

Regularization in Linear Regression Overfitting usually leads to very large parameter choices, e.g.: -2.2 + 3.1 × -0.30 ײ -1.1 + 4,700,910.7 × -8,585,638.4 ײ + ... Planting Regularized or penalized regression aims to impose a "complexity" penalty by penalizing large weights "Shrinkage" method | Yeyuhayaha

LASSO Regression

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- LASSO: least absolute shrinkage and selection operator
- New objective:

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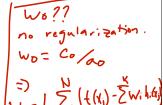
Coordinate Descent for LASSO (aka Shooting Algorithm)

- - Repeat until convergence

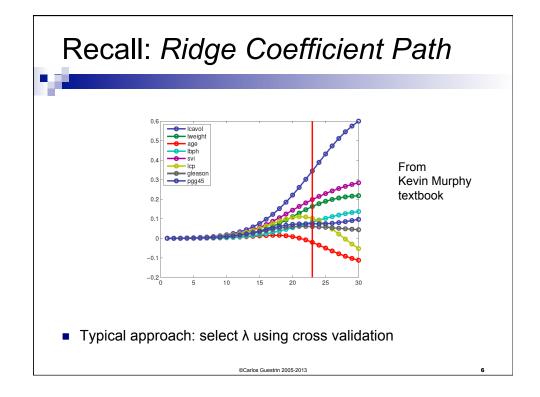
 □ Pick a coordinate j at (random or sequentially)

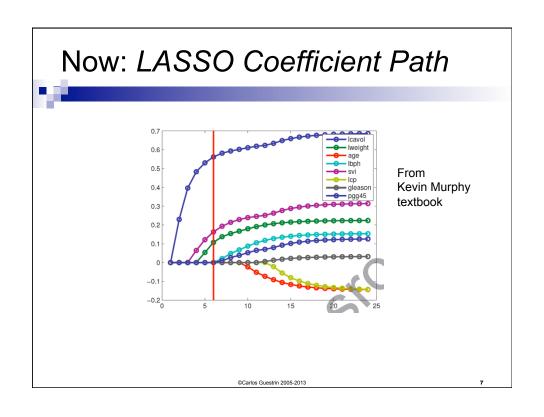
$$\hat{w}_{\ell} = \left\{ \begin{array}{ll} (c_{\ell} + \lambda)/a_{\ell} & c_{\ell} < -\lambda \\ 0 & c_{\ell} \in [-\lambda, \lambda] \\ (c_{\ell} - \lambda)/a_{\ell} & c_{\ell} > \lambda \end{array} \right.$$

 $\begin{aligned} & \text{Set:} \\ & \hat{w}_{\ell} = \left\{ \begin{array}{ll} (c_{\ell} + \lambda)/a_{\ell} & c_{\ell} < -\lambda \\ 0 & c_{\ell} \in [-\lambda, \lambda] \\ (c_{\ell} - \lambda)/a_{\ell} & c_{\ell} > \lambda \end{array} \right. \end{aligned}$ $\begin{aligned} & \text{Where:} \\ & a_{\ell} = 2\sum_{j=1}^{N}(h_{\ell}(\mathbf{x}_{j}))^{2} \\ & c_{\ell} = 2\sum_{j=1}^{N}h_{\ell}(\mathbf{x}_{j}) \left(t(\mathbf{x}_{j}) - (w_{0} + \sum_{i \neq \ell}w_{i}h_{i}(\mathbf{x}_{j}))\right) \end{aligned}$



- ☐ For convergence rates, see Shalev-Shwartz and Tewari 2009
- Other common technique = LARS
 - □ Least angle regression and shrinkage, Efron et al. 2004





LAS	SO Ex	ample			
	Term	Least Squares	Ridge	Lasso	
	Intercept	2.465	2.452	2.468	
	lcavol	0.680	0.420	0.533	From
	lweight	0.263	0.238	0.169	Rob Tibshirani
	age	-0.141	-0.046		slides
	lbph	0.210	0.162	0.002	
	svi	0.305	0.227	0.094	
	lcp	-0.288	0.000		
	gleason	-0.021	0.040		
	pgg45	0.267	0.133		
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What you need to know

