
\[ v ::= \lambda x. \ e \mid c \]

No new operational-semantics rules since constants are values

We could add + and other primitives

- Then we would need new rules (e.g., 3 small-step for +)
- Alternately, parameterize “programs” by primitives:
  \[ \lambda plus. \ \lambda times. \ldots \ e \]
  - Like Pervasives in Caml
  - A great way to keep language definitions small
Stuck

Key issue: can a program “get stuck” (reach a “bad” state)?

- Definition: $e$ is stuck if $e$ is not a value and there is no $e'$ such that $e \rightarrow e'$

- Definition: $e$ can get stuck if there exists an $e'$ such that $e \rightarrow^* e'$ and $e'$ is stuck
  - In a deterministic language, $e$ “gets stuck”

Most people don’t appreciate that stuckness depends on the operational semantics

- Inherent given the definitions above
What’s stuck?

Given our language, what are the set of stuck expressions?

- Note: Explicitly defining the stuck states is unusual

\[
\begin{align*}
  e &::= \lambda x. e \mid x \mid e\ e \mid c \\
  v &::= \lambda x. e \mid c
\end{align*}
\]

\[
\begin{align*}
  (\lambda x. e) \ v &\rightarrow e[v/x] \\
  e_1 \rightarrow e'_1 \\
  e_2 \rightarrow e'_2 \\
  v \ e_2 &\rightarrow v \ e'_2
\end{align*}
\]

(Hint: The full set is recursively defined.)

\[
S ::= \]

Dan Grossman
CSE505 Winter 2012, Lecture 9
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\[ e ::= \lambda x. e \mid x \mid e \ e \mid c \]

\[ v ::= \lambda x. e \mid c \]

\[ (\lambda x. e) \ v \rightarrow e[v/x] \quad e_1 \rightarrow e'_1 \quad e_2 \rightarrow e'_2 \]

\[ e_1 \ e_2 \rightarrow e'_1 \ e_2 \quad v \ e_2 \rightarrow v \ e'_2 \]

(Hint: The full set is recursively defined.)

\[ S ::= x \mid c \ v \mid S \ e \mid v \ S \]
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\begin{align*}
  (\lambda x.\ e)\ v &\rightarrow e[v/x] & e_1 &\rightarrow e'_1 \\
  e_1\ e_2 &\rightarrow e'_1\ e_2 & e_2 &\rightarrow e'_2 \\
v\ e_2 &\rightarrow v\ e'_2
\end{align*}
\]

(Hint: The full set is recursively defined.)

\[
S ::= x \mid c\ v \mid S\ e \mid v\ S
\]

Note: Can have fewer stuck states if we add more rules

- Example: Javascript
- Example: ________
  \[
  c\ v \rightarrow v
  \]
- In unsafe languages, stuck states can set the computer on fire
Soundness and Completeness

A *type system* is a judgment for classifying programs

- “accepts” a program if some complete derivation gives it a type, else “rejects”

A *sound* type system never accepts a program that can get stuck

- No false negatives

A *complete* type system never rejects a program that can’t get stuck

- No false positives

It is typically *undecidable* whether a stuck state can be reachable

- Corollary: If we want an *algorithm* for deciding if a type system accepts a program, then the type system cannot be sound and complete

- We’ll choose soundness, try to reduce false positives in practice
Wrong Attempt

\[ \tau ::= \text{int} \mid \text{fn} \]

\[ \vdash e : \tau \]

\[ \vdash \lambda x. e : \text{fn} \quad \vdash c : \text{int} \quad \vdash e_1 : \text{fn} \quad \vdash e_2 : \text{int} \]

\[ \vdash e_1 \ e_2 : \text{int} \]

1. NO: can get stuck, e.g., \((\lambda x. y)\ 3\)
2. NO: too restrictive, e.g., \((\lambda x. x)\ 3\) \((\lambda y. y)\)
3. NO: types not preserved, e.g., \((\lambda x. \lambda y. y)\ 3\)
Wrong Attempt

\[ \tau ::= \text{int} \mid \text{fn} \]

