

Lecture 20

- ◆ Logistics
 - HW6 due Wednesday
 - Lab 7 this week (Tuesday exception)
 - Midterm 2 Friday (covers material up to simple FSM (today))
 - Review on Thursday
 - Yoky office hour on Friday moved to Thursday 12-1:20pm online
- ◆ Last lecture
 - Counter design
 - Finite state machine – started vending machine example
- ◆ Today
 - Continue on the vending machine example
 - Moore/Mealy machines

The “WHY” slide

- ◆ Finite State Machine (FSM)
 - This is what we have been waiting for in this class. Using combinational and sequential logics, now you can design a lot of clever digital logic circuits for functional products. We will learn different steps you take to go from word problems to logic circuits.
- ◆ Moore/Mealy machines
 - There are two different ways to express the FSMs with respect to the output. Both have different advantages so it is good to know them.

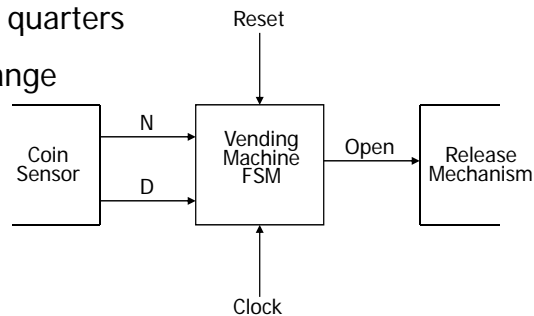
FSM design

- Counter-design procedure
 1. State diagram
 2. State-transition table
 3. Next-state logic minimization
 4. Implement the design

- FSM-design procedure
 1. State diagram
 2. state-transition table
 3. State minimization
 4. State encoding
 5. Next-state logic minimization
 6. Implement the design

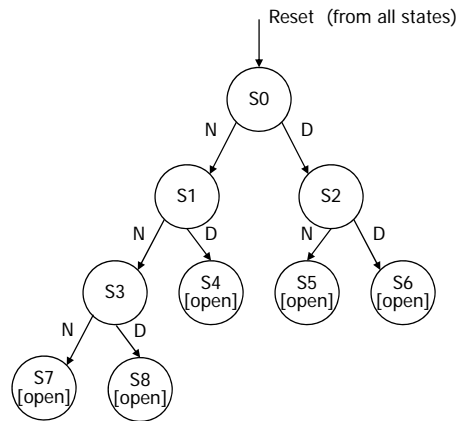
Example: A vending machine

- ◆ 15 cents for a cup of coffee
- ◆ Doesn't take pennies or quarters
- ◆ Doesn't provide any change



- FSM-design procedure
 1. State diagram
 2. state-transition table
 3. State minimization
 4. State encoding
 5. Next-state logic minimization
 6. Implement the design

A vending machine: (conceptual) state diagram



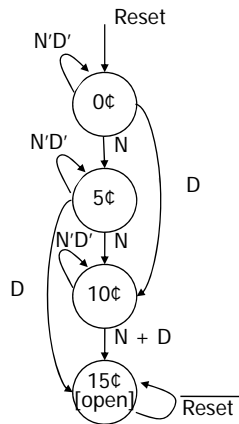
Draw self-loops for
N' D' for S0 to S3

Also draw self-loops for
1 for S4 to S8

A vending machine: State transition table

present state	inputs		next state	output open
	D	N		
S0	0	0	S0	0
	0	1	S1	0
	1	0	S2	0
	1	1	X	X
S1	0	0	S1	0
	0	1	S3	0
	1	0	S4	0
	1	1	X	X
S2	0	0	S2	0
	0	1	S5	0
	1	0	S6	0
	1	1	X	X
S3	0	0	S3	0
	0	1	S7	0
	1	0	S8	0
	1	1	X	X
S4	X	X	S4	1
S5	X	X	S5	1
S6	X	X	S6	1
S7	X	X	S7	1
S8	X	X	S8	1

