



CSE373: Data Structures & Algorithms

Lecture 22: Parallel Reductions, Maps, and Algorithm Analysis

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Outline

Done:

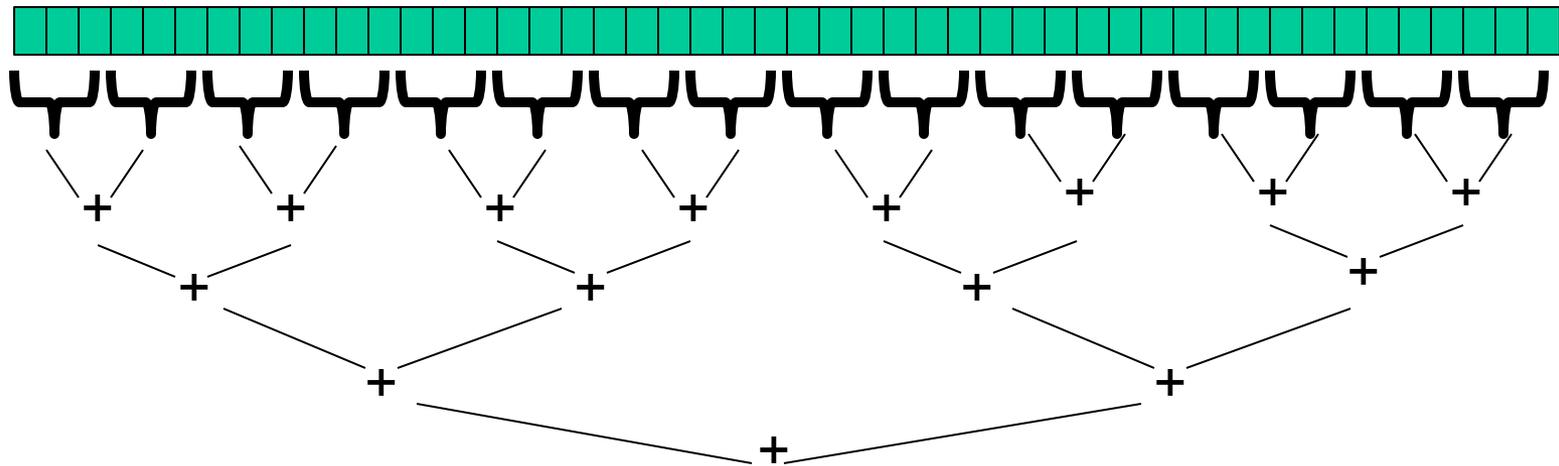
- How to write a parallel algorithm with fork and join
- Why using divide-and-conquer with lots of small tasks is best
 - Combines results in parallel
 - (Assuming library can handle “lots of small threads”)

Now:

- More examples of simple parallel programs that fit the “map” or “reduce” patterns
- Teaser: Beyond maps and reductions
- Asymptotic analysis for fork-join parallelism
- Amdahl’s Law

What else looks like this?

- Saw summing an array went from $O(n)$ sequential to $O(\log n)$ parallel (assuming **a lot** of processors and very large $n!$)
 - Exponential speed-up in theory ($n / \log n$ grows exponentially)



- Anything that can use results from two halves and merge them in $O(1)$ time has the same property...

Examples

- Maximum or minimum element
- Is there an element satisfying some property (e.g., is there a 17)?
- Left-most element satisfying some property (e.g., first 17)
 - What should the recursive tasks return?
 - How should we merge the results?
- Corners of a rectangle containing all points (a “bounding box”)
- Counts, for example, number of strings that start with a vowel
 - This is just summing with a different base case
 - Many problems are!

Reductions

- Computations of this form are called **reductions** (or **reduces**?)
- Produce single answer from collection via an **associative operator**
 - Associative: $a + (b+c) = (a+b) + c$
 - Examples: max, count, leftmost, rightmost, sum, product, ...
 - Non-examples: median, subtraction, exponentiation
- But some things are inherently sequential
 - How we process `arr[i]` may depend entirely on the result of processing `arr[i-1]`

Even easier: Maps (Data Parallelism)

- A **map** operates on each element of a collection independently to create a new collection of the same size
 - No combining results
 - For arrays, this is so trivial some hardware has direct support
- Canonical example: Vector addition

```
int[] vector add(int[] arr1, int[] arr2) {
    assert (arr1.length == arr2.length);
    result = new int[arr1.length];
    FORALL(i=0; i < arr1.length; i++) {
        result[i] = arr1[i] + arr2[i];
    }
    return result;
}
```

In Java

```
class VecAdd extends java.lang.Thread {
    int lo; int hi; int[] res; int[] arr1; int[] arr2;
    VecAdd(int l, int h, int[] r, int[] a1, int[] a2) { ... }
    protected void run() {
        if(hi - lo < SEQUENTIAL CUTOFF) {
            for(int i=lo; i < hi; i++)
                res[i] = arr1[i] + arr2[i];
        } else {
            int mid = (hi+lo)/2;
            VecAdd left = new VecAdd(lo, mid, res, arr1, arr2);
            VecAdd right = new VecAdd(mid, hi, res, arr1, arr2);
            left.start();
            right.run();
            left.join();
        }
    }
}

int[] add(int[] arr1, int[] arr2) {
    assert (arr1.length == arr2.length);
    int[] ans = new int[arr1.length];
    (new VecAdd(0, arr.length, ans, arr1, arr2).run());
    return ans;
}
```

