Natural Language Processing (CSE 490U): Neural Language Models

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Quick Review

A language model is a probability distribution over \mathcal{V}^{\dagger} .

Typically p decomposes into probabilities $p(x_i | \mathbf{h}_i)$.

- ▶ n-gram: h_i is (n-1) previous symbols; estimate by counting and normalizing (with smoothing)
- ▶ log-linear: featurized representation of $\langle \boldsymbol{h}_i, x_i \rangle$; estimate iteratively by gradient descent

Next: neural language models

Neural Network: Definitions

Warning: there is no widely accepted standard notation!

A feedforward neural network n_{ν} is defined by:

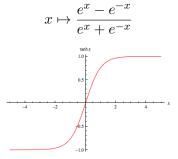
- ▶ A function family that maps parameter values to functions of the form $n: \mathbb{R}^{d_{in}} \to \mathbb{R}^{d_{out}}$; typically:
 - ► Non-linear
 - Differentiable with respect to its inputs
 - "Assembled" through a series of affine transformations and non-linearities, composed together
 - Symbolic/discrete inputs handled through lookups.
- ▶ Parameter values v
 - Typically a collection of scalars, vectors, and matrices
 - lacktriangle We often assume they are linearized into \mathbb{R}^D

A Couple of Useful Functions

ightharpoonup softmax: $\mathbb{R}^k \to \mathbb{R}^k$

$$\langle x_1, x_2, \dots, x_k \rangle \mapsto \left\langle \frac{e^{x_1}}{\sum_{j=1}^k e^{x_j}}, \frac{e^{x_2}}{\sum_{j=1}^k e^{x_j}}, \dots, \frac{e^{x_k}}{\sum_{j=1}^k e^{x_j}} \right\rangle$$

 \blacktriangleright tanh : $\mathbb{R} \to [-1, 1]$



Generalized to be *elementwise*, so that it maps $\mathbb{R}^k \to [-1,1]^k$.

► Others include: ReLUs, logistic sigmoids, PReLUs, ...

"One Hot" Vectors

Arbitrarily order the words in V, giving each an index in $\{1, \dots, V\}$.

Let $\mathbf{e}_i \in \mathbb{R}^V$ contain all zeros, with the exception of a 1 in position i.

This is the "one hot" vector for the ith word in \mathcal{V} .

Feedforward Neural Network Language Model (Bengio et al., 2003)

Define the n-gram probability as follows:

$$p(\cdot \mid \langle h_1, \dots, h_{\mathsf{n}-1} \rangle) = n_{\boldsymbol{\nu}} \left(\langle \mathbf{e}_{h_1}, \dots, \mathbf{e}_{h_{\mathsf{n}-1}} \rangle \right) =$$

$$\operatorname{softmax} \left(\underbrace{\mathbf{b}}_{v} + \sum_{j=1}^{\mathsf{n}-1} \mathbf{e}_{h_j}^{\mathsf{T}} \underbrace{\mathbf{M}}_{v \times d_{d \times v}} + \underbrace{\mathbf{W}}_{v \times H} \tanh \left(\underbrace{\mathbf{u}}_{H} + \sum_{j=1}^{\mathsf{n}-1} \mathbf{e}_{h_j}^{\mathsf{T}} \mathbf{M} \underbrace{\mathbf{T}}_{j} \right) \right)$$

where each $\mathbf{e}_{h_j} \in \mathbb{R}^V$ is a one-hot vector and H is the number of "hidden units" in the neural network (a "hyperparameter").

Parameters ν include:

- $lackbox{M} \in \mathbb{R}^{V imes d}$, which are called "embeddings" (row vectors), one for every word in $\mathcal V$
- ► Feedforward NN parameters $\mathbf{b} \in \mathbb{R}^V$, $\mathbf{A} \in \mathbb{R}^{(\mathsf{n}-1)\times d\times V}$, $\mathbf{W} \in \mathbb{R}^{V\times H}$, $\mathbf{u} \in \mathbb{R}^H$, $\mathbf{T} \in \mathbb{R}^{(\mathsf{n}-1)\times d\times H}$

Look up each of the history words $h_j, \forall j \in \{1, ..., n-1\}$ in M; keep two copies.

