Lecture 25: Kruskal and beyond...

- What we will munch on today:
$\Rightarrow$ Minimum Spanning Trees
- Prim's Algorithm
- Kruskal's Algorithm
$\Rightarrow$ Those Puzzles from $4^{\text {th }}$ grade!
$\Rightarrow$ Euler Circuits and Tours
- Covered in Chapter 9 in the textbook


## Recall from Last Time: Spanning Trees

- Spanning tree: subset of edges from a connected graph G $=(V, E)$ that:

1. touches all vertices in the graph (spans the graph), and
2. forms a tree (is connected, with no cycles $\rightarrow|\mathrm{V}|-1$ edges)


- Minimum spanning tree (MST): spanning tree with the least total edge cost


## Why greed works for finding MSTs...

- For any spanning tree T , inserting an edge e not in T creates a cycle $\rightarrow$ Removing any edge gives back a spanning tree $\Rightarrow$ If e had a lower cost than removed edge, we get a lower cost spanning tree
- Idea: Create a spanning tree as follows:

1. Add an edge of minimum cost that doesn't create a cycle
2. Repeat Step 1 for $|V|-1$ edges

- This spanning tree has minimum cost because:
$\Rightarrow$ if you can replace an edge with another edge of lower cost without creating a cycle, our algorithm would have picked it
- Two MST algorithms: Prim (1957) and Kruskal, Jr. (1956)
$\Rightarrow$ Differ in how an edge of minimum cost is picked


## Prim's Algorithm for Finding the MST

1. Starting from an empty tree, $T$, pick a vertex, $v 0$, at random and initialize: $V^{\prime}=\{v 0\}$ and $E^{\prime}=\{ \}$
2. Choose a vertex $v$ not in $V^{\prime}$ such that edge weight from $v$ to a vertex in $V^{\prime}$ is minimal (get greedy!)
3. Add $v$ to $V^{\prime}$ and the edge to $E^{\prime}$ if no cycle is created
4. Repeat until all vertices have been added


## Prim's Algorithm: Implemented and Analyzed

- Implementation details:

1. Initialize cost of each node to $\infty$ and mark it unknown
2. Initialize cost of one selected node $S$ to 0 , with $\operatorname{Prev}[\mathrm{S}]=0$
3. While there are unknown nodes left in the graph
4. Select the unknown node $N$ with the lowest cost
5. Mark $N$ as known
6. For each unknown node $A$ adjacent to $N$ If cost of ( $N, A$ ) < A's cost
$A$ 's cost $=\operatorname{cost}$ of $(N, A)$
$\operatorname{Prev}[A]=N / /$ store preceding node

- This is almost identical to Dijkstra's algorithm!
- Run time is $\mathrm{O}\left(|V|^{2}\right)$ without heaps and $\mathrm{O}(|V| \log |V|+|E| \log$ $|V|)$ using binary heaps


## Kruskal finds another greedy way to MST

- In 1956, J. B. Kruskal, Jr. found another way to find MSTs
- Main Idea: Select edges in order of increasing cost and accept an edge only if it does not cause a cycle
- Pseudocode for Kruskal's MST algorithm:
$\Rightarrow$ Put all the vertices into single node trees by themselves
$\Rightarrow$ Put all the edges in a priority queue with key $=$ edge cost
$\Rightarrow$ Repeat until $|\mathrm{V}|-1$ edges have been accepted
- Extract cheapest edge

If it forms a cycle, ignore it
else accept the edge - it will join two existing trees and yield a larger tree
$\Rightarrow$ Return the accepted edges (they form the spanning tree)

## Kruskal's Algorithm in C

```
Forest Kruskal_MST( Graph g, int n, double **costs )
{
    Forest T;
                                    n=|V|
    Queue q;
    Edge e;
    T = ConsForest( g ); Initial Forest: single vertex trees
    q = BuildHeap( g, costs ); Priority Q of edges
        for(i=0;i<(n-1);i++) {
            do {
                e = DeleteMin( q );
            } while ( Cycle( e, T ) );
            AddEdge( T, e );
    }
    return T;
}

Kruskal's Algorithm in C
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    for(i=0;i<(n-1);i++) {
            do {
                e = DeleteMin( q );
            } while ( Cycle( e, T ) );
            AddEdge( T, e );
    }
    return T; ... and add it to the forest!
}

Kruskal's Algorithm in C
```

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for(i=0;i<(n-1);i++) {
do {
e = DeleteMin( q );
} while ( Cycle( e, T ) );
AddEdge( T, e );
}
return T;
}

## Hints for Detecting Cycles in Kruskal's Method

- Initially, you have n different elements (single vertex trees)
- After you have added some edges, you have fewer elements - several disconnected trees, each with a subset of vertices
- When do you get a cycle? If you add an edge ( $u, v$ ) where both $u$ and $v$ are already in the same tree $T_{i}$, you get a cycle
$\Rightarrow$ Therefore, to check for cycles, you only need to find out if $u$ and v are in the same tree
$\Rightarrow$ If not, then the edge can be added and we union vertices in u's tree with vertices in v's tree
- What is your favorite data structure for such operations?


