



# CSE373: Data Structures & Algorithms

## Lecture 4: Dictionaries; Binary Search Trees

Dan Grossman

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# *Where we are*

Studying the absolutely essential ADTs of computer science and classic data structures for implementing them

ADTs so far:

1. Stack:                **push, pop, isEmpty, ...**
2. Queue:                **enqueue, dequeue, isEmpty, ...**

Next:

3. Dictionary (a.k.a. Map): associate keys with values
  - Extremely common

# The Dictionary (a.k.a. Map) ADT

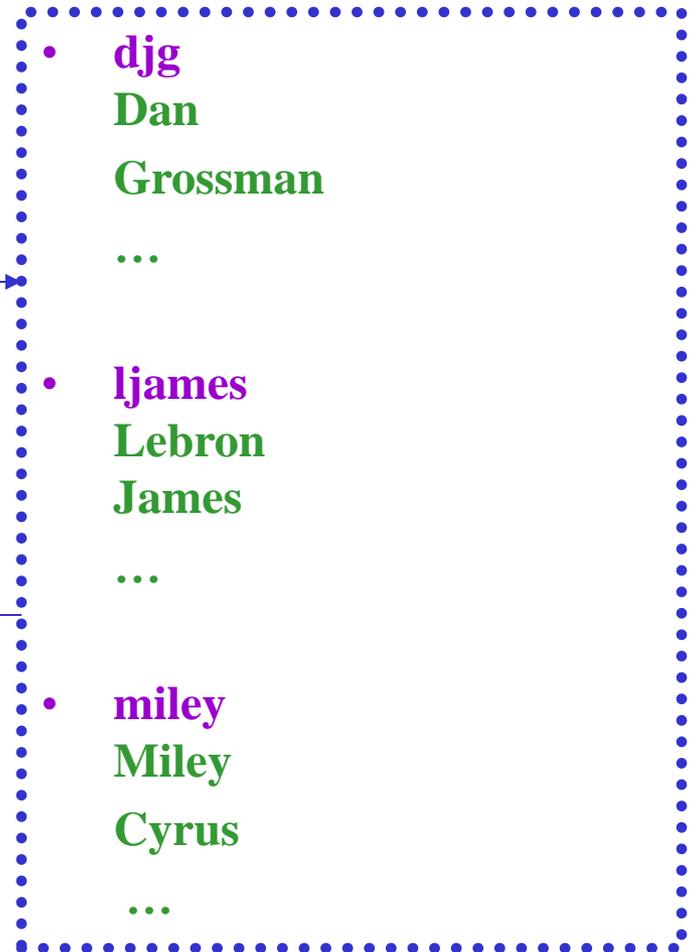
- Data:
  - set of (key, value) *pairs*
  - keys must be *comparable*

- Operations:
  - `insert(key, value)`
  - `find(key)`
  - `delete(key)`
  - ...

`insert(djg, ....)`

`find(miley)`

Miley, Cyrus, ...



*Will tend to emphasize the keys;  
don't forget about the stored values*

# *Comparison: The Set ADT*

The *Set* ADT is like a Dictionary without any values

- A key is *present* or not (no repeats)

For **find**, **insert**, **delete**, there is little difference

- In dictionary, values are “just along for the ride”
- So *same data-structure ideas* work for dictionaries and sets

But if your *Set* ADT has other important operations this may not hold

- **union**, **intersection**, **is\_subset**
- Notice these are binary operators on sets

# *Dictionary data structures*

There are many good data structures for (large) dictionaries

1. AVL trees
  - Binary search trees with *guaranteed balancing*
2. B-Trees
  - Also always balanced, but different and shallower
  - B≠Binary; B-Trees generally have large branching factor
3. Hashtables
  - Not tree-like at all

Skipping: Other balanced trees (e.g., red-black, splay)

But first some applications and less efficient implementations...

# *A Modest Few Uses*

Any time you want to store information according to some key and be able to retrieve it efficiently

– Lots of programs do that!

- Search: inverted indexes, phone directories, ...
- Networks: router tables
- Operating systems: page tables
- Compilers: symbol tables
- Databases: dictionaries with other nice properties
- Biology: genome maps
- ...

# *Simple implementations*

For dictionary with  $n$  key/value pairs

**insert**      **find**      **delete**

- Unsorted linked-list
- Unsorted array
- Sorted linked list
- Sorted array

We'll see a Binary Search Tree (BST) probably does better, but not in the worst case unless we keep it balanced

# Simple implementations

For dictionary with  $n$  key/value pairs

	<b>insert</b>	<b>find</b>	<b>delete</b>
• Unsorted linked-list	$O(1)^*$	$O(n)$	$O(n)$
• Unsorted array	$O(1)^*$	$O(n)$	$O(n)$
• Sorted linked list	$O(n)$	$O(n)$	$O(n)$
• Sorted array	$O(n)$	$O(\log n)$	$O(n)$

\* Unless we need to check for duplicates

We'll see a Binary Search Tree (BST) probably does better, but not in the worst case unless we keep it balanced

# Lazy Deletion

10	12	24	30	41	42	44	45	50
✓	✗	✓	✓	✓	✓	✗	✓	✓

A *general technique* for making **delete** as fast as **find**:

- Instead of actually removing the item just mark it deleted

Plusses:

- Simpler
- Can do removals later in batches
- If re-added soon thereafter, just unmark the deletion

Minuses:

- Extra *space* for the “is-it-deleted” flag
- Data structure full of deleted nodes wastes *space*
- **find**  $O(\log m)$  *time* where  $m$  is data-structure size (okay)
- May complicate other operations

