#### CSE 373: Disjoint sets

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Wednesday, Feb 28, 2018

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#### Review

Last time...

#### ► Prim's algorithm:

Nearly identical to Dijkstra's, except we use the distance to any already-visited node as the cost.

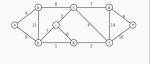
#### ► Kruskal's algorithm:

Loop over edges, from smallest to largest. Use the edge only if it doesn't introduce a cycle.

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# Kruskal's algorithm: example with a weighted graph

Example of the algorithm:



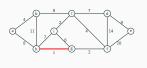
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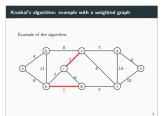


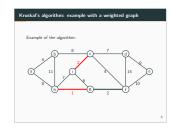
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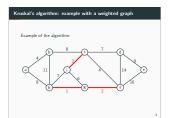
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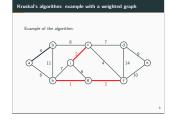


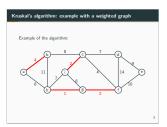
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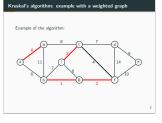


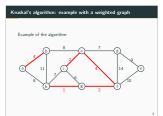


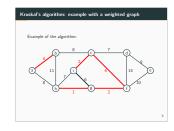


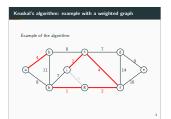


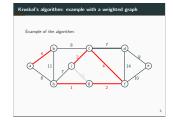


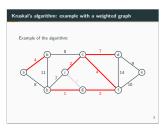


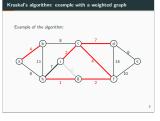


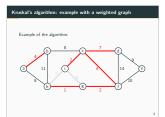


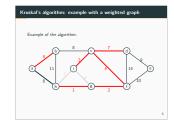


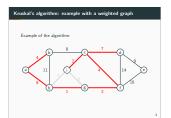


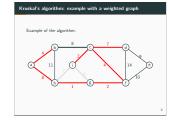


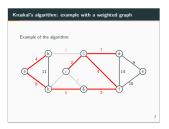


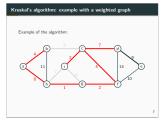


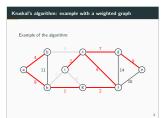


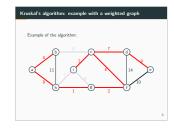


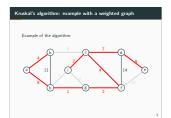


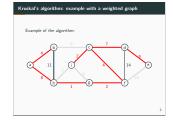


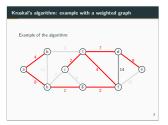


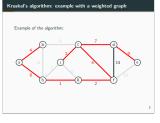












#### Kruskal's algorithm: example with a weighted graph

#### Example of the algorithm:



#### Kruskal's algorithm: analysis

#### Runtime analysis:

def kruskal():

sort edges in ascending order by their weight

mst - new SomeSet<Edge>()

for (edge : edges):
 if findMST(edge.src) != findMST(edge.dst):
 union(edge.src, edge.dst)
 mst.add(edge)

return mat

#### Note: assume that...

- ▶ makeMST(v) takes  $O(t_m)$  time
- ▶ findMST(v): takes O(t<sub>f</sub>) time
- ▶ union(u, v): takes  $O(t_u)$  time

#### Kruskal's algorithm: analysis

- Making the |V| MSTs takes O (|V| · t<sub>m</sub>) time
- ▶ Sorting the edges takes O(|E|·log(|E|)) time, assuming we use a general-purpose comparison sort
- ▶ The final loop takes  $O(|E| \cdot t_f + |V| \cdot t_u)$  time

#### Putting it all together:

$$\mathcal{O}\left(|V| \cdot t_m + |E| \cdot \log(|E|) + |E| \cdot t_f + |V| \cdot t_u\right)$$

# The DisjointSet ADT

But wait, what exactly is  $t_m$ ,  $t_f$ , and  $t_u$ ? How exactly do we implement makeMST(v), findMST(v), and union(u, v)?

We can do so using a new ADT called the DisjointSet ADT!

Interlude: What is a set?

Review: what is a set?

- ► A set is a "bag" of elements arranged in no particular order.
- ► A set may not contain duplicates.

We implemented a set in project 2: ChainedHashSet Interesting note: sets come up all the time in math.

#### The DisjointSet ADT

#### Properties of a disjoint-set data structure:

- A disjoint-set data structure maintains a collection of many different sets.
- An item may not be contained within multiple sets.
   Each set must be disjoint.
- Each set is associated with some representative.
   What is a representative? Any sort of unique "identifier".
  - We could pick some arbitrary element in the set to be the "representative"
  - ► We could assign each set some unique integer id.

