The Kernel Abstraction
Main Points

• Process concept
  – A process is the OS abstraction for executing a program with limited privileges

• Dual-mode operation: user vs. kernel
  – Kernel-mode: execute with complete privileges
  – User-mode: execute with fewer privileges

• Safe control transfer
  – How do we switch from one mode to the other?
Restoring User State

• We need to be able to interrupt and transparently resume the execution of a user program for several reasons:
  • I/O device signals I/O completion
  • Periodic hardware timer to check if app is hung
  • Multiplexing multiple apps on a single CPU
  • App unaware it has been interrupted!
Device I/O

• OS kernel needs to communicate with physical devices
  – Network, disk, keyboard, mouse
• Devices operate asynchronously from the CPU
  – Often with their own microprocessor!
• How does the OS communicate with the device?
  – I/O device memory addressable by the CPU
  – CPU pokes I/O memory to issue commands
Polling vs. Interrupts

- **Polling**
  - OS pokes I/O memory on device to issue request
  - Device completes, stores data in its buffers
  - Kernel polls I/O memory to wait until I/O is done

- **Interrupts**
  - OS pokes I/O memory on device to issue request
  - CPU goes back to work on some other task
  - Device completes, stores data in its buffers
  - Triggers CPU interrupt to signal I/O completion
I/O Devices and Memory

• Programmed I/O
  – I/O results stored in the device
  – CPU reads and writes to device memory

• Direct memory access (DMA)
  – I/O device reads/writes the computer’s memory
  – After I/O interrupt signals I/O completion, CPU can access results in memory
Buffer Descriptors

• Do we need to poke I/O memory for every I/O operation?
• Buffer descriptor: data structure to specify where to find the I/O request
  – E.g., packet header and packet body
  – Buffer descriptor itself is DMA’ed!
• CPU and device I/O share a queue of buffer descriptors
  – I/O device reads from front
  – CPU fills at tail
Device Interrupts

• How do device interrupts work?
  – Where does the CPU run after an interrupt?
  – What is the interrupt handler written in? C? Java?
  – What stack does it use?
  – Is the work the CPU had been doing before the interrupt lost forever?
  – If not, how does the CPU know how to resume that work?
Booting

Disk

Bootloader

OS kernel

Login app

(1) BIOS copies bootloader

(2) Bootloader copies OS kernel

(3) OS kernel copies login application

Physical Memory

BIOS

Bootloader instructions and data

OS kernel instructions and data

Login app instructions and data
Challenge: Protection

• How do we execute code with restricted privileges?
  – Either because the code is buggy or if it might be malicious

• Some examples:
  – A script running in a web browser
  – A program you just downloaded off the Internet
  – A program you just wrote that you haven’t tested yet
Process Abstraction

• Process: an *instance* of a program, running with limited rights
  – Thread: a sequence of instructions within a process
    • Potentially many threads per process (for now 1:1)
  – Address space: set of rights of a process
    • Memory that the process can access
    • Other permissions the process has (e.g., which system calls it can make, what files it can access)
Thought Experiment

• How can we implement execution with limited privilege?
  – Execute each program instruction in a simulator
  – If the instruction is permitted, do the instruction
  – Otherwise, stop the process
  – Basic model in Javascript and other interpreted languages

• How do we go faster?
  – Run the unprivileged code directly on the CPU!
Dual-Mode Operation

• Kernel mode
  – Execution with the full privileges of the hardware
  – Read/write to any memory, access any I/O device, read/write any disk sector, send/read any packet

• User mode
  – Limited privileges
  – Only those granted by the operating system kernel

• On the x86, mode stored in EFLAGS register
• On the MIPS, mode in the status register
A Model of a CPU

Select PC → +4 → New PC → Program Counter → CPU Instructions Fetch and Execute

Branch Address

opcode
A CPU with Dual-Mode Operation

Branch Address

Handler PC → +4 → Select PC → New PC → Program Counter → CPU Instructions Fetch and Execute

Select Mode → New Mode → Mode

opcode
Hardware Support for Dual-Mode Operation

- Privileged instructions
  - Available to kernel
  - Not available to user code

- Limits on memory accesses
  - To prevent user code from overwriting the kernel

- Timer
  - To regain control from a user program in a loop

- Safe way to switch from user mode to kernel mode, and vice versa
Privileged instructions

• Examples?

• What should happen if a user program attempts to execute a privileged instruction?
Question

• For a “Hello world” program, the kernel must copy the string from the user program memory into the screen memory.

• Why not allow the application to write directly to the screen’s buffer memory?
Towards Virtual Addresses

• Problems with base and bounds?
Virtual Addresses

• Translation done in hardware, using a table
• Table set up by operating system kernel
Virtual Address Example

```c
int staticVar = 0;    // a static variable
main() {
    staticVar += 1;
    sleep(10);    // sleep for x seconds
    printf ("static address: %x, value: %d\n", &staticVar,
            staticVar);
}

What happens if we run two instances of this program at the same time?
What if we took the address of a procedure local variable in two copies of the same program running at the same time?
```
Virtual Address != Physical Address

• The same virtual address in two different processes can refer to different physical addresses. Why?
• The same virtual address in two different processes can refer to the same physical address. Why?
• Different virtual addresses can refer to the same physical address. Why?
Question

• With an object-oriented language and compiler, only an object’s methods can access the internal data inside an object. If the operating system only ran programs written in that language, would it still need hardware memory address protection?

