



# CSE 401 – Compilers

Lecture 24: SSA, cont.

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Winter 2013



## Reminders



- Project Part 4 due on Friday, March 15.
- There will be a short project report due on Sunday, March 17 – at most **one** late day may be used for the report (if you have any left).
  - One-two pages
  - See posted assignment
- Guest lectures Wednesday and Friday
  - Wednesday: Real world parsing, David Mizell, YarcData (Cray)
  - Friday: Register allocation, Preston Briggs, UW/PNNL



## Review: SSA Form



```
if (...)  
  a = x;  
else  
  a = y;  
b = a;
```



```
if (...)  
  a1 = x;  
else  
  a2 = y;  
a3 =  $\Phi(a_1, a_2)$ ;  
b1 = a3;
```

- An IR where each variable has exactly one definition
  - Within a basic block, this is easy – simply need to create a new variable (by renumbering) at each definition.
  - At program merge points, add  $\Phi$ -functions



## Converting To SSA Form



- Basic idea
  - First, add  $\Phi$ -functions
  - Then, rename all definitions and uses of variables by adding subscripts
- Renaming is straightforward. Inserting  $\Phi$ -functions is where things get a little tricky.



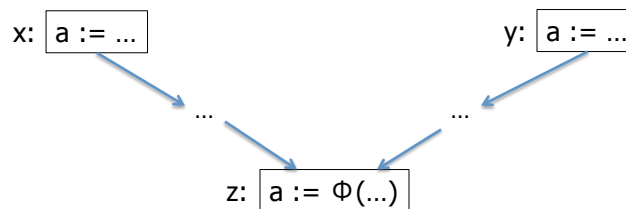
## Inserting $\Phi$ -Functions



- Could simply add  $\Phi$ -functions for every variable at every join point
- But
  - Wastes way too much space and time
  - Not needed



## When to Insert a $\Phi$ -Function



- We need a  $\Phi$ -function for variable  $a$  at entry to block  $z$  whenever
  - There are blocks  $x$  and  $y$ , both containing definitions of  $a$ , and  $x \neq y$
  - There are nonempty paths from  $x$  to  $z$  and from  $y$  to  $z$
  - These paths have no common nodes other than  $z$ 
    - i.e., this is where the paths first merge



## Some Details



- The start node of the control flow graph is considered to define every variable (possibly just to Undefined)
  - Makes following construction simpler
- Each  $\Phi$ -function itself defines a variable, which may create the need for a new  $\Phi$ -function.
  - So we need to keep adding  $\Phi$ -functions until things converge (no more changes).
- How do we do this efficiently?
  - Using a new concept: dominance



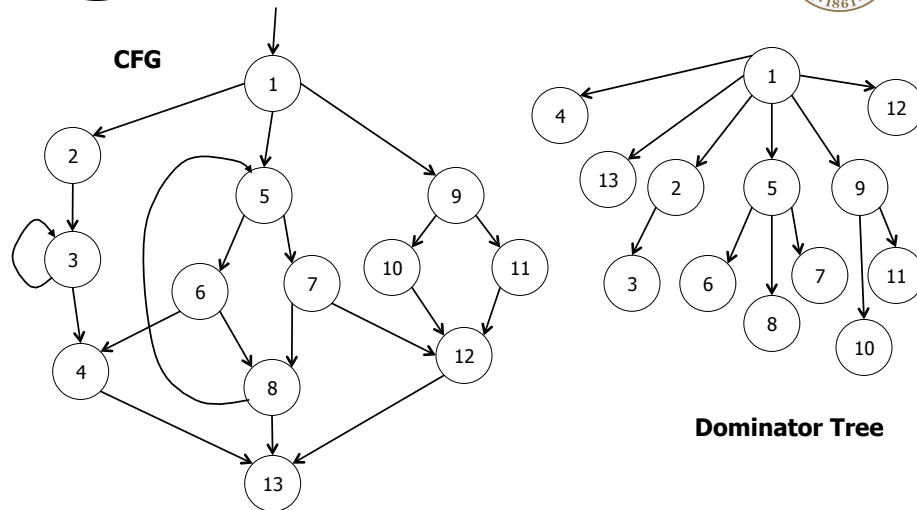
## Dominators



- Definition
  - A block  $x$  *dominates* a block  $y$  if and only if every path from the entry of the control-flow graph to  $y$  includes  $x$
- By definition,  $x$  dominates  $x$
- We can associate a  $\text{Dom}(inator)$  set with each CFG node
  - The set of all basic blocks that must execute before  $x$
  - $|\text{Dom}(x)| \geq 1$
- Properties:
  - Transitive: if  $a \text{ dom } b$  and  $b \text{ dom } c$ , then  $a \text{ dom } c$
  - No cycles, thus can view dominators a tree