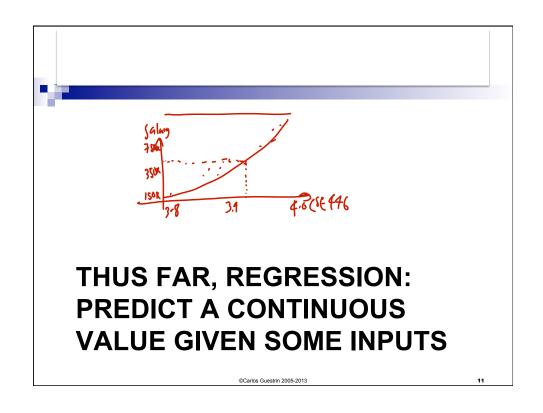


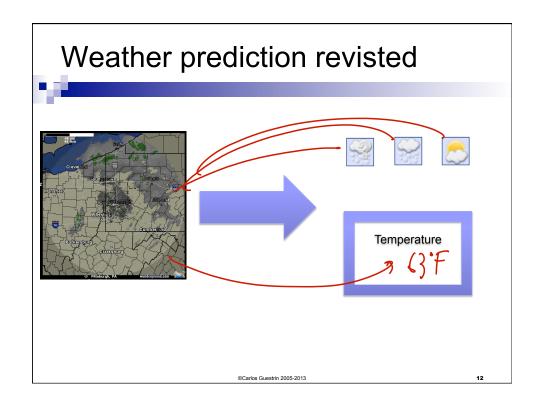
- Variable Selection: find a sparse solution to learning problem
- L₁ regularization is one way to do variable selection
 - □ Applies beyond regressions
 - ☐ Hundreds of other approaches out there
- LASSO objective non-differentiable, but convex → Use subgradient
- No closed-form solution for minimization → Use coordinate descent
- Shooting algorithm is very simple approach for solving LASSO

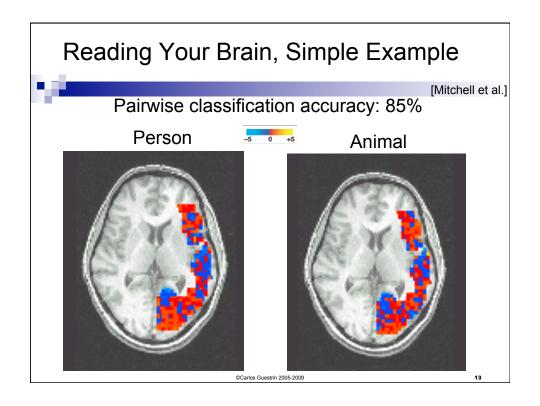
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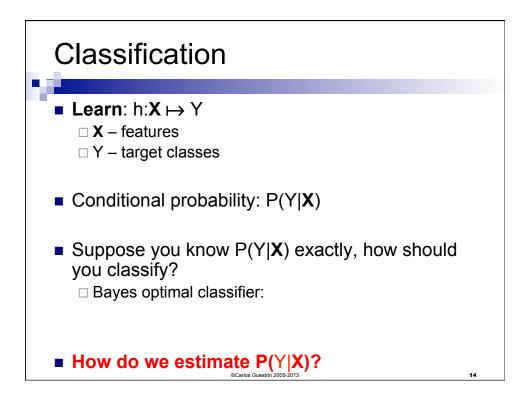
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Classification Logistic Regression Machine Learning – CSE446 Carlos Guestrin University of Washington April 15, 2013









Link Functions



■ Estimating P(Y|X): Why not use standard linear regression?

- Combing regression and probability?
 - □ Need a mapping from real values to [0,1]
 - □ A link function!

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Logistic Regression

Logistic function

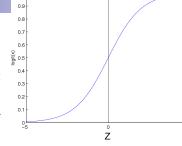
function (or Sigmoid):
$$\frac{1}{1 + exp(-z)}$$



Learn P(Y|X) directly

- ☐ Assume a particular functional form for link
- □ Sigmoid applied to a linear function of the input

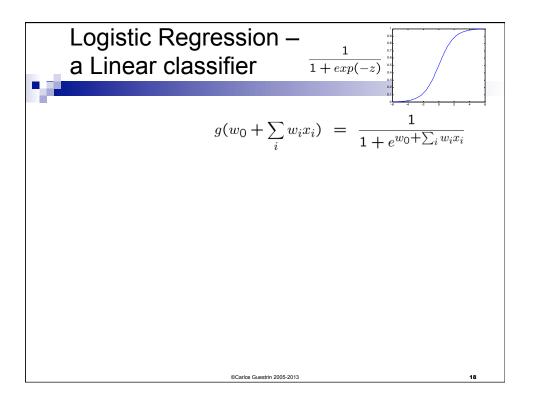
$$P(Y = 0|X, W) = \frac{1}{1 + exp(w_0 + \sum_i w_i X_i)}$$



Features can be discrete or continuous!

