Pipelining

CSE 410, Spring 2004
Computer Systems

http://www.cs.washington.edu/education/courses/410/04sp/

Reading and References

• Sections 6.1-6.3, *Computer Organization and Design*, Patterson and Hennessy

Execution Cycle

1. Instruction Fetch
   » Get the next instruction from memory
   » Increment Program Counter value by 4
2. Instruction Decode
   » Figure out what the instruction says to do
   » Get values from the named registers
   » Simple instruction format means we know which registers we may need before the instruction is fully decoded

IF and ID Stages

1. Instruction Fetch
2. Instruction Decode
3. Execute
4. Memory
5. Write Back
## Simple MIPS Instruction Formats

### R Format

<table>
<thead>
<tr>
<th>op code</th>
<th>source 1</th>
<th>source 2</th>
<th>dest</th>
<th>shamt</th>
<th>function</th>
</tr>
</thead>
<tbody>
<tr>
<td>6 bits</td>
<td>5 bits</td>
<td>5 bits</td>
<td>5 bits</td>
<td>5 bits</td>
<td>6 bits</td>
</tr>
</tbody>
</table>

### I Format

<table>
<thead>
<tr>
<th>op code</th>
<th>base reg</th>
<th>src/dest</th>
<th>offset or immediate value</th>
</tr>
</thead>
<tbody>
<tr>
<td>6 bits</td>
<td>5 bits</td>
<td>5 bits</td>
<td>16 bits</td>
</tr>
</tbody>
</table>

### J Format

<table>
<thead>
<tr>
<th>op code</th>
<th>word offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>6 bits</td>
<td>26 bits</td>
</tr>
</tbody>
</table>

## EX, MEM, and WB stages

3. **Execute**
   - On a memory reference, add up base and offset
   - On an arithmetic instruction, do the math

4. **Memory Access**
   - If load or store, access memory
   - If branch, replace PC with destination address
   - Otherwise do nothing

5. **Write back**
   - Place the results in the appropriate register

## Example: add $s0, $s1, $s2

- **IF** get instruction at PC from memory
  - op code | source 1 | source 2 | dest | shamt | function |
  - 000000 | 10001   | 10010   | 10000 | 00000 | 100000 |

- **ID** determine what instruction is and read registers
  - 000000 with 100000 is the add instruction
  - get contents of $s1 and $s2 (eg: $s1=7, $s2=12)

- **EX** add 7 and 12 = 19

- **MEM** do nothing for this instruction

- **WB** store 19 in register $s0

## Example: lw $t2, 16($s0)

- **IF** get instruction at PC from memory
  - op code | base reg | src/dest | offset or immediate value |
  - 010111   | 10000 | 01000   | 0000000000010000 |

- **ID** determine what 010111 is
  - 010111 is lw
    - get contents of $s0 and $t2 (we don’t know that we don’t care about $t2)
      - $s0=0x200D1C00, $t2=77763

- **EX** add 16 to 0x200D1C00 = 0x200D1C10

- **MEM** load the word stored at 0x200D1C10

- **WB** store loaded value in $t2
Latency & Throughput

1 2 3 4 5 6 7 8 9 10
IF ID EX MEM WB
IF ID EX MEM WB

Latency—the time it takes for an individual instruction to execute
What’s the latency for this implementation?
One instruction takes 5 clock cycles
Cycles per Instruction (CPI) = 5

Throughput—the number of instructions that execute per unit time
What’s the throughput of this implementation?
One instruction is completed every 5 clock cycles
Average CPI = 5

A case for pipelining

• If execution is non-overlapped, the functional units are underutilized because each unit is used only once every five cycles
• If Instruction Set Architecture is carefully designed, organization of the functional units can be arranged so that they execute in parallel
• Pipelining overlaps the stages of execution so every stage has something to do each cycle

Pipelined Latency & Throughput

1 2 3 4 5 6 7 8 9
IF ID EX MEM WB
IF ID EX MEM WB
IF ID EX MEM WB
IF ID EX MEM WB
IF ID EX MEM WB

What’s the latency of this implementation?
What’s the throughput of this implementation?

Pipelined Analysis

• A pipeline with N stages could improve throughput by N times, but
  » each stage must take the same amount of time
  » each stage must always have work to do
  » there may be some overhead to implement
• Also, latency for each instruction may go up
  » Within some limits, we don’t care
Throughput is good!