## Example



## Dominators and SSA



- Important property of SSA: definitions must dominate uses
  - In other words, the single assignment must occur prior to any uses of the variable. (Although that single assignment may just be the start node assignment of "Undefined".)
- More specifically:
  - If  $x := \Phi(\dots, x_i, \dots)$  in block  $n$ , then the definition of  $x_i$  dominates the  $i^{\text{th}}$  predecessor of  $n$
  - If  $x$  is used in a non- $\Phi$  statement in block  $n$ , then the definition of  $x$  dominates block  $n$



## Dominance Frontier (1)



- To get a practical algorithm for placing  $\Phi$ -functions, we need to avoid looking at all combinations of nodes leading from  $x$  to  $y$
- Instead, use the dominator tree in the flow graph.
  - Place merges *just beyond the end of the definitions' dominance*.
    - The first point where they may receive a value from an alternate definition.
  - This follows directly from the previous properties:
    - $\Phi$ -function means predecessors are dominated by defs
    - Non  $\Phi$  usage means dominated by def
  - This is referred to as the *dominance frontier*.



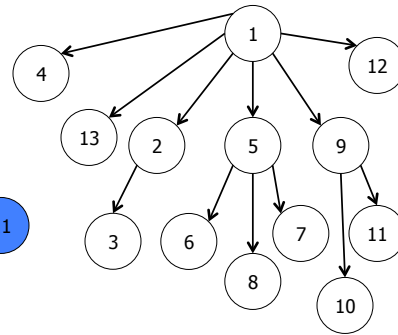
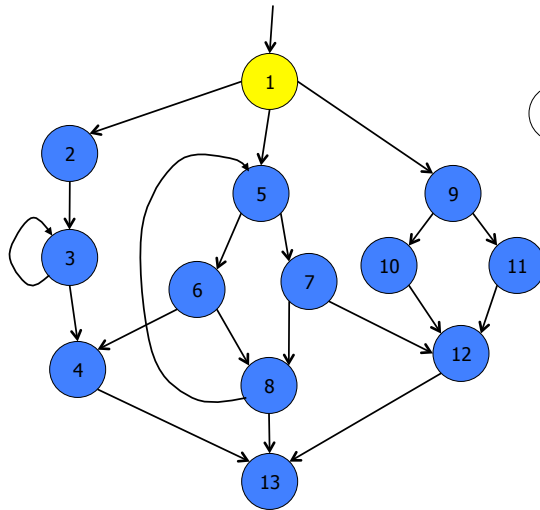
## Dominance Frontier (2)



- Definitions
  - $x$  *strictly dominates*  $y$  if  $x$  dominates  $y$  and  $x \neq y$
  - The *dominance frontier* of a node  $x$  is the set of all nodes  $w$  such that  $x$  dominates a predecessor of  $w$ , but  $x$  does not *strictly* dominate  $w$ 
    - Interestingly, this means that  $x$  can be in *its own dominance frontier*! This can happen if you have a back edge to  $x$  ( $x$  is the head of a loop).
- Essentially, the dominance frontier is the border between dominated and undominated nodes



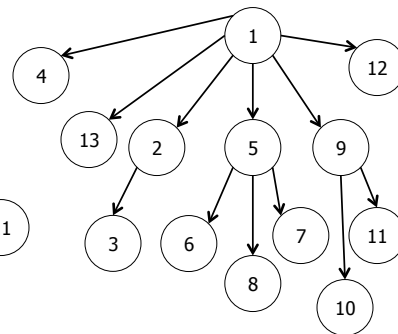
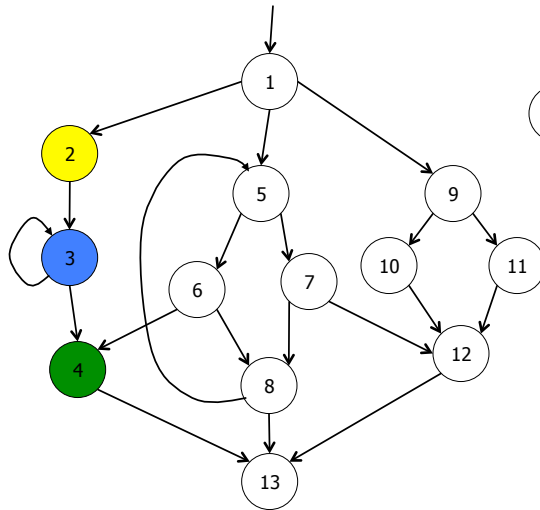
# Example



