C:

car *c = malloc(sizeof(car));
c->miles = 100;
c->gals = 17;
float mpg = get_mpg(c);
free(c);

Java:

Car c = new Car();
c.setMiles(100);
c.setGals(17);
float mpg =
c.getMPG();

Assembly language:

get_mpg:
    pushq %rbp
    movq %rsp, %rbp
    ...
    popq %rbp
    ret

Machine code:

0111010000011000
100011010000010000000010
1000100111000010
110000011111101000011111

Computer system:

Data & addressing
Integers & floats
Machine code & C
x86 assembly
Procedures & stacks
Arrays & structs
Memory & caches
Processes
Virtual memory
Memory allocation
Java vs. C

Winter 2016
Processes – another important abstraction

- First some preliminaries
  - Control flow
  - Exceptional control flow
  - Asynchronous exceptions (interrupts)
  - Synchronous exceptions (traps & faults)

- Processes
  - Creating new processes
  - Fork and wait
  - Zombies
Control Flow

- So far, we’ve seen how the flow of control changes as a *single program* executes

- But there are multiple programs running concurrently — we also need to understand how control flows across the many components of the system
  - In particular: More programs running than CPUs

- *Exceptional control flow* is the basic mechanism used for:
  - Transferring control between *processes* and OS
  - Handling *I/O* and *virtual memory* within the OS
  - Implementing multi-process applications like shells and web servers
  - Implementing concurrency
Processors do only one thing:

- From startup to shutdown, a CPU simply reads and executes (interprets) a sequence of instructions, one at a time
- This sequence is the CPU’s control flow (or flow of control)

**Physical control flow**

```
<startup>
inst_1
inst_2
inst_3
...
instrt_n
<shutdown>
```
Altering the Control Flow

Up to now: two ways to change control flow:
- Jumps (conditional and unconditional)
- Call and return

Both react to changes in program state

Processor also needs to react to changes in system state
- user hits “Ctrl-C” at the keyboard
- user clicks on a different application’s window on the screen
- data arrives from a disk or a network adapter
- instruction divides by zero
- system timer expires

Can jumps and procedure calls achieve this?
- Jumps and calls are not sufficient – the system needs mechanisms for “exceptional” control flow!
Java Digression #1

- Java has exceptions, but they’re *something different*
  - E.g., NullPointerException, MyBadThingHappenedException, ...
  - throw statements
  - try/catch statements (“throw to youngest matching catch on the call-stack, or exit-with-stack-trace if none”)

- Java exceptions are for reacting to (unexpected) program state
  - Can be implemented with stack operations and conditional jumps
  - A mechanism for “many call-stack returns at once”
  - Requires additions to the calling convention, but we already have the CPU features we need

- System-state changes on previous slide are mostly of a different sort (asynchronous/external except for divide-by-zero) and implemented very differently
Exceptional Control Flow

- Exists at all levels of a computer system
- Low level mechanisms
  - Exceptions
    - Change in processor’s control flow in response to a system event (i.e., change in system state, user-generated interrupt)
    - Implemented using a combination of hardware and OS software
- Higher level mechanisms
  - Process context switch
    - Implemented by OS software and hardware timer
  - Signals – you’ll hear about these in CSE451 and CSE/EE 466 474
    - Implemented by OS software

We’ll talk about exceptions and process context switch
Processes

- First some preliminaries
  - Control flow
  - Exceptional control flow
  - Asynchronous exceptions (interrupts)
  - Synchronous exceptions (traps & faults)

- Processes
  - Creating new processes
  - Fork and wait
  - Zombies
 Exceptions

- An **exception** is transfer of control to the operating system (OS) kernel in response to some **event** (i.e., change in processor state)
  - Kernel is the memory-resident part of the OS
  - Examples of events:
    - div by 0, page fault, I/O request completes, Ctrl-C

- How does the system know where to jump to in the OS?
Exception Table: a jump table for exceptions

