CSE 373: Data Structures and Algorithms

Lecture 15: Graph Data Structures, Topological Sort, and Traversals (DFS, BFS)

Instructor: Lilian de Greef
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Today:

• Announcements
• Graph data structures
• Topological Sort
• Graph Traversals
  • Depth First Search (DFS)
  • Breadth First Search (BFS)
Announcement: Received Course Feedback

What’s working well:
• Walking through in-class examples
• Posted, printed, and annotated slides
• Interactive questions & in-class partner discussion

Things to address:
• Amount to write on printed slides
• Why using polling system for in-class exercises
• Concern about not getting through entire slide deck
Represented Majors

• Engineering
• Math
• Science
• Informatics
• Geology
• Spanish
• Asian Language
• Pre-major
• And more!
Graph Data Structures

A couple of different ways to store adjacencies
What is the Data Structure?

• So graphs are really useful for lots of data and questions
  • For example, “what’s the lowest-cost path from x to y”

• But we need a data structure that represents graphs

• The “best one” can depend on:
  • Properties of the graph (e.g., dense versus sparse)
  • The common queries (e.g., “is (u, v) an edge?” versus “what are the neighbors of node u?”)

• So we’ll discuss the two standard graph representations
  • Adjacency Matrix and Adjacency List
  • Different trade-offs, particularly time versus space
Adjacency Matrix

• Assign each node a number from 0 to $|V| - 1$

• A $|V| \times |V|$ matrix (i.e., 2-D array) of Booleans (or 1 vs. 0)
  • If $M$ is the matrix, then $M[u][v] == true$ means there is an edge from $u$ to $v$

\[
\begin{array}{cccc}
0 & 1 & 2 & 3 \\
0 & F & F & F & F \\
1 & T & F & T & T \\
2 & F & F & F & T \\
3 & F & T & T & F \\
\end{array}
\]
Adjacency Matrix Properties

- Running time to:
  - Get a vertex’s out-edges: $O(|v|)$
  - Get a vertex’s in-edges: $O(|v|)$
  - Decide if some edge exists: $O(1)$
  - Insert an edge: $O(1)$
  - Delete an edge: $O(1)$

- Space requirements: $O(|v|^2)$
- Best for sparse or dense graphs?
Adjacency Matrix Properties

• How will the adjacency matrix vary for an *undirected graph*?
  • Undirected will be symmetric around the diagonal

• How can we adapt the representation for *weighted graphs*?
  • Instead of a Boolean, store a number in each cell
  • Need some value to represent ‘not an edge’
    • In *some* situations, 0 or -1 works
Adjacency List

- Assign each node a number from 0 to $|V| - 1$
- An array of length $|V|$ in which each entry stores a list of all adjacent vertices (e.g., linked list)
Adjacency List Properties

• Running time to:
  • Get all of a vertex’s out-edges:
    \( O(d) \) where \( d \) is out-degree of vertex
  • Get all of a vertex’s in-edges:
    \( O(|V| + |E|) \) (but could keep a second adjacency list for this!)
  • Decide if some edge exists:
    \( O(d) \) where \( d \) is out-degree of source
  • Insert an edge:
    \( O(1) \) (unless you need to check if it’s there)
  • Delete an edge:
    \( O(d) \) where \( d \) is out-degree of source

• Space requirements:
  \( O(|V| + |E|) \)

Best for sparse or dense graphs?

\( O(|V| + |E|) < O(|V|^2) \)
Algorithms

Okay, we can represent graphs

Now we’ll implement some useful and non-trivial algorithms!

• Topological Sort
• Shortest Paths
  • Related: Determining if such a path exists
  • Depth First Search
  • Breadth First Search
Graphs: Topological Sort
Ordering vertices in a DAG
Topological Sort

**Topological sort:** Given a DAG, order all the vertices so that every vertex comes before all of its neighbors

One example output:

\[ MATH 126, CSE 142, CSE 143, CSE 373, CSE 374, CSE 410, CSE 413, CSE 415, CSE 417, XYZ \]
Questions and comments

• Why do we perform topological sorts only on DAGs?
  cycle → no correct answer

• Is there always a unique answer?
  Depends on Graph

• Do some DAGs have exactly 1 answer?
  Yes, e.g. all lists

• Terminology: A DAG represents a partial order and a topological sort produces a total order that is consistent with it
A few of its uses

• Figuring out how to graduate

• Computing an order in which to recompute cells in a spreadsheet

• Determining an order to compile files using a Makefile

• In general, taking a dependency graph and finding an order of execution
A First Algorithm for Topological Sort

1. Label ("mark") each vertex with its in-degree
   • Could “write in a field in the vertex”
   • Could also do this via a data structure (e.g., array) on the side

2. While there are vertices not yet output:
   a) Choose a vertex $v$ with in-degree of 0
   b) Output $v$ and *conceptually* remove it from the graph
   c) For each vertex $u$ adjacent to $v$ (i.e. $u$ such that $(v,u)$ in $\mathcal{E}$),
      decrement the in-degree of $u$
Example

Output:

126
142
143
374
373
410
413
415
417
XYZ

Node: 126 142 143 374 373 410 413 415 417 XYZ
Removed? X X X X X X X X X X
In-degree: 0 0 0 0 0 0 0 0 0 0
Notice

• Needed a vertex with in-degree 0 to start
  • Will always have at least 1 because no cycles!