Maps and reductions

Maps and reductions: the “workhorses” of parallel programming

- By far the two most important and common patterns
- Learn to recognize when an algorithm can be written in terms of maps and reductions
- Use maps and reductions to describe (parallel) algorithms
- Programming them becomes “trivial” with a little practice
 - Exactly like sequential for-loops seem second-nature

Beyond maps and reductions

- Some problems are “inherently sequential”
 “Nine women can’t make a baby in one month”
- But not all parallelizable problems are maps and reductions
- If had one more lecture, would show “parallel prefix”, a clever algorithm to parallelize the *problem* that this sequential *code* solves

input	6	4	16	10	16	14	2	8
output	6	10	26	36	52	66	68	76

```
int[] prefix_sum(int[] input) {
    int[] output = new int[input.length];
    output[0] = input[0];
    for(int i=1; i < input.length; i++)
        output[i] = output[i-1]+input[i];
    return output;
}
```

Digression: MapReduce on clusters

- You may have heard of Google's "map/reduce"
 - Or the open-source version Hadoop
- Idea: Perform maps/reduces on data using many machines
 - The system takes care of distributing the data and managing fault tolerance
 - You just write code to map one element and reduce elements to a combined result
- Separates how to do recursive divide-and-conquer from what computation to perform
 - Separating concerns is good software engineering

Analyzing algorithms

- Like all algorithms, parallel algorithms should be:
 - Correct
 - Efficient
- For our algorithms so far, correctness is “obvious” so we’ll focus on efficiency
 - Want asymptotic bounds
 - Want to analyze the algorithm without regard to a specific number of processors
 - Here: Identify the “best we can do” *if* the underlying *thread-scheduler* does its part

Work and Span

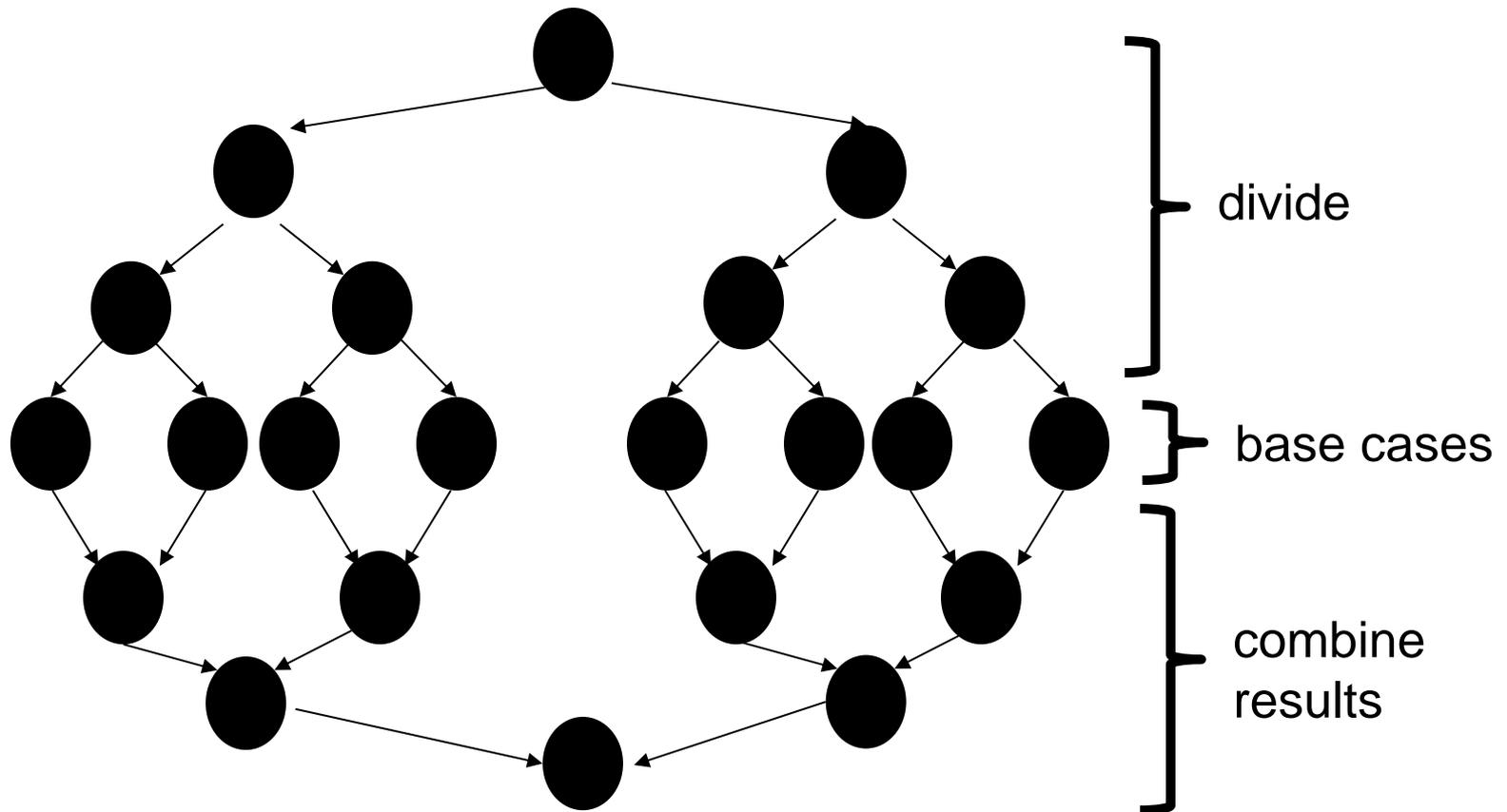
Let T_P be the running time if there are P processors available