- Each type of event has a unique exception number $k$
- $k = \text{index into exception table (a.k.a. interrupt vector)}$
- Handler $k$ is called each time exception $k$ occurs

Also called: Interrupt Vector Table
## Exception Table (Excerpt)

<table>
<thead>
<tr>
<th>Exception Number</th>
<th>Description</th>
<th>Exception Class</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Divide error</td>
<td>Fault</td>
</tr>
<tr>
<td>13</td>
<td>General protection fault</td>
<td>Fault</td>
</tr>
<tr>
<td>14</td>
<td>Page fault</td>
<td>Fault</td>
</tr>
<tr>
<td>18</td>
<td>Machine check</td>
<td>Abort</td>
</tr>
<tr>
<td>32-255</td>
<td>OS-defined</td>
<td>Interrupt or trap</td>
</tr>
</tbody>
</table>

Winter 2016
Processes
Types of Exceptions

- Asynchronous Exceptions (Interrupts) - Caused by events external to the processor

- Synchronous Exceptions – Caused by events that occur as a result of executing an instruction
  - Traps - Intentional
  - Faults - Unintentional
  - Aborts - Unintentional
Processes

- First some preliminaries
  - Control flow
  - Exceptional control flow
    - Asynchronous exceptions (interrupts)
    - Synchronous exceptions (traps & faults)

- Processes
  - Creating new processes
  - Fork and wait
  - Zombies
Asynchronous Exceptions (Interrupts)

- **Caused by events external to the processor**
  - Indicated by setting the processor’s interrupt pin(s) (wire into CPU)
  - After interrupt handler runs, the handler returns to “next” instruction

- **Examples:**
  - I/O interrupts
    - Hitting Ctrl-C on the keyboard
    - Clicking a mouse button or tapping a touchscreen
    - Arrival of a packet from a network
    - Arrival of data from a disk
  - Timer interrupt
    - Every few ms, an external timer chip triggers an interrupt
    - Used by the OS kernel to take back control from user programs
Synchronous Exceptions

Caused by events that occur as a result of executing an instruction:

- **Traps**
  - Intentional: transfer control to OS to perform some function
  - Examples: *system calls*, breakpoint traps, special instructions
  - Returns control to “next” instruction

- **Faults**
  - Unintentional but possibly recoverable
  - Examples: *page faults*, segment protection faults, integer divide-by-zero exceptions
  - Either re-executes faulting (“current”) instruction or aborts

- **Aborts**
  - Unintentional and unrecoverable
  - Examples: parity error, machine check (hardware failure detected)
  - Aborts current program
# System Calls

- Each x86-64 system call has a unique ID number
- Examples:

<table>
<thead>
<tr>
<th>Number</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>read</td>
<td>Read file</td>
</tr>
<tr>
<td>1</td>
<td>write</td>
<td>Write file</td>
</tr>
<tr>
<td>2</td>
<td>open</td>
<td>Open file</td>
</tr>
<tr>
<td>3</td>
<td>close</td>
<td>Close file</td>
</tr>
<tr>
<td>4</td>
<td>stat</td>
<td>Get info about file</td>
</tr>
<tr>
<td>57</td>
<td>fork</td>
<td>Create process</td>
</tr>
<tr>
<td>59</td>
<td>execve</td>
<td>Execute a program</td>
</tr>
<tr>
<td>60</td>
<td>_exit</td>
<td>Terminate process</td>
</tr>
<tr>
<td>62</td>
<td>kill</td>
<td>Send signal to process</td>
</tr>
</tbody>
</table>

Each x86-64 system call has a unique ID number.

