# CSE 373: Open addressing 

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## Warmup

## Warmup:

With your neighbor, discuss and review:

- How do we implement get, put, and remove in a hash table using separate chaining?
- What about in a hash table using open addressing with linear probing?
- Compare and contrast your answers: what do we do the same? What do we do differently?


## Warmup

## $\operatorname{hash}($ key $) \rightarrow 142$ <br> 

In both implementations, for all three methods, we start by finding the initial index to consider:

```
index = key.hashCode() % array.length
```


## Warmup

$$
\lambda=\frac{\text { dict.cizeD }}{\text { array.legsith }}
$$

If we're using separate chaining, we then search/insert/delete from the bucket:

```
IDictionary<K, V> bucket = array[index]
bucket.get(key) // or .put(...) or .remove(...)
```

...and resize when $\lambda \approx 1$.
(When exactly to resize is a tuneable parameter)

$$
\begin{aligned}
& \lambda=\frac{\text { total mum key-value pairs }}{\text { arrary.length }} \\
& \lambda=\text { avg } \# \text { items per bucket. }
\end{aligned}
$$

## Warmup

If we're using linear probing, search until we find an array element where the key is equal to ours or until the array index is null:

```
while (array[index] != null
        && array[index].hashcode != key.hashCode()
        && !array[index].equals(key)) {
    index = (index + 1) % this.array.length
}
if (array[index] == null)
    // throw exception if implementing get
    // add new key-value pair if implementing put
else
    // return or set array[index] Lash ms
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How do we delete? (complicated, see section 04 handouts)
When do we resize?

## Open addressing: linear probing

## Strategy: Linear probing

If we collide, checking each next element until we find an open slot.
So, $h^{\prime}(k, i)=(h(k)+i) \bmod T$, where $T$ is the table size

```
i = 0
while (index in use)
    try (hash(key) + i) % array.length
    i += 1
```


## Open addressing: linear probing

Assume internal capacity of 10 , insert the following keys:

$$
38,19,8,109,10
$$



## Open addressing: linear probing

Assume internal capacity of 10 , insert the following keys:


What's the problem? Lots of keys close together: a "cluster". We ended up having to probe many slots!

## Open addressing: linear probing

## Primary clustering

When using linear probing, we sometimes end up with a long chain of occupied slots.

This problem is known as "primary clustering"

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This problem is known as "primary clustering"

Happens when $\lambda$ is large, or if we get unlucky
In linear probing, we expect to get $\mathcal{O}(\lg (n))$ size clusters.

Open addressing: linear probing

$$
n=\text { size }
$$

Questions: What is norst-cuse runtime?

- When is performance good? When is it bad?
norst-cuse: $\theta(\eta)$ Best-cuse?
best-crose: $\theta(1)$
What is the maximum load factor?

$$
\lambda \leq \pi \quad \mid
$$

$\frac{\text { size }}{\text { cupuity }}$

## Open addressing: linear probing

Questions:

- When is performance good? When is it bad?

Runtime is bad when table is nearly full.
Runtime is also bad when we hit a "cluster"

- What is the maximum load factor?

Load factor is at most $\lambda=1.0$ !

## Open addressing: linear probing

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Load factor is at most $\lambda=1.0$ !

- When do we resize?


## Open addressing: linear probing



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Punchline: clustering can be potentially bad, but in practice, it tends to be ok as long as $\lambda$ is small

## Open addressing: linear probing

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Usually when $\lambda \approx \frac{1}{2}$

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## Nifty equations:

- Average number of probes for successful probe:

$$
\frac{1}{2}\left(1+\frac{1}{(1-\lambda)}\right)
$$

- Average number of probes for unsuccessful probe:

$$
\frac{1}{2}\left(1+\frac{1}{(1+\lambda)^{2}}\right)
$$

*These equations aren't important to know

Open addressing: quadratic probing

Problem: We can still get unlucky/somebody can feed us a malicious series of inputs that causes several slowdown

Can we pick a different collision strategy that minimizes clustering?
Idea: Rather then probing linearly, probe quadratically!

$$
\begin{array}{rr}
\text { nash }(x)+0 & \text { hash }(x) \\
+1 & +1 \\
+2 & +2^{2} \\
+3 & +3^{2} \\
& \\
& -4^{2}
\end{array}
$$

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Idea: Rather then probing linearly, probe quadratically!
Exercise: assume internal capacity of 10 , insert the following:

$$
\text { hop, 18, 49, 58, } 79
$$



## Open addressing: quadratic probing

## Strategy: Quadratic probing

If we collide: $h^{\prime}(k, i)=\left(h(k)+i^{2}\right) \bmod T$, where $T$ is table size