- =  $x$
- =  $\text{DominanceFrontier}(x)$
- =  $\text{StrictDom}(x)$



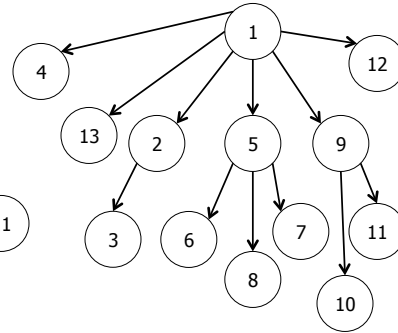
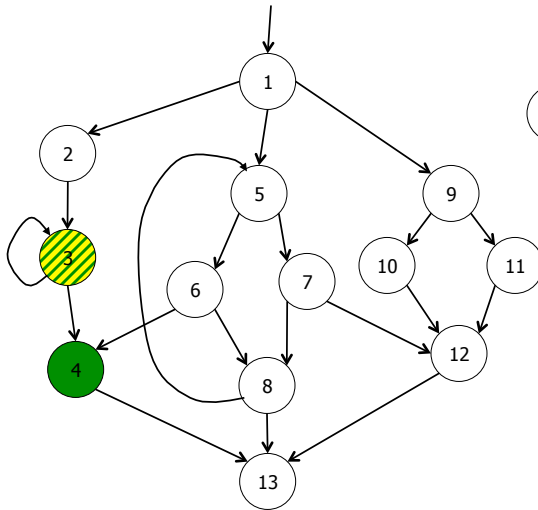
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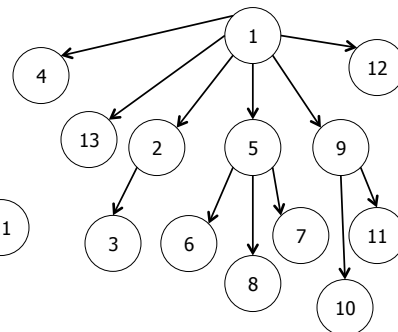
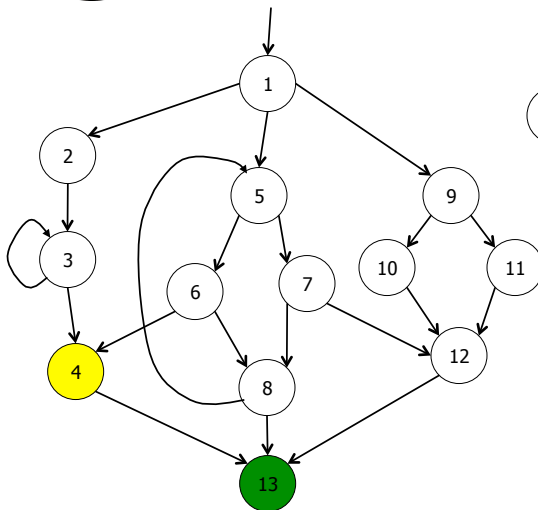
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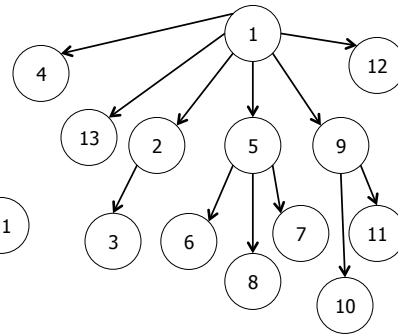
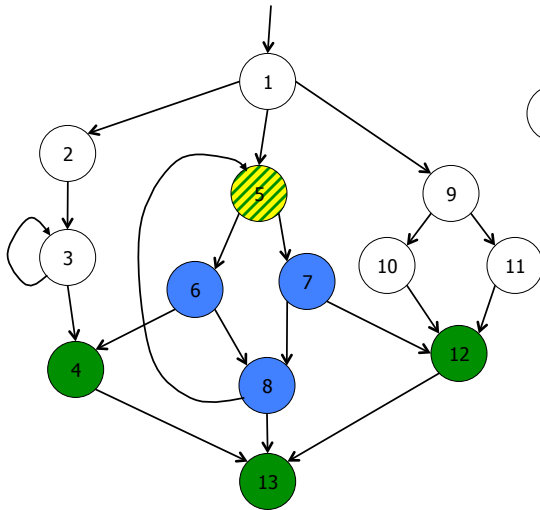