# Tree terms (review?)

*root(tree)*

*leaves(tree)*

*children(node)*

*parent(node)*

*siblings(node)*

*ancestors(node)*

*descendants(node)*

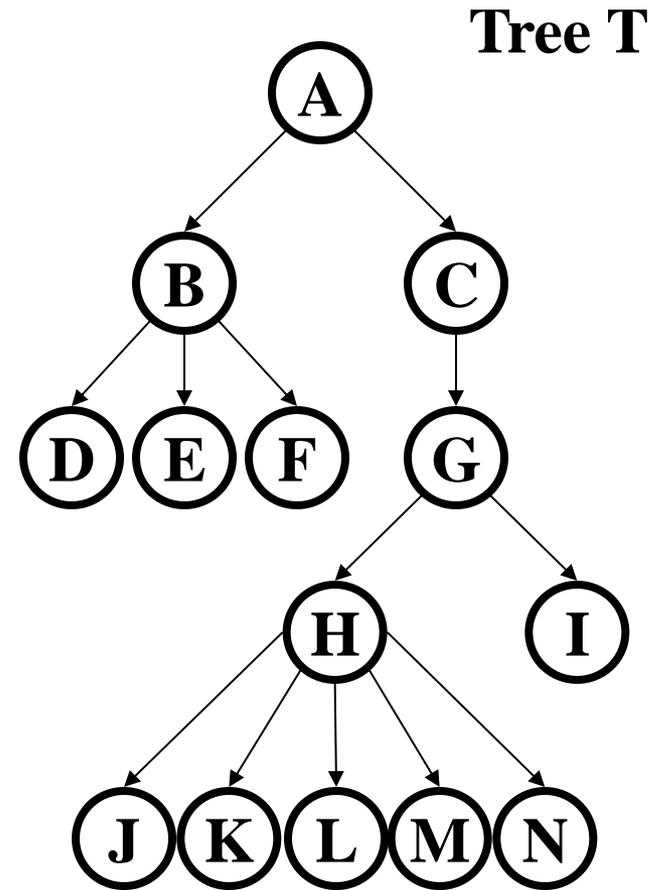
*subtree(node)*

*depth(node)*

*height(tree)*

*degree(node)*

*branching factor(tree)*



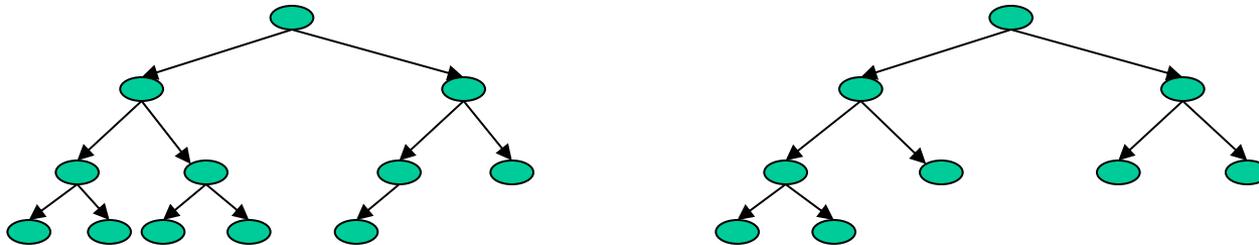
# *Some tree terms (mostly review)*

- There are many kinds of trees
  - Every binary tree is a tree
  - Every list is kind of a tree (think of “next” as the one child)
- There are many kinds of binary trees
  - Every binary search tree is a binary tree
  - Later: A binary heap is a different kind of binary tree
- A tree can be balanced or not
  - A balanced tree with  $n$  nodes has a height of  $O(\log n)$
  - Different tree data structures have different “balance conditions” to achieve this

# Kinds of trees

Certain terms define trees with specific structure

- **Binary tree**: Each node has at most 2 children (branching factor 2)
- **$n$ -ary tree**: Each node has at most  $n$  children (branching factor  $n$ )
- **Perfect tree**: Each row completely full
- **Complete tree**: Each row completely full except maybe the bottom row, which is filled from left to right



What is the height of a **perfect binary** tree with  $n$  nodes?

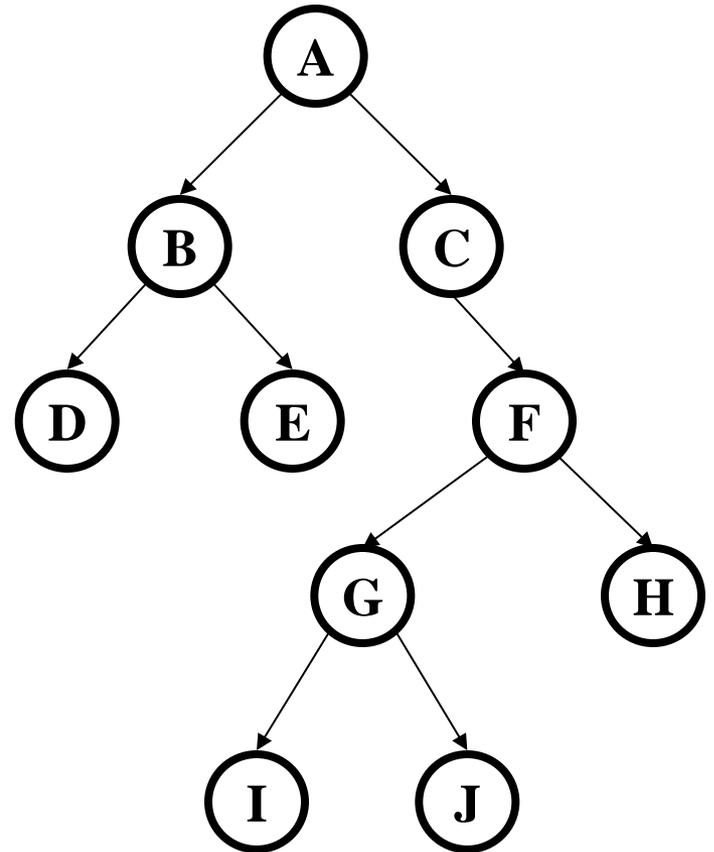
A **complete binary** tree?

# Binary Trees

- Binary tree is empty or
  - A root (*with data*)
  - A left subtree (*may be empty*)
  - A right subtree (*may be empty*)
- Representation:

<b>Data</b>	
left pointer	right pointer

- For a dictionary, data will include a key and a value



# *Binary Trees: Some Numbers*

Recall: height of a tree = longest path from root to leaf (count edges)

For binary tree of height  $h$ :

- max # of leaves:
- max # of nodes:
- min # of leaves:
- min # of nodes:

# *Binary Trees: Some Numbers*

Recall: height of a tree = longest path from root to leaf (count edges)

For binary tree of height  $h$ :

- max # of leaves:  $2^h$
- max # of nodes:  $2^{(h+1)} - 1$
- min # of leaves:  $1$
- min # of nodes:  $h + 1$

*For  $n$  nodes, we cannot do better than  $O(\log n)$  height,  
and we want to avoid  $O(n)$  height*

# *Calculating height*

What is the height of a tree with root `root`?

```
int treeHeight(Node root) {  
    ???  
}
```

# Calculating height

What is the height of a tree with root `root`?

```
int treeHeight(Node root) {  
    if (root == null)  
        return -1;  
    return 1 + max(treeHeight(root.left),  
                   treeHeight(root.right));  
}
```