Look up each of the history words $h_j, \forall j \in \{1, \dots, n-1\}$ in M; keep two copies. Rename the embedding for h_j as \mathbf{m}_{h_j} .

$$\mathbf{e}_{h_j}^{\mathsf{T}} \mathbf{M} = \mathbf{m}_{h_j}$$
 $\mathbf{e}_{h_j}^{\mathsf{T}} \mathbf{M} = \mathbf{m}_{h_j}$

Apply an affine transformation to the second copy of the history-word embeddings (\mathbf{u}, \mathbf{T})

$$egin{aligned} \mathbf{m}_{h_j} \ \mathbf{u} + \sum_{j=1}^{\mathsf{n}-1} \mathbf{m}_{h_j} \ \mathbf{T}_j \ rac{\mathbf{T}_j}{d imes H} \end{aligned}$$

Apply an affine transformation to the second copy of the history-word embeddings (\mathbf{u}, \mathbf{T}) and a \tanh nonlinearity.

$$\tanh\left(\frac{\mathbf{u} + \sum_{j=1}^{\mathsf{n}-1} \mathbf{m}_{h_j} \mathbf{T}_j}{\mathbf{n}}\right)$$

Apply an affine transformation to everything (b, A, W).

$$\begin{aligned} & \underset{v}{\mathbf{b}} + \sum_{j=1}^{\mathsf{n}-1} \mathbf{m}_{h_j} \underset{\scriptscriptstyle d \times v}{\mathbf{A}_j} \\ & + \underset{\scriptscriptstyle v \times H}{\mathbf{W}} \tanh \left(\mathbf{u} + \sum_{j=1}^{\mathsf{n}-1} \mathbf{m}_{h_j} \mathbf{T}_j \right) \end{aligned}$$

Apply a softmax transformation to make the vector sum to one.

softmax
$$\left(\mathbf{b} + \sum_{j=1}^{\mathsf{n}-1} \mathbf{m}_{h_j} \mathbf{A}_j + \mathbf{W} \tanh \left(\mathbf{u} + \sum_{j=1}^{\mathsf{n}-1} \mathbf{m}_{h_j} \mathbf{T}_j\right)\right)$$

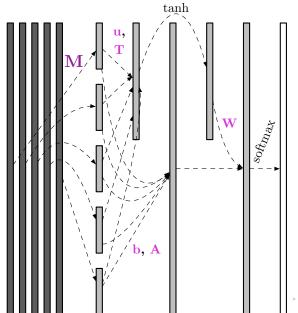
softmax
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Like a log-linear language model with two kinds of features:

- lacktriangle Concatenation of context-word embeddings vectors \mathbf{m}_{h_j}
- tanh-affine transformation of the above

New parameters arise from (i) embeddings and (ii) affine transformation "inside" the nonlinearity.

Visualization



Number of Parameters

$$D = \underbrace{Vd}_{\mathbf{M}} + \underbrace{V}_{\mathbf{b}} + \underbrace{(\mathbf{n} - 1)dV}_{\mathbf{A}} + \underbrace{VH}_{\mathbf{W}} + \underbrace{H}_{\mathbf{u}} + \underbrace{(\mathbf{n} - 1)dH}_{\mathbf{T}}$$

For Bengio et al. (2003):

- $V \approx 18000$ (after OOV processing)
- ▶ $d \in \{30, 60\}$
- $ightharpoonup H \in \{50, 100\}$
- ▶ n 1 = 5

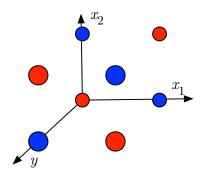
So D=461V+30100 parameters, compared to ${\cal O}(V^{\rm n})$ for classical n-gram models.