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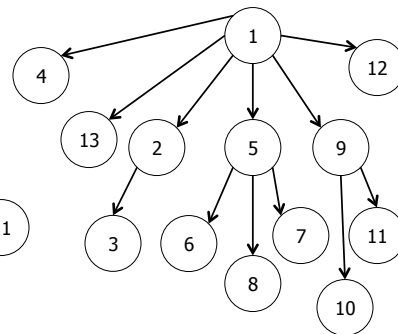
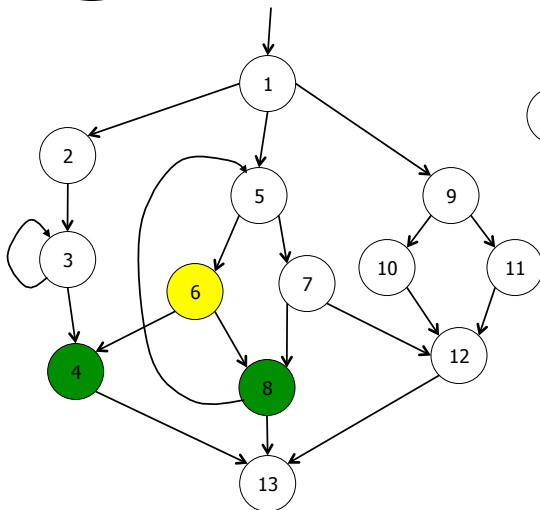
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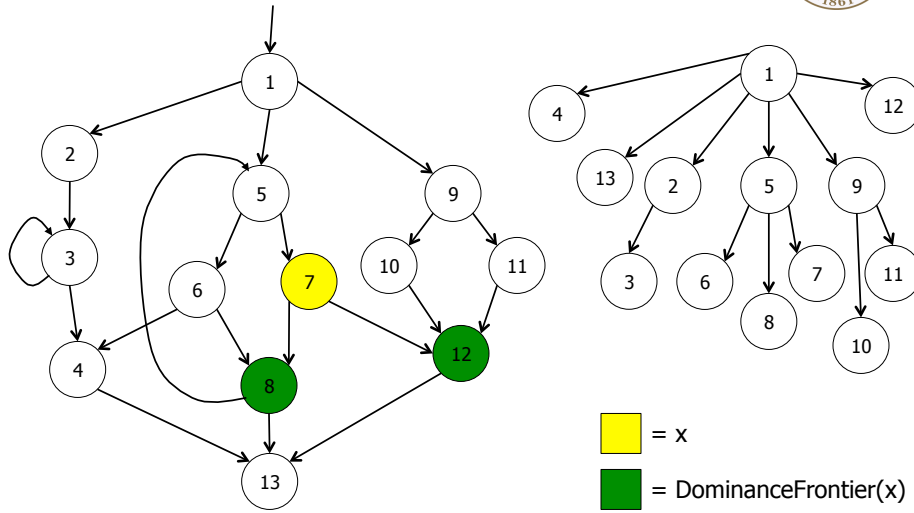
# Example