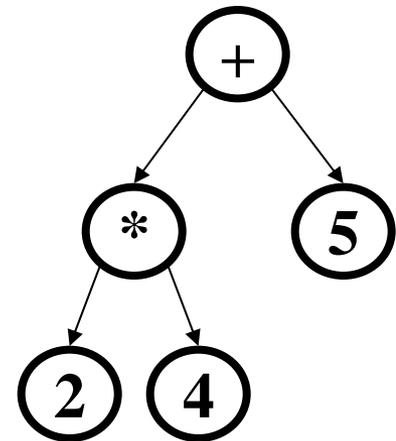
Running time for tree with  $n$  nodes:  $O(n)$  – single pass over tree

Note: non-recursive is painful – need your own stack of pending nodes; much easier to use recursion's call stack

# Tree Traversals

A *traversal* is an order for visiting all the nodes of a tree

- *Pre-order*: root, left subtree, right subtree
- *In-order*: left subtree, root, right subtree
- *Post-order*: left subtree, right subtree, root

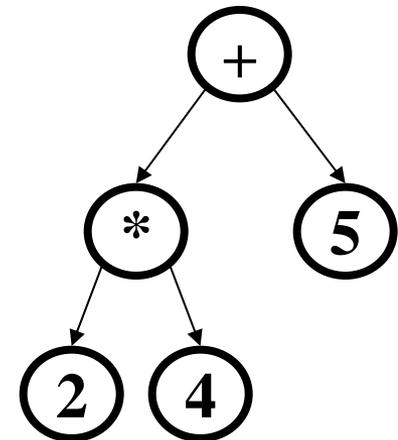


**(an expression tree)**

# Tree Traversals

A *traversal* is an order for visiting all the nodes of a tree

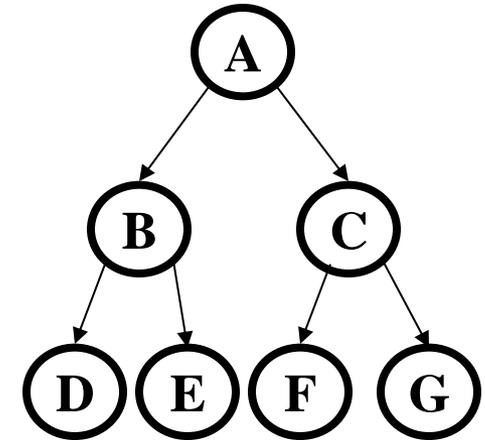
- *Pre-order*: root, left subtree, right subtree  
+ \* 2 4 5
- *In-order*: left subtree, root, right subtree  
2 \* 4 + 5
- *Post-order*: left subtree, right subtree, root  
2 4 \* 5 +



**(an expression tree)**

# More on traversals

```
void inOrderTraversal(Node t) {  
    if(t != null) {  
        inOrderTraversal(t.left);  
        process(t.element);  
        inOrderTraversal(t.right);  
    }  
}
```



Sometimes order doesn't matter

- Example: sum all elements

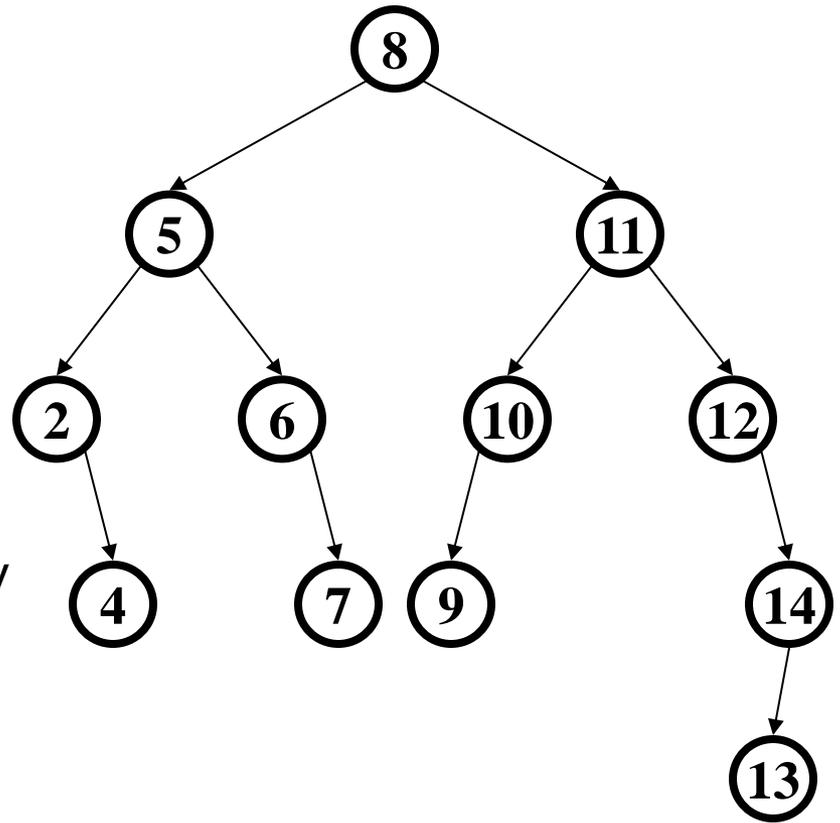
Sometimes order matters

- Example: print tree with parent above indented children (pre-order)
- Example: evaluate an expression tree (post-order)