# The DisjointSet ADT A disjoint-set has the following core operations:

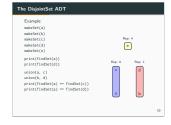
- makeSet(x) Creates a new set where the only member is x.
  We assign that set a representative.
- findSet(x) Looks up the set containing x. Then, returns the representative of that set.
- union(x, y) Looks up the set containing x and the set containing y. We combine these two sets together into one. We (arbitrarily) pick one of the two representatives to be the representative of this new set.



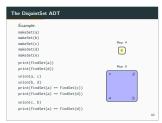








#### The DisjointSet ADT Example: makeSet(b) makeSet(c) makeSet(d) makeSet(e) print(findSet(a)) print(findSet(d)) union(a, c) union(h d) print(findSet(a) == findSet(c)) print(findSet(a) == findSet(d))



# The DisjointSet ADT

union(c, b)

print(findSet(a) == findSet(d))

What operations does a disjoint-set NOT support?

Answer: The ability to actually get the entire set

We can make a set, check if an item is in a set, and combine two sets, but we don't have a built-in way of getting the entire set itself.

Insight: The few operations we need to support, the more creative our implementation can be.

(If the client really wants the sets, they can get it themselves in O(n) time – how?)

# DisjointSet: implementation

So, how do we implement these?

# Core idea:

- ▶ We represent each set as a tree
- ► The disjoint-set keeps track of a "forest" of trees

#### Intuitions:

- ▶ We want union-ing to be cheap. Combining two trees is cheap; we just manipulate pointers.
- ► We want a single "representative" per set.

A tree has a single root!

#### DisjointSet: implementation

#### High-level overview:

- makeSet(x): Adds a new tree (of size 1) to our "forest"
- ► findSet(x): Looks up the node, then finds root of tree
- ▶ union(x, y): Combines two trees into one

# DisjointSet: implementation

Suppose we call makeSet(...) on 0 through 5.









Note that right now, each tree has only one element.

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#### DisjointSet: implementation

Suppose we call union(3, 5).













We combine those two trees into one.

Assumption: we have an O(1) way of getting each node. (E.g. maintain a hashmap of numbers to node objects.)

Question: how do we implement findSet(...)?

Once we find a node, move upwards until we're looking at root.

Then, return the root's data field.

DisjointSet: implementation

Suppose we call union(5, 4).







Algorithm: Find the roots of both trees and add one tree as a subchild of the other.

Which tree becomes the new root? For now, pick randomly.

# DisjointSet: implementation

Suppose we call union( $\theta$ , 1), then union(2,  $\theta$ ).





#### DisjointSet: implementation

Now, suppose we call union(2, 4). What happens?



#### DisjointSet: implementation

Now, suppose we call union(2, 4). What happens?



We look up 2 and 3, find their roots, and nest one tree inside the

# DisjointSet: Analysis

What's the worst-case runtime of our methods?

Better question: are our trees guaranted to be balanced?

Hint: When union-ing, we pick which tree is nested randomly. Does that guarantee we'll get a balanced tree?

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# Improving DisjointSet

How can we improve disjoint sets?

- 1. Union-by-rank:
- Strategy to make sure trees are balanced
- 2. Path compression:
- Hijack findSet(x) and make it do a little extra work to improve overall performance.
- 3. Array representation:
  - Takes advantage of cache locality, simplifies implementation, etc.

# Union-by-rank

Problem: Our trees could be unbalanced

#### Solution:

Let  $\operatorname{rank}(x)$  be a number representing the upper-bound of the height of x. So,  $\operatorname{rank}(x) \geq \operatorname{height}(x)$ .

We then...

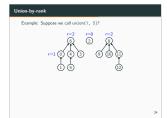
- 1. Keep track of the rank of all trees.
- 2. When unioning, make the tree with the larger rank the root!
- 3. If it's a tie, pick one randomly and increase the rank by one.

(Why not keep track of the height? When we look at path compression, keeping track of the height becomes more challenging.)

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# 

The tree with the root of "6" has the larger rank, so we make it the root. Note: we're not really "removing" the rank from node 0 - it's just



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#### Union-by-rank

Example: Suppose we call union(1, 5)?



The tree with the root of "6" has the larger rank, so we make it the root

Note: we're not really "removing" the rank from node 0-it's just irrelevant, so we're ignoring it and omitting it from the diagram to save space. We only care about the ranks at the roots.

#### Union-by-rank

Example: Suppose we call union(5, 11)?



Here, there's a tie. We break the tie arbitrarily, and increment the rank of the new tree by one.

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# Union-by-rank

Net effect? Our trees stay relatively balanced.

So, what are the worst-case runtimes now?

▶ makeSet(x):

 $\mathcal{O}\left(1\right)$  – still the same

► findSet(x):

 $\mathcal{O}\left(\log(n)\right)$  – since the tree is balanced

► union(x, y):

 $\mathcal{O}\left(\log(n)\right)$  – since union calls findSet

Path compression

Consider the following forest:



Suppose we call findSet(3) a few hundred times.

Why do we have to keep finding the root again and again?