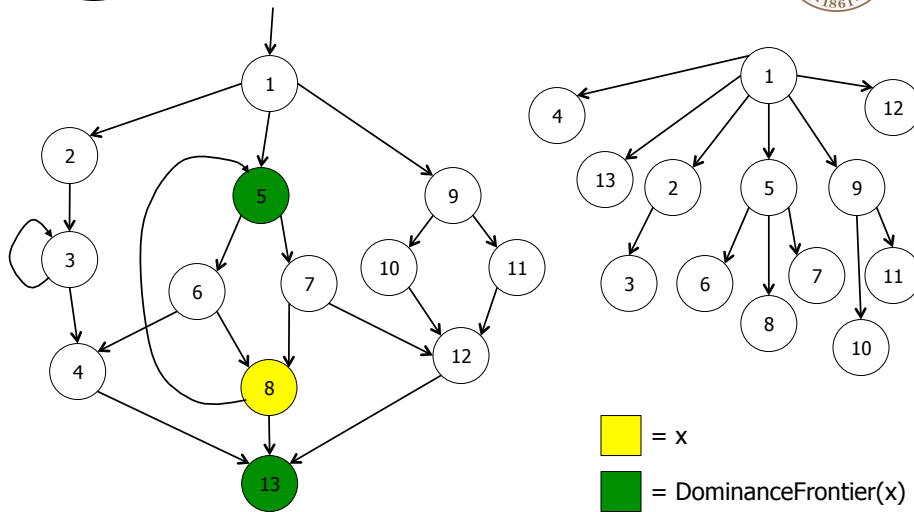
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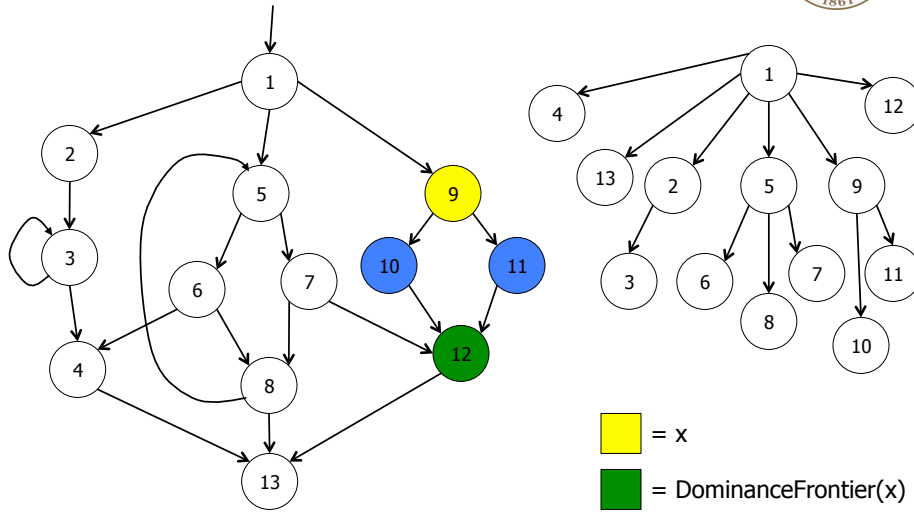


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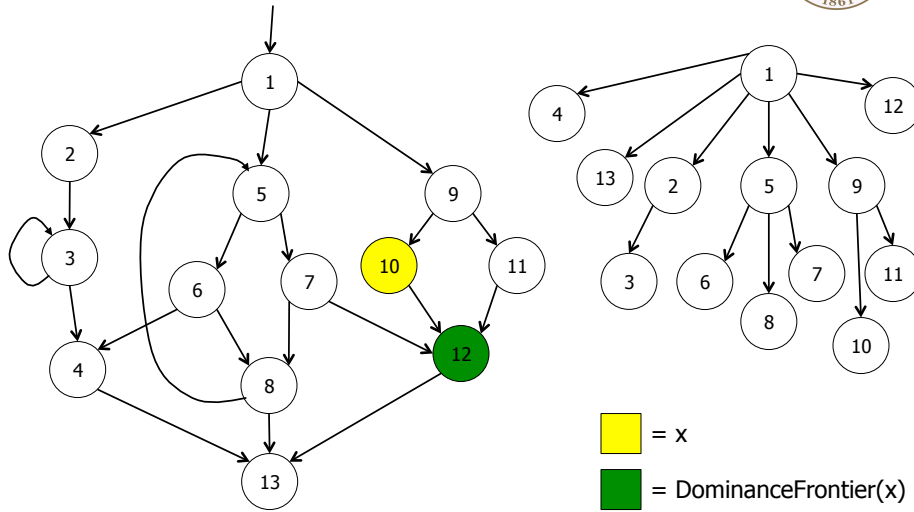




