CSE332: Data Structures & Algorithms

Lecture 12: Introduction to Graphs

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Graphs

• A graph is a formalism for representing relationships among items
  – Very general definition because very general concept

• A graph is a pair
  \( G = (V, E) \)
  – A set of vertices, also known as nodes
    \( V = \{v_1, v_2, \ldots, v_n\} \)
  – A set of edges
    \( E = \{e_1, e_2, \ldots, e_m\} \)
    • Each edge \( e_i \) is a pair of vertices
      \( (v_j, v_k) \)
    • An edge “connects” the vertices

• Graphs can be directed or undirected
An ADT?

- Can think of graphs as an ADT with operations like `isEdge((v_j,v_k))`, `addVertex(v_{new})`, ...
- But it is unclear what the “standard operations” are
- Instead we tend to develop algorithms over graphs and then use data structures that are efficient for those algorithms
- Many important problems can be solved by:
  1. Formulating them in terms of graphs
  2. Applying a standard graph algorithm
- To make the formulation easy and standard, we have a lot of *standard terminology* about graphs
Some Graphs

For each, what are the vertices and what are the edges?

- Web pages with links
- Facebook friends
- “Input data” for the “7 degrees of separation from Kevin Bacon game”
- Methods in a program that call each other
- Road maps (e.g., Google maps)
- Airline routes
- Family trees
- Course pre-requisites

**Wow:** Using the same algorithms for diverse problems across so many domains sounds like “core computer science and engineering”… cough cough
Undirected Graphs

• In undirected graphs, edges have no specific direction
  – Edges are always “two-way”

Thus, \((u, v) \in E\) implies \((v, u) \in E\)
  – Only one of these edges needs to be in the set
  – The other is implicit, so normalize how you check for it

• Degree of a vertex: number of edges containing that vertex
  – Put another way: the number of adjacent vertices
Directed Graphs

• In directed graphs (sometimes called digraphs), edges have a direction

[Diagram showing directed edges]

• Thus, \((u, v) \in E\) does not imply \((v, u) \in E\).
  • Let \((u, v) \in E\) mean \(u \rightarrow v\)
  • Call \(u\) the source and \(v\) the destination

• In-degree of a vertex: number of in-bound edges, i.e., edges where the vertex is the destination
• Out-degree of a vertex: number of out-bound edges i.e., edges where the vertex is the source
Self-Edges, Connectedness

- A self-edge a.k.a. a loop is an edge of the form \((u, u)\)
  - Depending on the use/algorithm, a graph may have:
    - No self edges
    - Some self edges
    - All self edges (often therefore implicit, but we will be explicit)
- A node can have a degree / in-degree / out-degree of zero
- A graph does not have to be connected
  - Even if every node has non-zero degree
More Notation

For a graph $G = (V, E)$

- $|V|$ is the number of vertices
- $|E|$ is the number of edges
  - Minimum?
  - Maximum for undirected? $|V|\cdot |V+1|/2 \in O(|V|^2)$
  - Maximum for directed? $|V|^2 - |V| \in O(|V|^2)$

- If $(u, v) \in E$
  - Then $v$ is a neighbor of $u$, i.e., $v$ is adjacent to $u$
  - Order matters for directed edges
    - $u$ is not adjacent to $v$ unless $(v, u) \in E$
Examples again

Which would use directed edges? Which would have self-edges? Which would be connected? Which could have 0-degree nodes?

- Web pages with links
- Facebook friends
- “Input data” for the Kevin Bacon game
- Methods in a program that call each other
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- …
Weighted Graphs

• In a weighed graph, each edge has a weight a.k.a. cost
  – Typically numeric (most examples use ints)
  – Orthogonal to whether graph is directed
  – Some graphs allow negative weights; many do not

```
        Clinton     Mukilteo
          20

        Kingston     Edmonds
          30

        Bainbridge     Seattle
          35

        Bremerton
          60
```

Examples

What, if anything, might weights represent for each of these? Do negative weights make sense?

- Web pages with links
- Facebook friends
- “Input data” for the Kevin Bacon game
- Methods in a program that call each other
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Paths and Cycles

- A path is a list of vertices \([v_0, v_1, ..., v_n]\) such that \((v_i, v_{i+1}) \in E\) for all \(0 \leq i < n\). Say "a path from \(v_0\) to \(v_n\”

- A cycle is a path that begins and ends at the same node \((v_0 == v_n)\)

Example: [Seattle, Salt Lake City, Chicago, Dallas, San Francisco, Seattle]
Path Length and Cost

- **Path length**: Number of edges in a path
- **Path cost**: Sum of weights of edges in a path

Example where

\[ P = \text{[Seattle, Salt Lake City, Chicago, Dallas, San Francisco, Seattle]} \]

\[
\begin{align*}
\text{length}(P) &= 5 \\
\text{cost}(P) &= 11.5
\end{align*}
\]
Simple Paths and Cycles

• A simple path repeats no vertices, except the first might be the last
  [Seattle, Salt Lake City, San Francisco, Dallas]
  [Seattle, Salt Lake City, San Francisco, Dallas, Seattle]

• Recall, a cycle is a path that ends where it begins
  [Seattle, Salt Lake City, San Francisco, Dallas, Seattle]
  [Seattle, Salt Lake City, Seattle, Dallas, Seattle]

• A simple cycle is a cycle and a simple path
  [Seattle, Salt Lake City, San Francisco, Dallas, Seattle]
Is there a path from A to D?

