

CSE401: Storage Layout

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Run-time storage layout: *focus on compilation, not interpretation*

- n Plan how and where to keep data at run-time
- n Representation of
 - n int, bool, etc.
 - n arrays, records, etc.
 - n procedures
- n Placement of
 - n global variables
 - n local variables
 - n parameters
 - n results

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Data layout of scalars *Based on machine representation*

Integer	Use hardware representation (2, 4, and/or 8 bytes of memory, maybe aligned)
Bool	1 byte or word
Char	1-2 bytes or word
Pointer	Use hardware representation (2, 4, or 8 bytes, maybe two words if segmented machine)

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Data layout of aggregates

- n Aggregate scalars together
- n Different compilers make different decisions
- n Decisions are sometimes machine dependent
 - n Note that through the discussion of the front-end, we never mentioned the target machine
 - n We didn't in interpretation, either
 - n But now it's going to start to come up constantly
 - n Necessarily, some of what we will say will be "typical", not universal.

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Layout of records

- n Concatenate layout of fields
 - n Respect alignment restrictions
 - n Respect field order, if required by language
 - n Why might a language choose to do this or not do this?
 - n Respect contiguity?

```

r : record
  b : bool;
  i : int;
  m : record
    b : bool;
    c : char;
  end
  j : int;
end;

```

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Layout of arrays

- n Repeated layout of element type
 - n Respect alignment of element type
- n How is the length of the array handled?

```

s : array [5] of
  record;
  i : int;
  c : char;
end;

```

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Layout of multi-dimensional arrays

- Recursively apply layout rule to subarray first
- This leads to row-major layout
- Alternative: column-major layout
 - Most famous example: FORTRAN

```
a : array [3] of
  array [2] of
    record;
      i : int;
      c : char;
    end;
```

```
a[1][1]
a[1][2]
a[2][1]
a[2][2]
a[3][1]
a[3][2]
```

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Implications of Array Layout

- Which is better if row-major? col-major?

```
a:array [1000, 2000] of int;
```

```
for i:= 1 to 1000 do
  for j:= 1 to 2000 do
    a[i,j] := 0 ;
```

```
for j:= 1 to 2000 do
  for i:= 1 to 1000 do
    a[i,j] := 0 ;
```

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Dynamically sized arrays

- Arrays whose length is determined at run-time
 - Different values of the same array type can have different lengths
- Can store length implicitly in array
 - Where? How much space?
- Dynamically sized arrays require pointer indirection
 - Each variable must have fixed, statically known size

```
a : array of
  record;
    i : int;
    c : char;
  end;
```

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Dope vectors

- PL/1 handled arrays differently, in particular storage of the length
- It used something called a dope vector, which was a record consisting of
 - A pointer to the array
 - The length of the array
 - Subscript bounds for each dimension
- Arrays could change locations in memory and size quite easily

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String representation

- A string \approx an array of characters
 - So, can use array layout rule for strings
- Pascal, C strings: statically determined length
 - Layout like array with statically determined length
- Other languages: strings have dynamically determined length
 - Layout like array with dynamically determined length
 - Alternative: special end-of-string char (e.g., $\backslash 0$)

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Storage allocation strategies

- Given layout of data structure, where in memory to allocate space for each instance?
- Key issue: what is the *lifetime (dynamic extent)* of a variable/data structure?
 - Whole execution of program (e.g., global variables)
 - Static allocation
 - Execution of a procedure activation (e.g., locals)
 - Stack allocation
 - Variable (dynamically allocated data)
 - Heap allocation

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Parts of run-time memory

The diagram shows a vertical stack of memory regions. From top to bottom: 'stack' with a downward arrow, 'heap' with an upward arrow, 'static data', and 'code/RO data'.

- Code/Read-only data area
 - Shared across processes running same program
- Static data area
 - Can start out initialized or zeroed
- Heap
 - Can expand upwards through (e.g. `sbrk`) system call
- Stack
 - Expands/contracts downwards automatically

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Static allocation

- Statically allocate variables/data structures with global lifetime
 - Machine code
 - Compile-time constant scalars, strings, arrays, etc.
 - Global variables
 - `static` locals in C, all variables in FORTRAN
- Compiler uses symbolic addresses
- Linker assigns exact address, patches compiled code

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Stack allocation

- Stack-allocate variables/data structures with LIFO lifetime
 - Data doesn't outlive previously allocated data on the same stack
- Stack-allocate procedure activation records
 - A stack-allocated activation record = a *stack frame*
 - Frame includes formals, locals, temps
 - And housekeeping: static link, dynamic link, ...
- Fast to allocate and deallocate storage
- Good memory locality