• What if the contents of every object were encrypted except when its method was running, including the OS?
Hardware Timer

• Hardware device that periodically interrupts the processor
  – Returns control to the kernel handler
  – Interrupt frequency set by the kernel
    • Not by user code!
  – Interrupts can be temporarily deferred
    • Not by user code!
    • Interrupt deferral crucial for implementing mutual exclusion
User->Kernel Mode Switch

• From user mode to kernel mode (trap)
  – Interrupts
    • Triggered by timer and I/O devices
  – Exceptions
    • Triggered by unexpected program behavior
    • Or malicious behavior!
  – System calls (protected procedure call)
    • Request by program for kernel to do some operation on its behalf
    • Only limited # of very carefully coded entry points
Question

- Examples of exceptions

- Examples of system calls
Kernel->User Mode Switch

• From kernel mode to user mode
  – New process/new thread start
    • Jump to first instruction in program/thread
  – Return from interrupt, exception, system call
    • Resume suspended execution
  – Process/thread context switch
    • Resume some other process
  – User-level upcall (UNIX signal)
    • Asynchronous notification to user program
How do we take interrupts safely?

• Interrupt vector
  – Limited number of entry points into kernel

• Atomic transfer of control
  – Single instruction to change:
    • Program counter
    • Stack pointer
    • Memory protection
    • Kernel/user mode

• Transparent restartable execution
  – User program does not know interrupt occurred
Interrupt Vector

• Table set up by OS kernel; pointers to code to run on different events

```
Processor
Register

Interrupt
Vector

handleTimerInterrupt() {
  ...
}

handleDivideByZero() {
  ...
}

handleSystemCall() {
  ...
}
```
Interrupt Stack

• Per-processor, located in kernel (not user) memory
  – Usually a process/thread has both: kernel and user stack

• Why can’t the interrupt handler run on the stack of the interrupted user process?
Interrupt Stack

User Stack
- Running
  - ...  
  - Proc2
  - Proc1
  - Main
- Ready to Run
  - ...  
  - Proc2
  - Proc1
  - Main
- Waiting for I/O
  - Syscall
  - Proc2
  - Proc1
  - Main

Kernel Stack
- User CPU State
  - I/O Driver
  - Top Half
  - Syscall Handler
  - User CPU State
Interrupt Masking

• Interrupt handler runs with interrupts off
  – Re-enabled when interrupt completes

• OS kernel can also turn interrupts off
  – Eg., when determining the next process/thread to run
  – On x86
    • CLI: disable interrupts
    • STI: enable interrupts
    • Only applies to the current CPU (on a multicore)

• We’ll need this to implement synchronization in chapter 5
Case Study: MIPS Interrupt/Trap (Hardware Support)

- Two entry points: TLB miss handler, everything else
- Hardware saves trap type: syscall, exception, interrupt
  - And which type of interrupt/exception/syscall
- Saves program counter: where to resume
- Saves old mode (kernel/user), interruptable bits
- Sets kernel-mode, interrupts disabled
- For TLB (memory) faults
  - Saves virtual address and virtual page
- Jumps to general exception handler
- Handler saves stack pointer, registers (using k0, k1)
Case Study: x86 Interrupt (Hardware Support)

- Hardware saves current stack pointer
- Saves current program counter
- Saves current processor status word (condition codes)
- Switches to kernel stack
- Puts SP, PC, PSW on stack
- Switches to kernel mode
- Vectors through interrupt table
- Interrupt handler saves registers it might clobber
Before Interrupt

User-level Process

```
foo () {
  while(...) {
    x = x+1;
    y = y-2;
  }
}
```

User Stack

Kernel

```
handler() {
  pushad
  ...
}
```

Interrupt Stack

Registers

- SS: ESP
- CS: EIP
- EFLAGS
- Other Registers: EAX, EBX, ...

Interrupt Stack
During Interrupt

User-level Process

foo () {
    while(...) {
        x = x + 1;
        y = y - 2;
    }
}

User Stack

Registers

SS: ESP
CS: EIP
EFLAGS
other registers: EAX, EBX, ...

Kernel

handler() {
    pushad ...
}

Interrupt Stack

Error
EIP
CS
EFLAGS
ESP
SS
foo () {
  while(...) {
    x = x + 1;
    y = y - 2;
  }
}

handler() {
  pushad
  ...
}

Stack

User-level Process

Registers

Kernel

Interrupt Stack

All Registers

SS: ESP
CS: EIP
EFLAGS
other registers: EAX, EBX, ...

EBX
EAX
ESP
SS
Error
EIP
CS
EFLAGS
ESP
SS
Question

• Why is the stack pointer saved twice on the interrupt stack?
  – Hint: is it the same stack pointer?
At end of handler

• Handler restores saved registers
• Atomically return to interrupted process/thread
  – Restore program counter
  – Restore program stack
  – Restore processor status word/condition codes
  – Switch to user mode
Question

• Suppose the OS over-writes a value in the trapframe. What happens when the handler returns?