Does the graph contain any cycles?
Paths and Cycles in Directed Graphs

Example:

Is there a path from A to D?  
\(\text{No}\)

Does the graph contain any cycles?  
\(\text{No}\)
Undirected-Graph Connectivity

• An undirected graph is **connected** if for all pairs of vertices \( u, v \), there exists a path from \( u \) to \( v \)

![Connected graph](image1)

![Disconnected graph](image2)

• An undirected graph is **complete**, a.k.a. fully connected if for all pairs of vertices \( u, v \), there exists an edge from \( u \) to \( v \) plus self edges

![Complete graph](image3)
Directed-Graph Connectivity

• A directed graph is **strongly connected** if there is a path from every vertex to every other vertex.

• A directed graph is **weakly connected** if there is a path from every vertex to every other vertex *ignoring direction of edges*.

• A **complete** a.k.a. **fully connected** directed graph has an edge from every vertex to every other vertex *plus self edges*.
Examples

For undirected graphs: connected?
For directed graphs: strongly connected? weakly connected?

- Web pages with links
- Facebook friends
- “Input data” for the Kevin Bacon game
- Methods in a program that call each other
- Road maps (e.g., Google maps)
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- …
Trees as Graphs

When talking about graphs, we say a tree is a graph that is:
- Acyclic
- Connected

So all trees are graphs, but not all graphs are trees

How does this relate to the trees we know and love?...
Rooted Trees

- We are more accustomed to rooted trees where:
  - We identify a unique root
  - We think of edges as directed: parent to children

- Given a tree, picking a root gives a unique rooted tree
  - The tree is just drawn differently and with undirected edges
Rooted Trees

- We are more accustomed to rooted trees where:
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Directed Acyclic Graphs (DAGs)

- A **DAG** is a directed graph with no (directed) cycles
  - Every rooted directed tree is a DAG
  - But not every DAG is a rooted directed tree

- Every DAG is a directed graph
- But not every directed graph is a DAG
Examples

Which of our directed-graph examples do you expect to be a DAG?

• Web pages with links
• “Input data” for the Kevin Bacon game
• Methods in a program that call each other
• Airline routes
• Family trees
• Course pre-requisites
• …
Density / Sparsity

- Recall: In an undirected graph, $0 \leq |E| < |V|^2$
- Recall: In a directed graph: $0 \leq |E| \leq |V|^2$
- So for any graph, $O(|E|+|V|^2)$ is $O(|V|^2)$
- Another fact: If an undirected graph is connected, then $|V|-1 \leq |E|$
- Because $|E|$ is often much smaller than its maximum size, we do not always approximate $|E|$ as $O(|V|^2)$
  - This is a correct bound, it just is often not tight
  - If it is tight, i.e., $|E|$ is $\Theta(|V|^2)$ we say the graph is dense
    - More sloppily, dense means “lots of edges”
  - If $|E|$ is $O(|V|)$ we say the graph is sparse
    - More sloppily, sparse means “most possible edges missing”
What is the Data Structure?

• So graphs are really useful for lots of data and questions
  – For example, “what’s the lowest-cost path from x to y”

• But we need a data structure that represents graphs

• The “best one” can depend on:
  – Properties of the graph (e.g., dense versus sparse)
  – The common queries (e.g., “is \((u, v)\) an edge?” versus “what are the neighbors of node \(u\)?”)

• So we’ll discuss the two standard graph representations
  – Adjacency Matrix and Adjacency List
  – Different trade-offs, particularly time versus space
Adjacency Matrix

- Assign each node a number from 0 to $|V| - 1$
- A $|V| \times |V|$ matrix (i.e., 2-D array) of Booleans (or 1 vs. 0)
  - If $M$ is the matrix, then $M[u][v]$ being \textbf{true} means there is an edge from $u$ to $v$
Adjacency Matrix Properties

- Running time to:
  - Get a vertex’s out-edges: $O(|V|)$
  - Get a vertex’s in-edges: $O(|V|)$
  - Decide if some edge exists: $O(1)$
  - Insert an edge: $O(1)$
  - Delete an edge: $O(1)$

- Space requirements:
  - $|V|^2$ bits

- Best for sparse or dense graphs?
  - Best for dense graphs
Adjacency Matrix Properties

- How will the adjacency matrix vary for an *undirected graph*?
  - Undirected will be symmetric around the diagonal

- How can we adapt the representation for *weighted graphs*?
  - Instead of a Boolean, store a number in each cell
  - Need some value to represent ‘not an edge’
    - In some situations, 0 or -1 works

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<td>F</td>
</tr>
</tbody>
</table>
```
**Adjacency List**

- Assign each node a number from 0 to $|V| - 1$
- An array of length $|V|$ in which each entry stores a list of all adjacent vertices (e.g., linked list)
Adjacency List Properties

- Running time to:
  - Get all of a vertex’s out-edges: $O(d)$ where $d$ is out-degree of vertex
  - Get all of a vertex’s in-edges: $O(|E|)$ (but could keep a second adjacency list for this!)
  - Decide if some edge exists: $O(d)$ where $d$ is out-degree of source
  - Insert an edge: $O(1)$ (unless you need to check if it’s there)
  - Delete an edge: $O(d)$ where $d$ is out-degree of source
- Space requirements:
  - $O(|V|+|E|)$
- Best for dense or sparse graphs?
  - Best for sparse graphs, so usually just stick with linked lists
Undirected Graphs

Adjacency matrices & adjacency lists both do fine for undirected graphs

- Matrix: Can save roughly 2x space
  - But may slow down operations in languages with “proper” 2D arrays (not Java, which has only arrays of arrays)
  - How would you “get all neighbors”?
- Lists: Each edge in two lists to support efficient “get all neighbors”

Example:
Okay, we can represent graphs

Now let’s implement some useful and non-trivial algorithms

- **Topological sort**: Given a DAG, order all the vertices so that every vertex comes before all of its neighbors

- **Shortest paths**: Find the shortest or lowest-cost path from $x$ to $y$
  - Related: Determine if there even is such a path