



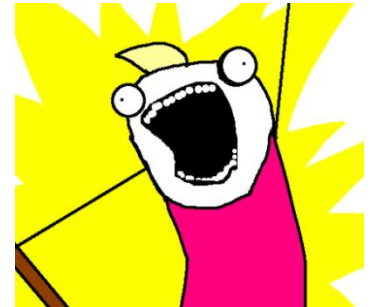
# CSE332: Data Abstractions

## Lecture 10: Comparison Sorting

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Winter 2012

# *Introduction to Sorting*

- We have covered stacks, queues, priority queues, and dictionaries
  - All focused on providing one element at a time
- But often we know we want “all the things” in some order
  - Anyone can sort, but a computer can sort faster
  - Very common to need data sorted somehow
    - Alphabetical list of people
    - List of countries ordered by population
- Algorithms have different asymptotic and constant-factor trade-offs
  - No single “best” sort for all scenarios
  - Knowing “one way to sort” is not sufficient



# *More Reasons to Sort*

General technique in computing:

*Preprocess data to make subsequent operations faster*

Example: Sort the data so that you can

- Find the  $k^{\text{th}}$  largest in constant time for any  $k$
- Perform binary search to find elements in logarithmic time

Whether the performance of the preprocessing matters depends on

- How often the data will change
- How much data there is

# Careful Statement of the Basic Problem

Assume we have  $n$  comparable elements in an array, and we want to rearrange them to be in increasing order

Input:

- An array  $\mathbf{A}$  of data records
- A key value in each data record (potentially a set of fields)
- A comparison function (must be consistent and total)
  - Given keys  $a$  and  $b$ , what is their relative ordering?  $<$ ,  $=$ ,  $>$ ?

Effect:

- Reorganize the elements of  $\mathbf{A}$  such that for any  $i$  and  $j$ ,  
if  $i < j$  then  $\mathbf{A}[i] \leq \mathbf{A}[j]$
- Unspoken assumption:  $\mathbf{A}$  must have all the data it started with

An algorithm doing this is a **comparison sort**

# *Variations on the basic problem*

1. Maybe elements are in a linked list (could convert to array and back in linear time, but some algorithms need not do so)
2. Maybe ties need to be resolved by “original array position”
  - Sorts that do this naturally are called **stable sorts**
  - Others could tag each item with its original position and adjust their comparisons (non-trivial constant factors)
3. Maybe we must not use more than  $O(1)$  “auxiliary space”
  - Sorts meeting this requirement are called **in-place sorts**
4. Maybe we can do more with elements than just compare
  - Sometimes leads to faster algorithms
5. Maybe we have too much data to fit in memory
  - Use an “**external sorting**” algorithm

# Sorting: The Big Picture

**Simple algorithms:**  
 $O(n^2)$

**Insertion sort**  
**Selection sort**  
**Shell sort**  
...

**Fancier algorithms:**  
 $O(n \log n)$

**Heap sort**  
**Merge sort**  
**Quick sort (avg)**  
...

**Comparison lower bound:**  
 $\Omega(n \log n)$

**Specialized algorithms:**  
 $O(n)$

**Bucket sort**  
**Radix sort**

**Handling huge data sets**

**External sorting**

# *Insertion Sort*

- Idea: At step  $k$ ,  
put the  $k^{\text{th}}$  input element in the correct position  
among the first  $k$  elements
- Alternate way of saying this:
  - Sort first element (this is easy)
  - Now insert 2<sup>nd</sup> element in order
  - Now insert 3<sup>rd</sup> element in order
  - Now insert 4<sup>th</sup> element in order
  - ...
- “Loop invariant”: when loop index is  $i$ , first  $i$  elements are sorted
- Time?  
Best-case \_\_\_\_\_ Worst-case \_\_\_\_\_ “Average” case \_\_\_\_\_

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  - ...
- “Loop invariant”: when loop index is  $i$ , first  $i$  elements are sorted
- Time?
  - Best-case  $O(n)$  Worst-case  $O(n^2)$  “Average” case  $O(n^2)$   
start sorted start reverse sorted (see text)



# *Selection Sort*

- Idea: At step  $k$ ,  
find the smallest element among the unsorted elements  
and put it at position  $k$
- Alternate way of saying this:
  - Find smallest element, put it 1<sup>st</sup>
  - Find next smallest element, put it 2<sup>nd</sup>
  - Find next smallest element, put it 3<sup>rd</sup>
  - ...
- “Loop invariant”: when loop index is  $i$ ,  
first  $i$  elements are the  $i$  smallest elements in sorted order
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- Time?  
Best-case  $O(n^2)$  Worst-case  $O(n^2)$  “Average” case  $O(n^2)$   
*Always*  $T(1) = 1$  and  $T(n) = n + T(n-1)$

# Mystery Sort

This is one implementation of which sorting algorithm (shown for ints)?

```
void mystery(int[] arr) {
    for(int i = 1; i < arr.length; i++) {
        int tmp = arr[i];
        int j;
        for(j=i; j > 0 && tmp < arr[j-1]; j--)
            arr[j] = arr[j-1];
        arr[j] = tmp;
    }
}
```

Note: As with heaps, “moving the hole” is faster than unnecessary swapping (impacts constant factor)

