

## CSE 373 Lecture 10: Heaps and Priority Queues

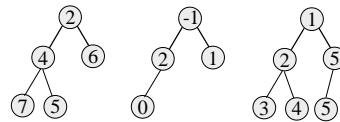
### ◆ Today's Topics:

- ⇒ Binary Heaps
  - ◆ Array Implementation
  - ◆ FindMin/DeleteMin and Percolate Down
  - ◆ Insert and Percolate Up
  - ◆ BuildHeap, DecreaseKey, IncreaseKey
- ⇒ Introduction to Binomial Queues

### ◆ Covered in Chapter 6 in the text

## Heaps

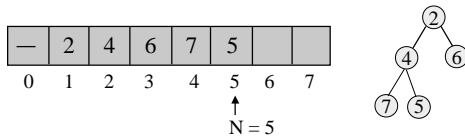
- ◆ A binary heap is a binary tree that is:
  1. Complete: the tree is completely filled except possibly the bottom level, which is filled from left to right
  2. Satisfies the heap order property: every node is smaller than (or equal to) its children
- ◆ Therefore, the root node is always the smallest in a heap



Which of these is not a heap?

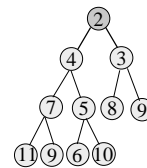
## Array Implementation of Heaps

- ◆ Since heaps are complete binary trees, we can avoid pointers and use an array
- ◆ Array Implementation:
  - ⇒ Root node =  $A[1]$
  - ⇒ Children of  $A[i] = A[2i], A[2i + 1]$
  - ⇒ Keep track of current size  $N$  (number of nodes)



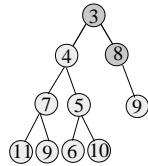
## Heaps: FindMin and DeleteMin Operations

- ◆ FindMin: Easy! Return root value  $A[1]$ 
  - ⇒ Run time = ?
- ◆ DeleteMin:
  - ⇒ Delete (and return) value at root node
  - ⇒ We now have a "Hole" at the root
  - ⇒ Need to fill the hole with another value
  - ⇒ Replace with smallest child?
    - ◆ Try replacing 2 with smallest child and that node with its smallest child, and so on... what happens?



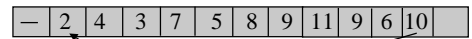
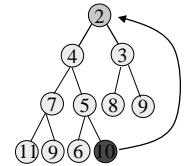
## Heaps: DeleteMin Operation

- ◆ DeleteMin:
  - ⇒ Delete (and return) value at root node
  - ⇒ We now have a "Hole" at the root
  - ⇒ Need to fill the hole with another value
  - ⇒ Replace with smallest child?
    - ◆ Try replacing 2 with smallest child and so on...what happens?
    - ◆ Tree is no longer complete!
    - ◆ Let's try another strategy...

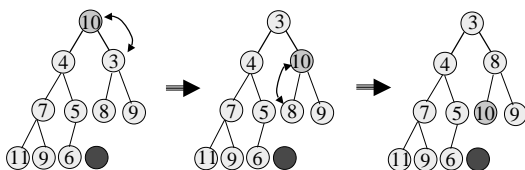


## Heaps: DeleteMin Operation

- ◆ DeleteMin:
  - ⇒ Delete (and return) value at root node
  - ⇒ We now have a "Hole" at the root
  - ⇒ Need to fill the hole with another value
- ◆ Since heap is one node smaller, we need to empty the last slot
- ◆ Steps:
  - ⇒ Move last item to top; decrease size by 1
  - ⇒ Percolate down the top item to its correct position in the heap



## DeleteMin: Percolate Down



- Keep comparing with children  $A[2i]$  and  $A[2i + 1]$
- Replace with smaller child and go down one level
- Done if both children are  $\geq$  item or reached a leaf node
- What is the run time?

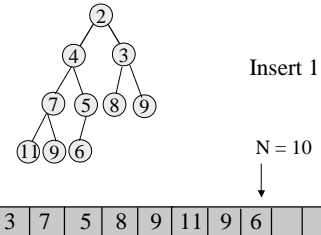
## DeleteMin: Run Time Analysis

- ◆ Run time is  $O(\text{depth of tree})$
- ◆ What is the depth of a complete binary tree of  $N$  nodes?

