Primary/Backup
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Lab 2 posted
HW1 up Friday
Next week’s papers posted
Today

State machine replication
Primary/Backup
Single-node key/value store

Client | Put “key1” “value1”
---|---
Client | Put “key2” “value2”
Client | Get “key1”
Single-node state machine

Client → State machine
Op1 args1

Client → State machine
Op2 args2

Client → State machine
Op args3
Single-node state machine

Client

Op1 args1

Op2 args2

Op args3

State machine
Single-node state machine

Client
Op1 args1

Client
Op2 args2

Client
Op args3

State machine
?
State machine replication

Replicate the state machine across multiple servers
Clients can view all servers as one state machine
What’s the simplest form of replication?
Two servers!

At a given time:

- Clients talk to one server, the primary
- Data are replicated on primary and backup
- If the primary fails, the backup becomes primary

Goals:

- Correct and available
- Despite some failures
Basic operation

Clients send operations (Put, Get) to primary

Primary decides on order of ops

Primary forwards sequence of ops to backup

Backup performs ops in same order (hot standby)
  - Or just saves the log of operations (cold standby)

After backup has saved ops, primary replies to client
Challenges

Non-deterministic operations
Dropped messages
State transfer between primary and backup
  - Write log? Write state?
There can be only one primary at a time
  - Clients, primary and backup need to agree
The View Service

Who is primary?

Client → Ops

View server

Primary

Ping

Backup

Ops

Ping
The View service

View server decides who is primary and backup

- Clients and servers depend on view server

The hard part:

- Must be only one primary at a time
- Clients shouldn’t communicate with view server on every request
- Careful protocol design

View server is a single point of failure (fixed in Lab 3)
On failure

Primary fails

View server declares a new “view”, moves backup to primary

View server promotes an idle server as new backup

Primary initializes new backup’s state

Now ready to process ops, OK if primary fails
“Views”

Comes from Viewstamped Replication (I think?)
A view is a version of the current roles in the system
Logically, time is a sequence of views

- **View 1**
  - Primary = A
  - Backup = B

- **View 2**
  - Primary = B
  - Backup = C

- **View 3**
  - Primary = C
  - Backup = A
Detecting failure

Each server periodically pings (Ping RPC) view server
- “dead” if missed $n$ Pings
- “live” after a single Ping

Can a server ever be up but declared dead?
Managing servers

Any number of servers can send Pings
  - If more than two servers, extras are “idle”
  - Can be promoted to backup
If primary dies
  - New view with old backup as primary
If backup is dead, or no backup
  - New view with idle server as backup
OK to have a view with a primary and no backup
  - Why?
Question

How to ensure new primary has up-to-date state?
- Only promote the backup \(\rightarrow\) primary
- Idle server can become primary at startup (why?)

What if the backup hasn’t gotten the state yet?
- Remember, first thing = transfer state to backup
A stops pinging

B *immediately* stops pinging

Can’t move to View 3 until C gets state

How does view server know C has state?
Primary acks

Track whether primary has acked (with ping) current view

MUST stay with current view until ack

Even if primary seems to have failed

This is another weakness of this protocol
Question

Can more than one server think it’s primary?
Split brain

1: A, B

A is still up, but can’t reach view server

2: B, _

B learns it is promoted to primary
A still thinks it is primary
Split brain

Can more than one server act as primary?
- Act as = respond to clients
Rules

1. Primary in view \( i+1 \) must have been backup or primary in view \( i \)

2. Primary must wait for backup to accept/execute each op before doing op and replying to client

3. Backup must accept forwarded requests only if view is correct

4. Non-primary must reject client requests

5. Every operation must be before or after state transfer