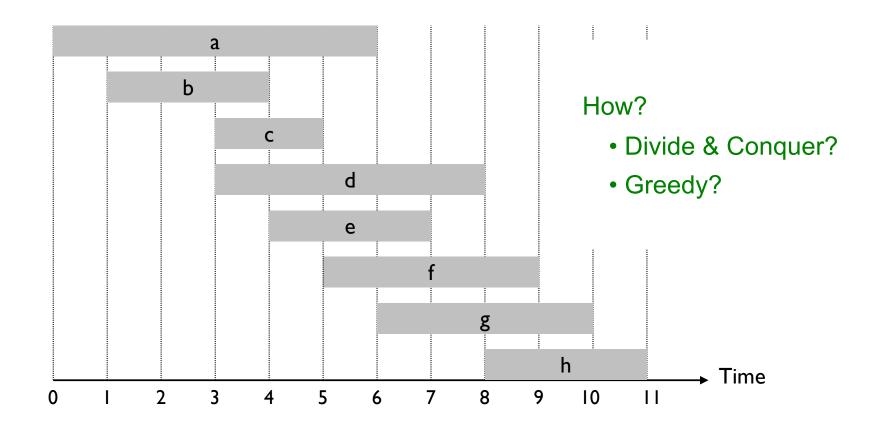
Dynamic Programming: Interval Scheduling and Knapsack

6.1 Weighted Interval Scheduling

Weighted Interval Scheduling

Weighted interval scheduling problem.

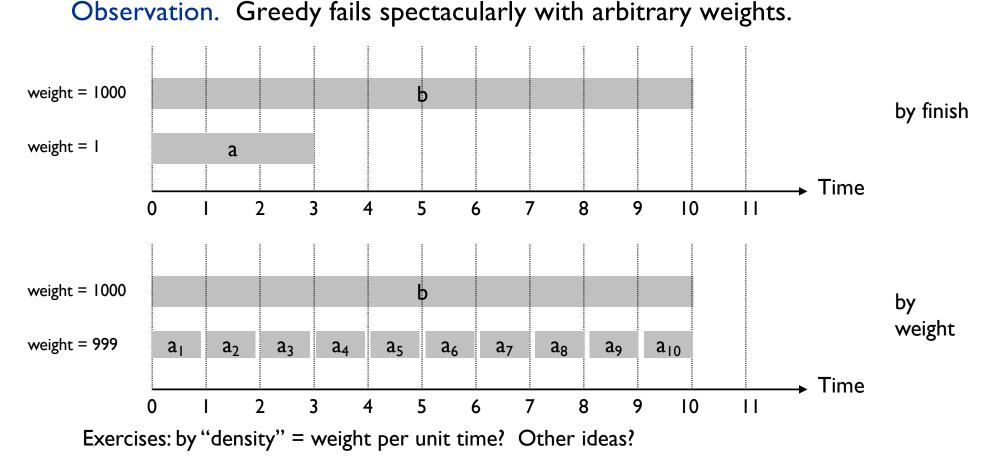
- Job j starts at s_j, finishes at f_j, and has weight or value v_j.
 Two jobs compatible if they don't overlap.
- Goal: find <u>maximum weight</u> subset of mutually compatible jobs.