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Stack allocation II

- What about variables local to nested scopes within one procedure?

```

procedure P() {
  int x;
  for(int i=0; i<10; i++){
    double x;
    ...
  }
  for(int j=0; j<10; j++){
    double y;
    ...
  }
}
  
```

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Stack allocation: constraints I

- No references to stack-allocated data allowed after returns
- This is violated by general first-class functions

```

proc foo(x:int): proctype(int):int;
  proc bar(y:int):int;
    begin
      return x + y;
    end bar;
  begin
    return bar;
  end foo;

var f:proctype(int):int;
var g:proctype(int):int;

f := foo(3);  g := foo(4);
output := f(5); output := g(6);
  
```

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Stack allocation: constraints II

- Also violated if pointers to locals are allowed

```

proc foo (x:int): *int;
  var y:int;
  begin
    y := x * 2;
    return &y;
  end foo;

var w,z:*int;

z := foo(3);
w := foo(4);

output := *z;
output := *w;
  
```

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Heap allocation

- n For data with unknown lifetime
 - n `new/malloc` to allocate space
 - n `delete/free`/garbage collection to deallocate
- n Heap-allocate activation records of first-class functions
- n Relatively expensive to manage
- n Can have dangling reference, storage leaks
 - n Garbage collection reduces (but may not eliminate) these classes of errors

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Stack frame layout

- n Need space for
 - n Formals
 - n Locals
 - n Various housekeeping data
 - n Dynamic link (pointer to caller's stack frame)
 - n Static link (pointer to lexically enclosing stack frame)
 - n Return address, saved registers, ...
- n Dedicate registers to support stack access
 - n FP - frame pointer: ptr to start of stack frame (fixed)
 - n SP - stack pointer: ptr to end of stack (can move)

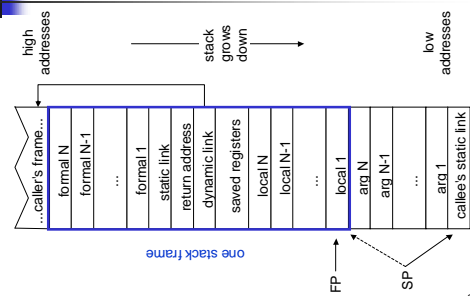
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Key property

- n All data in stack frame is at a *fixed, statically computed* offset from the FP
- n This makes it easy to generate fast code to access the data in the stack frame
 - n And even lexically enclosing stack frames
- n Can compute these offsets solely from the symbol tables
 - n Based also on the chosen layout approach

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Stack Layout



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Accessing locals

- n If a local is in the same stack frame then


```
t := *(fp + local_offset)
```
- n If in lexically-enclosing stack frame


```
t := *(fp + static_link_offset)
t := *(t + local_offset)
```
- n If farther away


```
t := *(fp + static_link_offset)
t := *(t + static_link_offset)
...
t := *(t + local_offset)
```

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At compile-time...

- n ...need to calculate
 - n Difference in nesting depth of use and definition
 - n Offset of local in defining stack frame
 - n Offsets of static links in intervening frames

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Calling conventions

- n Define responsibilities of caller and callee
 - n To make sure the stack frame is properly set up and torn down
- n Some things can only be done by the caller
- n Other things can only be done by the callee
- n Some can be done by either
- n So, we need a protocol

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PL/0 calling sequence

- | | |
|---|---|
| <ul style="list-style-type: none"> n Caller <ul style="list-style-type: none"> n Evaluate actual args <ul style="list-style-type: none"> n Order? n Push onto stack <ul style="list-style-type: none"> n Order? n Alternative: First k args in registers n Push callee's static link <ul style="list-style-type: none"> n Or in register? n Before or after stack arguments? n Execute call instruction <ul style="list-style-type: none"> n Hardware puts return address in a register | <ul style="list-style-type: none"> n Callee <ul style="list-style-type: none"> n Save return address on stack n Save caller's frame pointer (dynamic link) on stack n Save any other registers that might be needed by caller n Allocates space for locals, other data <ul style="list-style-type: none"> $sp := sp - size_of_locals - other_data$ n Locals stored in what order? n Set up new frame pointer ($fp := sp$) n Start executing callee's code |
|---|---|