Understanding the sigmoid $g(w_0 + \sum_i w_i x_i) = \frac{1}{1 + e^{w_0 + \sum_i w_i x_i}}$ $w_0 = -2, w_1 = -1 \qquad w_0 = 0, w_1 = -1 \qquad w_0 = 0, w_1 = -0.5$

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Very convenient!

$$P(Y = 0 \mid X = \langle X_1, ... X_n \rangle) = \frac{1}{1 + exp(w_0 + \sum_i w_i X_i)}$$

implies

$$P(Y = 1 \mid X = < X_1, ... X_n >) = \frac{exp(w_0 + \sum_i w_i X_i)}{1 + exp(w_0 + \sum_i w_i X_i)}$$

implies

$$\frac{P(Y=1|X)}{P(Y=0|X)} = exp(w_0 + \sum_i w_i X_i)$$

linear classification rule!

implies

$$\ln \frac{P(Y = 1 | X)}{P(Y = 0 | X)} = w_0 + \sum_i w_i X_i$$

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Loss function: Conditional Likelihood



- Have a bunch of iid data of the form:
- Discriminative (logistic regression) loss function:
 Conditional Data Likelihood

$$\ln P(\mathcal{D}_Y \mid \mathcal{D}_{\mathbf{X}}, \mathbf{w}) = \sum_{j=1}^{N} \ln P(y^j \mid \mathbf{x}^j, \mathbf{w})$$

Expressing Conditional Log Likelihood

$$P(Y = 0|\mathbf{X}, \mathbf{w}) = \frac{1}{1 + exp(w_0 + \sum_i w_i X_i)}$$

$$l(\mathbf{w}) \equiv \sum_j \ln P(y^j | \mathbf{x}^j, \mathbf{w})$$

$$P(Y = 1|\mathbf{X}, \mathbf{w}) = \frac{exp(w_0 + \sum_i w_i X_i)}{1 + exp(w_0 + \sum_i w_i X_i)}$$

$$\ell(\mathbf{w}) = \sum_{j} y^{j} \ln P(Y = 1 | \mathbf{x}^{j}, \mathbf{w}) + (1 - y^{j}) \ln P(Y = 0 | \mathbf{x}^{j}, \mathbf{w})$$

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Maximizing Conditional Log Likelihood

$$l(\mathbf{w}) \equiv \ln \prod_{j} P(y^{j} | \mathbf{x}^{j}, \mathbf{w})$$

$$= \sum_{j} y^{j} (w_{0} + \sum_{i} w_{i} x_{i}^{j}) - \ln(1 + exp(w_{0} + \sum_{i} w_{i} x_{i}^{j}))$$

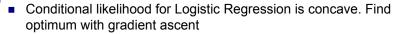
Good news: $I(\mathbf{w})$ is concave function of \mathbf{w} , no local optima problems

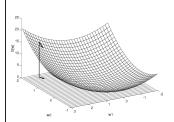
Bad news: no closed-form solution to maximize I(w)

Good news: concave functions easy to optimize

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Optimizing concave function – Gradient ascent





Gradient:
$$\nabla_{\mathbf{w}} l(\mathbf{w}) = [\frac{\partial l(\mathbf{w})}{\partial w_0}, \dots, \frac{\partial l(\mathbf{w})}{\partial w_n}]'$$

Step size, η>0

Update rule: $\Delta \mathbf{w} = \eta \nabla_{\mathbf{w}} l(\mathbf{w})$

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \frac{\partial l(\mathbf{w})}{\partial w_i}$$

- Gradient ascent is simplest of optimization approaches
 - □ e.g., Conjugate gradient ascent can be much better

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Maximize Conditional Log Likelihood: Gradient ascent



$$l(\mathbf{w}) = \sum_{j} y^{j} (w_{0} + \sum_{i}^{n} w_{i} x_{i}^{j}) - \ln(1 + exp(w_{0} + \sum_{i}^{n} w_{i} x_{i}^{j}))$$

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Gradient Ascent for LR



Gradient ascent algorithm: iterate until change < ε

$$w_0^{(t+1)} \leftarrow w_0^{(t)} + \eta \sum_j [y^j - \hat{P}(Y^j = 1 \mid \mathbf{x}^j, \mathbf{w}^{(t)})]$$

For i=1,...,n,
$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \sum_j x_i^j [y^j - \hat{P}(Y^j = 1 \mid \mathbf{x}^j, \mathbf{w}^{(t)})]$$

repeat

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Regularization in linear regression



Overfitting usually leads to very large parameter choices, e.g.:





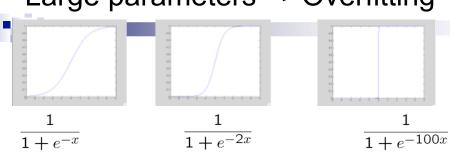
Regularized least-squares (a.k.a. ridge regression), for λ>0:

$$\mathbf{w}^* = \arg\min_{\mathbf{w}} \sum_{j} \left(t(\mathbf{x}_j) - \sum_{i} w_i h_i(\mathbf{x}_j) \right)^2 + \lambda \sum_{i=1}^k w_i^2$$

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Large parameters → Overfitting



- If data is linearly separable, weights go to infinity
- Leads to overfitting:
- Penalizing high weights can prevent overfitting...

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Regularized Conditional Log Likelihood



■ Add regularization penalty, e.g., L₂:

$$\ell(\mathbf{w}) = \ln \prod_{j} P(y^{j} | \mathbf{x}^{j}, \mathbf{w})) - \lambda ||\mathbf{w}||_{2}^{2}$$

- Practical note about w₀:
- Gradient of regularized likelihood:

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Standard v. Regularized Updates



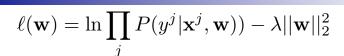
$$\begin{split} \mathbf{w}^* &= \arg\max_{\mathbf{w}} \ln \left[\prod_{j=1}^N P(y^j \mid \mathbf{x}^j, \mathbf{w}) \right] \\ w_i^{(t+1)} &\leftarrow w_i^{(t)} + \eta \sum_j x_i^j [y^j - \hat{P}(Y^j = \mathbf{1} \mid \mathbf{x}^j, \mathbf{w}^{(t)})] \end{split}$$

Regularized maximum conditional likelihood estimate

$$\mathbf{w}^* = \arg \max_{\mathbf{w}} \ln \left[\prod_{j} P(y^j | \mathbf{x}^j, \mathbf{w}) \right] - \lambda \sum_{i>0} w_i^2$$

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \left\{ -\lambda w_i^{(t)} + \sum_{j} x_i^j [y^j - \hat{P}(Y^j = 1 \mid \mathbf{x}^j, \mathbf{w}^{(t)})] \right\}$$

Please Stop!! Stopping criterion



- When do we stop doing gradient descent?
- Because *l*(**w**) is strongly concave:
 - □ i.e., because of some technical condition

$$\ell(\mathbf{w}^*) - \ell(\mathbf{w}) \le \frac{1}{2\lambda} ||\nabla \ell(\mathbf{w})||_2^2$$

Thus, stop when:

Stopping criterion



$$\ell(\mathbf{w}) = \ln \prod_{j} P(y^j | \mathbf{x}^j, \mathbf{w})) - \lambda ||\mathbf{w}||_2^2$$

- Regularized logistic regression is strongly concave
 - □ Negative second derivative bounded away from zero:
- Strong concavity (convexity) is super helpful!!
- For example, for strongly concave *l*(**w**):

$$\ell(\mathbf{w}^*) - \ell(\mathbf{w}) \le \frac{1}{2\lambda} ||\nabla \ell(\mathbf{w})||_2^2$$

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Convergence rates for gradient descent/ascent



Number of Iterations to get to accuracy

$$\ell(\mathbf{w}^*) - \ell(\mathbf{w}) \le \epsilon$$

- If func Lipschitz: $O(1/\epsilon^2)$
- If gradient of func Lipschitz: O(1/ε)
- If func is strongly convex: O(ln(1/є))

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Digression: Logistic regression for more than 2 classes



 Logistic regression in more general case (k+1 classes), where Y in {y₁,...,y_R}

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Digression: Logistic regression more generally



Logistic regression in more general case, where
 Y in {y₁,...,y_R}

for k<R

$$P(Y = y_k | X) = \frac{\exp(w_{k0} + \sum_{i=1}^{n} w_{ki} X_i)}{1 + \sum_{j=1}^{R-1} \exp(w_{j0} + \sum_{i=1}^{n} w_{ji} X_i)}$$

for k=R (normalization, so no weights for this class)

$$P(Y = y_R | X) = \frac{1}{1 + \sum_{j=1}^{R-1} \exp(w_{j0} + \sum_{i=1}^{n} w_{ji} X_i)}$$

Learning procedure is basically the same as what we derived!

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What you should know...



- Classification: predict discrete classes rather than real values
- Logistic regression model: Linear model

 □ Logistic function maps real values to [0,1]
- Optimize conditional likelihood
- Gradient computation
- Overfitting
- Regularization
- Regularized optimization

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