# *Insertion Sort vs. Selection Sort*

- They are different algorithms
- They solve the same problem
- Have the same worst-case and average-case asymptotic complexity
  - Insertion-sort has better best-case complexity; preferable when input is “mostly sorted”
- Other algorithms are more efficient
  - for non-small arrays that are not already almost sorted*
  - Small arrays may do well with Insertion sort

## *Aside: We Will Not Cover Bubble Sort*

- It does not have good asymptotic complexity:  $O(n^2)$
- It is not particularly efficient with respect to constant factors
- Almost everything it is good at, some other algorithm is at least as good at
- Perhaps some people teach it just because it was taught to them
- For fun see: “Bubble Sort: An Archaeological Algorithmic Analysis”, Owen Astrachan, SIGCSE 2003

# Sorting: The Big Picture

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**Heap sort**  
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**Handling huge data sets**

**External sorting**

# Heap Sort

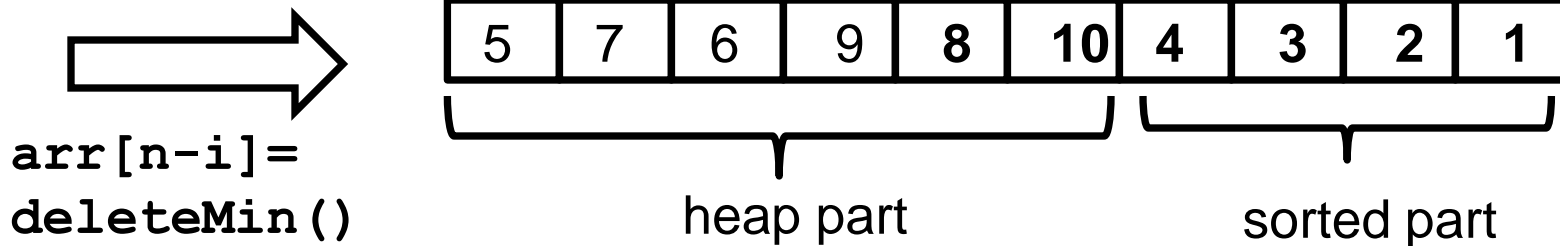
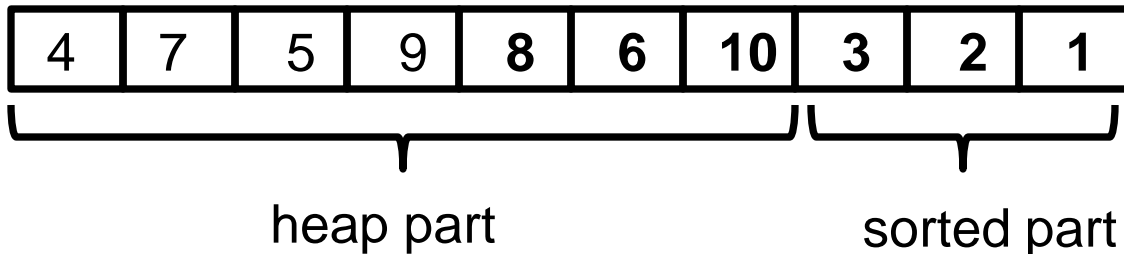
- As you are seeing in Project 2, sorting with a heap is easy:
  - `insert` each `arr[i]`, or better yet do a `buildHeap`
  - `for(i=0; i < arr.length; i++)`  
`arr[i] = deleteMin();`
- Worst-case running time:  $O(n \log n)$   
**Why?**
- We have the array-to-sort and the heap
  - So this is not an in-place sort
  - There's a trick to make it in-place

But this reverse sorts –  
how would you fix that?

# *In-Place Heap Sort*

Reverse your comparator,  
so you build a maxHeap

- Treat the initial array as a heap (via `buildHeap`)
- When you delete the  $i^{\text{th}}$  element, put it at `arr[n-i]`
  - That array location is not part of the heap anymore!





# “AVL sort”

- We can also use a balanced tree to:
  - **insert** each element: total time  $O(n \log n)$
  - Repeatedly **deleteMin**: total time  $O(n \log n)$
- But this cannot be made in-place, and it has worse constant factors than heap sort
  - both are  $O(n \log n)$  in worst, best, and average case
  - neither parallelizes well
  - heap sort is better
- Do not even think about trying to sort with a hash table

# *Divide and Conquer*

Very important technique in algorithm design

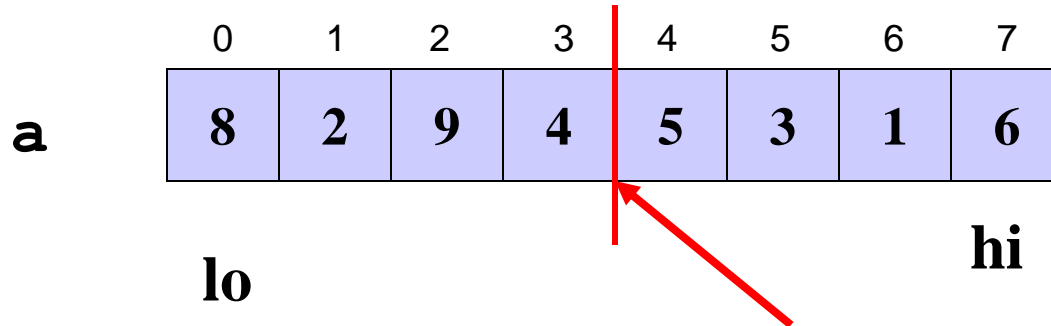
1. Divide problem into smaller parts
2. Independently solve the simpler parts
  - Think recursion
  - Or potential parallelism
3. Combine solution of parts to produce overall solution

