

CSE 505: Concepts of Programming Languages

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Fall 2009

Lecture 10— Curry-Howard Isomorphism; Evaluation Contexts

Outline

A couple left-over topics from last lecture:

- Sums in “real” programming languages
- A fuller explanation of why it’s called fix

Two totally different topics:

- Curry-Howard Isomorphism
 - Types are propositions
 - Programs are proofs
- Evaluation contexts, explicit stacks, and first-class continuations

Recall sums

$$e ::= \dots \mid \mathbf{A}(e) \mid \mathbf{B}(e) \mid \text{match } e \text{ with } \mathbf{A}x. e \mid \mathbf{B}x. e$$

$$v ::= \dots \mid \mathbf{A}(v) \mid \mathbf{B}(v)$$

$$\tau ::= \dots \mid \tau_1 + \tau_2$$

$$\frac{}{\text{match } \mathbf{A}(v) \text{ with } \mathbf{A}x. e_1 \mid \mathbf{B}y. e_2 \rightarrow e_1[v/x]}$$

$$\frac{}{\text{match } \mathbf{B}(v) \text{ with } \mathbf{A}x. e_1 \mid \mathbf{B}y. e_2 \rightarrow e_2[v/y]}$$

$$\frac{e \rightarrow e'}{\mathbf{A}(e) \rightarrow \mathbf{A}(e')} \qquad \frac{e \rightarrow e'}{\mathbf{B}(e) \rightarrow \mathbf{B}(e')}$$

$$e \rightarrow e'$$

$$\frac{}{\text{match } e \text{ with } \mathbf{A}x. e_1 \mid \mathbf{B}y. e_2 \rightarrow \text{match } e' \text{ with } \mathbf{A}x. e_1 \mid \mathbf{B}y. e_2}$$

$$\frac{\Gamma \vdash e : \tau_1}{\Gamma \vdash \mathbf{A}(e) : \tau_1 + \tau_2} \qquad \frac{\Gamma \vdash e : \tau_2}{\Gamma \vdash \mathbf{B}(e) : \tau_1 + \tau_2}$$

$$\frac{\Gamma \vdash e : \tau_1 + \tau_2 \quad \Gamma, x:\tau_1 \vdash e_1 : \tau \quad \Gamma, y:\tau_2 \vdash e_2 : \tau}{\Gamma \vdash \text{match } e \text{ with } \mathbf{A}x. e_1 \mid \mathbf{B}y. e_2 : \tau}$$

What are sums for?

- Pairs, structs, records, aggregates are fundamental data-builders
- Sums are just as fundamental: “this or that not both”
- You have seen how Caml does sums (datatypes)
- Worth showing how C and Java do the same thing
 - A primitive in one language is an idiom in another

Sums in C

```
type t = A of t1 | B of t2 | C of t3  
match e with A x -> ...
```

One way in C:

```
struct t {  
    enum {A, B, C}          tag;  
    union {t1 a; t2 b; t3 c;} data;  
};  
... switch(e->tag){ case A: t1 x=e->data.a; ...
```

- No static checking that tag is obeyed
- As fat as the fattest variant (avoidable with casts)
 - Mutation costs us again!
- Shameless plug: Cyclone has ML-style datatypes

Sums in Java

```
type t = A of t1 | B of t2 | C of t3  
match e with A x -> ...
```

One way in Java (t4 is the match-expression's type):

```
abstract class t {abstract t4 m();}  
class A extends t { t1 x; t4 m(){...}}  
class B extends t { t2 x; t4 m(){...}}  
class C extends t { t3 x; t4 m(){...}}  
... e.m() ...
```

- A new method for each match expression
- Supports extensibility via new variants (subclasses) instead of extensibility via new operations (match expressions)