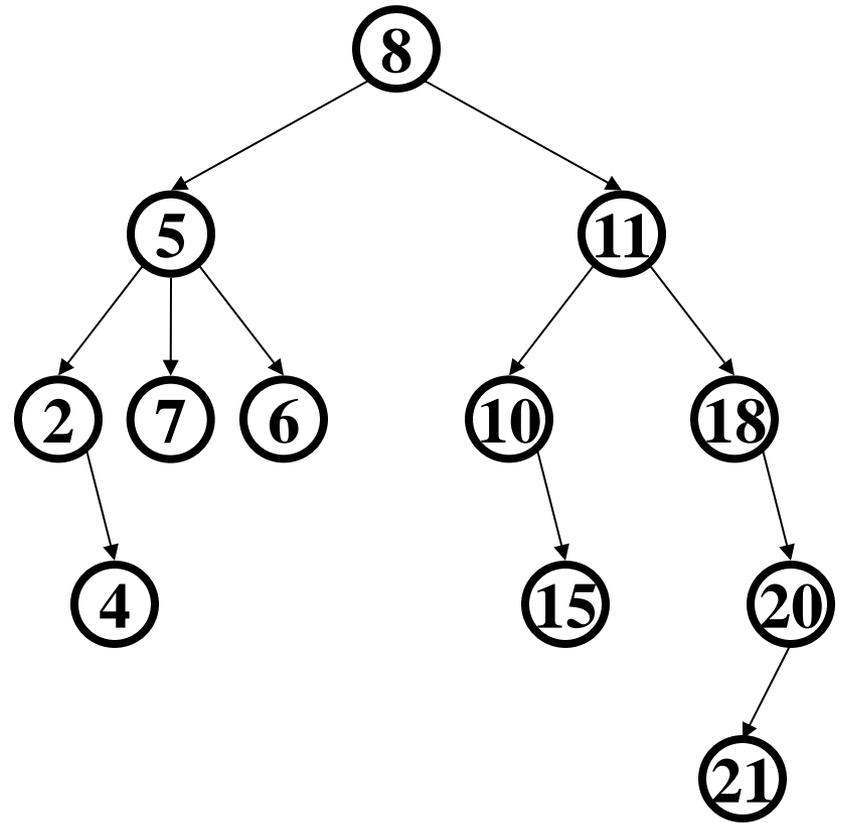
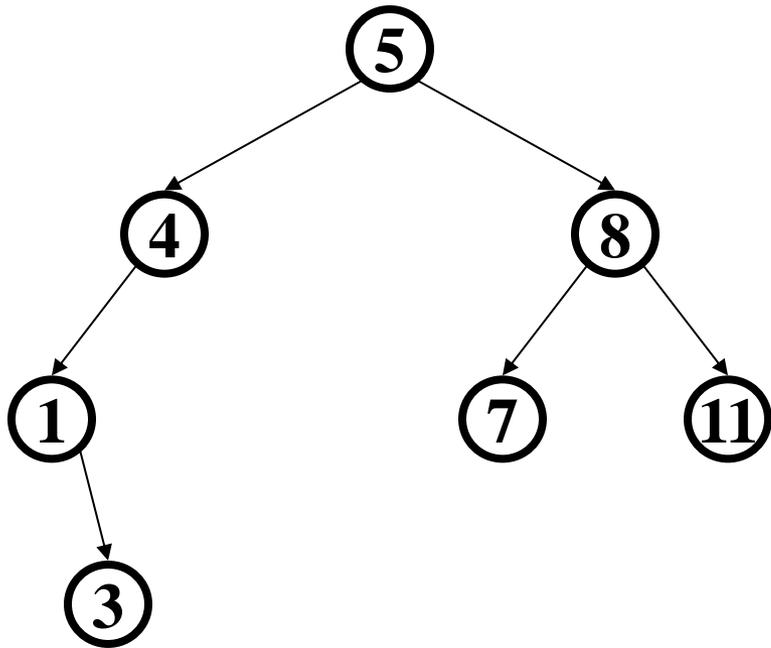
A  
  B  
    D  
    E  
  C  
    F  
    G

# Binary Search Tree

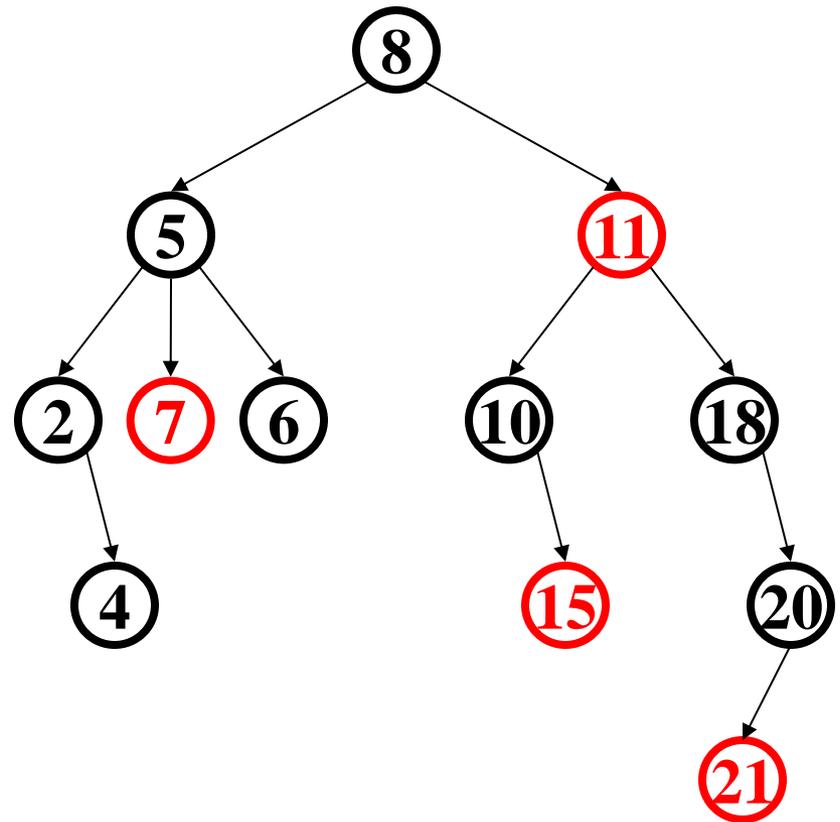
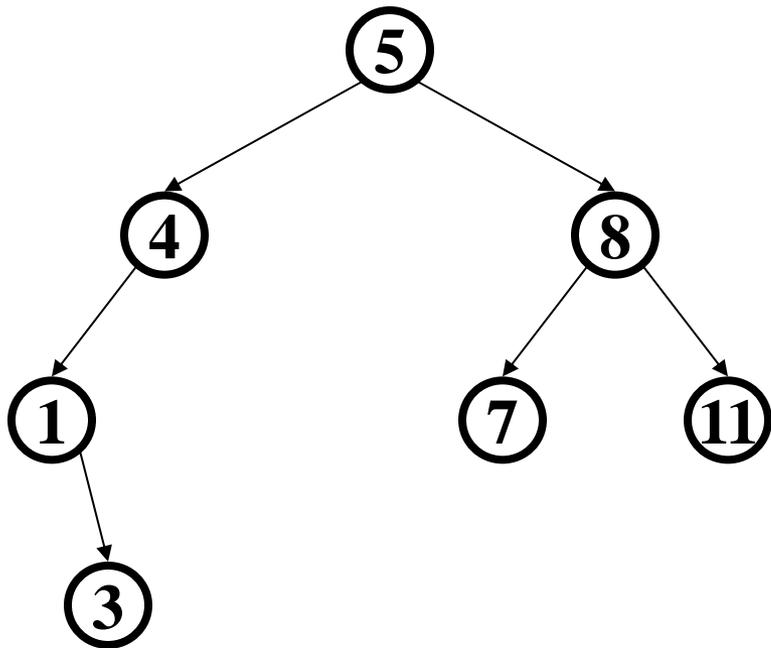
- Structure property (“binary”)
  - Each node has  $\leq 2$  children
  - Result: keeps operations simple
- Order property
  - All keys in left subtree smaller than node’s key
  - All keys in right subtree larger than node’s key
  - Result: easy to find any given key