# *Divide-and-Conquer Sorting*

Two great sorting methods are fundamentally divide-and-conquer

1. Mergesort: Sort the left half of the elements (recursively)  
Sort the right half of the elements (recursively)  
Merge the two sorted halves into a sorted whole
2. Quicksort: Pick a “pivot” element  
Divide elements into less-than pivot  
and greater-than pivot  
Sort the two divisions (recursively on each)  
Answer is [ *sorted-less-than*,  
then *pivot*,  
then *sorted-greater-than* ]

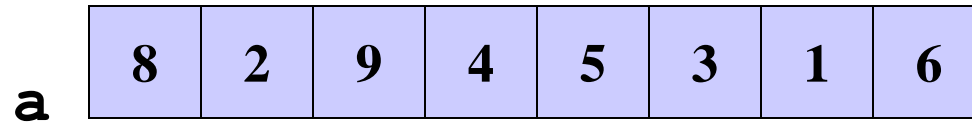
# Mergesort



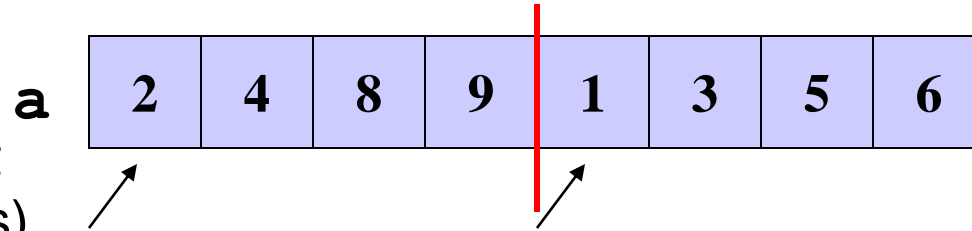
- To sort array from position `lo` to position `hi`:
  - If range is 1 element long, it is already sorted! (our base case)
  - Else, split into two halves:
    - Sort from `lo` to  $(hi+lo)/2$
    - Sort from  $(hi+lo)/2$  to `hi`
    - Merge the two halves together
- Merging takes two sorted parts and sorts everything
  - $O(n)$  but requires auxiliary space...

# Example: Focus on Merging

Start with:

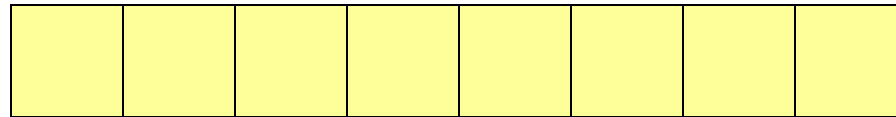


After recursion:  
(for now we just  
assume it works)



Merge:

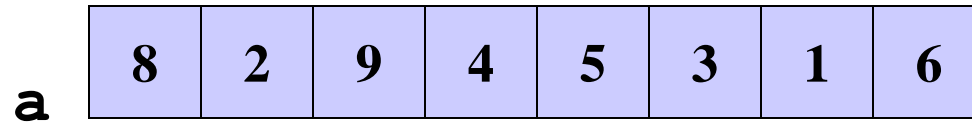
Use 3 "fingers" **aux**  
and 1 more array



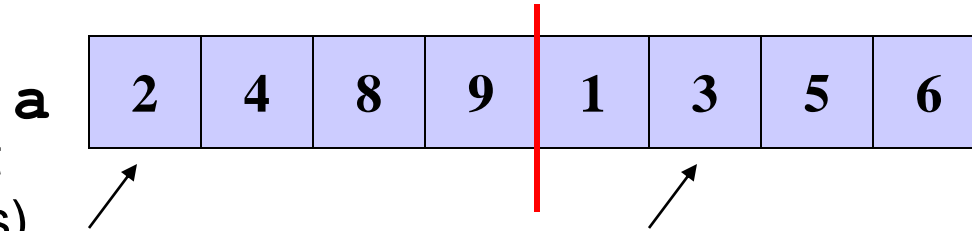
(After merge,  
copy back to  
original array)

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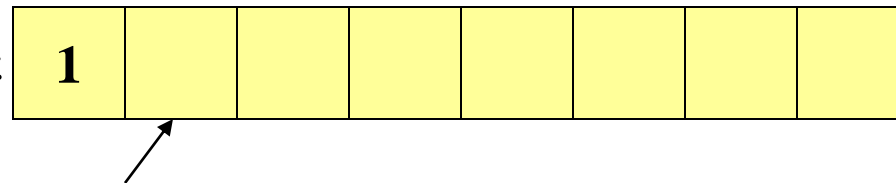