Recall Fix

Note: Like `let` `rec` but using a λ to bind the name

$e ::= \dots \mid \mathbf{fix} \ e$

$$\frac{e \rightarrow e'}{\mathbf{fix} \ e \rightarrow \mathbf{fix} \ e'}$$

$$\frac{}{\mathbf{fix} \ \lambda x. \ e \rightarrow e[\mathbf{fix} \ \lambda x. \ e/x]}$$

$$\frac{\Gamma \vdash e : \tau \rightarrow \tau}{\Gamma \vdash \mathbf{fix} \ e : \tau}$$

Factorial example:

$\mathbf{fix} \ \lambda f. \ \lambda n. \ \mathbf{if} \ n < 1 \ \mathbf{then} \ 1 \ \mathbf{else} \ n * (f(n - 1))$

- Operationally, substitution unrolls the recursion one level
- For type system, $\lambda f. \ \lambda n. \ \mathbf{if} \ n < 1 \ \mathbf{then} \ 1 \ \mathbf{else} \ n * (f(n - 1))$ has type $(\mathbf{int} \rightarrow \mathbf{int}) \rightarrow (\mathbf{int} \rightarrow \mathbf{int})$.

Why called fix?

My slide in the last lecture could have explained fix-points much better...

In math, the fix-point of a function g is an x such that $g(x) = x$.

- This makes sense only if g has type $\tau \rightarrow \tau$ for some τ .
- A particular g could have have 0, 1, 39, or infinity fix-points
- Examples for functions of type **int** \rightarrow **int**:
 - $\lambda x. x + 1$ has no fix-points
 - $\lambda x. x * 0$ has one fix-point
 - $\lambda x. \text{absolute_value}(x)$ has an infinite number of fix-points
 - $\lambda x. \text{if } x < 10 \ \&\& \ x > 0 \ \text{then } x \ \text{else } 0$ has 10 fix-points

Higher types

At higher types like $(\mathbf{int} \rightarrow \mathbf{int}) \rightarrow (\mathbf{int} \rightarrow \mathbf{int})$, the notion of fix-point is exactly the same (but harder to think about)

- For what inputs f of type $\mathbf{int} \rightarrow \mathbf{int}$ is $g(f) = f$.

Examples:

- $\lambda f. \lambda x. (f\ x) + 1$ has no fix-points
- $\lambda f. \lambda x. (f\ x) * 0$ (or just $\lambda f. \lambda x. 0$) has 1 fix-point
 - The function that always returns 0
 - In math, there is exactly one such function (cf. equivalence)
- $\lambda f. \lambda x. \text{absolute_value}(f\ x)$ has an infinite number of fix-points:
Any function that never returns a negative result

Back to factorial

Now, what are the fix-points of

$\lambda f. \lambda x. \text{if } x < 1 \text{ then } 1 \text{ else } x * (f(x - 1))?$

It turns out there is exactly one (in math): the factorial function!

And **fix** $\lambda f. \lambda x. \text{if } x < 1 \text{ then } 1 \text{ else } x * (f(x - 1))$ behaves just like the factorial function, i.e., it behaves just like the fix-point of $\lambda f. \lambda x. \text{if } x < 1 \text{ then } 1 \text{ else } x * (f(x - 1))$.

(This isn't really important, but I like explaining terminology and showing that programming is deeply connected to mathematics.)

Curry-Howard Isomorphism

What we did:

- Define a programming language
- Define a type system to rule out programs we don't want

What logicians do:

- Define a logic (a way to state propositions)
 - Example: Propositional logic $p ::= b \mid p \wedge p \mid p \vee p \mid p \rightarrow p$
- Define a proof system (a way to prove propositions)

But it turns out we did that too!

