## Reading

## Recommended:

- Stollnitz, DeRose, and Salesin. Wavelets for Computer Graphics: Theory and Applications, 1996, section 6.1-6.3, 10.2, A.5.


## 16. Subdivision curves and surfaces

## Subdivision curves

## Idea:

- repeatedly refine the control polygon

$$
P_{0} \rightarrow P_{1} \rightarrow P_{2} \rightarrow \cdots
$$

- curve is the limit of an infinite process

$$
C=\lim _{i \rightarrow \infty} P_{i}
$$



## Chaikin's algorithm (1974)

Chakin introduced the following "corner-cutting" scheme in 1974:

- Start with a piecewise linear curve
- Insert new vertices at the midpoints (the splitting step)
- Average each vertex with the "next" neighbor (the averaging step)
- Go to the splitting step



## Averaging masks

The limit curve is a quadratic B-spline!
Instead of averaging with the nearest neighbor, we can generalize by applying an averaging mask during the averaging step:

$$
r=\left(\ldots, r_{-1}, r_{0}, r_{1}, \ldots\right)
$$

In the case of Chaikin's algorithm:

$$
r=
$$

## Lane-Riesenfeld algorithm (1980)

Use averaging masks from Pascal's triangle:

$$
r=\frac{1}{2^{n}}\left(\binom{n}{0},\binom{n}{1}, \cdots,\binom{n}{n}\right)
$$

Gives B-splines of degree $n+1$.

$$
\mathrm{n}=0
$$

$\mathrm{n}=1$ :
$\mathrm{n}=2$ :

## Subdivide ad nauseum?

After each split-average step, we are closer to the limit curve.

How many steps until we reach the final (limit) position?

Can we push a vertex to its limit position without infinite subdivision? Yes!

## Recipe for subdivision curves

After subdividing and averaging a few times, we can push each vertex to its limit position by applying an evaluation mask.

Each subdivision scheme has its own evaluation mask, mathematically determined by analyzing the subdivision and averaging rules.

For Lane-Riesenfeld cubic B-spline subdivision, we get:

$$
\frac{1}{6}\left(\begin{array}{lll}
1 & 4 & 1
\end{array}\right)
$$

Now we can cook up a simple procedure for creating subdivision curves:

- Subdivide (split+average) the control polygon a few times. Use the averaging mask.
- Push the resulting points to the limit positions. Use the evaluation mask.


## Subdivision surfaces

Chaikin's use of subdivision for curves inspired similar techniques for subdivision surfaces.

Iteratively refine a control polyhedron (or control mesh) to produce the limit surface

$$
\sigma=\lim _{j \rightarrow \infty} M^{j}
$$

using splitting and averaging steps.


## Loop averaging step

Once again we can use masks for the averaging step:


Vertex neighorhood


Averaging mask

$$
\mathbf{Q} \leftarrow \frac{\alpha(n) \mathbf{Q}+\mathbf{Q}_{1}+\cdots+\mathbf{Q}_{n}}{\alpha(n)+n}
$$

where

$$
\alpha(n)=\frac{n(1-\beta(n))}{\beta(n)} \quad \beta(n)=\frac{5}{4}-\frac{(3+2 \cos (2 \pi / n))^{2}}{32}
$$

These values, due to Charles Loop, are carefully chosen to ensure smoothness - namely, tangent plane or normal continuity.

Note: tangent plane continuity is also know as $\mathrm{G}^{1}$ continuity.

## Triangular subdivision

There are a variety of ways to subdivide a poylgon mesh.

A common choice for triangle meshes is $4: 1$ subdivision - each triangular face is split into four subfaces:


Original


After splitting

## Loop evaluation and tangent masks

As with subdivision curves, we can split and average a number of times and then push the points to their limit positions.


Evaluation mask


Tangent masks

$$
\begin{aligned}
& \mathbf{Q}^{\infty}=\frac{\mathcal{E}(n) \mathbf{Q}+\mathbf{Q}_{1}+\cdots+\mathbf{Q}_{n}}{\mathcal{E}(n)+n} \\
& \mathbf{T}_{1}^{\infty}=\tau_{1}(n) \mathbf{Q}_{1}+\tau_{2}(n) \mathbf{Q}_{2}+\cdots+\tau_{n}(n) \mathbf{Q}_{n} \\
& \mathbf{T}_{2}^{\infty}=\tau_{n}(n) \mathbf{Q}_{1}+\tau_{1}(n) \mathbf{Q}_{2}+\cdots+\tau_{n-1}(n) \mathbf{Q}_{n}
\end{aligned}
$$

where

$$
\varepsilon(n)=\frac{3 n}{\beta(n)} \quad \tau_{i}(n)=\cos (2 \pi i / n)
$$

How do we compute the normal?

## Recipe for subdivision surfaces

As with subdivision curves, we can now describe a recipe for creating and rendering subdivision surfaces:

- Subdivide (split+average) the control polyhedron a few times. Use the averaging mask.
- Compute two tangent vectors using the tangent masks.
- Compute the normal from the tangent vectors.
- Push the resulting points to the limit positions. Use the evaluation mask.
- Render!


## Adding creases without trim curves

In some cases, we want a particular feature such as a crease to be preserved. With NURBS surfaces, this required the use of trim curves.

For subdivision surfaces, we can just modify the subdivision mask:


This gives rise to $\mathrm{G}^{0}$ continuous surfaces (i.e., having positional but not tangent plane continuity)


## Creases without trim curves, cont.

Here's an example using Catmull-Clark surfaces (based on subdividing quadrilateral meshes):


## Summary

What to take home:

- The meanings of all the boldfaced terms.
- How to perform the splitting and averaging steps on subdivision curves.
- The various kinds of mesh splitting steps for subdivision surfaces, especially Loop.
- How to construct and render subdivision surfaces from their averaging masks, evaluation masks, and tangent masks.

