

# **CSE 451: Operating Systems**

## **Winter 2003**

### **Lecture 2**

### **Architectural Support for**

### **Operating Systems**

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# Architecture affects the OS

- Operating system functionality is dictated, at least in part, by the underlying hardware architecture
  - includes instruction set (synchronization, I/O, ...)
  - also hardware components like MMU or DMA controllers
- Architectural support can vastly simplify (or complicate!) OS tasks
  - e.g.: early PC operating systems (DOS, MacOS) lacked support for virtual memory, in part because at that time PCs lacked necessary hardware support
  - Current Intel-based PCs still lack support for 64-bit addressing (which has been available for a decade on other platforms: MIPS, Alpha, IBM, etc...) [this will change mostly due to AMD's new 64-bit architecture]

# Architectural Features affecting OS's

- These features were built primarily to support OS's:
  - timer (clock) operation
  - synchronization instructions (e.g. atomic test-and-set)
  - memory protection
  - I/O control operations
  - interrupts and exceptions
  - protected modes of execution (kernel vs. user)
  - protected instructions
  - system calls (and software interrupts)

# Protected Instructions

- some instructions are restricted to the OS
  - known as **protected or privileged instructions**
- e.g., only the OS can:
  - directly access I/O devices (disks, network cards)
    - why?
  - manipulate memory state management
    - page table pointers, TLB loads, etc.
    - why?
  - manipulate special ‘mode bits’
    - interrupt priority level
    - why?
  - halt instruction
    - why?

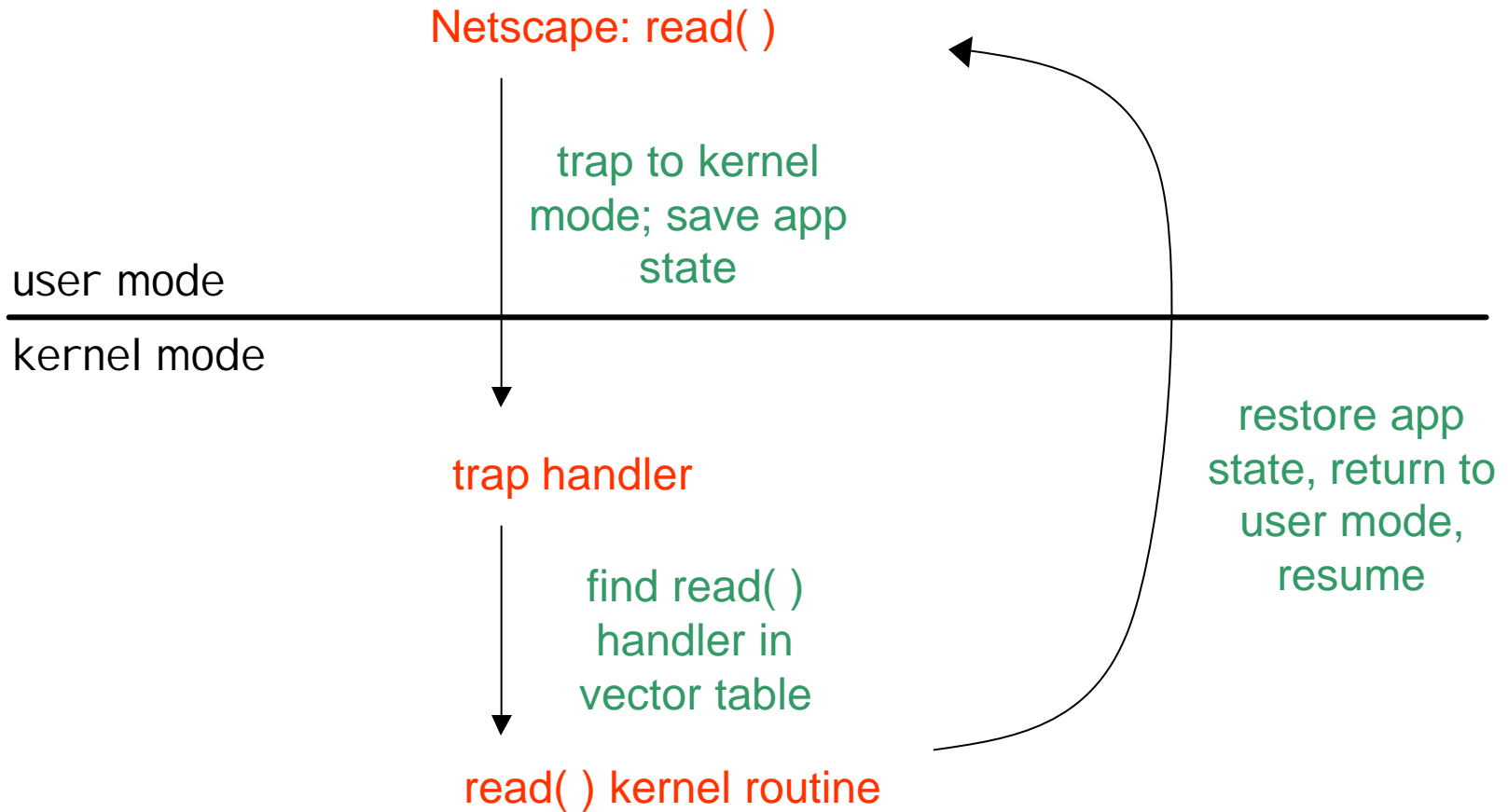
# OS Protection

- So how does the processor know if a protected instruction should be executed?
  - the architecture must support at least two modes of operation: **kernel** mode and **user** mode
    - VAX, x86 support 4 protection modes
    - why more than 2?
  - mode is set by status bit in a protected processor register
    - user programs execute in user mode
    - OS executes in kernel mode (OS == kernel)
- Protected instructions can only be executed in the kernel mode
  - what happens if user mode executes a protected instruction?