A vending machine: State minimization



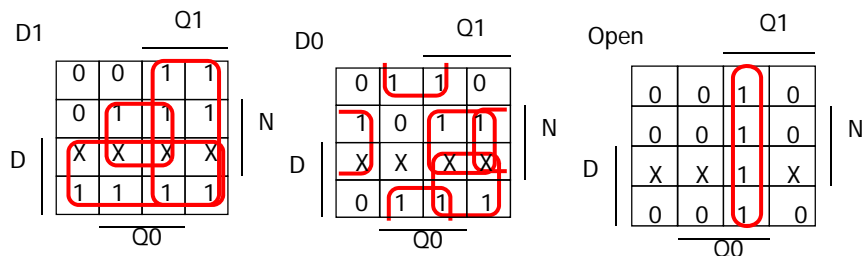
present state	inputs		next state	output open
	D	N		
0¢	0	0	0¢	0
	0	1	5¢	0
	1	0	10¢	0
	1	1	-	-
5¢	0	0	5¢	0
	0	1	10¢	0
	1	0	15¢	0
	1	1	-	-
10¢	0	0	10¢	0
	0	1	15¢	0
	1	0	15¢	0
	1	1	-	-
15¢	-	-	15¢	1

symbolic state table

A vending machine: State encoding

present state		inputs		next state		output open
Q1	Q0	D	N	D1	D0	
0	0	0	0	0	0	0
		0	1	0	1	0
		1	0	1	0	0
		1	1	-	-	-
0	1	0	0	0	1	0
		0	1	1	0	0
		1	0	1	1	0
		1	1	-	-	-
1	0	0	0	1	0	0
		0	1	1	1	0
		1	0	1	1	0
		1	1	-	-	-
1	1	-	-	1	1	1

A vending machine: Logic minimization

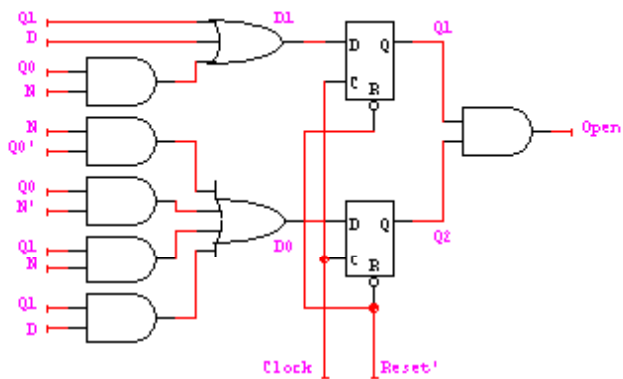


$$D1 = Q1 + D + Q0 N$$

$$D0 = Q0' N + Q0 N' + Q1 N + Q1 D$$

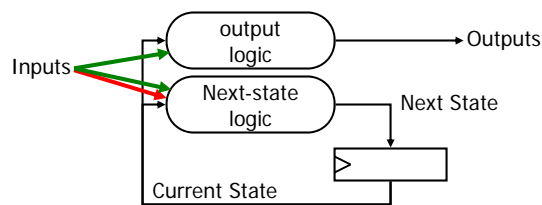
$$OPEN = Q1 Q0$$

A vending machine: Implementation

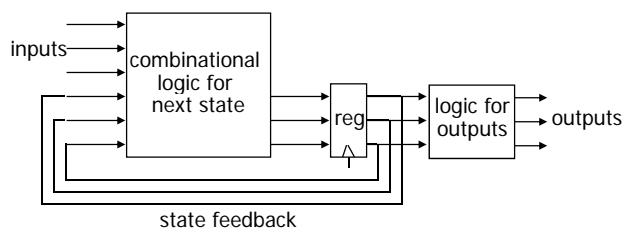


Generalized FSM model: Moore and Mealy

- ◆ Combinational logic computes next state and outputs
 - Next state is a function of current state and inputs
 - Outputs are functions of
 - ☛ Current state (**Moore** machine)
 - ☛ Current state and inputs (**Mealy** machine)