MIPS ISA: Born to Pipeline

- Instructions all one length
  » simplifies Instruction Fetch stage
- Regular format
  » simplifies Instruction Decode
- Few memory operands, only registers
  » only lw and sw instructions access memory
- Aligned memory operands
  » only one memory access per operand

Memory accesses

- Efficient pipeline requires each stage to take about the same amount of time
- CPU is much faster than memory hardware
- Cache is provided on chip
  » i-cache holds instructions
  » d-cache holds data
  » critical feature for successful RISC pipeline
  » more about caches next week

The Hazards of Parallel Activity

- Any time you get several things going at once, you run the risk of interactions and dependencies
  » juggling doesn’t take kindly to irregular events
- Unwinding activities after they have started can be very costly in terms of performance
  » drop everything on the floor and start over
Design for Speed

• Most of what we talk about next relates to the CPU hardware itself
  » problems keeping a pipeline full
  » solutions that are used in the MIPS design
• Some programmer visible effects remain
  » many are hidden by the assembler or compiler
  » the code that you write tells what you want done, but the tools rearrange it for speed

Pipeline Hazards

• Structural hazards
  » Instructions in different stages need the same resource, eg, memory
• Data hazards
  » data not available to perform next operation
• Control hazards
  » data not available to make branch decision

Structural Hazards

• Concurrent instructions want same resource
  » \texttt{lw} instruction in stage four (memory access)
  » \texttt{add} instruction in stage one (instruction fetch)
  » Both of these actions require access to memory; they would collide if not designed for
• Add more hardware to eliminate problem
  » separate instruction and data caches
• Or stall (cheaper & easier), not usually done

Data Hazards

• When an instruction depends on the results of a previous instruction still in the pipeline
• This is a data dependency

\texttt{add \$s0, \$s1, \$s2}

\begin{tabular}{c|c|c|c|c|c}
 & IF & ID & EX & MEM & WB \\
\hline
\$s0\ is\ written\ here
\end{tabular}

\texttt{add \$s4, \$s3, \$s0}

\begin{tabular}{c|c|c|c|c|c}
 & IF & ID & EX & MEM & WB \\
\hline
\$s0\ is\ read\ here
\end{tabular}
Stall for register data dependency

- Stall the pipeline until the result is available
  » this would create a 3-cycle pipeline bubble

\[
\text{IF} \quad \text{ID} \quad \text{EX} \quad \text{MEM} \quad \text{WB}
\]
\[
\text{IF} \quad \text{stall} \quad \text{ID} \quad \text{EX} \quad \text{MEM} \quad \text{WB}
\]

Read & Write in same Cycle

- Write the register in the first part of the clock cycle
- Read it in the second part of the clock cycle
- A 2-cycle stall is still required

\[
\text{IF} \quad \text{ID} \quad \text{EX} \quad \text{MEM} \quad \text{WB}
\]

Solution: Forwarding

- The value of $s0$ is known internally after cycle 3
  (after the first instruction’s EX stage)
- The value of $s0$ isn’t needed until cycle 4 (before the second instruction’s EX stage)
- If we forward the result there isn’t a stall

\[
\text{IF} \quad \text{ID} \quad \text{EX} \quad \text{MEM} \quad \text{WB}
\]

Another data hazard

- What if the first instruction is lw?
- $s0$ isn’t known until after the MEM stage
  » We can’t forward back into the past
- Either stall or reorder instructions

\[
\text{IF} \quad \text{ID} \quad \text{EX} \quad \text{MEM} \quad \text{WB}
\]
Z stall for \texttt{lw} hazard

- We can stall for one cycle, but we hate to stall

\begin{center}
\begin{tabular}{c|c|c|c|c|c|c}
  & IF & ID & EX & MEM & WB \\
\hline
\texttt{lw} s0,0(s2) & & & & & \\
\texttt{add} s4,s3,s0 & & & & & \\
\end{tabular}
\end{center}

\textit{Instruction Reorder for \texttt{lw} hazard}

- Try to execute an unrelated instruction between the two instructions

\begin{center}
\begin{tabular}{c|c|c|c|c|c|c}
  & IF & ID & EX & MEM & WB \\
\hline
\texttt{lw} s0,0(s2) & & & & & \\
\texttt{sub} t4,t2,t3 & & & & & \\
\texttt{add} s4,s3,s0 & & & & & \\
\texttt{sub} t4,t2,t3 & & & & & \\
\end{tabular}
\end{center}

\textbf{Reordering Instructions}

- Reordering instructions is a common technique for avoiding pipeline stalls
- Static reordering
  - programmer, compiler and assembler do this
- Dynamic reordering
  - modern processors can see several instructions
  - they execute any that have no dependency
  - this is known as \textit{out-of-order execution} and is complicated to implement, but effective