Slogans:

- “Propositions are Types”
- “Proofs are Programs”

A slight variant

Let's take the explicitly typed ST λ C with base types b_1, b_2, \dots ,
no constants, pairs, and sums

$$\begin{aligned} e & ::= x \mid \lambda x. e \mid e e \\ & \mid (e, e) \mid e.1 \mid e.2 \\ & \mid \mathbf{A}(e) \mid \mathbf{B}(e) \mid \mathbf{match} \ e \ \mathbf{with} \ \mathbf{Ax}. e \mid \mathbf{Bx}. e \\ \tau & ::= b \mid \tau \rightarrow \tau \mid \tau * \tau \mid \tau + \tau \end{aligned}$$

Even without constants, plenty of terms type-check with $\Gamma = \cdot \dots$

Example programs

$\lambda x:b_{17}. x$

has type

$b_{17} \rightarrow b_{17}$

Example programs

$\lambda x:b_1. \lambda f:b_1 \rightarrow b_2. f x$

has type

$b_1 \rightarrow (b_1 \rightarrow b_2) \rightarrow b_2$

Example programs

$\lambda x:b_1 \rightarrow b_2 \rightarrow b_3. \lambda y:b_2. \lambda z:b_1. x z y$

has type

$(b_1 \rightarrow b_2 \rightarrow b_3) \rightarrow b_2 \rightarrow b_1 \rightarrow b_3$

Example programs

$\lambda x:b_1. (\mathbf{A}(x), \mathbf{A}(x))$

has type

$b_1 \rightarrow ((b_1 + b_7) * (b_1 + b_4))$

Example programs

$\lambda f:b_1 \rightarrow b_3. \lambda g:b_2 \rightarrow b_3. \lambda z:b_1 + b_2.$
 $(\text{match } z \text{ with } \mathbf{A}x. f\ x \mid \mathbf{B}x. g\ x)$

has type

$(b_1 \rightarrow b_3) \rightarrow (b_2 \rightarrow b_3) \rightarrow (b_1 + b_2) \rightarrow b_3$

Example programs

$\lambda x:b_1 * b_2. \lambda y:b_3. ((y, x.1), x.2)$

has type

$(b_1 * b_2) \rightarrow b_3 \rightarrow ((b_3 * b_1) * b_2)$

Empty and Nonempty Types

So we have seen several “nonempty” types (closed terms of that type):

$$b_{17} \rightarrow b_{17}$$

$$b_1 \rightarrow (b_1 \rightarrow b_2) \rightarrow b_2$$

$$(b_1 \rightarrow b_2 \rightarrow b_3) \rightarrow b_2 \rightarrow b_1 \rightarrow b_3$$

$$b_1 \rightarrow ((b_1 + b_7) * (b_1 + b_4))$$

$$(b_1 \rightarrow b_3) \rightarrow (b_2 \rightarrow b_3) \rightarrow (b_1 + b_2) \rightarrow b_3$$

$$(b_1 * b_2) \rightarrow b_3 \rightarrow ((b_3 * b_1) * b_2)$$

But there are also lots of “empty” types (no closed term of that type):

$$b_1 \quad b_1 \rightarrow b_2 \quad b_1 + (b_1 \rightarrow b_2) \quad b_1 \rightarrow (b_2 \rightarrow b_1) \rightarrow b_2$$

And “I” have a “secret” way of knowing whether a type will be empty;
let me show you propositional logic...

Propositional Logic

With \rightarrow for implies, $+$ for inclusive-or and $*$ for and:

$$p ::= b \mid p \rightarrow p \mid p * p \mid p + p$$

$$\Gamma ::= \cdot \mid \Gamma, p$$

$\Gamma \vdash p$

$$\frac{\Gamma \vdash p_1 \quad \Gamma \vdash p_2}{\Gamma \vdash p_1 * p_2}$$

$$\frac{\Gamma \vdash p_1 * p_2}{\Gamma \vdash p_1}$$

$$\frac{\Gamma \vdash p_1 * p_2}{\Gamma \vdash p_2}$$

$$\frac{\Gamma \vdash p_1}{\Gamma \vdash p_1 + p_2}$$

$$\frac{\Gamma \vdash p_2}{\Gamma \vdash p_1 + p_2}$$

$$\frac{\Gamma \vdash p_1 + p_2 \quad \Gamma, p_1 \vdash p_3 \quad \Gamma, p_2 \vdash p_3}{\Gamma \vdash p_3}$$

$$\frac{p \in \Gamma}{\Gamma \vdash p}$$

$$\frac{\Gamma, p_1 \vdash p_2}{\Gamma \vdash p_1 \rightarrow p_2}$$

$$\frac{\Gamma \vdash p_1 \rightarrow p_2 \quad \Gamma \vdash p_1}{\Gamma \vdash p_2}$$

Guess what!!!!