Unweighted Interval Scheduling Review

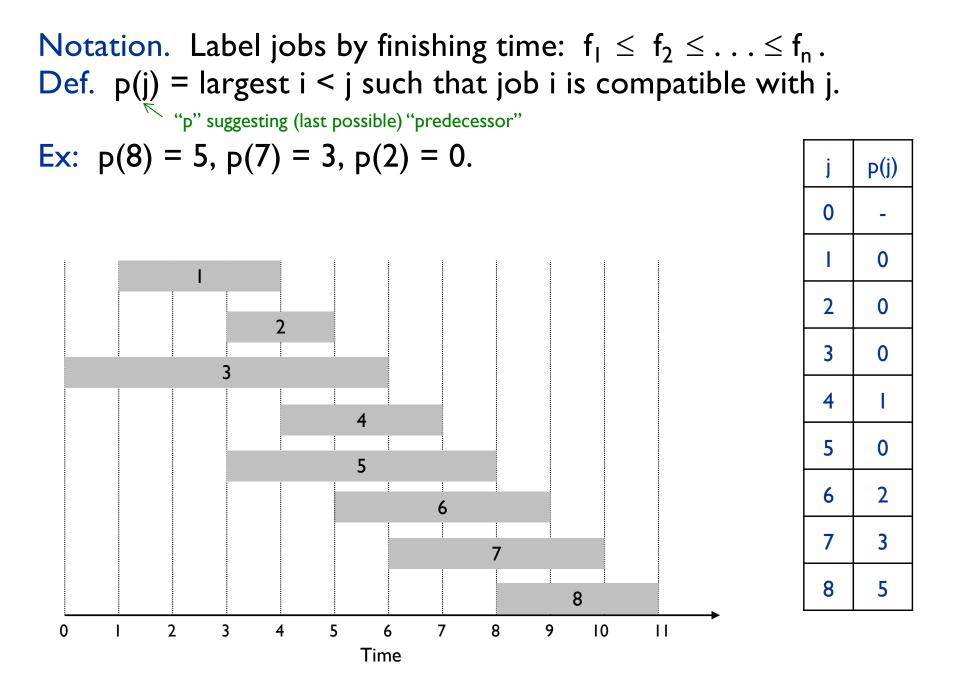
Recall. Greedy algorithm works if all weights are 1.

- Consider jobs in ascending order of finish time.
- Keep job if compatible with previously chosen jobs.



9

Weighted Interval Scheduling



Dynamic Programming: Binary Choice

Notation. OPT(j) = value of optimal solution to the problem consisting of job requests 1, 2, ..., j. key idea:

- Case I: Optimum selects job j.
 can't use incompatible jobs { p(j) + 1, p(j) + 2, ..., j 1 }
- \rightarrow must include optimal solution to problem consisting of remaining compatible jobs 1, 2, ..., p(j)

principle of optimality

- Case 2: Optimum does not select job j.
- must include optimal solution to problem consisting of remaining compatible jobs 1, 2, ..., j-1

$$OPT(j) = \begin{cases} 0 & \text{if } j = 0\\ \max \{ v_j + OPT(p(j)), OPT(j-1) \} & \text{otherwise} \end{cases}$$

Weighted Interval Scheduling: Brute Force Recursion

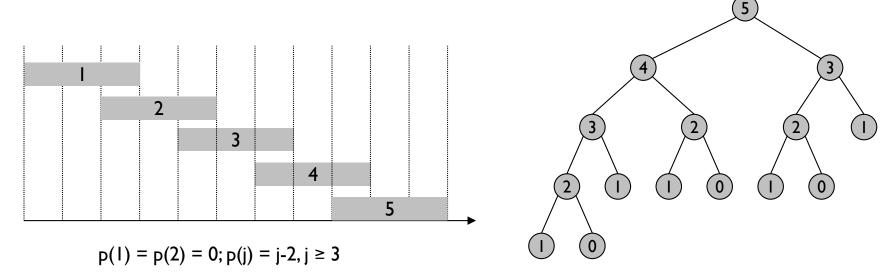
Brute force recursive algorithm.

```
Input: n, s<sub>1</sub>,...,s<sub>n</sub>, f<sub>1</sub>,...,f<sub>n</sub>, v<sub>1</sub>,...,v<sub>n</sub>
Sort jobs by finish times so that f_1 \leq f_2 \leq \ldots \leq f_n.
Compute p(1), p(2), ..., p(n)
Compute-Opt(j) {
    if (j = 0)
        return 0
    else
        return max(v<sub>j</sub> + Compute-Opt(p(j)), Compute-Opt(j-1))
}
```

Weighted Interval Scheduling: Brute Force

Observation. Recursive algorithm is correct, but spectacularly slow because of redundant sub-problems \Rightarrow exponential time.