- Forcing A = 0 eliminated 300V parameters and performed a bit better, but was slower to converge.
- If we averaged \mathbf{m}_{h_j} instead of concatenating, we'd get to 221V+6100 (this is a variant of "continuous bag of words," Mikolov et al., 2013).

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xor Example



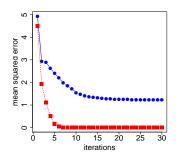
Correct tuples are marked in red; incorrect tuples are marked in blue.

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 - ▶ Suppose $y = xor(x_1, x_2)$; this can't be expressed as a linear function of x_1 and x_2 . But:

$$z = x_1 \cdot x_2$$
$$y = x_1 + x_2 - 2z$$

xor Example (D = 13)

Credit: Chris Dyer (https://github.com/clab/cnn/blob/master/examples/xor.cc)



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- ► Modern answer: representations of words and histories are tuned to the prediction problem.
- Word embeddings: a powerful idea . . .

Important Idea: Words as Vectors

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You should think of this as a *generalization* of the discrete view of \mathcal{V} .

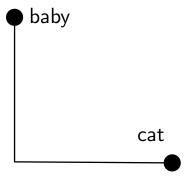
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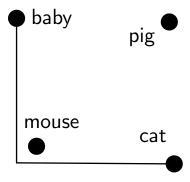
You should think of this as a generalization of the discrete view of \mathcal{V} .

 Considerable ongoing research on learning word representations to capture linguistic *similarity* (Turney and Pantel, 2010); this is known as **vector space semantics**.

Words as Vectors: Example



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Parameter Estimation

Bad news for neural language models:

- Log-likelihood function is not concave.
 - ► So any perplexity experiment is evaluating the model *and* an algorithm for estimating it.
- Calculating log-likelihood and its gradient is very expensive (5 epochs took 3 weeks on 40 CPUs).

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Good news:

- ν_{ν} is differentiable with respect to M (from which its inputs come) and ν (its parameters), so gradient-based methods are available.
- Essential: the chain rule from calculus (sometimes called "backpropagation")

Lots more details in Bengio et al. (2003) and (for NNs more generally) in Goldberg (2015).

Next Up

- ► The log-bilinear language model
- ► Recurrent neural network language models

Log-Bilinear Language Model

(Mnih and Hinton, 2007)

Define the n-gram probability as follows, for each $v \in \mathcal{V}$:

$$p(v \mid \langle h_1, \dots, h_{\mathsf{n}-1} \rangle) = \frac{\exp\left(\sum_{j=1}^{\mathsf{n}-1} \left(\mathbf{m}_{h_j}^{\mathsf{T}} \mathbf{A}_j + \mathbf{b}_{_d}^{\mathsf{T}}\right) \mathbf{m}_v + c_v\right)}{\sum_{v' \in \mathcal{V}} \exp\left(\sum_{j=1}^{\mathsf{n}-1} \left(\mathbf{m}_{h_j}^{\mathsf{T}} \mathbf{A}_j + \mathbf{b}_{_d}^{\mathsf{T}}\right) \mathbf{m}_{v'} + c_v\right)}$$

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- ▶ The predicted word's probability depends on its vector \mathbf{m}_v , not just on the vectors of the history words.
- ► Training this model involves a sum over the vocabulary (like log-linear models we saw earlier).
- ► Later work explored variations to make learning faster (related to class-based models in "extra" slides for traditional language models).

- ▶ There's no knowledge built in that the most recent word h_{n-1} should generally be more informative than earlier ones.
 - ► This has to be learned.
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 - ▶ Example: ℓ_2 -norm of \mathbf{A}_j and \mathbf{T}_j in the feedforward model correspond to the importance of history position j.
 - ▶ Individual word embeddings can be clustered and dimensions can be analyzed (e.g., Tsvetkov et al., 2015).