Examples:

- read: Read file
- write: Write file
- open: Open file
- close: Close file
- stat: Get info about file
- fork: Create process
- execve: Execute a program
- _exit: Terminate process
- kill: Send signal to process
Traps: System Call Example: Opening File

- User calls: `open(filename, options)`
- Calls `__open` function, which invokes system call instruction `syscall`

```
000000000000e5d70 <__open>:
...
e5d79:   b8 02 00 00 00      mov $0x2,%eax  # open is syscall #2
e5d7e:   0f 05               syscall    # Return value in %rax
e5d80:   48 3d 01 f0 ff ff   cmp $0xfffffffffffffff001,%rax
...
e5dfa:   c3                  retq
```

User code

OS Kernel code

- `%rax` contains syscall number
- Other arguments in `%rdi`, `%rsi`, `%rdx`, `%r10`, `%r8`, `%r9
- Return value in `%rax`
- Negative value is an error corresponding to negative `errno`
Fault Example: Page Fault

- User writes to memory location
- That portion (page) of user’s memory is currently on disk

```
int a[1000];
main ()
{
    a[500] = 13;
}
```

![User code vs. OS Kernel code diagram]

- Page fault handler must load page into physical memory
- Returns to faulting instruction: **mov** is executed again!
- Successful on second try
Fault Example: Invalid Memory Reference

```c
int a[1000];
main ()
{
    a[5000] = 13;
}
```

User Process

```
80483b7:   c7 05 60 e3 04 08 0d  movl  $0xd,0x804e360
```

OS

- Page fault handler detects invalid address
- Sends **SIGSEGV** signal to user process
- User process exits with “segmentation fault”
Summary

Exceptions

- Events that require non-standard control flow
- Generated externally (interrupts) or internally (traps and faults)
- After an exception is handled, one of three things may happen:
  - Re-execute the current instruction
  - Resume execution with the next instruction
  - Abort the process that caused the exception
Java Digression #2

- Recall: Java exceptions are [just] “pop all the way to the nearest matching catch statement”
  - Fully explains “throw new MyParticularException()”

- Java language defines “built-in” exceptions like ArrayBoundsException and NullPointerException
  - Not so special: just means `a[i]` and `e.f` and `e.m()` have to be compiled to include checking for exceptional case
  - Slower but safer than C!
  - Arraybounds: Array-pointed-to has a length field
  - Null-pointer: Represent `null` as 0
    - Just like C, but type system prevents using it in if-statements, etc.
A 351-worthy trick

- In principle, implement Java’s `e.f` as C’s
  
  ```c
  tmp = e;
  tmp ? tmp->f : throw NullPointerException
  ```
  (This is the idea; C doesn’t actually have exceptions)

- In practice, that’s *lots* of extra code and branches, so do this instead:
  - Just execute `tmp->f`
  - But install SIGSEGV trap handler that recognizes 0 and modifies program state to make the exception happen
  - (Traps are very slow, but null-pointer exceptions should be very rare, so this is a good engineering trade-off)
Processes

First some preliminaries

- Control flow
- Exceptional control flow
- Asynchronous exceptions (interrupts)
- Synchronous exceptions (traps & faults)

Processes

- Creating new processes
- Fork and wait
- Zombies
What is a process?

- **Processes** are another *abstraction* in our computer system
  - Provided by the OS
  - OS uses a data structure to represent each process
  - Provides an *interface* between the program and the underlying hardware (CPU + memory)

- What do processes have to do with *exceptional control flow*?
  - Exceptional control flow is the *mechanism* the OS uses to enable *multiple processes* to run on the same system.

- What is the difference between:
  - a processor? a program? a process?
Processes

Definition: A process is an instance of a running program
- One of the most profound ideas in computer science
- Not the same as “program” or “processor”

Process provides each program with two key abstractions:
- **Logical control flow**
  - Each program seems to have exclusive use of the CPU
  - Provided by kernel mechanism called *context switching*

- **Private address space**
  - Each program seems to have exclusive use of main memory
  - Provided by kernel mechanism called *virtual memory*
Multiprocessing: The Illusion