Ex. Number of recursive calls for family of "layered" instances grows like Fibonacci sequence.



Weighted Interval Scheduling: Bottom-Up

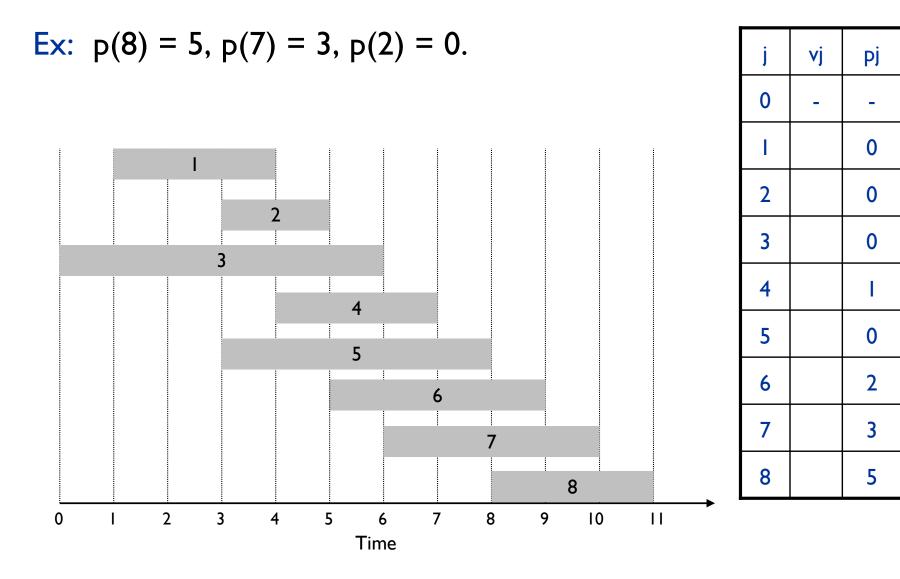
Bottom-up dynamic programming. Unwind recursion.

```
Input: n, s_1, ..., s_n, f_1, ..., f_n, v_1, ..., v_n
Sort jobs by finish times so that f_1 \leq f_2 \leq ... \leq f_n.
Compute p(1), p(2), ..., p(n)
Iterative-Compute-Opt {
    OPT[0] = 0
    for j = 1 to n
        OPT[j] = max(v<sub>j</sub> + OPT[p(j)], OPT[j-1])
}
```

Claim: OPT[j] is value of optimal solution for jobs 1..j Timing: Loop is O(n); sort is $O(n \log n)$; what about p(j)?

Weighted Interval Scheduling

Notation. Label jobs by finishing time: $f_1 \leq f_2 \leq \ldots \leq f_n$. Def. p(j) = largest i < j such that job i is compatible with j.