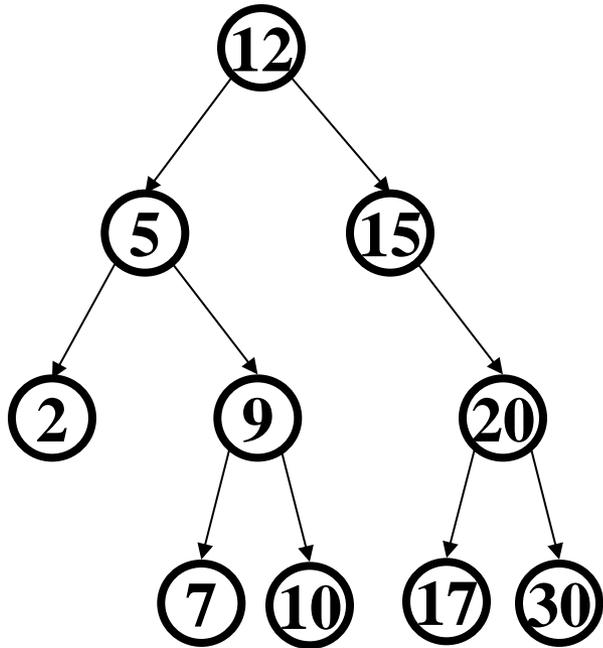
*Are these BSTs?*



# Are these BSTs?

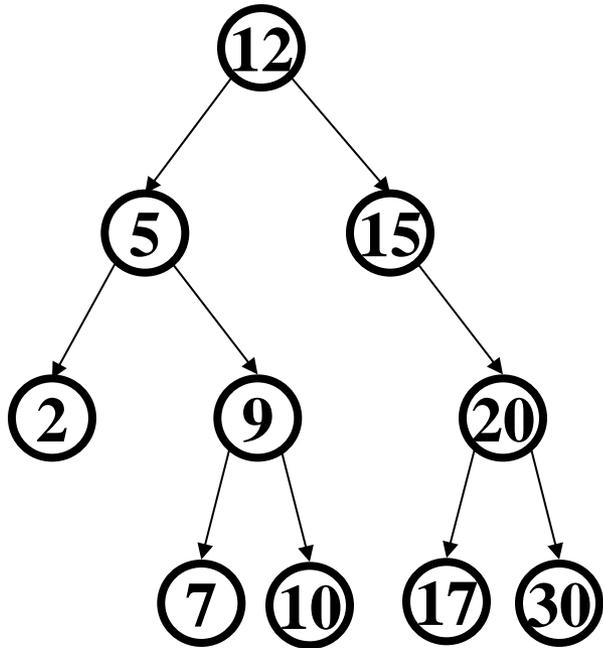


# Find in BST, Recursive



```
Data find(Key key, Node root) {  
    if(root == null)  
        return null;  
    if(key < root.key)  
        return find(key, root.left);  
    if(key > root.key)  
        return find(key, root.right);  
    return root.data;  
}
```