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\[ \vdash e_1 e_2 : \text{int} \]

1. NO: can get stuck, e.g., \((\lambda x. y) 3\)

2. NO: too restrictive, e.g., \((\lambda x. x 3) (\lambda y. y)\)

3. NO: types not preserved, e.g., \((\lambda x. \lambda y. y) 3\)
Getting it right

1. Need to type-check function bodies, which have free variables
2. Need to classify functions using argument and result types

For (1): $\Gamma ::= \cdot \mid \Gamma, x : \tau$ and $\Gamma \vdash e : \tau$
   
   ▶ Require whole program to type-check under empty context $\cdot$

For (2): $\tau ::= \text{int} \mid \tau \rightarrow \tau$

   ▶ An infinite number of types:
      $\text{int} \rightarrow \text{int}, (\text{int} \rightarrow \text{int}) \rightarrow \text{int}, \text{int} \rightarrow (\text{int} \rightarrow \text{int}), \ldots$

Concrete syntax note: $\rightarrow$ is right-associative, so
$\tau_1 \rightarrow \tau_2 \rightarrow \tau_3$ is $\tau_1 \rightarrow (\tau_2 \rightarrow \tau_3)$
The function-introduction rule is the interesting one...
A closer look

\[
\Gamma, x : \tau_1 \vdash e : \tau_2 \\
\frac{}{\Gamma \vdash \lambda x. e : \tau_1 \rightarrow \tau_2}
\]

Where did \(\tau_1\) come from?

- Our rule “inferred” or “guessed” it
- To be syntax directed, change \(\lambda x. e\) to \(\lambda x : \tau. e\)
  and use that \(\tau\)

Can think of “adding \(x\)” as shadowing or requiring \(x \not\in \text{Dom}(\Gamma)\)

- Systematic renaming (\(\alpha\)-conversion) ensures \(x \not\in \text{Dom}(\Gamma)\) is not a problem
A closer look

\[
\frac{\Gamma, x : \tau_1 \vdash e : \tau_2}{\Gamma \vdash \lambda x. e : \tau_1 \rightarrow \tau_2}
\]

Is our type system too restrictive?

- That’s a matter of opinion
- But it does reject programs that don’t get stuck

Example: \((\lambda x. (x (\lambda y. y)) (x \ 3)) \ \lambda z. \ z\)

- Does not get stuck: Evaluates to 3
- Does not type-check:
  - There is no \(\tau_1, \tau_2\) such that \(x : \tau_1 \vdash (x (\lambda y. y)) (x \ 3) : \tau_2\)
  - because you have to pick one type for \(x\)
Always restrictive

Whether or not a program “gets stuck” is undecidable:

▶ If $e$ has no constants or free variables, then $e \ (3 \ 4)$ or $e \ x$ gets stuck if and only if $e$ terminates (cf. the halting problem)

Old conclusion: “Strong types for weak minds”

▶ Need a back door (unchecked casts)

Modern conclusion: Unsafe constructs almost never worth the risk

▶ Make “false positives” (rejecting safe program) rare enough
  ▶ Have compile-time resources for “fancy” type systems
▶ Make workarounds for false positives convenient enough
How does STLC measure up?

So far, STLC is sound:

- As language dictators, we decided \( c \) and undefined variables were “bad” meaning neither values nor reducible.
- Our type system is a conservative checker that an expression will never get stuck.

But STLC is far too restrictive:

- In practice, just too often that it prevents safe and natural code reuse.
- More fundamentally, it’s not even Turing-complete.
  - Turns out all (well-typed) programs terminate.
  - A good-to-know and useful property, but inappropriate for a general-purpose PL.
- That’s okay: We will add more constructs and typing rules.
Type Soundness

We will take a *syntactic* (operational) approach to soundness/safety

- The popular way since the early 1990s

**Theorem (Type Safety):** If $\cdot \vdash e : \tau$ then $e$ diverges or $e \rightarrow^n v$ for an $n$ and $v$ such that $\cdot \vdash v : \tau$

- That is, if $\cdot \vdash e : \tau$, then $e$ cannot get stuck

Proof: Next lecture