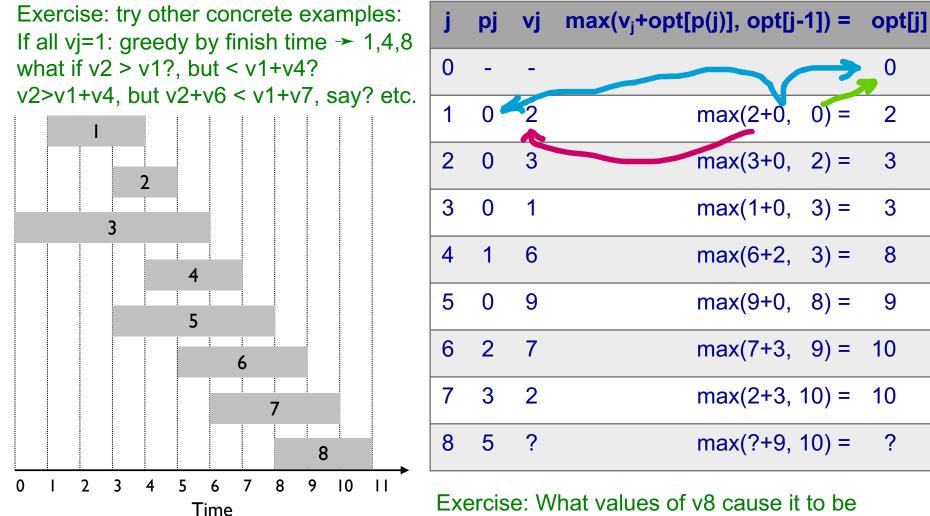


optj

0

Weighted Interval Scheduling Example

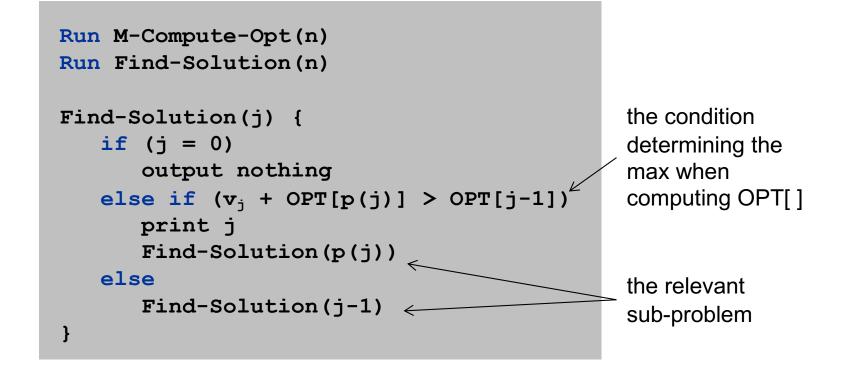
Label jobs by finishing time: $f_1 \leq f_2 \leq \ldots \leq f_n$. p(j) = largest i < j s.t. job i is compatible with j.



in/ex-cluded from opt?

Weighted Interval Scheduling: Finding a Solution

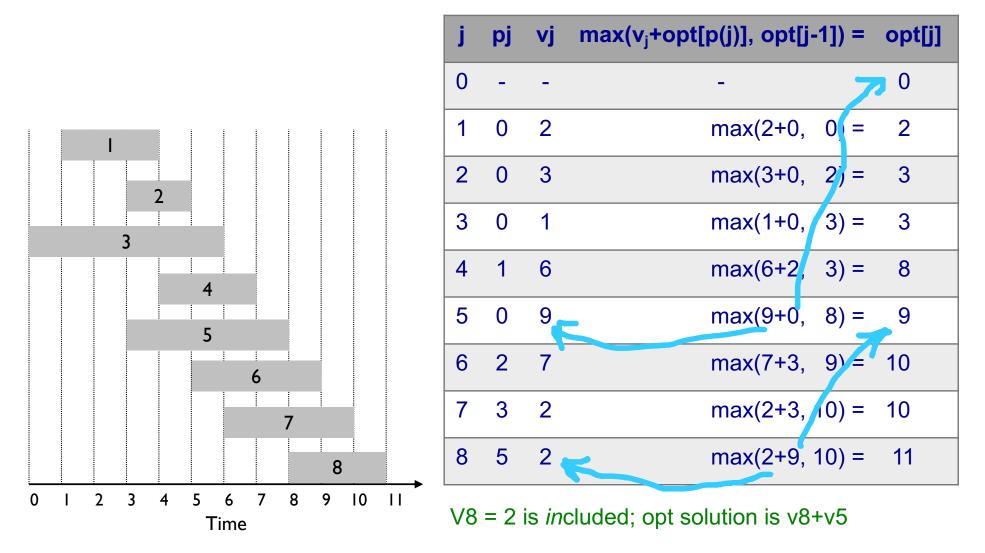
- Q. Dynamic programming algorithms computes optimal value. What if we want the solution itself?
- A. Do some post-processing "traceback"



• # of recursive calls $\leq n \implies O(n)$.