- Computer runs many processes simultaneously
  - Applications for one or more users
    - Web browsers, email clients, editors, ...
  - Background tasks
    - Monitoring network & I/O devices
Single processor executes multiple processes concurrently
- Process executions interleaved (multitasking)
- Address spaces managed by virtual memory system (later in course)
- Register values for nonexecuting processes saved in memory
Save current registers in memory
Multiprocessing: The (Traditional) Reality

- Schedule next process for execution
Multiprocessing: The (Traditional) Reality

- Load saved registers and switch address space (context switch)
Multiprocessing: The (Modern) Reality

- **Multicore processors**
  - Multiple CPUs on single chip
  - Share main memory (and some of the caches)
  - Each can execute a separate process
    - Scheduling of processors onto cores done by kernel
Concurrent Processes

- Each process is a logical control flow
- Two processes run concurrently (are concurrent) if their instruction executions (flows) overlap in time
- Otherwise, they are sequential
- Examples (running on single core):
  - Concurrent: A & B, A & C
  - Sequential: B & C (B ends before C starts)

Assume only one CPU
User’s View of Concurrent Processes

- Control flows for concurrent processes are physically disjoint in time
  - CPU only executes instructions for one process at a time
- However, the user can think of concurrent processes as executing at the same time, in parallel
Context Switching

- Processes are managed by a shared chunk of OS code called the **kernel**
  - The kernel is not a separate process, but rather runs as part of a user process

- **Control flow passes from one process to another via a context switch...** (how?)

---

**Processes**

Assume only one CPU

```
Process A        Process B
```

<table>
<thead>
<tr>
<th>Time</th>
<th>Process A</th>
<th>Process B</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>user code</td>
<td>user code</td>
</tr>
<tr>
<td></td>
<td>kernel code</td>
<td>kernel code</td>
</tr>
<tr>
<td></td>
<td>user code</td>
<td>user code</td>
</tr>
</tbody>
</table>

\[\text{context switch}\]

\[\text{context switch}\]
Processes

First some preliminaries
- Control flow
- Exceptional control flow
- Asynchronous exceptions (interrupts)
- Synchronous exceptions (traps & faults)

Processes
- Creating new processes
- Fork and wait
- Zombies
Creating New Processes & Programs

- **fork-exec model (Linux):**
  - `fork()` creates a copy of the current process
  - `execve()` replaces the current process’ code & address space with the code for a different program

- `fork()` and `execve()` are **system calls**

- **Other system calls for process management:**
  - ` getpid()`
  - ` exit()`
  - ` wait() / waitpid()`
fork: Creating New Processes

pid_t fork(void)

- creates a new process (child process) that is identical to the calling process (parent process), including all state (memory, registers, etc.)
  - returns 0 to the child process
  - returns child’s process ID (pid) to the parent process
- Child is almost identical to parent:
  - Child gets an identical (but separate) copy of the parent’s virtual address space
  - Child has a different PID than the parent

- fork is unique (and often confusing) because it is called once but returns twice

```c
pid_t pid = fork();
if (pid == 0) {
    printf("hello from child\n");
} else {
    printf("hello from parent\n");
}
```
Understanding fork

Process x  (parent)

```c
pid_t pid = fork();
if (pid == 0) {
    printf("hello from child\n");
} else {
    printf("hello from parent\n");
}
```
Understanding fork

**Process x (parent)**

```c
pid_t pid = fork();
if (pid == 0) {
    printf("hello from child\n");
} else {
    printf("hello from parent\n");
}
```

**Process y (child)**

```c
pid_t pid = fork();
if (pid == 0) {
    printf("hello from child\n");
} else {
    printf("hello from parent\n");
}
```
Understanding fork

**Process x  (parent)**

```c
pid_t pid = fork();
if (pid == 0) {
    printf("hello from child\n");
} else {
    printf("hello from parent\n");
}
```

**Process y  (child)**

```c
pid_t pid = fork();
if (pid == 0) {
    printf("hello from child\n");
} else {
    printf("hello from parent\n");
}
```