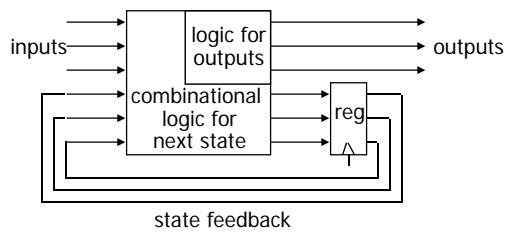
Moore versus Mealy machines



Moore machine

Outputs are a function of current state

Outputs change synchronously with state changes



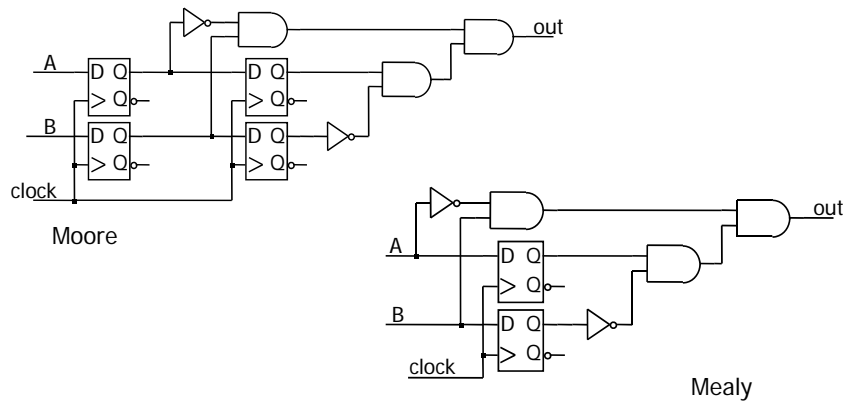
Mealy machine

Outputs depend on state and on inputs

Input changes can cause immediate output changes
(asynchronous)

Example 10 -> 01: Moore or Mealy?

- ◆ Circuits recognize AB=10 followed by AB=01
 - What kinds of machines are they?

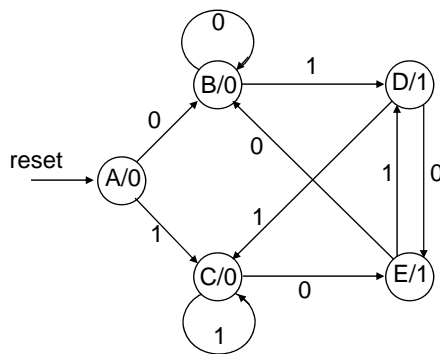


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13

Example 01/10 detector: a Moore machine

- ◆ Output is a function of state only
 - Specify output in the state bubble



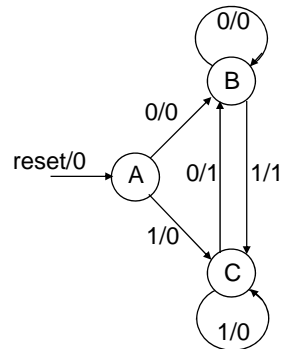
reset	input	current state	next state	current output
1	-	-	A	0
0	0	A	B	0
0	1	A	C	0
0	0	B	B	0
0	1	B	D	0
0	0	C	E	0
0	1	C	C	0
0	0	D	E	1
0	1	D	C	1
0	0	E	B	1
0	1	E	D	1

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14

Example 01/10 detector: a Mealy machine

- ◆ Output is a function of state and inputs
 - Specify outputs on transition arcs



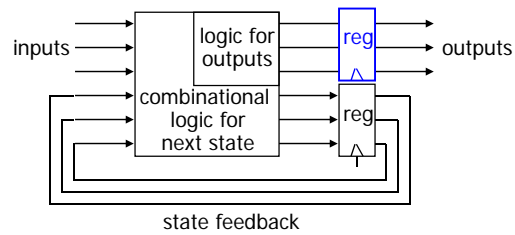
reset	input	current state	next state	current output
1	–	–	A	0
0	0	A	B	0
0	1	A	C	0
0	0	B	B	0
0	1	B	C	1
0	0	C	B	1
0	1	C	C	0

Comparing Moore and Mealy machines

- ◆ Moore machines
 - + Safer to use because outputs change at clock edge
 - May take additional logic to decode state into outputs
- ◆ Mealy machines
 - + Typically have fewer states
 - + React faster to inputs — don't wait for clock
 - Asynchronous outputs can be dangerous
- ◆ We often design synchronous Mealy machines
 - Design a Mealy machine
 - Then register the outputs

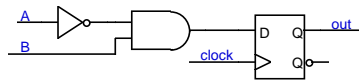
Synchronous (registered) Mealy machine

- ◆ Registered state **and** registered outputs
 - No glitches on outputs
 - No race conditions between communicating machines



Example 0 -> 1: Moore or Mealy?

- ◆ Recognize $A, B = 0, 1$
 - Mealy or Moore?



Registered Mealy
(actually Moore)