• Why might the OS want to do this?
Question

• The trapframe is stored on the interrupt stack; where is it stored after a context switch to a different process?
Upcall: User-level event delivery

• Notify user process of some event that needs to be handled right away
  – Time expiration
    • Real-time user interface
    • Time-slice for user-level thread manager
  – Interrupt delivery for VM player
  – Asynchronous I/O completion (async/await)

• AKA UNIX signal
Upcalls vs Interrupts

• Signal handlers = interrupt vector
• Signal stack = interrupt stack
• Automatic save/restore registers = transparent resume
• Signal masking: signals disabled while in signal handler
Upcall: Before

\[ x = y + z; \]

\[
\begin{aligned}
\text{signal\_handler}() \{ \\
\quad \ldots \\
\}
\end{aligned}
\]
Upcall: During

\[ x = y + z; \]

Signal Stack

Program Counter

Stack Pointer

Stack

\[ \text{signal\_handler()} \{ \]
\[ \quad \]
\[ \quad \}

Signal Stack

Saved Registers

SP

PC
User Program

```c
main () {
    file_open(arg1, arg2);
}
```

Kernel

```c
file_open(arg1, arg2) {
    // do operation
}
```

User Stub

```c
file_open(arg1, arg2) {
    push #SYSCALL_OPEN
    trap
    return
}
```

Kernel Stub

```c
file_open_handler() {
    // copy arguments
    // from user memory
    // check arguments
    file_open(arg1, arg2);
    // copy return value
    // into user memory
    return;
}
```
Kernel System Call Handler

- Locate arguments
  - In registers or on user stack
  - *Translate* user addresses into kernel addresses

- Copy arguments
  - From user memory into kernel memory
  - Protect kernel from malicious code evading checks

- Validate arguments
  - Protect kernel from errors in user code

- Copy results back into user memory
  - *Translate* kernel addresses into user addresses
Question

• How many user-kernel transitions are needed for a static web server to read an incoming HTTP request and reply with the file data?
Virtual Machines

• How do we debug an operating system kernel?
  – Is the debugger an application? Part of the kernel?
• Can we run legacy applications on a new operating system kernel?
• Solution: virtual machine
  – Run a “guest” operating system as a process
  – Run “guest” applications on the guest OS kernel
• Examples: KVM, Vmware, Xen, Citrix, QEMU, System 161
System 161

• Machine simulator that runs the OS kernel in a user-level process
  – Simulates the execution of each instruction in turn
• User-level applications run inside the simulator, as if running on real hardware running the OS
• No special support needed from the underlying OS kernel
• Flexible but slow
Question

• Can we run a guest operating system directly on the CPU in user mode?

• If hardware is “virtualizable”
  – Privileged instructions must cause trap when at user level, rather than fail silently
  – Or kernel must somehow re-write those instructions to cause a trap (vmware)
  – Kernel emulates the behavior of the privileged instruction, as if executed on the hardware

• Underlying kernel called the “virtual machine monitor” or “host kernel”
Hardware

Virtual Disk

Guest Kernel

Timer Handler

Guest Flags

Guest Process

Guest Interrupt Table

Guest User Mode

Host User Mode

Guest file system and other kernel services

Guest Exception Stack

Guest PC

Guest SP

Guest Flags

Program Counter

Guest Process

... trap ...

Host User Mode

Guest Kernel Mode

Host Kernel Mode

Host PC

Host SP

Host Flags

Host Kernel

Virtual Disk

Host Interrupt Table

Timer Handler

Syscall Handler

Hardware

Physical Disk
User-Level Virtual Machine

• How does VM Player work?
  – Runs as a user-level application
  – How does it catch privileged instructions, interrupts, device I/O?

• Installs kernel driver, transparent to host kernel
  – Requires administrator privileges!
  – Modifies interrupt table to redirect to kernel VM code
  – If interrupt is for VM, upcall
  – If interrupt is for another process, reinstalls interrupt table and resumes kernel
Debugging as Engineering

• Much of your time in this course will be spent debugging
  – In industry, 50% of software dev is debugging
  – Even more for kernel development

• How do you reduce time spent debugging?
  – Produce working code with smallest effort

• Optimize a process involving you, code, computer
Debugging as Science

• Understanding -> design -> code
  – not the opposite

• Form a hypothesis that explains the bug
  – Which tests work, which don’t. Why?
  – Add tests to narrow possible outcomes

• Use best practices
  – Always walk through your code line by line
  – Module tests – narrow scope of where problem is
  – Develop code in stages, with dummy replacements for later functionality
ABET

You can’t debug effectively without this:

b. Ability to design and conduct experiments, analyze and interpret data.
Interrupt Handlers

• Non-blocking, run to completion
  – Minimum necessary to allow device to take next interrupt
  – Any waiting must be limited duration
  – Wake up other threads to do any real work
    • Linux: semaphore

• Rest of device driver runs as a kernel thread