Two key measures of run-time:

- **Work**: How long it would take 1 processor = T_1
 - Just “sequentialize” the recursive forking
- **Span**: How long it would take infinity processors = T_∞
 - The longest dependence-chain
 - Example: $O(\log n)$ for summing an array
 - Notice having $> n/2$ processors is no additional help

Our simple examples

- Picture showing all the “stuff that happens” during a reduction or a map: it’s a (conceptual!) DAG



Connecting to performance

- Recall: T_P = running time if there are P processors available
- Work = T_1 = sum of run-time of all nodes in the DAG
 - That lonely processor does everything
 - Any topological sort is a legal execution
 - $O(n)$ for maps and reductions
- Span = T_∞ = sum of run-time of all nodes on the most-expensive path in the DAG
 - Note: costs are on the nodes not the edges
 - Our infinite army can do everything that is ready to be done, but still has to wait for earlier results
 - $O(\log n)$ for simple maps and reductions

Speed-up

Parallel algorithms is about decreasing span without increasing work too much

- **Speed-up** on **P** processors: T_1 / T_P
- **Parallelism** is the maximum possible speed-up: T_1 / T_∞
 - At some point, adding processors won't help
 - What that point is depends on the span
- In practice we have **P** processors. How well can we do?
 - We cannot do better than $O(T_\infty)$ (“must obey the span”)
 - We cannot do better than $O(T_1 / P)$ (“must do all the work”)
 - Not shown: With a “good thread scheduler”, can do this well (within a constant factor of optimal!)

Examples

$$T_p = O(\max((T_1 / P), T_\infty))$$

- In the algorithms seen so far (e.g., sum an array):
 - $T_1 = O(n)$
 - $T_\infty = O(\log n)$
 - So expect (ignoring overheads): $T_p = O(\max(n/P, \log n))$
- Suppose instead:
 - $T_1 = O(n^2)$
 - $T_\infty = O(n)$
 - So expect (ignoring overheads): $T_p = O(\max(n^2/P, n))$

Amdahl's Law (mostly bad news)

- So far: analyze parallel programs in terms of work and span
- In practice, typically have parts of programs that parallelize well...
 - Such as maps/reductions over arrays
- ...and parts that don't parallelize at all
 - Such as reading a linked list, getting input, doing computations where each needs the previous step, etc.

Amdahl's Law (mostly bad news)

Let the **work** (time to run on 1 processor) be 1 unit time

Let **S** be the portion of the execution that can't be parallelized

Then: $T_1 = S + (1-S) = 1$

Suppose *parallel portion parallelizes perfectly (generous assumption)*

Then: $T_p = S + (1-S)/P$

So the overall speedup with **P** processors is (Amdahl's Law):

$$T_1 / T_p = 1 / (S + (1-S)/P)$$

And the parallelism (infinite processors) is:

$$T_1 / T_\infty = 1 / S$$

Why such bad news

$$T_1 / T_P = 1 / (S + (1-S)/P)$$

$$T_1 / T_\infty = 1 / S$$

- Suppose 33% of a program's execution is sequential
 - Then a billion processors won't give a speedup over 3
- Suppose you miss the good old days (1980-2005) where 12ish years was long enough to get 100x speedup
 - Now suppose in 12 years, clock speed is the same but you get 256 processors instead of 1
 - For 256 processors to get at least 100x speedup, we need
$$100 \leq 1 / (S + (1-S)/256)$$
Which means $S \leq .0061$ (i.e., 99.4% perfectly parallelizable)

All is not lost

Amdahl's Law is a bummer!

- Unparallelized parts become a bottleneck very quickly
- But it doesn't mean additional processors are worthless
- We can find new parallel algorithms
 - Some things that seem sequential are actually parallelizable
- We can change the problem or do new things
 - Example: Video games use tons of parallel processors
 - They are not rendering 10-year-old graphics faster
 - They are rendering more beautiful(?) monsters

Moore and Amdahl



- Moore's "Law" is an observation about the progress of the semiconductor industry
 - Transistor density doubles roughly every 18 months
- Amdahl's Law is a mathematical theorem
 - Diminishing returns of adding more processors
- Both are incredibly important in designing computer systems