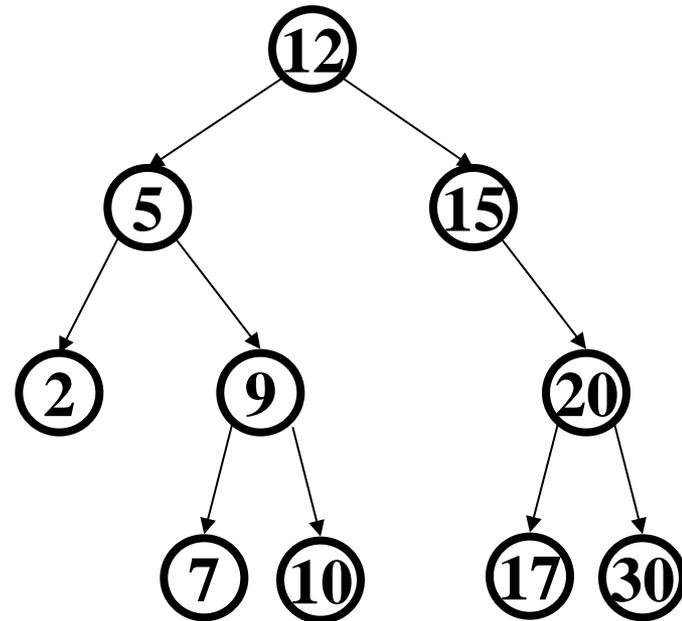
# Find in BST, Iterative



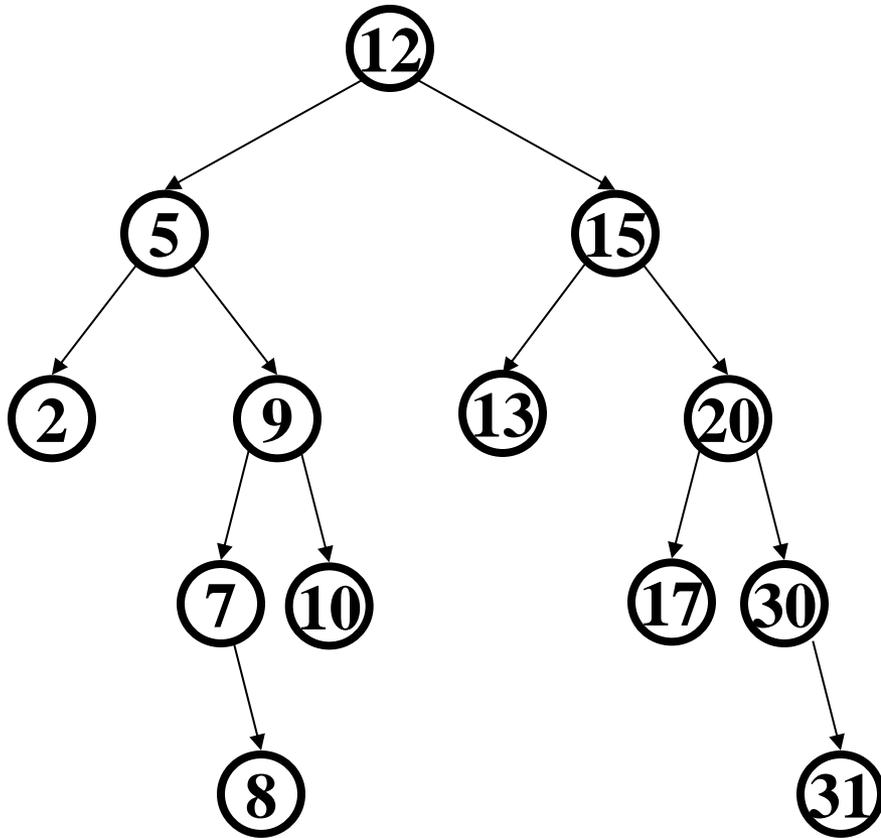
```
Data find(Key key, Node root) {  
    while (root != null  
           && root.key != key) {  
        if (key < root.key)  
            root = root.left;  
        else (key > root.key)  
            root = root.right;  
        }  
    if (root == null)  
        return null;  
    return root.data;  
}
```

# Other “Finding” Operations

- Find *minimum* node
  - “the liberal algorithm”
- Find *maximum* node
  - “the conservative algorithm”
- Find *predecessor* of a non-leaf
- Find *successor* of a non-leaf
- Find *predecessor* of a leaf
- Find *successor* of a leaf



# Insert in BST



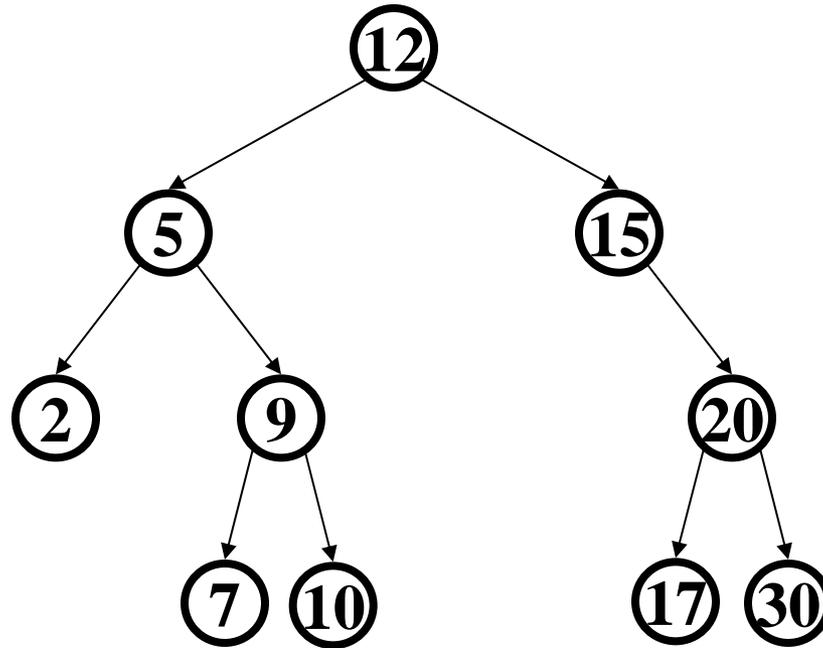
`insert(13)`

`insert(8)`

`insert(31)`

(New) insertions happen only at leaves – easy!

# Deletion in BST



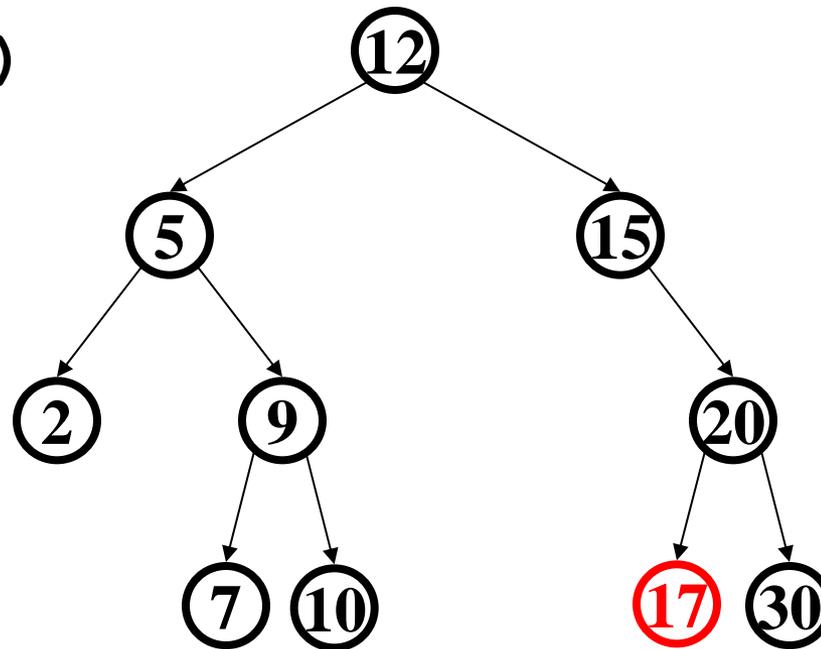
Why might deletion be harder than insertion?