Path compression

Observation: To find root, we must also traverse these nodes:



What if, next time, we could just jump straight to the root?

Same for the other nodes we visited

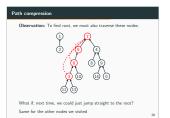
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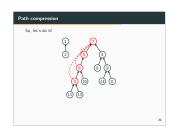
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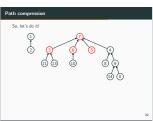
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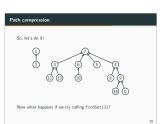


Now what happens if we try calling findSet(3)?



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Path compression

One additional note: path compression changes the heights of our trees.

This means it could be the case that rank # height. Is this a problem?

Answer: No, proof is beyond the scope of this class

#### Path compression: runtime

Now, what are the worst-case and best-case runtime of the following?

- ► makeSet(x):
- O(1) still the same
- ► findSet(x):
  - In the best case, O(1), in the worst case  $O(\log(n))$
- ▶ union(x, y):

In the best case, O(1), in the worst case  $O(\log(n))$ 

#### Back to Kruskal's

Why are we doing this? To help us implement Kruskal's algorithm:

def kruskal(): for (v : vertices): makeMST(v)

sort edges in ascending order by their weight

mst = new SomeSet<Edge>() for (edge : edges): if findMST(edge.arc) != findMST(edge.dat): union(edge.src, edge.dst)

- mst.add(edge) ▶ makeMST(v) takes O(t\_) time
- ▶ findMST(v): takes O(t<sub>f</sub>) time
- ▶ union(u, v): takes O(t<sub>u</sub>) time

#### Back to Kruskal's

We concluded that the runtime is:

$$O\left(\underbrace{|V| \cdot t_m}_{\text{setup}} + \underbrace{|E| \cdot \log(|E|)}_{\text{sorting edges}} + \underbrace{|E| \cdot t_f + |V| \cdot t_u}_{\text{core loop}}\right)$$

Well, we just said that in the worst case:

- ▶  $t_m \in \mathcal{O}(1)$
- ▶  $t_i \in O(\log(|V|))$
- ▶  $t_n \in \mathcal{O}(\log(|V|))$

So the worst-case overall runtime of Kruskal's is:

 $O(|V| + |E| \cdot \log(|E|) + (|E| + |V|) \cdot \log(|V|))$ 

# Back to Kruskal's

Our worst-case runtime:

$$\mathcal{O}(|V| + |E| \cdot \log(|E|) + (|E| + |V|) \cdot \log(|V|))$$

One minor improvement: since our edge weights are numbers, we can likely use a linear sort and improve the runtime to:

$$\mathcal{O}\left(|V| + |E| + (|E| + |V|) \cdot \log(|V|)\right)$$

We can drop the |V| + |E|, since they're dominated by the last term:

$$\mathcal{O}(|E| + |V|) \cdot \log(|V|)$$

...and we're left with something that's basically the same as Prim's algorithm.

#### Disjoint-sets, amortized analysis

...or are we?

Observation: each call to findSet(x) improves all future calls. How much of a difference does that make?

Interesting result:

It turns out union and find are amortized  $\log^*(n)$ .

#### Disjoint-sets, amortized analysis

#### Iterated log

The expression  $\log^*(n)$  is equivalent to the number of times you need to compute log(x) to bring the value down to at most 1

#### Example:

- $\triangleright \log^*(2) = \log(2) = 1$
- ▶  $log^*(4) = log(log(4)) = 2$
- ▶  $\log^*(8) = \log(\log(\log(8))) = 3$
- $\triangleright \log^*(65536) = \log^*(2^{2^{2^2}}) = 4$
- log\*(2<sup>65536</sup>) = . . . = 5

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#### A big number

#### What is 265536?

William IS 2

#### A big number

913:315-9714-98/97/12484-77/02-27/904-90/00/99/12/33:21:309880/5/00/4699 1458387/2008980-16887445893557/0052986512/47/500574865693139459 166117-49/0617526671-49/07/21761283308-627/39/36-69/24-4528925713888 7783905630048248379983969/202922221548614590237347822268252153 9957440801727144146179559226175083890/200741699926238300262268

#### Inverse of the Ackerman function

#### Rut writt

Somebody then came along and proved that find and union are amortized  $O(\alpha(n))$  – the inverse of the Ackermann function.

This grows even more slowly then  $\log^*(n)!$ 

#### A big number

2316289958007187419057916124153689751489285190484794657173660 1005899247665544584088383479054414481768425527207315568498347 60513741977952519036503219802010876473838668625310251833773339 0880142618489037400808223810407646897847164755294352964764705 0424461063311230211345889633220011656407852702307249246705

#### A big number

...I got tired of copying and pasting, but we're not even a fourth of the way through.

Punchline?  $\log^*(n) \le 5$ , for basically any reasonable value of n. Runtime of Kruskal?  $O((|E| + |V|) \log^*(|V|)) \approx O(|E| + |V|)$ 

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