**pid = y**

```c
pid_t pid = fork();
if (pid == 0) {
    printf("hello from child\n");
} else {
    printf("hello from parent\n");
}
```

**pid = 0**

```c
pid_t pid = fork();
if (pid == 0) {
    printf("hello from child\n");
} else {
    printf("hello from parent\n");
}
```
Understanding fork

**Process x (parent)**

```
pid_t pid = fork();
if (pid == 0) {
    printf("hello from child\n");
} else {
    printf("hello from parent\n");
}
```

**Process y (child)**

```
pid_t pid = fork();
if (pid == 0) {
    printf("hello from child\n");
} else {
    printf("hello from parent\n");
}
```

Which one is first?

```
hello from parent
```

```
which one is first?
```

```
hello from child
```
Fork Example

- Parent and child both run the same code
  - Distinguish parent from child by return value from `fork()`
  - Which process runs first after the `fork()` is undefined
    - Could be parent, could be child!

- Start with same state, but each has a **private copy**
  - Same variables, same call stack, same file descriptors, same register contents, **same program counter**...

```c
void fork1()
{
    int x = 1;
    pid_t pid = fork();
    if (pid == 0) {
        printf("Child has x = %d\n", ++x);
    } else {
        printf("Parent has x = %d\n", --x);
    }
    printf("Bye from process %d with x = %d\n", getpid(), x);
}
```
Fork Example

```c
void fork1()
{
    int x = 1;
    pid_t pid = fork();
    if (pid == 0) {
        printf("Child has x = %d\n", ++x);
    } else {
        printf("Parent has x = %d\n", --x);
    }
    printf("Bye from process %d with x = %d\n", getpid(), x);
}
```
Fork Example

```c
void fork1()
{
    1.   int x = 1;
    2.   pid_t pid = fork();
    3.   if (pid == 0) {
        4.     printf("Child has x = %d\n", ++x);
        5.   } else {
        6.     printf("Parent has x = %d\n", --x);
        7.   }
    8.   printf("Bye from process %d with x = %d\n", getpid(), x);
}
```

- **Both processes continue/start execution at line 3**
  - Child does not call fork! The instruction pointer points to the instruction after the call to fork, the instruction pointer is part of the state that is copied to the child
  - Child has variable pid = 0, parent has pid = process ID of child

- **Concurrent execution:** Can’t predict execution order of parent and child

- **Duplicate but separate address space:** both processes have a copy of x
  - x has a value of 1 at line 3 in both parent and child
  - Subsequent changes to x are independent

- **Shared open files:** `stdout` is the same in both parent and child
Fork-Exec

- fork-exec model:
  - `fork()` creates a copy of the current process
  - `execve()` replaces the current process' code & address space with the code for a different program
    - There is a whole family of `exec` calls – see `exec(3)` and `execve(2)`

```c
// Example arguments: path="/usr/bin/ls",
void fork_exec(char *path, char *argv[])
{
    pid_t pid = fork();
    if (pid ! = 0) {
        printf("Parent: created a child %d\n", pid);
    } else {
        printf("Child: exec-ing new program now\n");
        execv(path, argv);
    }
    printf("This line printed by parent only!\n");
}
```

Note: the return values of `fork` & `execv` should be checked for errors.
Exec-ing a new program

Very high-level diagram of what happens when you run the command "ls" in a Linux shell:
execve Example

Execute “/usr/bin/ls -l lab4” in child process using current environment:

```
myargv[argc] = NULL
myargv[2]
myargv[1]
myargv[0]
```

```
envp[n] = NULL
envp[n-1]
...
envp[0]
```

if ((pid = Fork()) == 0) { /* Child runs program */
    if (execve(myargv[0], myargv, environ) < 0) {
        printf("%s: Command not found.\n", myargv[0]);
        exit(1);
    }
}

Run the `printenv` command in a linux shell to see your own environment variables.
Structure of the stack when a new program starts