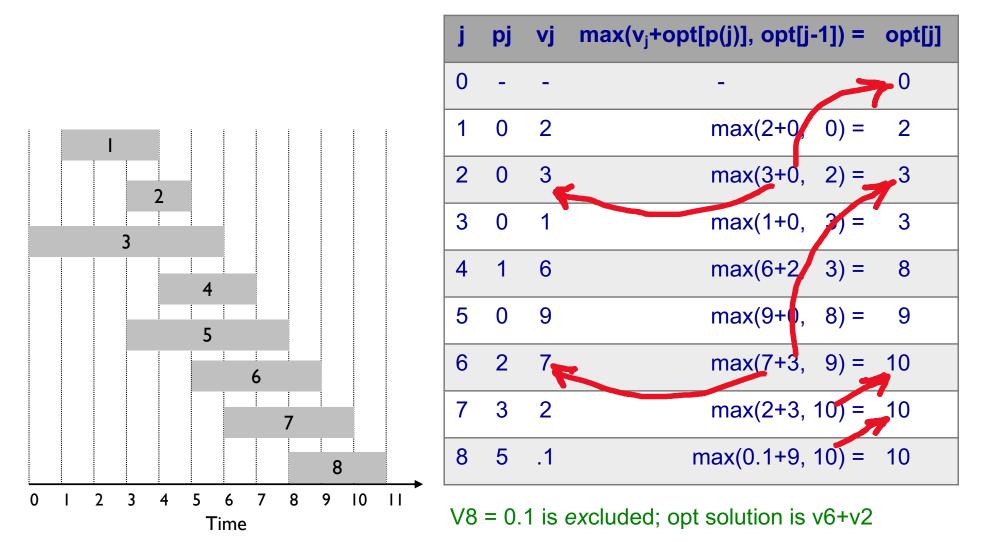
Weighted Interval Scheduling Example

Label jobs by finishing time: $f_1 \le f_2 \le \ldots \le f_n$. p(j) = largest i < j s.t. job i is compatible with j.



Weighted Interval Scheduling Example

Label jobs by finishing time: $f_1 \le f_2 \le \ldots \le f_n$. p(j) = largest i < j s.t. job i is compatible with j.



Sidebar: why does job ordering matter?

It's *Not* for the same reason as in the greedy algorithm for unweighted interval scheduling.

Instead, it's because it allows us to consider only a small number of subproblems (O(n)), vs the exponential number that seem to be needed if the jobs aren' t ordered (seemingly, *any* of the 2ⁿ possible subsets might be relevant)

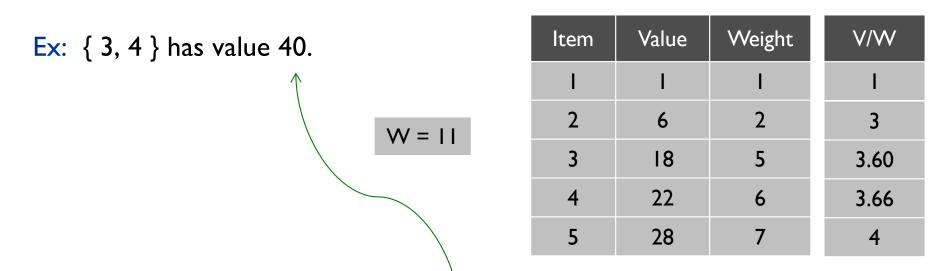
Don't believe me? Think about the analogous problem for weighted *rectangles* instead of intervals... (I.e., pick max weight non-overlapping subset of a set of axisparallel rectangles.) Same problem for squares or circles also appears difficult.

6.4 Knapsack Problem

Knapsack Problem

Knapsack problem.