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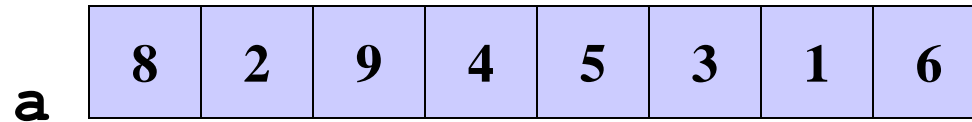
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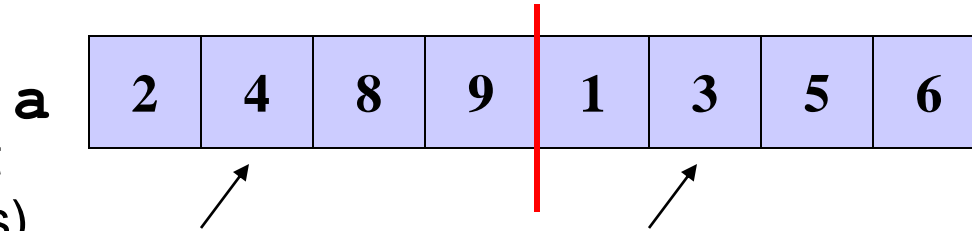
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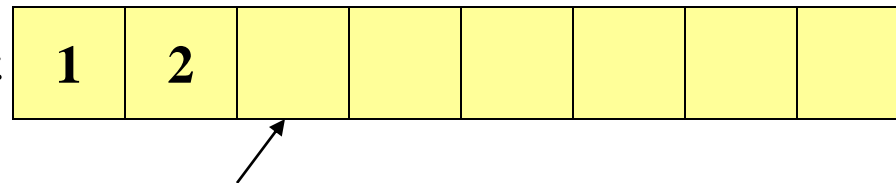


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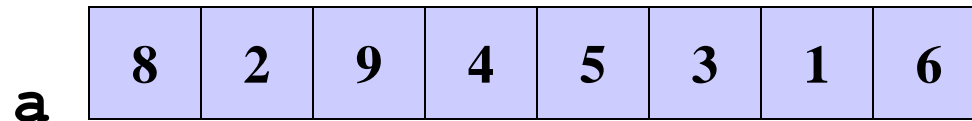




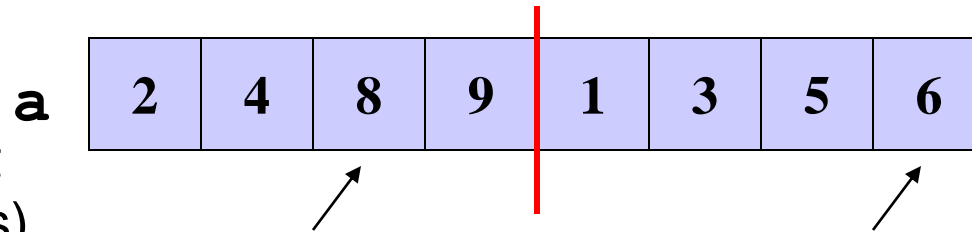


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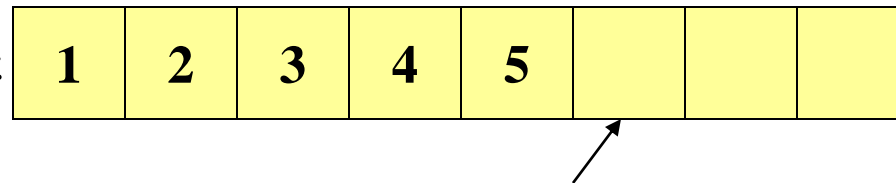


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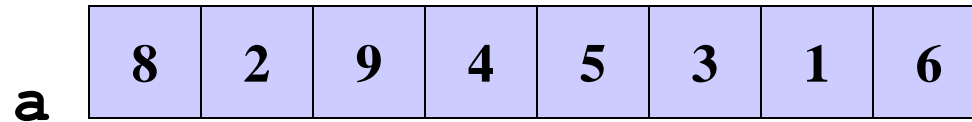
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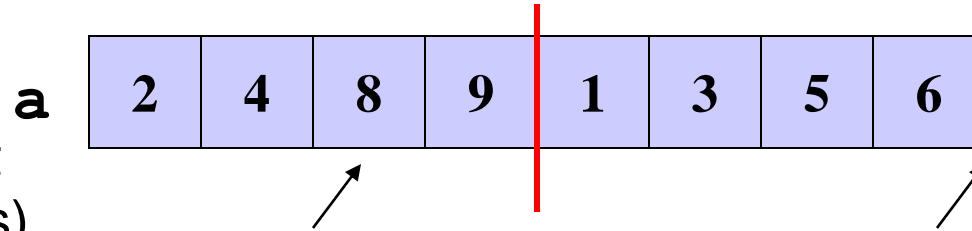
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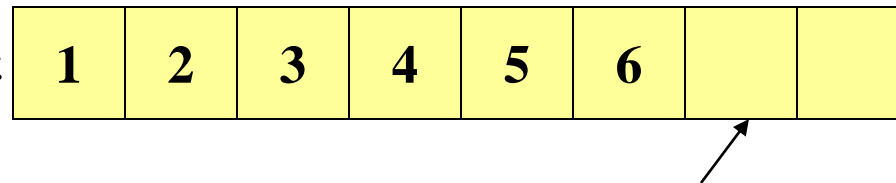