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PL/0 return sequence

- | | |
|--|---|
| <ul style="list-style-type: none"> n Callee <ul style="list-style-type: none"> n Deallocate space for local, other data <ul style="list-style-type: none"> $sp := sp + size_of_locals + other_data$ n Restore caller's frame pointer, return address & other regs, all without losing addresses of stuff still needed in stack n Execute return instruction | <ul style="list-style-type: none"> n Caller <ul style="list-style-type: none"> n Deallocate space for callee's static link, args <ul style="list-style-type: none"> n $sp := fp$ n Continue execution in caller after call |
|--|---|

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Accessing callee procedures *similar to accessing locals*

- n Call to procedure declared in same scope:


```
static_link := fp
call p
```
- n Call to procedure in lexically-enclosing scope:


```
static_link := *(fp + static_link_offset)
call p
```
- n If farther away


```
t := *(fp + static_link_offset)
t := *(t + static_link_offset)
...
static_link := *(t + static_link_offset)
call p
```

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Some questions

- n Return values?
- n Local, variable-sized, arrays


```
proc P(int n) {
    var x array[1 .. n] of int;
    var y array[-5 .. 2*n] of array[1 .. n] int;
    ...
}
```
- n Max length of dynamic-link chain?
- n Max length of static-link chain?

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Exercise: apply to this example

```
module M;
  var x:int;
  proc P(y:int);
    proc Q(y:int);
      var qx:int;
      begin R(x+y);end Q;
    proc R(z:int);
      var rx,ry:int;
      begin P(x+y+z);end R;
    begin Q(x+y); R(42); P(0); end P;
begin
  x := 1;
  P(2);
end M.
```

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Exercise: symbol table

M	x	int	0
P		proc	-
s/			
dl			

P	y	int	
Q		proc	-
R		proc	-
s/			
dl			

Q	y	int	
qx		int	
s/			
dl			

R	z	int	
rx		int	
ry		int	
s/			
dl			

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Exercise: stack frames

M	x	int	0
P		proc	
s/			
dl			

P	y	int	
Q		proc	
R		proc	
s/			
dl			

Q	y	int	
qx		int	
s/			
dl			

R	z	int	
rx		int	
ry		int	
s/			
dl			

static link	
return address	
dynamic link	
saved registers	
x	

y	
static link	
return address	
dynamic link	
saved registers	

y	
static link	
return address	
dynamic link	
saved registers	
qx	

z	
static link	
return address	
dynamic link	
saved registers	
ry	
rx	

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What do these mean?

```

proc P(int a);
begin
  i := i + 5;
  output := a;
  output := a+1;
  a := a+1;
  output := a;
end;

int i=2;
P(i); output i;
P(2); output 2;

```

```

proc Q(int a,int b);
  int c;
begin
  c := a;
  a := b;
  b := c;
end;

int i=2; j=3;
Q(i,j);

```

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Parameter passing

- When passing args, need to support right semantics
- Issue #1: when is argument expression evaluated?
 - Before call?
 - When first used by callee?
 - At every use by callee?
- Issue #2: what happens if callee assigns to formal?
 - Is this visible to the caller? If so, when?
 - What happens with aliasing among arguments and lexically visible variables?
- Different choices lead to
 - Different representations for passed arguments and
 - Different code to access formals

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Parameter passing modes

- call-by-value
- call-by-sharing
- call-by-reference
- call-by-value-result
- call-by-name
- call-by-need
- ...

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Call-by-value

- Assignment to formal doesn't affect caller's value
- Implementation: pass copy of argument value
 - Trivial for scalars
 - Inefficient for aggregates(?)

```

var a : int;
proc foo(x:int,y:int);
begin
  x := x + 1;
  y := y + a;
end foo;

a := 2;
foo(a,a);
output := a;

```

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Call-by-reference

- Assignment to formal changes actual value in caller
 - Immediately
 - Actual must be lvalue
- Implementation: pass pointer to actual
 - Efficient for big data structures(?)
 - References to formal must do extra dereference

```
var a : int;
proc foo(x:int,y:int);
begin
  x := x + 1;
  y := y + a;
end foo;

a := 2;
foo(a,a);
output := a;
```

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Big immutable data

for example, a constant string

- Suppose language has call-by-value semantics
- But, it's expensive to pass by-value
- Could implement as call-by-reference
 - Since you can't assign to the data, you don't care
 - Let the compiler decide?

