

# Linear Classification: The Perceptron

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## **Linear Classifiers**

- A hyperplane partitions  $\mathbb{R}^d$  into two half-spaces
  - Defined by the normal vector  $oldsymbol{ heta} \in \mathbb{R}^d$ 
    - $\theta$  is orthogonal to any vector lying on the hyperplane



- Assumed to pass through the origin
  - This is because we incorporated bias term  $\, heta_0$  into it by  $\,x_0=1$

• Consider classification with +1, -1 labels ...

#### **Linear Classifiers**

• Linear classifiers: represent decision boundary by hyperplane

#### The Perceptron

 $h(\boldsymbol{x}) = \operatorname{sign}(\boldsymbol{\theta}^{\intercal}\boldsymbol{x}) \text{ where } \operatorname{sign}(z) = \begin{cases} 1 & \text{if } z \ge 0 \\ -1 & \text{if } z < 0 \end{cases}$ 

• The perceptron uses the following update rule each time it receives a new training instance  $(x^{(i)}, y^{(i)})$ 

$$\theta_j \leftarrow \theta_j - \frac{\alpha}{2} \left( h_{\theta} \left( \boldsymbol{x}^{(i)} \right) - y^{(i)} \right) x_j^{(i)}$$
  
either 2 or -2

- If the prediction matches the label, make no change
- Otherwise, adjust  $\theta$

## The Perceptron

• The perceptron uses the following update rule each time it receives a new training instance  $(x^{(i)}, y^{(i)})$ 

$$\theta_j \leftarrow \theta_j - \frac{\alpha}{2} \left( h_{\theta} \left( \boldsymbol{x}^{(i)} \right) - y^{(i)} \right) x_j^{(i)}$$
  
either 2 or -2

• Re-write as  $\theta_j \leftarrow \theta_j + \alpha y^{(i)} x_j^{(i)}$  (only upon misclassification) – Can eliminate  $\alpha$  in this case, since its only effect is to scale  $\theta$ by a constant, which doesn't affect performance

Perceptron Rule: If  $m{x}^{(i)}$  is misclassified, do  $m{ heta} \leftarrow m{ heta} + y^{(i)} m{x}^{(i)}$ 

## Why the Perceptron Update Works



## Why the Perceptron Update Works

Consider the misclassified example (y = +1)

– Perceptron wrongly thinks that  $\, {m heta}_{
m old}^{\, {
m T}} {m x} < 0 \,$ 

• Update:

$$\boldsymbol{\theta}_{\text{new}} = \boldsymbol{\theta}_{\text{old}} + y\boldsymbol{x} = \boldsymbol{\theta}_{\text{old}} + \boldsymbol{x} \qquad (\text{since } y = +1)$$

• Note that

$$egin{aligned} m{ heta}_{ ext{new}}^{\intercal} m{x} &= (m{ heta}_{ ext{old}} + m{x})^{\intercal} m{x} \ &= m{ heta}_{ ext{old}}^{\intercal} m{x} + m{ heta}_{ ext{old}}^{\intercal} m{x} \ &= m{ heta}_{ ext{old}}^{\intercal} m{x} + m{ heta}_{ ext{old}}^{\intercal} m{x} \ &= m{ heta}_{ ext{old}}^{\intercal} m{x} + m{ heta}_{ ext{old}}^{\intercal} m{x} \ &= m{ heta}_{ ext{old}}^{\intercal} m{x} + m{ heta}_{ ext{old}}^{\intercal} m{x} \ &= m{ heta}_{ ext{old}}^{\intercal} m{x} + m{ heta}_{ ext{old}}^{\intercal} m{x} \ &= m{ heta}_{ ext{old}}^{\intercal} m{x} + m{ heta}_{ ext{old}}^{\intercal} m{x} \ &= m{ heta}_{ ext{old}}^{\intercal} m{x} + m{ heta}_{ ext{old}}^{\intercal} m{x} \ &= m{ heta}_{ ext{old}}^{\intercal} m{x} + m{ heta}_{ ext{old}}^{\intercal} m{x} \ &= m{ heta}_{ ext{old}}^{\intercal} m{x} + m{ heta}_{ ext{old}}^{\intercal} m{x} \ &= m{ heta}_{ ext{old}}^{\intercal} m{x} \ &= m{ heta}_{ ext{old}}^{\intercal} m{x} + m{ heta}_{ ext{old}}^{\intercal} m{x} \ &= m{ heta}_{ ext{$$

- Therefore,  $heta_{
  m new}^{\intercal} x$  is less negative than  $heta_{
  m old}^{\intercal} x$ 
  - So, we are making ourselves more correct on this example!

#### **The Perceptron Cost Function**

• The perceptron uses the following cost function

$$J_p(\boldsymbol{\theta}) = \frac{1}{n} \sum_{i=1}^n \max(0, -y^{(i)} x^{(i)} \boldsymbol{\theta})$$

-  $\max(0, -y^{(i)}x^{(i)} \boldsymbol{\theta})$  is 0 if the prediction is correct

- Otherwise, it is the confidence in the misprediction

## **Online Perceptron Algorithm**

$$\begin{array}{l} \text{Let } \boldsymbol{\theta} \leftarrow [0, 0, \dots, 0] \\ \text{Repeat:} \\ \text{Receive training example } (\boldsymbol{x}^{(i)}, y^{(i)}) \\ \text{if } y^{(i)} \boldsymbol{x}^{(i)} \boldsymbol{\theta} \leq 0 \\ \boldsymbol{\theta} \leftarrow \boldsymbol{\theta} + y^{(i)} \boldsymbol{x}^{(i)} \end{array} // \text{ prediction is incorrect}$$

**Online learning** – the learning mode where the model update is performed each time a single observation is received

**Batch learning** – the learning mode where the model update is performed after observing the entire training set

## **Online Perceptron Algorithm**



## **Batch Perceptron**

Given training data 
$$\{(\boldsymbol{x}^{(i)}, y^{(i)})\}_{i=1}^{n}$$
  
Let  $\boldsymbol{\theta} \leftarrow [0, 0, \dots, 0]$   
Repeat:  
Let  $\boldsymbol{\Delta} \leftarrow [0, 0, \dots, 0]$   
for  $i = 1 \dots n$ , do  
if  $y^{(i)} \boldsymbol{x}^{(i)} \boldsymbol{\theta} \leq 0$  // prediction for i<sup>th</sup> instance is incorrect  
 $\boldsymbol{\Delta} \leftarrow \boldsymbol{\Delta} + y^{(i)} \boldsymbol{x}^{(i)}$   
 $\boldsymbol{\Delta} \leftarrow \boldsymbol{\Delta}/n$  // compute average update  
 $\boldsymbol{\theta} \leftarrow \boldsymbol{\theta} + \alpha \boldsymbol{\Delta}$   
Until  $\|\boldsymbol{\Delta}\|_{2} < \epsilon$ 

- Simplest case: α = 1 and don't normalize, yields the fixed increment perceptron
- Guaranteed to find a separating hyperplane if one exists