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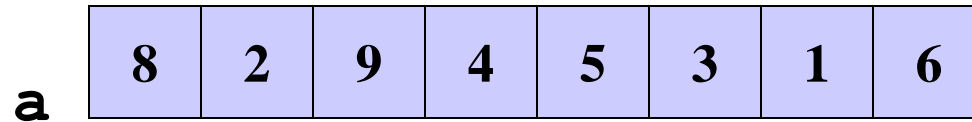
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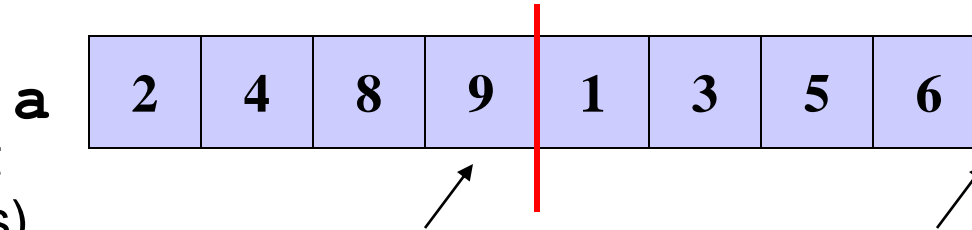
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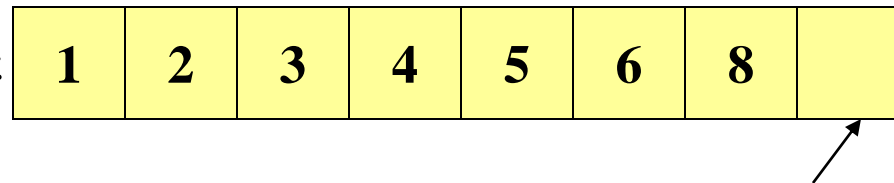


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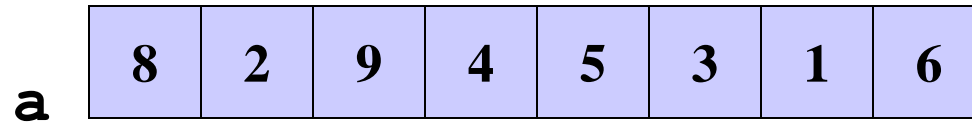
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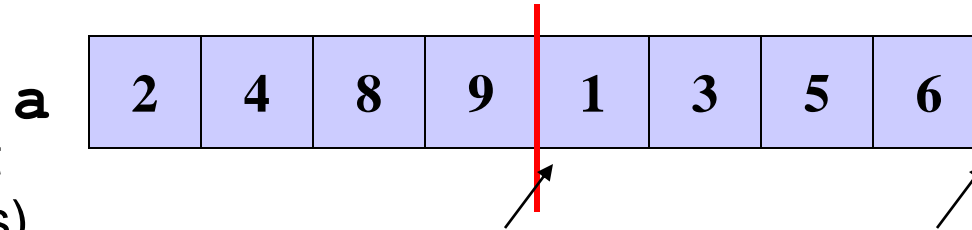
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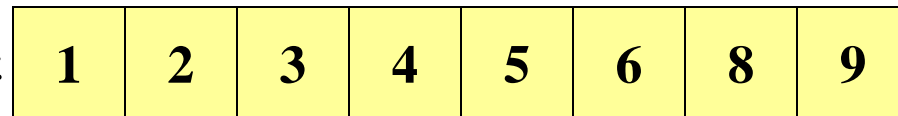


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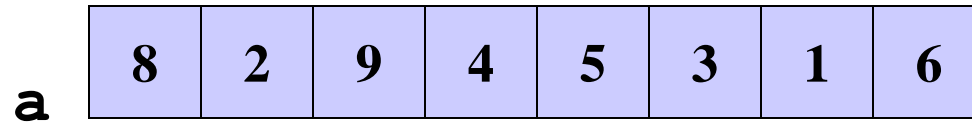
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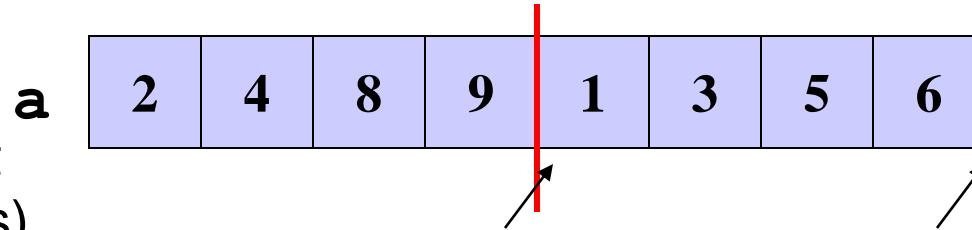
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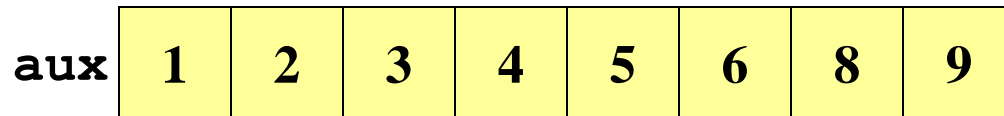