# *Deletion*

- Removing an item disrupts the tree structure
- Basic idea: **find** the node to be removed, then “fix” the tree so that it is still a binary search tree
- Three cases:
  - Node has no children (leaf)
  - Node has one child
  - Node has two children

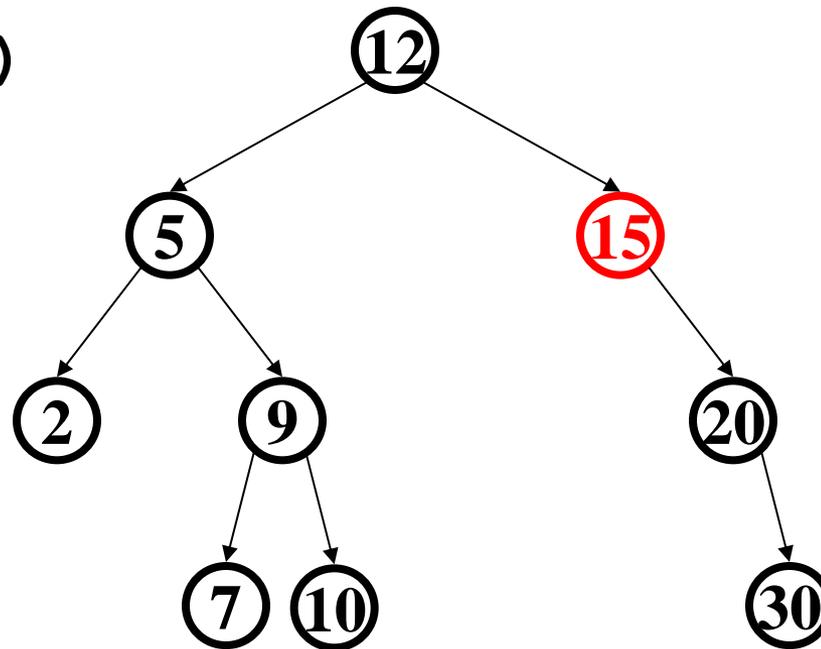
# Deletion – The Leaf Case

delete (17)



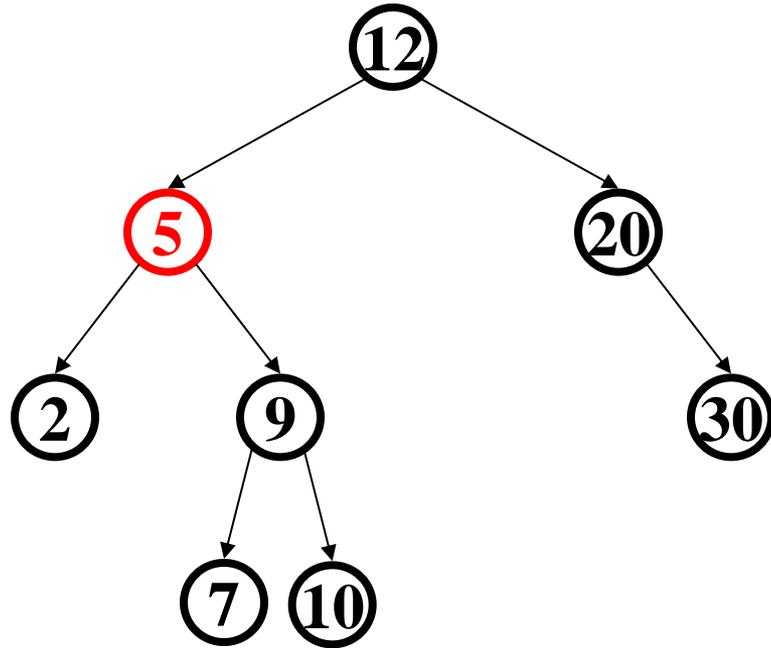
# Deletion – The One Child Case

delete (15)



# Deletion – The Two Child Case

delete (5)



What can we replace **5** with?

# *Deletion – The Two Child Case*

Idea: Replace the deleted node with a value guaranteed to be between the two child subtrees

Options:

- *successor* from right subtree: `findMin(node.right)`
- *predecessor* from left subtree: `findMax(node.left)`
  - These are the easy cases of predecessor/successor

Now delete the original node containing *successor* or *predecessor*

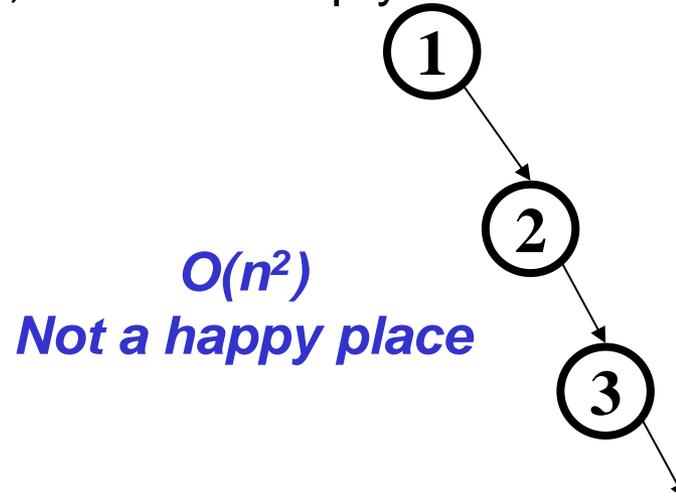
- Leaf or one child case – easy cases of delete!

# *Lazy Deletion*

- Lazy deletion can work well for a BST
  - Simpler
  - Can do “real deletions” later as a batch
  - Some inserts can just “undelete” a tree node
- But
  - Can waste space and slow down find operations
  - Make some operations more complicated:
    - How would you change **findMin** and **findMax**?

# *BuildTree for BST*

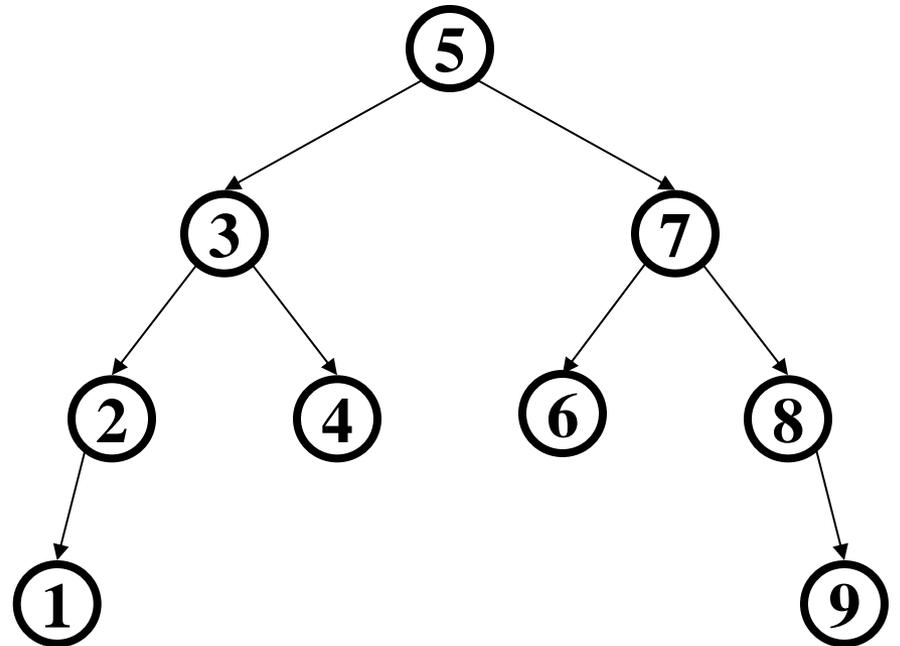
- Let's consider `buildTree`
  - Insert all, starting from an empty tree
- Insert keys 1, 2, 3, 4, 5, 6, 7, 8, 9 into an empty BST
  - If inserted in given order, what is the tree?
  - What big-O runtime for this kind of sorted input?
  - Is inserting in the reverse order any better?