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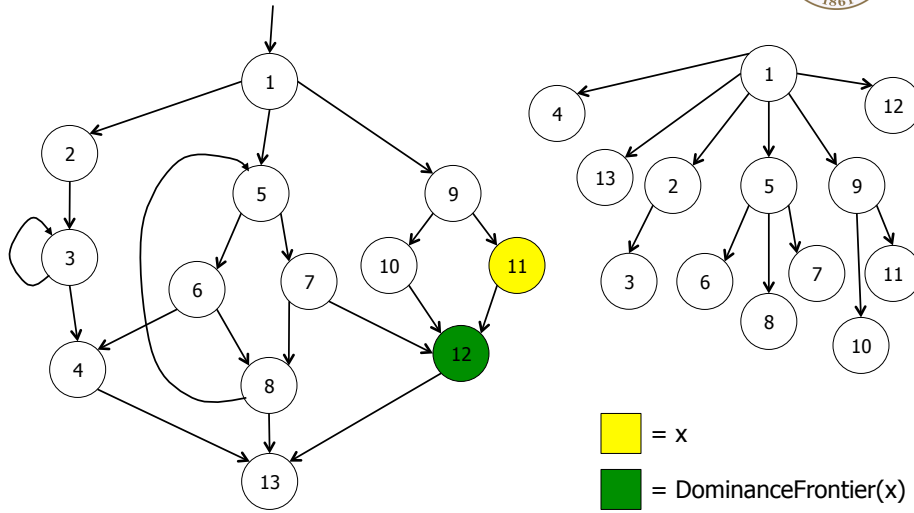


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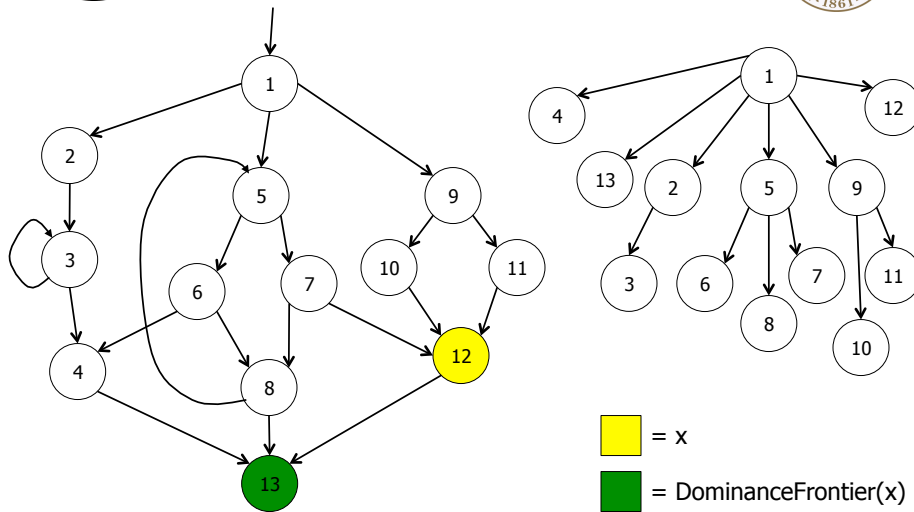




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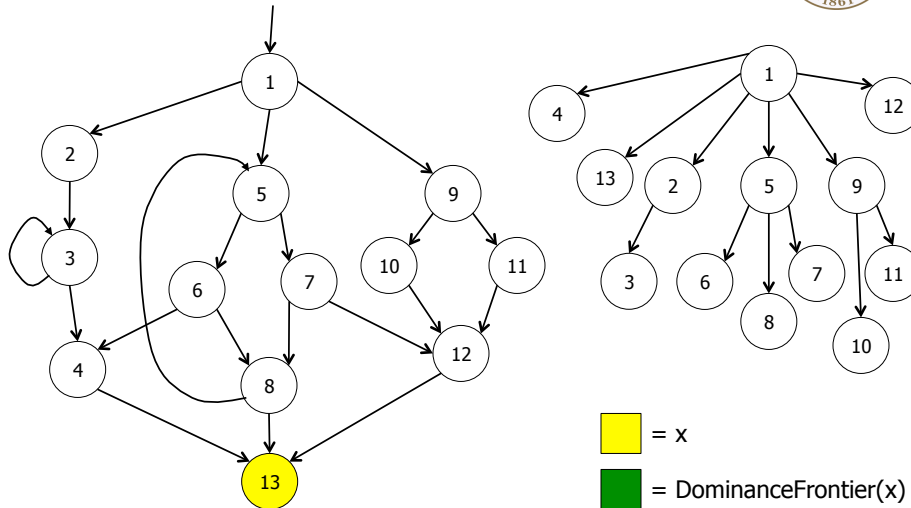