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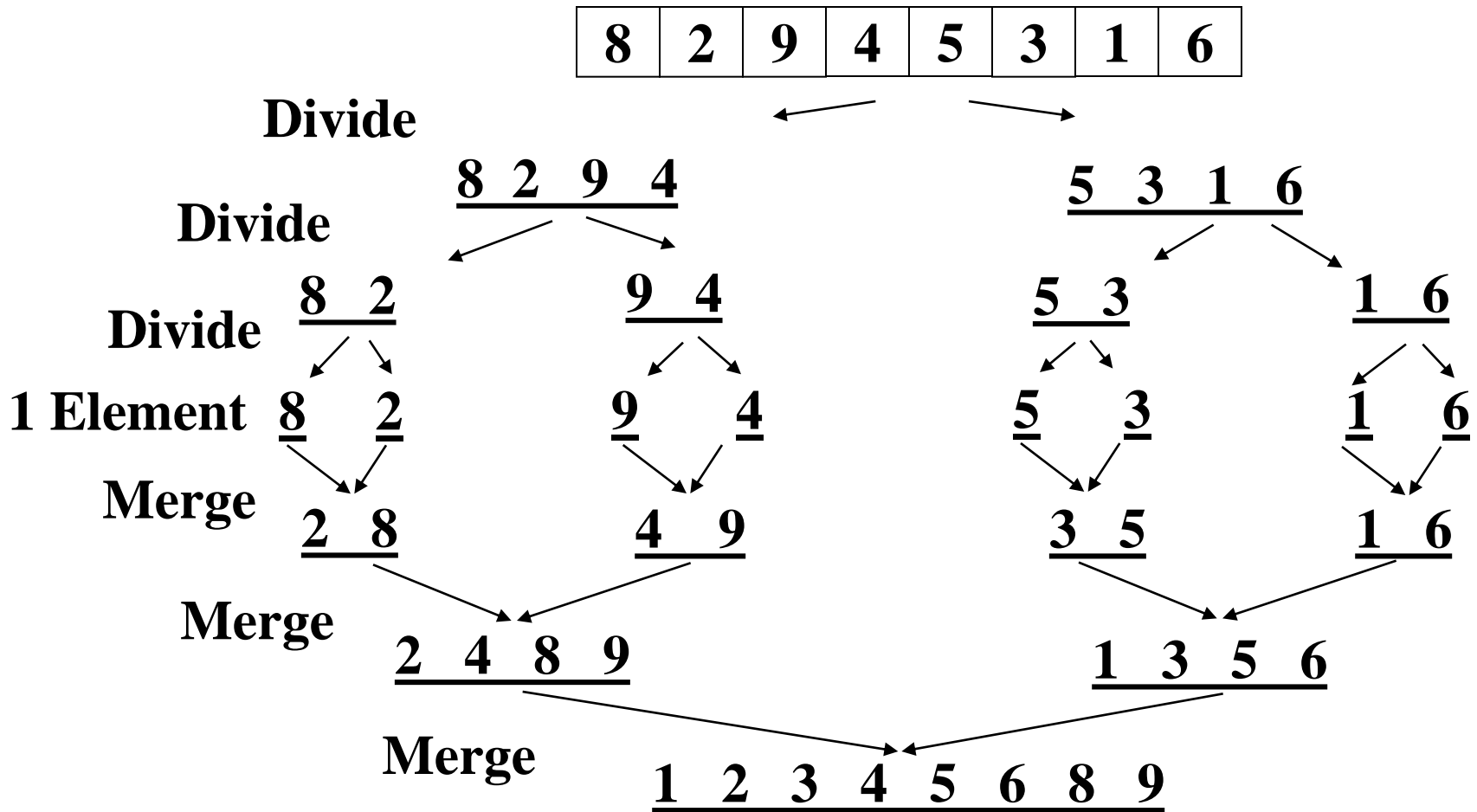
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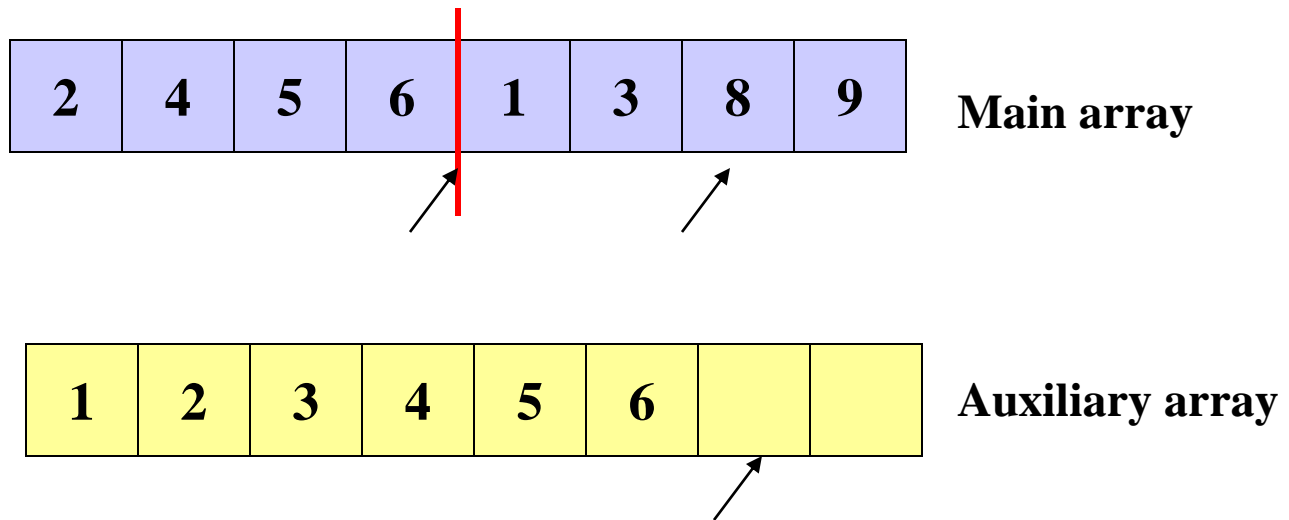