- Null-terminated environment variable strings
- Null-terminated command-line arg strings
- `envp[n] == NULL`
- `envp[n-1]`
- `...`
- `envp[0]`
- `argv[argc] = NULL`
- `argv[argc-1]`
- `...`
- `argv[0]`

Future stack frame for `libc_start_main`

Stack frame for `main`

- `argv (in %rsi)`
- `argc (in %rdi)`

Bottom of stack

Environ (global var)

Envp (in %rdx)

Top of stack
exit: Ending a process

- **void exit(int status)**
  - Exits a process
    - Status code: 0 is used for a normal exit, nonzero for abnormal exit
  - **atexit()** registers functions to be executed upon exit

```c
void cleanup(void) {
    printf("cleaning up\n");
}

void fork6() {
    atexit(cleanup);
    fork();
    exit(0);
}
```

“cleanup” is a function pointer
Processes

First some preliminaries
- Control flow
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Processes
- Creating new processes
  - Fork and wait
  - Zombies
Zombies

■ Idea
  ▪ When process terminates, it still consumes system resources
    ▪ Various tables maintained by OS
    ▪ Called a “zombie”
      ▪ A living corpse, half alive and half dead

■ Reaping
  ▪ Performed by parent on terminated child
  ▪ Parent is given exit status information
  ▪ Kernel then deletes zombie child process

■ What if parent doesn’t reap?
  ▪ If any parent terminates without reaping a child, then the orphaned child will be reaped by init process (pid == 1)
  ▪ But in long-running processes we need explicit reaping
    ▪ e.g., shells and servers

On more recent Linux systems, init has been renamed as “systemd”. 
wait: Synchronizing with Children

- Parent reaps a child by calling the `wait` function

```
int wait(int *child_status)
```

- Suspends current process (i.e. the parent) until one of its children terminates
- Return value is the `pid` of the child process that terminated
  - On successful return, the child process is reaped
- If `child_status` != NULL, then the `int` that it points to will be set to a value indicating why the child process terminated
  - NULL is a macro for address 0, the null pointer
  - There are special macros for interpreting this status – see `man wait(2)`

- If parent process has multiple children, `wait()` will return when any of the children terminates
  - `waitpid` can be used to wait on a specific child process
Modeling \texttt{fork} with Process Graphs

- A \textit{process graph} is a useful tool for capturing the partial ordering of statements in a concurrent program:
  - Each vertex is the execution of a statement
  - $a \rightarrow b$ means $a$ happens before $b$
  - Edges can be labeled with current value of variables
  - \texttt{printf} vertices can be labeled with output
  - Each graph begins with a vertex with no inedges

- Any \textit{topological sort} of the graph corresponds to a feasible total ordering.
  - Total ordering of vertices where all edges point from left to right
wait: Synchronizing with Children

```c
void fork_wait() {
    int child_status;
    if (fork() == 0) {
        printf("HC: hello from child\n");
        exit(0);
    } else {
        printf("HP: hello from parent\n");
        wait(&child_status);
        printf("CT: child has terminated\n");
    }
    printf("Bye\n");
}
```

Feasible output:
```
HC
HP
CT
Bye
```

Infeasible output:
```
HP
CT
Bye
HC
```
Process management summary

- **fork** gets us two copies of the same process (but **fork()** returns different values to the two processes)

- **execve** has a new process substitute itself for the one that called it
  - Two-process program:
    - First **fork**()
    - if (pid == 0) { /* child code */ } else { /* parent code */ }
  - Two different programs:
    - First **fork**()
    - if (pid == 0) { **execve**() } else { /* parent code */ }
    - Now running two completely different programs

- **wait** / **waitpid** used to synchronize parent/child execution and to reap child process
Summary

- **Processes**
  - At any given time, system has multiple active processes
  - On a one-CPU system, only one can execute at a time, but each process appears to have total control of the processor
  - OS periodically “context switches” between active processes
    - Implemented using *exceptional control flow*