# BuildTree for BST

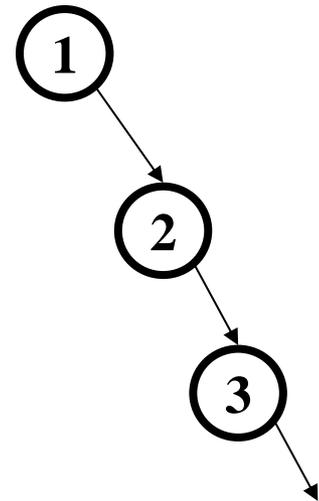
- Insert keys 1, 2, 3, 4, 5, 6, 7, 8, 9 into an empty BST
- What we if could somehow re-arrange them
  - median first, then left median, right median, etc.
  - 5, 3, 7, 2, 1, 4, 8, 6, 9
  - What tree does that give us?
  - What big-O runtime?

***$O(n \log n)$ , definitely better***



# Unbalanced BST

- Balancing a tree at build time is insufficient, as sequences of operations can eventually transform that carefully balanced tree into the dreaded list
- At that point, everything is  $O(n)$  and nobody is happy
  - **find**
  - **insert**
  - **delete**



# Balanced BST

## Observation

- BST: the shallower the better!
- For a BST with  $n$  nodes inserted in arbitrary order
  - Average height is  $O(\log n)$  – see text for proof
  - Worst case height is  $O(n)$
- Simple cases, such as inserting in key order, lead to the worst-case scenario

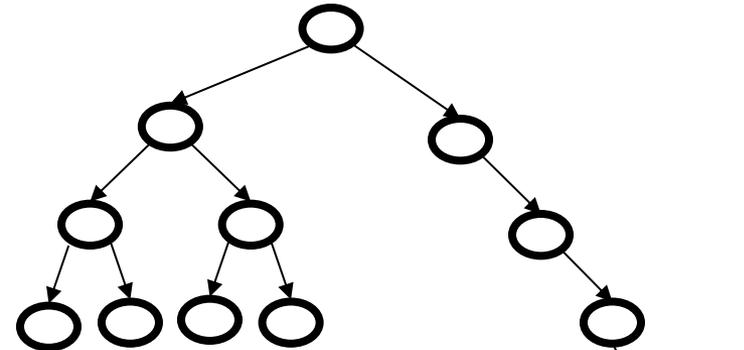
*Solution:* Require a **Balance Condition** that

1. Ensures depth is always  $O(\log n)$  – strong enough!
2. Is efficient to maintain – not too strong!

# Potential Balance Conditions

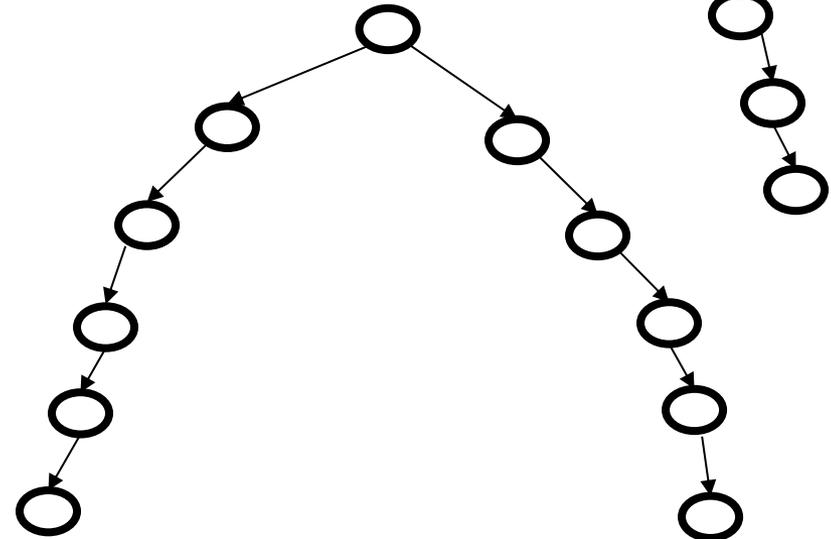
1. Left and right subtrees of the *root* have equal number of nodes

*Too weak!*  
*Height mismatch example:*



2. Left and right subtrees of the *root* have equal *height*

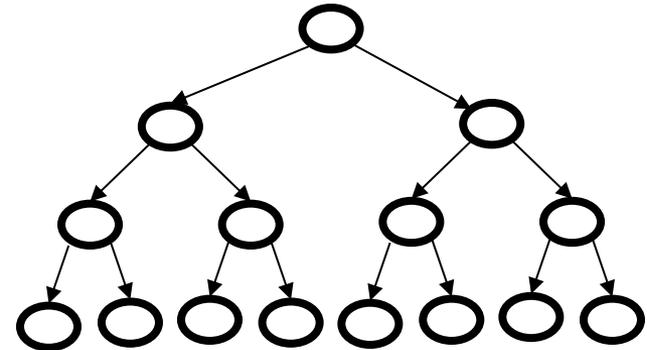
*Too weak!*  
*Double chain example:*



# Potential Balance Conditions

3. Left and right subtrees of every node have equal number of nodes

*Too strong!*  
*Only perfect trees ( $2^n - 1$  nodes)*



4. Left and right subtrees of every node have equal *height*

*Too strong!*  
*Only perfect trees ( $2^n - 1$  nodes)*

# *The AVL Balance Condition*

Left and right subtrees of *every node*  
have *heights differing by at most 1*

*Definition:* **balance**(*node*) = height(*node*.left) – height(*node*.right)

*AVL property:* **for every node  $x$ ,  $-1 \leq \text{balance}(x) \leq 1$**

- Ensures small depth
  - Will prove this by showing that an AVL tree of height  $h$  must have a number of nodes *exponential* in  $h$
- Efficient to maintain
  - Using single and double rotations