## Disjoint Set ADT in Kruskal's Algorithm

$\checkmark$ Here's how the disjoint set ADT makes an appearance:
$\Rightarrow$ In Kruskal's algorithm, connected vertices form equivalence classes (they are in the same tree)
*"Being connected" is the equivalence relation

- Initially, each vertex is in a class by itself
- As edges are added, more vertices become related and the equivalence classes grow
$\uparrow$ Until finally all the vertices are in a single equivalence class


## Union/Find in Kruskal's Algorithm

- Representatives
$\Rightarrow$ One vertex in each class can be the representative of that class
$\Rightarrow$ Vertices can be stored in up-tree data structures with roots = class representatives
- This is what we used for Union-Find
$\rightarrow$ Detecting cycles is easy!
$\Rightarrow$ For each edge (u,v) that you're going to add
- If Find( $u$ ) $==$ Find(v), then $u$ and $v$ are in the same class (same tree) and therefore the edge will form a cycle
- Otherwise, we accept the edge and do Union(u,v)


## Kruskal's Algorithm in C

```
Forest Kruskal_MST( Graph g, int n, double **costs ) {
    Forest T;
    Queue q;
    Edge e;
    DisjSet S = InitializeSet( g );
    T = ConsForest( g );
    q = BuildHeap( g, costs );
    for(i=0;i<(n-1);i++) {
            do {
                e = DeleteMin( q ); // e = (u,v)
            } while ( (Find(u,S) == Find(v,S)) );
            AddEdge( T, e );
            Union(S, u, v);
    }
    return T; }

Kruskal in action

> \begin{tabular}{l}  All the vertices are in \\ single element trees \\ \hline \end{tabular}


> Each vertex is its own representative

Kruskal in action


The cheapest edge
is \(\mathrm{h}-\mathrm{g}\)
Add it to the forest,
joining \(h\) and \(g\) into a
2-element tree

Kruskal in action


Kruskal in action


Our forest now has 2 two-element trees and 5 single vertex ones

Kruskal in action
\begin{tabular}{|c|}
\hline \begin{tabular}{c} 
The next cheapest edge \\
is \(g-f\)
\end{tabular} \\
\hline
\end{tabular}


Our forest now has 1 three-element tree, 1 two-element tree, and 4 single vertex ones

Kruskal in action


Our forest now has only 2 single vertex trees

Kruskal in action


Kruskal in action



Find \((\mathbf{g})\) is \(\mathbf{C}\)
Find( i ) is also C
g-i forms a cycle!

Ignore this edge

Kruskal in action


Kruskal in action

The next cheapest edge is \(\mathrm{h}-\mathrm{i}\)


Find(h) is C
Find( \(i\) is \(\mathbf{C}\)
h-i forms a cycle, so ignore it!

Kruskal in action

The next cheapest edge is a-h


Kruskal done!


But b-c forms a cycle


That's n-1 edges added - we now have a spanning tree!

\section*{Kruskal's Algorithm: Analysis}
```

Forest Kruskal_MST( Graph g, int n, double **costs ) {
Forest T;
Queue q;
Edge e;
DisjSet S = InitializeSet( g ); }\longrightarrow\textrm{T}=\textrm{COnsForest( g );
q = BuildHeap( g, costs ); }\longrightarrow\textrm{O}(|E|
for(i=0;i<(n-1);i++) {

```

Worst case: do \{
\(\operatorname{DeleteMin}|E| \quad e=\operatorname{DeleteMin}(\mathrm{q}) ; / / e=(u, v)\) edges, each \(\}\) while ( (Find \((u, S)==F i n d(v, S))\) ) \(\mathrm{O}(\log |E|)\) AddEdge \((\mathrm{T}, \mathrm{e}) ; \mathrm{O}(1) \longrightarrow \mathrm{O}(1)\) amortized Union(S, u, v);
\}
return \(\mathrm{T} ; \quad\} \quad\) Total time \(=\mathrm{O}(|E| \log |E|)\)
R. Rao, CSE 373

\section*{Kruskal versus Prim}
- Worst case running time
\(\Rightarrow\) Prim: \(\mathrm{O}(|V| \log |V|+|E| \log |V|)\)
\(\Rightarrow\) Kruskal: \(\mathrm{O}(|E| \log |E|)=\mathrm{O}(|E| \log |V|)\) since \(|E|=\mathrm{O}\left(|V|^{2}\right)\)
- Kruskal usually runs much faster than \(\mathrm{O}(|E| \log |V|)\) in practice
\(\Rightarrow\) Not all edges need to be DeleteMin-ed typically
\(\Rightarrow\) The required \(|V|-1\) edges are usually found quickly
\(\Rightarrow\) So, Kruskal tends to be faster than Prim

\section*{It's Puzzle Time!}


\section*{It's Puzzle Time!}


Historical Puzzle: Seven Bridges of Königsberg


Want to cross all bridges but...
Can cross each bridge only once (High toll to cross twice?!)

A "Multigraph" for the Bridges of Königsberg


\section*{Euler Circuits and Tours}
- Euler tour: a path through a graph that visits each edge exactly once
- Euler circuit: an Euler tour that starts and ends at the same vertex
\(\downarrow\) Named after Leonhard Euler (1707-1783), who cracked this problem and founded graph theory in 1736
- Some observations for undirected graphs:
\(\Rightarrow\) An Euler circuit is only possible if the graph is connected and each vertex has even degree (= \# of edges on the vertex) [Why?]
\(\Rightarrow\) An Euler tour is only possible if the graph is connected and either all vertices have even degree or exactly two have odd degree [Why?]

\section*{Euler Circuit Problem}
\(\rightarrow\) Problem: Given an undirected graph \(G=(V, E)\), find an Euler circuit in G
- Note: Can check if one exists in linear time (how?)
- Given that an Euler circuit exists, how do we construct an Euler circuit for G?
- Hint: Think deep! We've discussed the answer in depth before...

\section*{Next Class:}

Constructing Euler circuits
The vast gulf between Euler and Hamiltonian circuits
The dreaded world of NP hardness
To Do:
Programming Assignment \#2 (Due in 6 days!!)
Finish reading chapter 9 (and have a great weekend!)```