- **Process management**
  - *fork*: one call, two returns
  - *exec*: one call, usually no return
  - *wait* or *waitpid*: synchronization
  - *exit*: one call, no return
Detailed examples
fork Example: Two consecutive forks

```c
void fork2()
{
    printf("L0\n");
    fork();
    printf("L1\n");
    fork();
    printf("Bye\n");
}
```

Feasible output:
L0
L1
Bye
Bye
L1
Bye
Bye

Infeasible output:
L0
Bye
L1
Bye
L1
Bye
Bye
Bye
fork Example: Three consecutive forks

- Both parent and child can continue forking

```c
void fork3()
{
    printf("L0\n");
    fork();
    printf("L1\n");
    fork();
    printf("L2\n");
    fork();
    printf("Bye\n");
}
```

Diagram showing the execution flow.
**fork Example:** Nested forks in children

```c
void fork5()
{
    printf("L0\n");
    if (fork() == 0) {
        printf("L1\n");
        if (fork() == 0) {
            printf("L2\n");
        }
    }
    printf("Bye\n");
}
```

**Diagram:**

- Feasible output:
  - L0
  - Bye
  - L1
  - L2
  - Bye
  - Bye

- Infeasible output:
  - L0
  - Bye
  - L1
  - L2
  - Bye
  - Bye
  - L2

Winter 2016
Zombie Example

```c
void fork7()
{
    if (fork() == 0) {
        /* Child */
        printf("Terminating Child, PID = %d\n", getpid());
        exit(0);
    } else {
        printf("Running Parent, PID = %d\n", getpid());
        while (1)
            ; /* Infinite loop */
    }
}
```

**Example**

- `ps` shows child process as "defunct"
- Killing parent allows child to be reaped by `init`
Non-terminating Child Example

```c
void fork8()
{
    if (fork() == 0) {
        /* Child */
        printf("Running Child, PID = %d\n", getpid());
        while (1)
            ; /* Infinite loop */
    } else {
        printf("Terminating Parent, PID = %d\n", getpid());
        exit(0);
    }
}
```

- Child process still active even though parent has terminated
- Must kill explicitly, or else will keep running indefinitely

```
linux> ./forks 8
Terminating Parent, PID = 6675
Running Child, PID = 6676
linux> ps
    PID TTY          TIME CMD
   6585 ttyp9    00:00:00 tcsh
   6676 ttyp9    00:00:06 forks
   6677 ttyp9    00:00:00 ps
linux> kill 6676
linux> ps
    PID TTY          TIME CMD
   6585 ttyp9    00:00:00 tcsh
   6678 ttyp9    00:00:00 ps
```
wait() Example

- If multiple children completed, will take in arbitrary order
- Can use macros WIFEXITED and WEXITSTATUS to get information about exit status

```c
void fork10()
{
    pid_t pid[N];
    int i;
    int child_status;
    for (i = 0; i < N; i++)
        if ((pid[i] = fork()) == 0)
            exit(100+i); /* Child */
    for (i = 0; i < N; i++) {
        pid_t wpid = wait(&child_status);
        if (WIFEXITED(child_status))
            printf("Child %d terminated with exit status %d\n", wpid, WEXITSTATUS(child_status));
        else
            printf("Child %d terminated abnormally\n", wpid);
    }
}
```
waitpid(): Waiting for a Specific Process

```c
void fork11()
{
    pid_t pid[N];
    int i;
    int child_status;
    for (i = 0; i < N; i++)
        if ((pid[i] = fork()) == 0)
            exit(100+i); /* Child */
    for (i = 0; i < N; i++) {
        pid_t wpid = waitpid(pid[i], &child_status, 0);
        if (WIFEXITED(child_status))
            printf("Child %d terminated with exit status %d\n", wpid, WEXITSTATUS(child_status));
        else
            printf("Child %d terminated abnormally\n", wpid);
    }
}
```