# Crossing Protection Boundaries

- So how do user programs do something privileged?
  - e.g., how can you write to a disk if you can't do I/O instructions?
- User programs must call an OS procedure
  - OS defines a sequence of **system calls**
  - how does the user-mode to kernel-mode transition happen?
- There must be a system call instruction, which:
  - causes an exception (throws a **software interrupt**), which vectors to a kernel handler
  - passes a parameter indicating which system call to invoke
  - saves caller's state (regs, mode bit) so they can be restored
  - OS must verify caller's parameters (e.g. pointers)
  - must be a way to return to user mode once done

# A Kernel Crossing Illustrated



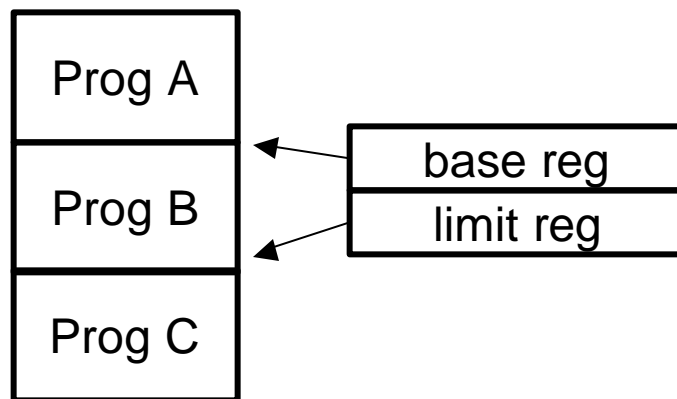
# System Call Issues

- What would happen if kernel didn't save state?
- Why must the kernel verify arguments?
- How can you reference kernel objects as arguments or results to/from system calls?



# Memory Protection

- OS must protect user programs from each other
  - maliciousness, ineptitude
- OS must also protect itself from user programs
  - integrity and security
  - what about protecting user programs from OS?
- Simplest scheme: **base** and **limit** registers
  - are these protected?



base and limit registers  
are loaded by OS before  
starting program

# More sophisticated memory protection

- coming later in the course
- virtual memory
  - paging, segmentation
  - page tables, page table pointers
  - translation lookaside buffers (TLBs)

# OS control flow

- after the OS has booted, all entry to the kernel happens as the result of an **event**
  - event immediately stops current execution
  - changes mode to kernel mode, event handler is called
- kernel defines handlers for each event type
  - specific types are defined by the architecture
    - e.g.: timer event, I/O interrupt, system call trap
  - when the processor receives an event of a given type, it
    - transfers control to handler within the OS
    - handler saves program state (PC, regs, etc.)
    - handler functionality is invoked
    - handler restores program state, returns to program

# Interrupts and Exceptions

- Two main types of events: **interrupts** and **exceptions**
  - exceptions are caused by software executing instructions
    - e.g. the x86 'int' instruction
    - e.g. a page fault, write to a read-only page
    - an expected exception is a “trap”, unexpected is a “fault”
  - interrupts are caused by hardware devices
    - e.g. device finishes I/O
    - e.g. timer fires

# I/O Control

- Issues:
  - how does the kernel start an I/O?
    - special I/O instructions
    - memory-mapped I/O
  - how does the kernel notice an I/O has finished?
    - polling
    - interrupts
- Interrupts are basis for asynchronous I/O
  - device performs an operation asynch to CPU
  - device sends an interrupt signal on bus when done
  - in memory, a **vector table** contains list of addresses of kernel routines to handle various interrupt types
    - who populates the vector table, and when?
  - CPU switches to address indicated by vector specified by interrupt signal

# Timers

- How can the OS prevent runaway user programs from hogging the CPU (infinite loops?)
  - use a hardware timer that generates a periodic interrupt
  - before it transfers to a user program, the OS loads the timer with a time to interrupt
    - “quantum”: how big should it be set?
  - when timer fires, an interrupt transfers control back to OS
    - at which point OS must decide which program to schedule next
    - very interesting policy question: we’ll dedicate a class to it
- Should the timer be privileged?
  - for reading or for writing?

# Synchronization

- Interrupts cause a wrinkle:
  - may occur any time, causing code to execute that interferes with code that was interrupted
  - OS must be able to **synchronize** concurrent processes
- Synchronization:
  - guarantee that short instruction sequences (e.g., read-modify-write) execute atomically
  - one method: turn off interrupts before the sequence, execute it, then re-enable interrupts
    - architecture must support disabling interrupts
  - another method: have special complex atomic instructions
    - read-modify-write
    - test-and-set
    - load-linked store-conditional