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- ▶ In addition to choosing n, also have to choose dimensionalities like d and H.
- Parameters of these models are hard to interpret.
- Architectures are not intuitive.
- ► Still, impressive perplexity gains got people's interest.

Recurrent Neural Network

- ▶ Each input element is understood to be an element of a sequence: $\langle \mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_{\ell} \rangle$
- ► At each timestep *t*:
 - ▶ The tth input element \mathbf{x}_t is processed alongside the previous state \mathbf{s}_{t-1} to calculate the new **state** (\mathbf{s}_t) .
 - ▶ The tth output is a function of the state s_t .
 - ▶ The same functions are applied at each iteration:

$$\mathbf{s}_t = f_{\text{recurrent}}(\mathbf{x}_t, \mathbf{s}_{t-1})$$
$$\mathbf{y}_t = f_{\text{output}}(\mathbf{s}_t)$$

In RNN language models, words and histories are represented as vectors (respectively, $\mathbf{x}_t = \mathbf{e}_{x_t}$ and \mathbf{s}_t).

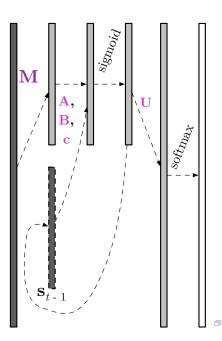
RNN Language Model

The original version, by Mikolov et al. (2010) used a "simple" RNN architecture along these lines:

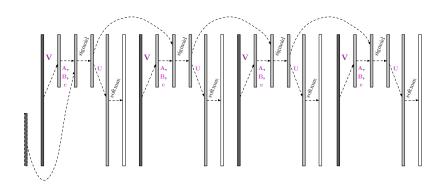
$$\mathbf{s}_{t} = f_{\text{recurrent}}(\mathbf{e}_{x_{t}}, \mathbf{s}_{t-1}) = \operatorname{sigmoid}\left(\left(\mathbf{e}_{x_{t}}^{\top}\mathbf{M}\right)^{\top}\mathbf{A} + \mathbf{s}_{t-1}^{\top}\mathbf{B} + \mathbf{c}\right)$$
$$\mathbf{y}_{t} = f_{\text{output}}(\mathbf{s}_{t}) = \operatorname{softmax}\left(\mathbf{s}_{t}^{\top}\mathbf{U}\right)$$
$$p(v \mid x_{1}, \dots, x_{t-1}) = [\mathbf{y}_{t}]_{v}$$

Note: this is not an n-gram (Markov) model!

Visualization



Visualization



Improvements to RNN Language Models

The simple RNN is known to suffer from two related problems:

- "Vanishing gradients" during learning make it hard to propagate error into the distant past.
- State tends to change a lot on each iteration; the model "forgets" too much.

Some variants:

- "Stacking" these functions to make deeper networks.
- ▶ Sundermeyer et al. (2012) use "long short-term memories" (LSTMs) and Cho et al. (2014) use "gated recurrent units" (GRUs) to define $f_{\rm recurrent}$.
- ▶ Mikolov et al. (2014) engineer the linear transformation in the simple RNN for better preservation.
- ▶ Jozefowicz et al. (2015) used randomized search to find even better architectures.

Comparison: Probabilistic vs. Connectionist Modeling

	Probabilistic	Connectionist
What do we engineer?	features, assumptions	architectures
Theory?	as N gets large	not really
Interpretation of parameters?	often easy	usually hard

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- ► This progression is worth reflecting on:

	history:	represented as:
before 1996	(n-1)-gram	discrete
1996-2003		feature vector
2003-2010		embedded vector
since 2010	unrestricted	embedded

To-Do List

- ▶ If you really want to learn more about neural networks for NLP: Goldberg (2015), §0–4 and §10–13
- ▶ Assignment 1
- ▶ Quiz coming soon

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