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Call-by-value-result

- Assignment to formal copies final value back to caller on return
 - "copy-in, copy-out"
- Implement as call-by-value with copy back when procedure returns
 - More efficient than call-by-reference
 - For scalars?
 - For arrays?

```
var a : int;
proc
foo(x:int,y:int);
begin
  x := x + 1;
  y := y + a;
end foo;

a := 2;
foo(a,a);
output := a;
```

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Call-by-result

```
var a : int;
proc foo(x:int,y:int);
begin
  x := x + 1;
  y := y + a;
end foo;

a := 2;
foo(a,a);
output := a;
```

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Ada: in, out, in out

- Programmer selects intent
- Compiler decides which mechanism is more efficient
- Program's meaning "shouldn't" depend on which is chosen

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Call-by-name, call-by-need

- Variations on lazy evaluation
 - Only evaluate argument expression if and when needed by callee
- Supports very cool programming tricks
- Somewhat hard to implement efficiently in traditional compilers
 - Thunks
- Largely incompatible with side-effects
 - So more common in purely functional languages like Haskell and Miranda
 - But did appear first in Algol-60

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Call-by-name

- Replace each use of a parameter in the callee, by the text of the actual parameter, but in the *caller's* context
- This implies reevaluation of the actual every time the formal parameter is used
 - And evaluation of the actual might return different values each time

```
proc square(x);
  int x;
  begin
    x := x * x
  end;

square(A[i]);
```

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Jensen's device

- How to implement the equivalent of a math formula like $\sum_{0 \leq i \leq n} A_{2i}$
 - sum(i, 0, n, A[2*i])?
- Pass by-reference or by-value do not work, since they can only pass *one* element of A
- So: Jensen's device

```
int proc sum(j, lo, hi, Aj, s);
  int j, lo, hi, Aj, s;
  begin
    s := 0;
    for j := lo to hi do
      s := s + Aj;
    end;
    return s;
  end;
```

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A classic problem: *a procedure to swap two elements*

```
proc swap(int a, int b);
  int temp;
  begin
    temp := a;
    a := b;
    b := temp;
  end;
```

```
int x, y;
x = 2;
y = 5;
swap(x, y);

int j, z[10];
j = 2;
z[2] = 5;
swap(j, z[j]);
```

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Call-by-name advantages

- Textual substitution is a simple, clear semantic model
- There are some useful applications, like Jensen's device
- Argument expressions are evaluated lazily

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Call-by-name disadvantages

- Repeatedly evaluating arguments can be inefficient
- Pass-by-name precludes some standard procedures from being implemented
- Pass-by-name is difficult to implement

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thunks

- Call-by-name arguments are compiled to thunks, special parameter-less procedures
 - One gives value of actual, appropriately evaluated in caller's environment
 - Other gives l-value, again in caller's environment
- Thunks are passed into the called procedure and called to evaluate the argument whenever necessary

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Call-by-sharing

- If implicitly reference aggregate data via pointer (e.g., Java, Lisp, Smalltalk, ML, ...) then call-by-sharing is call-by-value applied to implicit pointer
 - "call-by-pointer-value"
 - Efficient, even for big aggregates
 - Assignments of formal to a different aggregate don't affect caller (e.g., `f := x`)
 - Updates to contents of aggregate visible to caller immediately (e.g., `f[i] := x`)
 - Aliasing/sharing relationships are preserved

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Parameters and compiling

- There is an intimate link between the semantics of a programming language and the mechanisms used for parameter passing
- Maybe more than other programming language constructs, the connection is extremely strong between implementation and language semantics in this area

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PL/0 storage allocation

- How and when it is decided how big a stack frame will be?
 - It's necessary that the frame always be the same size for every invocation of a given procedure
- Also, how and when is it decided exactly where in a stack frame specific data will be?
 - Some pieces are decided a priori (such as the return address)
 - Others must be decided during compile-time, such as local variables (since the number and size can't be known beforehand)
- This is all done during the storage allocation phase

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PL/0 storage allocation

```
void SymTabScope::allocateSpace() {
    _localsSize = 0;
    _formalsSize = 0;

    for (int i = 0; i < _symbols->length(); i++)
    {
        _symbols->fetch(i)->allocateSpace(this);
    }

    for (int j = 0; j < _children->length(); j++)
    {
        _children->fetch(j)->allocateSpace();
    }
}
```

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```
int SymTabScope::allocateFormal(int size) {
    int offset = _formalsSize;
    _formalsSize += size;
    return offset;
}

int SymTabScope::allocateLocal(int size) {
    int offset = _localsSize;
    _localsSize += size;
    return offset;
}

void VarSTE::allocateSpace(SymTabScope* s) {
    int size = _type->size();
    _offset = s->allocateLocal(size);
}

void FormalSTE::allocateSpace(SymTabScope* s) {
    int size = _type->size();
    _offset = s->allocateFormal(size);
}
```