Lecture 22:

Friday, November 22, 2002

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Outline

• Query execution: 15.1 – 15.5

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Two-Pass Algorithms Based on Sorting

• Recall: multi-way merge sort needs only two passes!

Assumption: B(R) <= M²
Cost for sorting: 3B(R)

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Two-Pass Algorithms Based on Sorting

Duplicate elimination $\delta(R)$

- · Trivial idea: sort first, then eliminate duplicates
- Step 1: sort chunks of size M, write cost 2B(R)
- Step 2: merge M-1 runs, but include each tuple only once
 - cost B(R)
- Total cost: 3B(R), Assumption: B(R) <= M²

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Two-Pass Algorithms Based on Sorting

Grouping: $\gamma_{a, sum(b)}(R)$

- Same as before: sort, then compute the sum(b) for each group of a's
- Total cost: 3B(R)
- Assumption: $B(R) \le M^2$

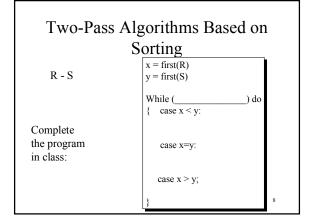
Sorting $\begin{array}{c}
x = first(R) \\
y = first(S)
\end{array}$ While (______) do

Two-Pass Algorithms Based on

Complete the program in class:

While (______) do { case x < y: output(x) x = next(R) case x=y: case x > y; }

Two-Pass Algorithms Based on Sorting $R \cap S \qquad \begin{array}{c} x = first(R) \\ y = first(S) \\ \end{array}$ While $(\underline{\hspace{0.5cm}})$ do (ab) case x < y: Complete the program in class: (ab) case x > y; (ab)



Two-Pass Algorithms Based on Sorting

Binary operations: $R \cup S$, $R \cap S$, R - S

- Idea: sort R, sort S, then do the right thing
- · A closer look:
 - Step 1: split R into runs of size M, then split S into runs of size M. Cost: 2B(R) + 2B(S)
 - Step 2: merge M/2 runs from R; merge M/2 runs from S; ouput a tuple on a case by cases basis
- Total cost: 3B(R)+3B(S)
- Assumption: $B(R)+B(S) \le M^2$

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Two-Pass Algorithms Based on Sorting

Join $R \bowtie S$

- Start by sorting both R and S on the join attribute:

 Cost: 4B(R)+4B(S) (because need to write to disk)
- Read both relations in sorted order, match tuples
 Cost: B(R)+B(S)
- · Difficulty: many tuples in R may match many in S
 - If at least one set of tuples fits in M, we are OK
 - Otherwise need nested loop, higher cost
- Total cost: 5B(R)+5B(S)
- Assumption: $B(R) \le M^2$, $B(S) \le M^2$

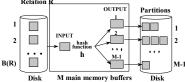
Two-Pass Algorithms Based on Sorting

Join $R \bowtie S$

- If the number of tuples in R matching those in S is small (or vice versa) we can compute the join during the merge phase
- Total cost: 3B(R)+3B(S)
- Assumption: $B(R) + B(S) \le M^2$

Two Pass Algorithms Based on Hashing

- · Idea: partition a relation R into buckets, on disk
- Each bucket has size approx. B(R)/M



- Does each bucket fit in main memory?
 - Yes if $B(R)/M \le M$, i.e. $B(R) \le M^2$

Hash Based Algorithms for δ

- Recall: $\delta(R)$ = duplicate elimination
- Step 1. Partition R into buckets
- Step 2. Apply δ to each bucket (may read in main memory)
- Cost: 3B(R)
- Assumption:B(R) <= M²

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Hash Based Algorithms for γ

- Recall: $\gamma(R)$ = grouping and aggregation
- Step 1. Partition R into buckets
- Step 2. Apply γ to each bucket (may read in main memory)
- Cost: 3B(R)
- Assumption:B(R) \leq M²

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Partitioned Hash Join

$R \bowtie S$

- Step 1:
 - Hash S into M buckets
 - send all buckets to disk
- Step 2
 - Hash R into M buckets
 - Send all buckets to disk
- Step 3
 - Join every pair of buckets

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Original Relation Hash-Join OUTPUT Partition both relations using hash fn \mathbf{h} : R tuples in partition i will ... only match S tuples in partition i. Disk Disk B main memory buffers Partitions Join Result of R & S Hash table for partition Si (< M-1 pages) Read in a partition of R, hash it using h2 (<> h!). Scan matching partition ... of S. search for matches. B main memory buffers Disk

Partitioned Hash Join

• Cost: 3B(R) + 3B(S)

• Assumption: $min(B(R), B(S)) \le M^2$

Hybrid Hash Join Algorithm

- · Partition S into k buckets
- But keep first bucket S_1 in memory, k-1 buckets to disk
- Partition R into k buckets
 - First bucket R₁ is joined immediately with S₁
 - Other k-1 buckets go to disk
- Finally, join k-1 pairs of buckets:
 - $-(R_2,S_2), (R_3,S_3), ..., (R_k,S_k)$

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Hybrid Join Algorithm

- How big should we choose k?
- Average bucket size for S is B(S)/k
- Need to fit B(S)/k + (k-1) blocks in memory
 - $-B(S)/k + (k-1) \le M$
 - k slightly smaller than B(S)/M

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Hybrid Join Algorithm

- · How many I/Os?
- Recall: cost of partitioned hash join:
 3B(R) + 3B(S)
- Now we save 2 disk operations for one bucket
- Recall there are k buckets
- Hence we save 2/k(B(R) + B(S))
- Cost: (3-2/k)(B(R) + B(S)) = (3-2M/B(S))(B(R) + B(S))

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Hybrid Join Algorithm

• Question in class: what is the real advantage of the hybrid algorithm ?

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Indexed Based Algorithms

• Recall that in a clustered index all tuples with the same value of the key are clustered on as few blocks as possible

aaa aaaaa aa

 Note: book uses another term: "clustering index". Difference is minor...

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Index Based Selection

- Selection on equality: $\sigma_{a=v}(R)$
- Clustered index on a: cost B(R)/V(R,a)
- Unclustered index on a: cost T(R)/V(R,a)

Index Based Selection

- Example: B(R) = 2000, T(R) = 100,000, V(R, a) = 20, compute the cost of $\sigma_{a=v}(R)$
- · Cost of table scan:
 - If R is clustered: B(R) = 2000 I/Os
 - If R is unclustered: T(R) = 100,000 I/Os
- · Cost of index based selection:
 - If index is clustered: B(R)/V(R,a) = 100
 - If index is unclustered: T(R)/V(R,a) = 5000
- Notice: when V(R,a) is small, then unclustered index is useless

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Index Based Join

- R ⋈ S
- Assume S has an index on the join attribute
- Iterate over R, for each tuple fetch corresponding tuple(s) from S
- Assume R is clustered. Cost:
 - If index is clustered: B(R) + T(R)B(S)/V(S,a)
 - If index is unclustered: B(R) + T(R)T(S)/V(S,a)

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Index Based Join

- Assume both R and S have a sorted index (B+ tree) on the join attribute
- Then perform a merge join (called zig-zag join)
- Cost: B(R) + B(S)

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Questions in Class

- B(Product), B(Company) are large
- Which join method would you use?
- Consider:
 - 10 bozos
 - v.s. 100...0
 - 10 cool
 - companies

v.s. 100...00

SELECT Product.name, Company.city

FROM Product, Company

WHERE Product.maker = Company.name and Product.category = 'bozo' and

Company.rating = 'cool'