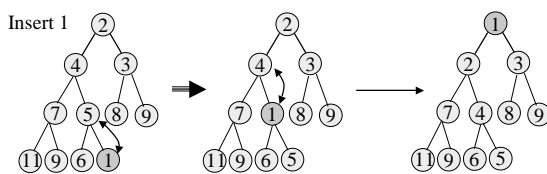
## DeleteMin: Run Time Analysis

- ◆ Run time is  $O(\text{depth of heap})$
- ◆ A heap is a complete binary tree
- ◆ What is the depth of a complete binary tree of  $N$  nodes?
  - ⇒ At depth  $d$ , you can have:  $N = 2^d$  (one leaf at depth  $d$ ) to  $2^{d+1}-1$  nodes (all leaves at depth  $d$ )
  - ⇒ So, depth  $d$  for a heap is:  $\log N \leq d \leq \log(N+1)-1$  or  $\Theta(\log N)$
- ◆ Therefore, run time of DeleteMin is  $O(\log N)$

## Heaps: Insert Operation



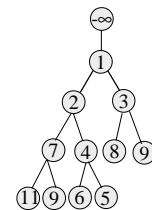
## Insert: Percolate Up



- Insert at last node and keep comparing with parent  $A[i/2]$
- If parent larger, replace with parent and go up one level
- Done if parent  $\leq$  item or reached top node  $A[1]$
- Run time?

## Sentinel Values

- ◆ Every iteration of Insert needs to test:
  1. if it has reached the top node  $A[1]$
  2. if parent  $\leq$  item
- ◆ Can avoid first test if  $A[0]$  contains a very large negative value (denoted by  $-\infty$ )
- ◆ Then, test #2 always stops at top
  - ⇒  $-\infty <$  item for all items
- ◆ Such a data value that serves as a marker is called a sentinel
  - ⇒ Used to improve efficiency and simplify code



A 

$-\infty$	1	2	3	7	4	8	9	11	9	6	5
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## Summary of Heap ADT Analysis

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- ◆ Consider a heap of  $N$  nodes
- ◆ Space needed:  $O(N)$ 
  - ⇒ Actually,  $O(\text{MaxSize})$  where  $\text{MaxSize}$  is the size of the array
  - ⇒ One more variable to store the size  $N$
  - ⇒ With sentinel, array-based implementation uses  $N+2$  space
  - ⇒ Pointer-based implementation: pointers for children and parent
    - ◆ Total space =  $3N + 1$  (3 pointers per node + 1 for size)
- ◆ FindMin:  $O(1)$  time; DeleteMin and Insert:  $O(\log N)$  time
- ◆ BuildHeap from  $N$  inputs: What is the run time?
  - ⇒  $N$  Insert operations =  $O(N \log N)$ . Actually, can do better...
  - ⇒  $O(N)$ : Treat input array as a heap and fix it using percolate down
    - ◆ See text for proof that this takes  $O(N)$  time.

## Other Heap Operations

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- ◆ Find( $X, H$ ): Find the element  $X$  in heap  $H$  of  $N$  elements
  - ⇒ What is the running time?
- ◆ FindMax( $H$ ): Find the maximum element in  $H$ 
  - ⇒ What is the running time?

## Other Heap Operations

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- ◆ Find and FindMax:  $O(N)$
- ◆ DecreaseKey( $P, \Delta, H$ ): Decrease the key value of node at position  $P$  by a positive amount  $\Delta$ . E.g. System administrators can increase priority of important jobs.
  - ⇒ First, subtract  $\Delta$  from current value at  $P$
  - ⇒ Heap order property may be violated
  - ⇒ Percolate up or down?
  - ⇒ Running time?