That's *exactly* our type system, erasing terms and changing every τ to a p

$\Gamma \vdash e : \tau$

$$\frac{\Gamma \vdash e_1 : \tau_1 \quad \Gamma \vdash e_2 : \tau_2}{\Gamma \vdash (e_1, e_2) : \tau_1 * \tau_2} \quad \frac{\Gamma \vdash e : \tau_1 * \tau_2}{\Gamma \vdash e.1 : \tau_1} \quad \frac{\Gamma \vdash e : \tau_1 * \tau_2}{\Gamma \vdash e.2 : \tau_2}$$

$$\frac{\Gamma \vdash e : \tau_1}{\Gamma \vdash \mathbf{A}(e) : \tau_1 + \tau_2} \quad \frac{\Gamma \vdash e : \tau_2}{\Gamma \vdash \mathbf{B}(e) : \tau_1 + \tau_2}$$

$$\frac{\Gamma \vdash e : \tau_1 + \tau_2 \quad \Gamma, x:\tau_1 \vdash e_1 : \tau \quad \Gamma, y:\tau_2 \vdash e_2 : \tau}{\Gamma \vdash \mathbf{match } e \mathbf{ with } \mathbf{Ax}. e_1 \mid \mathbf{By}. e_2 : \tau}$$

$$\frac{\Gamma(x) = \tau}{\Gamma \vdash x : \tau} \quad \frac{\Gamma, x : \tau_1 \vdash e : \tau_2}{\Gamma \vdash \lambda x. e : \tau_1 \rightarrow \tau_2} \quad \frac{\Gamma \vdash e_1 : \tau_2 \rightarrow \tau_1 \quad \Gamma \vdash e_2 : \tau_2}{\Gamma \vdash e_1 e_2 : \tau_1}$$

Curry-Howard Isomorphism

- Given a closed term that type-checks, we can take the typing derivation, erase the terms, and have a propositional-logic proof.
- Given a propositional-logic proof, there exists a closed term with that type.
- A term that type-checks is a *proof* — it tells you exactly how to derive the logic formula corresponding to its type.
- Intuitionistic (hold that thought) propositional logic and simply-typed lambda-calculus with pairs and sums are *the same thing*.
 - Computation and logic are *deeply* connected
 - λ is no more or less made up than implication
- Let's revisit our examples under the logical interpretation...

Example proofs

$\lambda x:b_{17}. x$

is a proof that

$b_{17} \rightarrow b_{17}$

Example proofs

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is a proof that

$b_1 \rightarrow (b_1 \rightarrow b_2) \rightarrow b_2$

Example proofs

$\lambda x:b_1 \rightarrow b_2 \rightarrow b_3. \lambda y:b_2. \lambda z:b_1. x z y$

is a proof that

$(b_1 \rightarrow b_2 \rightarrow b_3) \rightarrow b_2 \rightarrow b_1 \rightarrow b_3$

Example proofs

$$\lambda x:b_1. (\mathbf{A}(x), \mathbf{A}(x))$$

is a proof that

$$b_1 \rightarrow ((b_1 + b_7) * (b_1 + b_4))$$

Example proofs

$\lambda f:b_1 \rightarrow b_3. \lambda g:b_2 \rightarrow b_3. \lambda z:b_1 + b_2.$
(match z with $\mathbf{A}x. f\ x \mid \mathbf{B}x. g\ x$)

is a proof that

$(b_1 \rightarrow b_3) \rightarrow (b_2 \rightarrow b_3) \rightarrow (b_1 + b_2) \rightarrow b_3$

Example proofs

$\lambda x:b_1 * b_2. \lambda y:b_3. ((y, x.1), x.2)$

is a proof that

$(b_1 * b_2) \rightarrow b_3 \rightarrow ((b_3 * b_1) * b_2)$

Why care?