- Given n objects and a "knapsack."
- Item i weighs $w_i > 0$ kilograms and has value $v_i > 0$.
- Knapsack has capacity of W kilograms.
- Goal: maximize total value without overfilling knapsack



Greedy: repeatedly add item with maximum ratio v_i / w_i . Ex: { 5, 2, 1 } achieves only value = $35 \Rightarrow$ greedy not optimal. [NB greedy is optimal for "fractional knapsack": take #5 + 4/6 of #4]

Dynamic Programming: False Start

Def. OPT(i) = max profit subset of items 1, ..., i.

- Case I: OPT does not select item i.
 OPT selects best of { 1, 2, ..., i-1 } binary choice
- Case 2: OPT selects item i.
 accepting item 1 does not immediately imply that we will have to reject other items
 - without knowing what other items were selected before
 i, we don't even know if we have enough room for i

Conclusion. Need more sub-problems!

$$OPT(i,w) = \begin{cases} 0 & \text{if } i = 0\\ OPT(i-1,w) & \text{if } w_i > w\\ \max \left\{ OPT(i-1,w), v_i + OPT(i-1,w-w_i) \right\} & \text{otherwise} \end{cases}$$

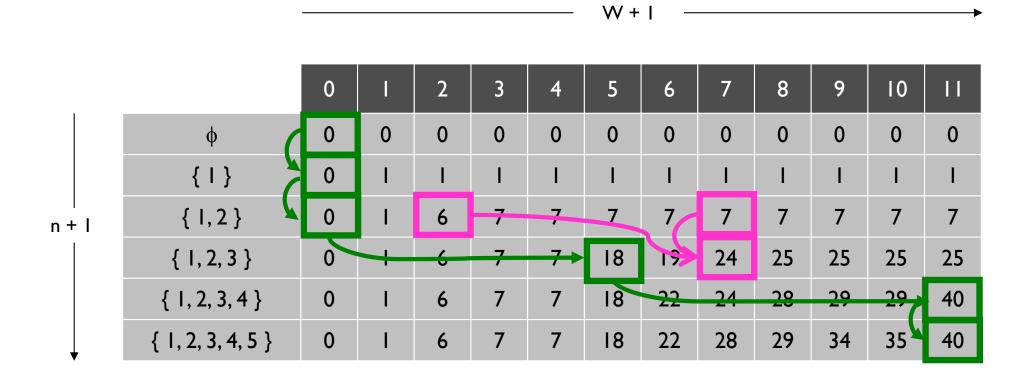
Knapsack Problem: Bottom-Up

OPT(i, w) = max profit from subset of items 1, ..., i with weight limit w.

```
Input: n, w<sub>1</sub>,...,w<sub>n</sub>, v<sub>1</sub>,...,v<sub>n</sub>
for w = 0 to W
    OPT[0, w] = 0
for i = 1 to n
    for w = 1 to W
        if (w<sub>i</sub> > w)
            OPT[i, w] = OPT[i-1, w]
        else
            OPT[i, w] = max {OPT[i-1, w], v<sub>i</sub> + OPT[i-1, w-w<sub>i</sub>]}
return OPT[n, W]
```

(Correctness: prove it by induction on i & w.)

Knapsack Algorithm



OPT: { 4, 3 } value = 22 + 18 = 40	ltem	Value	Weight
	I	I	I
	2	6	2
<pre>if (w_i > w) OPT[i, w] = OPT[i-1, w] else</pre>	3	18	5
	4	22	6
OPT[i, w] = max{OPT[i-1,w], v_i +OPT[i-1, w- w_i]}	5	28	7

Knapsack Problem: Running Time

Running time. $\Theta(n W)$.

- If W is "small' this is fine, but in worst case...
- Not polynomial in input size! ("W" takes only log₂W bits)
- Called "Pseudo-polynomial"
- Knapsack is NP-hard. [Chapter 8]

Knapsack approximation algorithm [Section 11.8].

Good News: There exists a polynomial time algorithm that produces a feasible solution (i.e., satisfies weight-limit constraint) that has value within 0.01% (or any other desired factor ε) of optimum.

Bad News: as ε goes down, polynomial goes up.