## Other Heap Operations

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- ◆ DecreaseKey( $P, \Delta, H$ ): Subtract  $\Delta$  from current key value at  $P$  and percolate up. Running Time:  $O(\log N)$
- ◆ IncreaseKey( $P, \Delta, H$ ): Add  $\Delta$  to current key value at  $P$  and percolate down. Running Time:  $O(\log N)$ 
  - ⇒ E.g. Schedulers in OS often decrease priority of CPU-hogging jobs
- ◆ Delete( $P, H$ ): E.g. Delete a job waiting in queue that has been preemptively terminated by user
  - ⇒ Use DecreaseKey followed by DeleteMin.
  - ⇒ How? (Idea: Decrease key to bubble node at  $P$  to the top)
  - ⇒ Running Time?

## Other Heap Operations

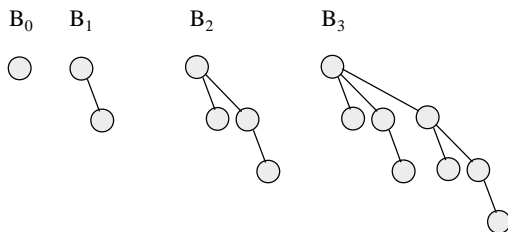
- ◆ Delete(P,H): E.g. Delete a job waiting in queue that has been preemptively terminated by user
  - ⇒ Use DecreaseKey(P,∞,H) followed by DeleteMin(H).
  - ⇒ Running Time:  $O(\log N)$
- ◆ Merge(H1,H2): Merge two heaps H1 and H2 of size  $O(N)$ . H1 and H2 are stored in two arrays. E.g. Combine queues from two different sources to run on one CPU.
  1. Can do  $O(N)$  Insert operations:  $O(N \log N)$  time
  2. Better: Copy H2 at the end of H1 and use BuildHeap  
Running Time:  $O(N)$

Can we do even better? (i.e. Merge in  $O(\log N)$  time?)

## Binomial Queues

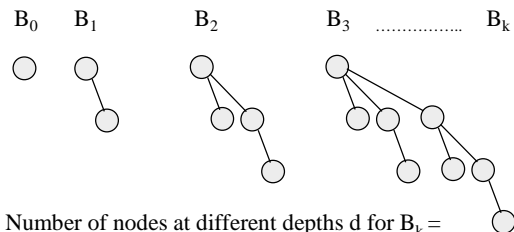
- ◆ Binomial queues support all three priority queue operations Merge, Insert and DeleteMin in  $O(\log N)$  time
- ◆ Idea: Maintain a collection of heap-ordered trees
  - ⇒ Forest of binomial trees
- ◆ Recursive Definition of Binomial Tree (based on height  $k$ ):
  - ⇒ Only one binomial tree for a given height
  - ⇒ Binomial tree of height 0 = single root node
  - ⇒ Binomial tree of height  $k = B_k =$  Attach  $B_{k-1}$  to root of another  $B_{k-1}$
- ◆ Binomial tree of height  $k$  has exactly  $2^k$  nodes (by induction)

## The First Four Binomial Trees



Why are these trees called binomial?  
(hint: how many nodes at depth  $d$ ?)

## Why “Binomial”?

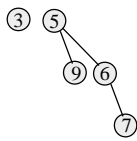


Number of nodes at different depths  $d$  for  $B_k =$   
 $[1], [1\ 1], [1\ 2\ 1], [1\ 3\ 3\ 1], \dots =$   
 Binomial coefficients of  $(a + b)^k = k!/((k-d)!d!)$

## Binomial Queues

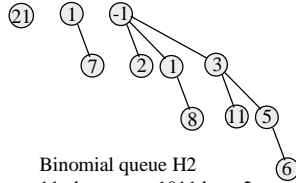
Binomial Queue = "forest" of heap-ordered binomial trees

$B_0$   $B_2$



Binomial queue H1  
5 elements = 101 base 2  
→  $B_2 B_0$

$B_0$   $B_1$   $B_3$



Binomial queue H2  
11 elements = 1011 base 2  
→  $B_3 B_1 B_0$

Next Class:

How do we merge H1 and H2?

More on Binomial Heaps and Priority Queues

To Do:

Read Chapter 6

Programming Assignment #1 will be on-line  
tomorrow (due April 27)