Because:

- This is just fascinating (glad I'm not a dog).
- For decades these were separate fields.
- Thinking “the other way” can help you know what's possible/impossible
- Can form the basis for automated theorem provers
- Type systems should not be *ad hoc* piles of rules!

So, every typed λ -calculus is a proof system for some logic...

Is ST λ C with pairs and sums a *complete* proof system for propositional logic? Almost...

Classical vs. Constructive

Classical propositional logic has the “law of the excluded middle”:

$$\frac{}{\Gamma \vdash p_1 + (p_1 \rightarrow p_2)}$$

(Think “ p or not p ” – also equivalent to double-negation.)

ST λ C has *no* proof for this; there is no closed expression with this type.

Logics without this rule are called *constructive*. They’re useful because proofs “know how the world is” and “are executable” and “produce examples”.

You can still “branch on possibilities”:

$$((p_1 + (p_1 \rightarrow p_2)) * (p_1 \rightarrow p_3) * ((p_1 \rightarrow p_2) \rightarrow p_3)) \rightarrow p_3$$

Example classical proof

Theorem: I can always wake up at 9AM and get to campus by 10AM.

Proof: If it is a weekday, I can take a bus that leaves at 9:30AM. If it is not a weekday, traffic is light and I can drive. Since it is a weekday or not a weekday, I can get to campus by 10AM.

Problem: If you wake up and don't know if it's a weekday, this proof does not let you construct a plan to get to campus by 10AM.

In constructive logic, that never happens. You can always extract a program from a proof that “does” what you proved “could be”.

You could not prove the theorem above, but you could prove, “If I know whether it is a weekday or not, then I can get to campus by 10AM.”

Fix

A “non-terminating proof” is no proof at all.

Remember the typing rule for fix:

$$\frac{\Gamma \vdash e : \tau \rightarrow \tau}{\Gamma \vdash \mathbf{fix} \ e : \tau}$$

That let's us prove anything! For example: **fix** $\lambda x:b_3. x$ has type b_3 .

So the “logic” is *inconsistent* (and therefore worthless)

Related: In ML, a value of type 'a never terminates normally (raises an exception, infinite loop, etc.)

```
let rec f x = f x
let z = f 0
```

Last word on Curry-Howard

It's not just $ST\lambda C$ and intuitionistic propositional logic.

Every logic has a corresponding typed λ calculus (and no consistent logic has something like fix).

- Example: When we add universal types (“generics”) in a few lectures, that corresponds to adding universal quantification.

If you remember one thing: the typing rule for function application is *modus ponens*.

Toward Evaluation Contexts

(untyped) λ -calculus with extensions has lots of “boring inductive rules”:

$$\begin{array}{c}
 \frac{e_1 \rightarrow e'_1}{e_1 e_2 \rightarrow e'_1 e_2} \quad \frac{e_2 \rightarrow e'_2}{v e_2 \rightarrow v e'_2} \quad \frac{e \rightarrow e'}{e.1 \rightarrow e'.1} \quad \frac{e \rightarrow e'}{e.2 \rightarrow e'.2} \\
 \\
 \frac{e_1 \rightarrow e'_1}{(e_1, e_2) \rightarrow (e'_1, e_2)} \quad \frac{e_2 \rightarrow e'_2}{(v_1, e_2) \rightarrow (v_1, e'_2)} \quad \frac{e \rightarrow e'}{\mathbf{A}(e) \rightarrow \mathbf{A}(e')} \quad \frac{e \rightarrow e'}{\mathbf{B}(e) \rightarrow \mathbf{B}(e')} \\
 \\
 \frac{e \rightarrow e'}{\text{match } e \text{ with } \mathbf{A}x. e_1 \mid \mathbf{B}y. e_2 \rightarrow \text{match } e' \text{ with } \mathbf{A}x. e_1 \mid \mathbf{B}y. e_2}
 \end{array}$$