```
\(\mathrm{i}=0\)
while (index in use)
    try (hash(key) + i * i) \% array.length
    i += 1
```


## Open addressing: quadratic probing

What problems are there?
Problem 1: If $\lambda \geq \frac{1}{2}$, quadratic probing may fail to find an empty slot: it can potentially loop forever!

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Problem 1: If $\lambda \geq \frac{1}{2}$, quadratic probing may fail to find an empty slot: it can potentially loop forever!

Problem 2: Still can get clusters (though not as badly)

## Open addressing: quadratic probing

## Secondary clustering

When using quadratic probing, we sometimes need to probe a sequence of table cells (that are not necessary next to each other). This problem is known as "secondary clustering".

Ex: inserting 19, 39. 29 9:


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## Secondary clustering

When using quadratic probing, we sometimes need to probe a sequence of table cells (that are not necessary next to each other). This problem is known as "secondary clustering".

Ex: inserting 19, 39, 29, 9 :

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| :---: | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :---: |
| 39 |  |  | 29 |  |  |  |  | 9 | 19 |

Secondary clustering can also be bad, but is generally milder then primary clustering

## Recap

Note: let $s=\underline{h(k)}$ k. hashlodel

- Linear probing:

$$
\underline{s+0}, \underline{s+1}, s+2, s \pm 3, s+4, \cdots
$$

## Recap

Note: let $s=h(k)$

- Linear probing:
$s+0, s+1, s+2, s+3, s+4, \ldots$
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Basic pattern: try $h^{\prime}(k, i)=(h(k)+i) \bmod T$
- Quadratic probing: $s+\underline{0}, s+\underline{1}, s+\underline{2^{2}}, s+\underline{3^{2},} s+\underline{4^{2}}, \ldots$


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Observation: For both probing strategies, there are just $\mathcal{O}(T)$ different "probe sequences" - distinct ways we can probe the array.

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Observation: For both probing strategies, there are just $\mathcal{O}(T)$ different "probe sequences" - distinct ways we can probe the array.

Idea: Can we increase the number of distinct probe sequences to decrease odds of collision?

## Open addressing: double-hashing

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Let $s=h(k)$, let $j=g(k)$ :

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Let $s=h(k)$, let $\begin{aligned} & J=g(k)\end{aligned}$

$$
\text { Let } s=h(k) \text {, let } j=g(k): ~, ~ c o j, s+1 j, s+2 j, \underbrace{s+3 j}, s+4 j, \ldots j=\text { array. length }-1
$$

Hint: were aluuys Going to med by orray.lengtr
how mary unique storting pos? $G S=$ array.lensth
how may different "jump" intervals?
$n(n-1) \sim O\left(n^{2}\right)$

## Open addressing: double-hashing

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Idea: With linear and quadratic probing, we jump by the same increments. Can we try jumping in a different way per each key?

Use a second hash function!
Let $s=h(k)$, let $j=g(k)$ :
$s+0 j, s+1 j, s+2 j, s+3 j, s+4 j, \ldots$
Basic pattern: try $h^{\prime}(k, i)=(h(k)+i \cdot g(k)) \bmod T$
In pseudocode:

```
i = 0
while (index in use)
    try (hash(key) + i * jump_hash(key)) % array.length
    i += 1
```


## Open addressing: double-hashing

Only effective if $g(k)$ returns a value that's relatively prime to the table size.

## Open addressing: double-hashing

$$
T=[0,0,0,0,0]
$$

Only effective if $g(k)$ returns a value that's relatively prime to the table size. 2

Ways we can do this:

- If $T$ is a power of two, make $g(k)$ return any odd integer
- If $T$ is a prime, make $g(k)$ return any smaller, non-zero $\overline{\text { integer }(\text { e.g. } g(k)=1+(k \bmod (T-1))) ~}$


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There are $T$ different starting positions, $T-1$ different jump intervals (since we can't jump by 0 ), so there are $\mathcal{O}\left(T^{2}\right)$ different probe sequences

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Result: in practice, double-hashing is very effective and commonly used "in the wild".

## Summary

So, what strategy is best? Separate chaining? Open addressing?
No obvious answer: both implementations are common.

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So, what strategy is best? Separate chaining? Open addressing?
No obvious answer: both implementations are common.
Separate chaining:

- Don't have to worry about clustering
- Potentially more "compact" ( $\lambda$ can be higher)

Open addressing:

- Managing clustering can be tricky
- Less compact (we typically keep $\lambda<\frac{1}{2}$ )
- Array lookups tend to be a constant factor faster then traversing pointers


## Applications of hash functions

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Yes!
Lots of possible applications, ranging from cryptography to biology.

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Lots of possible applications, ranging from cryptography to biology.

Important: Depending on the application, we might want our hash function to have different properties.

## Applications of hash functions

How would you implement the following using hash functions?
For each application, also discuss what properties you want your hash function to have.

- Suppose we're sending a message over the internet. This message might become mildly corrupted. How can we detect if corruption probably occurred?
- Suppose you have many fragments of DNA and want to see where they appears in a (significantly longer) segment of DNA. How can we do this efficiently?



## Applications of hash functions

Same question as before:

- Suppose you're designing an video uploading site and want to detect if somebody is uploading a pirated movie. A naive way to do this is to check if the movie is byte-for-byte identical to some movie. How can we do this more efficiently?
- Suppose you're designing a website with a user login system. Directly storing your user's passwords is dangerous - what if they get stolen? How can you store password in a safe way so that even if they're stolen, the passwords aren't compromised?


## Applications of hash functions

Same question as before:

- You are trying to build an image sharing site. Users upload many images, and you need to assign each image some unique ID. How might you do this?
- Suppose we have a long series of financial transactions stored on some (potentially untrustworthy) computer. Somebody claims they made a specific transaction several months ago. Can you design a system that lets you audit and determine if they're lying or not? Assume you have access to just the very latest transaction, obtained from a different trustworthy source.