• Ties among vertices with in-degrees of 0 can be broken arbitrarily
  • Can be more than one correct answer, by definition, depending on the graph
Running time?

• What is the worst-case running time?
  • Initialization $O(|V| + |E|)$ (assuming adjacency list)
  • Sum of all find-new-vertex $O(|V|^2)$ (because each $O(|V|)$)
  • Sum of all decrements $O(|E|)$ (assuming adjacency list)
  • So total is $O(|V|^2)$ – not good for a sparse graph!

```cpp
labelEachVertexWithItsInDegree();
for(i = 0; i < numVertices; i++){
    v = findNewVertexOfDegreeZero();
    put v next in output
    for each u adjacent to v
        u.indegree--;
}
```
Doing better

The trick is to avoid searching for a zero-degree node every time!

• Keep the “pending” zero-degree nodes in a list, stack, queue, bag, table, or something
• Order we process them affects output but not correctness or efficiency, provided that add/remove are both $O(1)$

Using a queue:

1. Label each vertex with its in-degree, enqueue 0-degree nodes
2. While queue is not empty
   a) $v = \text{dequeue}()$
   b) Output $v$ and remove it from the graph
   c) For each vertex $u$ adjacent to $v$ (i.e. $u$ such that $(v, u)$ in $E$), decrement the in-degree of $u$, if new degree is 0, enqueue it
Example: Topological Sort Using Queues

The trick is to avoid searching for a zero-degree node every time!

1. Label each vertex with its in-degree, enqueue 0-degree nodes
2. While queue is not empty
   a) \( v = \text{dequeue}() \)
   b) Output \( v \) and remove it from the graph
   c) For each vertex \( u \) adjacent to \( v \) (i.e. \( u \) such that \((v,u)\) in \( E\)), decrement the in-degree of \( u \), if new degree is 0, enqueue it
Running time?

```java
labelAllAndEnqueueZeros();
for (i=0; ctr < numVertices; ctr++) {
    v = dequeue();
    put v next in output
    for each u adjacent to v {
        u.indegree--;
        if (u.indegree==0)
            enqueue(u);
    }
}
```

• What is the worst-case running time?
  • Initialization: $O(|V| + |E|)$ (assuming adjacency list)
  • Sum of all enqueues and dequeues: $O(|V|)$
  • Sum of all decrements: $O(|E|)$ (assuming adjacency list)
  • Total: $O(|V| + |E|)$ — much better for sparse graph!
Graph Traversals

Depth- and Breadth-First Searches!
Introductory Example: Graph Traversals

How would a computer systematically find a path through the maze?
Note: under the hood, we’re using a graph to represent the maze.

In graph terminology: find a path (if any) from one vertex to another.
Find a path (if any) from one vertex to another.

Idea: Repeatedly explore and keep track of adjacent vertices. Mark each vertex we visit, so we don’t process each more than once.
Depth First Search (DFS)

**Depth First Search (DFS):**

Explore as far as possible along each branch before backtracking.

Repeatedly explore adjacent vertices using **recursion** or a **stack**.

Mark each vertex we visit, so we don’t process each more than once.

Example pseudocode:

```
DFS(Node start) {
    mark and process start
    for each node u adjacent to start
        if u is not marked
            DFS(u)
}
```
Find a path (if any) from one vertex to another.

Idea: Repeatedly explore and keep track of adjacent vertices.
Mark each vertex we visit, so we don’t process each more than once.

Now let’s try using a queue!

Store as additional variable in vertices

BFS!
Breadth First Search (BFS)

**Breadth First Search (BFS):**

Explore neighbors first, before moving to the next level of neighbors.

Repeatedly explore adjacent vertices using a queue.

Mark each vertex we visit, so we don’t process each more than once.

Example pseudocode:

```plaintext
BFS(Node start) {
    initialize queue q and enqueue start
    mark start as visited
    while(q is not empty) {
        next = q.dequeue() // and “process”
        for each node u adjacent to next
            if(u is not marked)
                mark u and enqueue onto q
    }
}
```
Practice time!
What is one possible order of visiting the nodes of the following graph when using Breadth First Search (BFS)?

A) MNOPQR  
B) NQMPOR  
C) QMNPOR  
D) QMNPOR
PREPARING FOR A DATE:
WHAT SITUATIONS MIGHT I PREPARE FOR?
1) MEDICAL EMERGENCY
2) DANCING
3) FOOD TOO EXPENSIVE
4) LATE DINNER OUT?

OKAY, WHAT KINDS OF EMERGENCIES CAN HAPPEN?
A) SNAKEBITE
B) LIGHTNING STRIKE
C) FALL FROM CHAIR
D) DEADANIMAL DANGER

HMM, WHICH SNAKES ARE DANGEROUS? LET'S SEE...
A) 1) CORN SNAKE
B) GARTER SNAKE
C) COBRA SNAKE

THE RESEARCH COMPARING SNAKE VENOMS IS SCATTERED AND INCONSISTENT. I'LL MAKE A SPREADSHEET TO ORGANIZE IT.

I'M HERE TO PICK YOU UP. YOU'RE NOT DRESSED?
BY LEA, THE INLAND TaIPAN HAS THE DEADLIEST VENOM OF ANY SNAKE!

I REALLY NEED TO STOP USING DEPTH-FIRST SEARCHES.