and some “interesting do-work rules”:

$$\begin{array}{c}
 \frac{}{(\lambda x. e) v \rightarrow e[v/x]} \quad \frac{}{(v_1, v_2).1 \rightarrow v_1} \quad \frac{}{(v_1, v_2).2 \rightarrow v_2} \\
 \\
 \frac{}{\text{match } \mathbf{A}(v) \text{ with } \mathbf{A}x. e_1 \mid \mathbf{B}y. e_2 \rightarrow e_1[v/x]} \\
 \\
 \frac{}{\text{match } \mathbf{B}(v) \text{ with } \mathbf{A}y. e_1 \mid \mathbf{B}x. e_2 \rightarrow e_2[v/x]}
 \end{array}$$

Evaluation Contexts

We can define *evaluation contexts*, which are expressions with one hole where “interesting work” may occur:

$$\begin{aligned}
 E ::= & [\cdot] \mid E e \mid v E \mid (E, e) \mid (v, E) \mid E.1 \mid E.2 \\
 & \mid A(E) \mid B(E) \mid (\text{match } E \text{ with } Ax. e_1 \mid By. e_2)
 \end{aligned}$$

Define “filling the hole” $E[e]$ in the obvious way (stapling).

Semantics now uses two judgments $e \rightarrow e'$ and $e \xrightarrow{P} e'$, but the former has only 1 rule and the latter has just the “interesting work”:

$$\begin{array}{c}
 \frac{e \xrightarrow{P} e'}{E[e] \rightarrow E[e']} \\
 \\
 \frac{}{(\lambda x. e) v \xrightarrow{P} e[v/x]} \qquad \frac{}{(v_1, v_2).1 \xrightarrow{P} v_1} \qquad \frac{}{(v_1, v_2).2 \xrightarrow{P} v_2} \\
 \\
 \frac{}{\text{match } A(v) \text{ with } Ax. e_1 \mid By. e_2 \xrightarrow{P} e_1[v/x]} \\
 \\
 \frac{}{\text{match } B(v) \text{ with } Ay. e_1 \mid Bx. e_2 \xrightarrow{P} e_2[v/x]}
 \end{array}$$

So what?

So far, all we have done is rearrange our semantics to be more concise

- Each boring rule become a form of E

Evaluation relies on *decomposition* (unstapling the right subtree):

Given e , find an E, e_a, e'_a such that $e = E[e_a]$ and $e_a \xrightarrow{P} e'_a$.

Theorem (Unique Decomposition): If $\cdot \vdash e : \tau$, then e is a value or there is exactly one decomposition of e .

- Hence evaluation is deterministic
- In fact it's still CBV left-to-right

But the real power from defining E is that it lets us *reify* continuations (evaluation stacks) ...

Continuations

First-class continuations in one slide:

$$e ::= \dots \mid \text{letcc } x. e \mid \text{throw } e e \mid \text{cont } E$$
$$v ::= \dots \mid \text{cont } E$$
$$E ::= \dots \mid \text{throw } E e \mid \text{throw } v E$$

$$E[\text{letcc } x. e] \rightarrow E[(\lambda x. e)(\text{cont } E)]$$

$$E[\text{throw } (\text{cont } E') v] \rightarrow E'[v]$$

Very powerful and general: For example, non-preemptive multithreading *in the language*. Exceptions. “Time travel.”

Connection to interpreters

A “real” (efficient, natural) interpreter for lambda-calculus (or ML) would not be like our small-step semantics

- Would re-decompose the whole program for each step!

Instead, maintain the decomposition incrementally

- With a stack to remember “what to work on next”!

Also, don’t use substitution; use environments (see your homework)

- At this point, need just one while-loop, pairs, and malloc

And if your stacks are heap-allocated and immutable, you can implement continuation operations (letcc and throw) in $O(1)$ time.

- A nice (and provably correct) sequence of more primitive interpreters
- Can post Caml code for the curious