# Example





# Example



# Placing $\Phi$ -Functions



- If a node  $x$  contains the definition of variable  $a$ , then every node in the dominance frontier of  $x$  needs a  $\Phi$ -function for  $a$ 
  - Idea: Everything dominated by  $x$  will see  $x$ 's definition. Dominance frontier represents first nodes we could have reached via an alternate path, which *will* have an alternate reaching definition (recall that the entry defines everything).
    - Why does this work for loops? Hint: Strict dominance ...
  - Since the  $\Phi$ -function itself is a definition, this needs to be iterated until it reaches a fixed-point
- Theorem: this algorithm places exactly the same set of  $\Phi$ -functions as the path criterion given previously.



## Placing $\Phi$ -Functions: Details



- We won't give the full constructions here (see your text). The basic steps are:
  1. Compute the dominance frontiers for each node in the control flow graph
  2. Insert just enough  $\Phi$ -functions to satisfy the criterion. Use a worklist algorithm to avoid reexamining nodes unnecessarily
  3. Walk the dominator tree and rename the different definitions of variable  $a$  to be  $a_1, a_2, a_3, \dots$



## SSA Optimizations



- Advantage of SSA: Makes many optimizations and analyses simpler and more efficient.
  - We'll show a couple examples.
- But first, what do we know? (i.e., what information is kept in the SSA graph?)



## SSA Data Structures



- Statement: links to containing block, next and previous statements, variables defined, variables used.
- Variable: link to its (single) definition statement and (possibly multiple) use sites
- Block: List of contained statements, ordered list of predecessors, successor(s)



## Dead-Code Elimination



- A variable is live if and only if its list of uses is not empty(!)
  - Without SSA, possibly many stores to each variable. Have to disambiguate which might be used. With SSA each store defines a new variable, so this becomes trivial ...
- Algorithm to delete dead code:
  - while there is some variable  $v$  with no uses
    - if the statement that defines  $v$  has no other side effects, then delete it
    - Need to remove this statement from the list of uses for its *operand variables* – which may cause those variables to become dead



## Sparse Simple Constant Propagation (SSCP)



- If  $c$  is a constant in  $v := c$ , any use of  $v$  can be replaced by  $c$ 
  - Then update every use of  $v$  to use constant  $c$
- If the  $c_i$ 's in  $v := \Phi(c_1, c_2, \dots, c_n)$  are all the same constant  $c$  (or "Undefined" via start node, if you like), we can replace this with  $v := c$
- Can also incorporate copy propagation, constant folding, and others in the same worklist algorithm



## Sparse Simple Constant Propagation



$W :=$  list of all statements in SSA program  
while  $W$  is not empty  
  remove some statement  $S$  from  $W$   
  if  $S$  is  $v := \Phi(c, c, \dots, c)$ , replace  $S$  with  $v := c$   
  if  $S$  is  $v := c$   
    delete  $S$  from the program  
  for each statement  $T$  that uses  $v$   
    substitute  $c$  for  $v$  in  $T$   
    add  $T$  to  $W$





## Converting Back from SSA



- Unfortunately, real machines do not include a  $\Phi$  instruction
- So after analysis, optimization, and transformation, need to convert back to a “ $\Phi$ -less” form for execution



## Translating $\Phi$ -functions



- The meaning of  $x := \Phi(x_1, x_2, \dots, x_n)$  is “set  $x := x_1$  if arriving on edge 1, set  $x := x_2$  if arriving on edge 2, etc.”
- So, for each  $i$ , insert  $x := x_i$  at the end of predecessor block  $i$
- Rely on copy propagation and coalescing in register allocation to eliminate redundant moves



## SSA



- There are many details needed to fully and efficiently implement SSA, but these are the main ideas
  - Your text has some more details
- SSA is used in most modern optimizing compilers & has been retrofitted into many older ones (gcc is a well-known example)



## Course Evaluations



- You all know the drill by now. Doing them today because rest of this week will be busy.
  - Two guest lectures (Wednesday and Friday)
- Any volunteers to collect and send them in?
  - Or I can always volunteer someone 😊