# Example: Mergesort Recursion



# Mergesort: Some Time Saving Details

- What if the final steps of our merge looked like this:

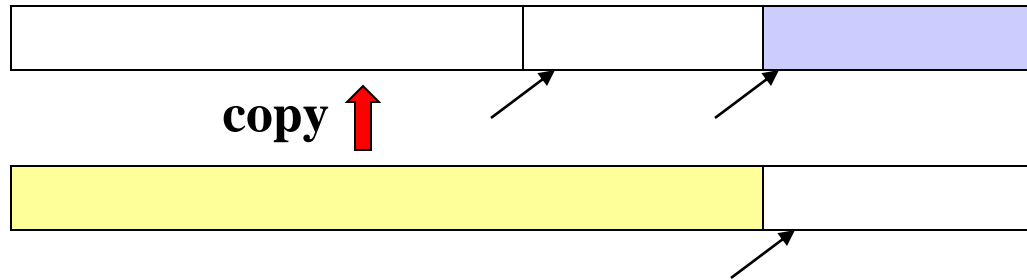


- Wasteful to copy to the auxiliary array just to copy back...

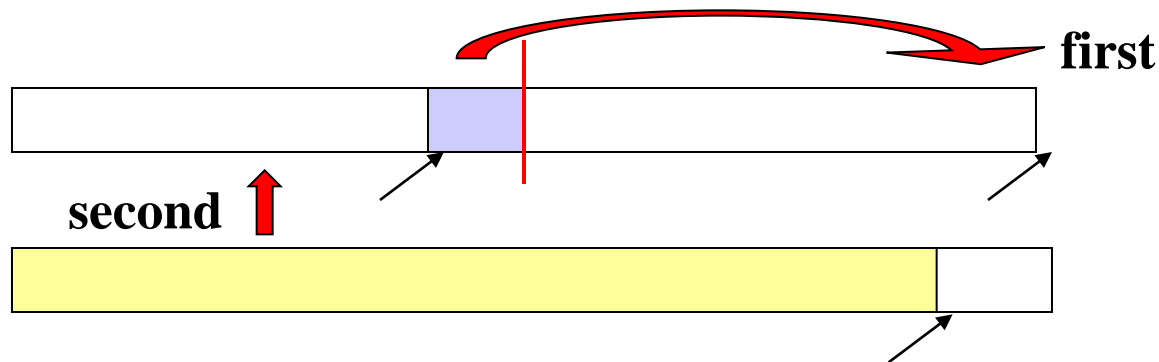


# Mergesort: Some Time Saving Details

- If left-side finishes first, just stop the merge and copy back:



- If right-side finishes first, copy drags into right then copy back:



# *Mergesort: Saving Space and Copying*

Simplest / Worst:

Use a new auxiliary array of size  $(hi-lo)$  for every merge

Better:

Use a new auxiliary array of size  $n$  for every merging stage

Better:

Reuse same auxiliary array of size  $n$  for every merging stage

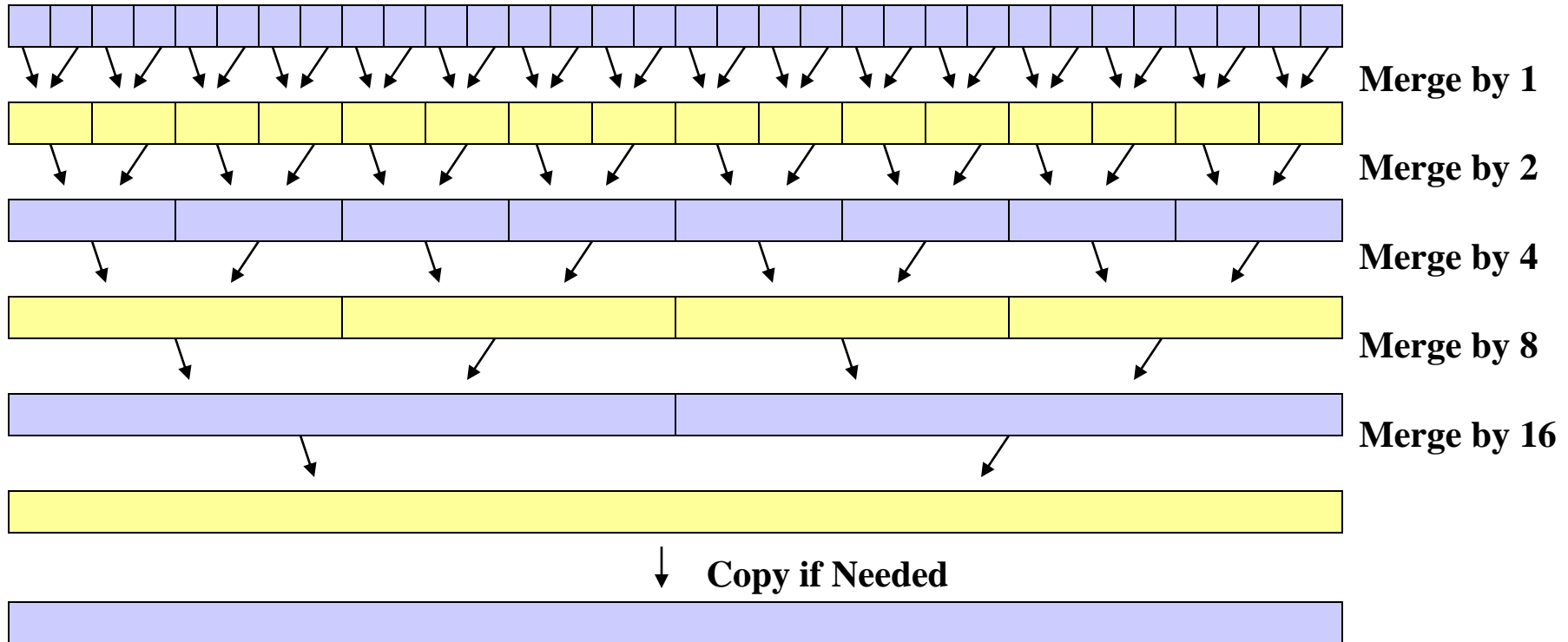
Best:

Do not copy back after merge, instead swap usage of the original and auxiliary array (i.e., even levels move to auxiliary array, odd levels move back to original array)

- Need one copy at end if number of stages is odd

# Swapping Original and Auxiliary Array

- First recurse down to lists of size 1
- As we return from the recursion, swap between arrays



- Arguably easier to code without using recursion at all

# *Mergesort Analysis*

Having defined an algorithm and argued it is correct, we can analyze its running time and space:

To sort  $n$  elements, we:

- Return immediately if  $n=1$
- Else do 2 subproblems of size  $n/2$  and then an  $O(n)$  merge

Recurrence relation:

$$T(1) = c_1$$

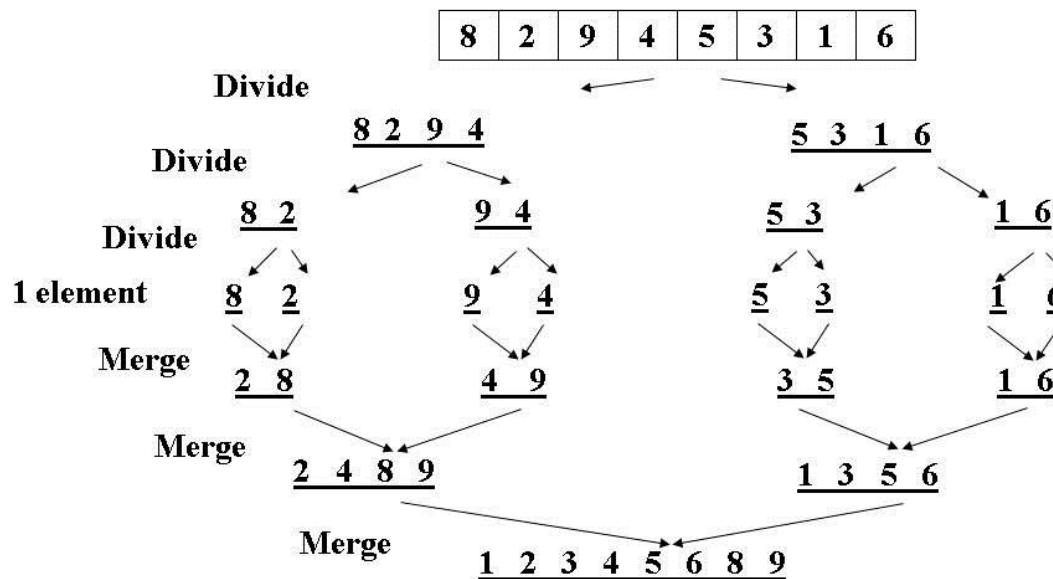
$$T(n) = 2T(n/2) + c_2n$$

# Mergesort Analysis

This recurrence is common enough you just “know” it’s  $O(n \log n)$

Merge sort is relatively easy to intuit (best, worst, and average):

- The recursion “tree” will have  $\log n$  height
- At each level we do a *total* amount of merging equal to  $n$



# Quicksort

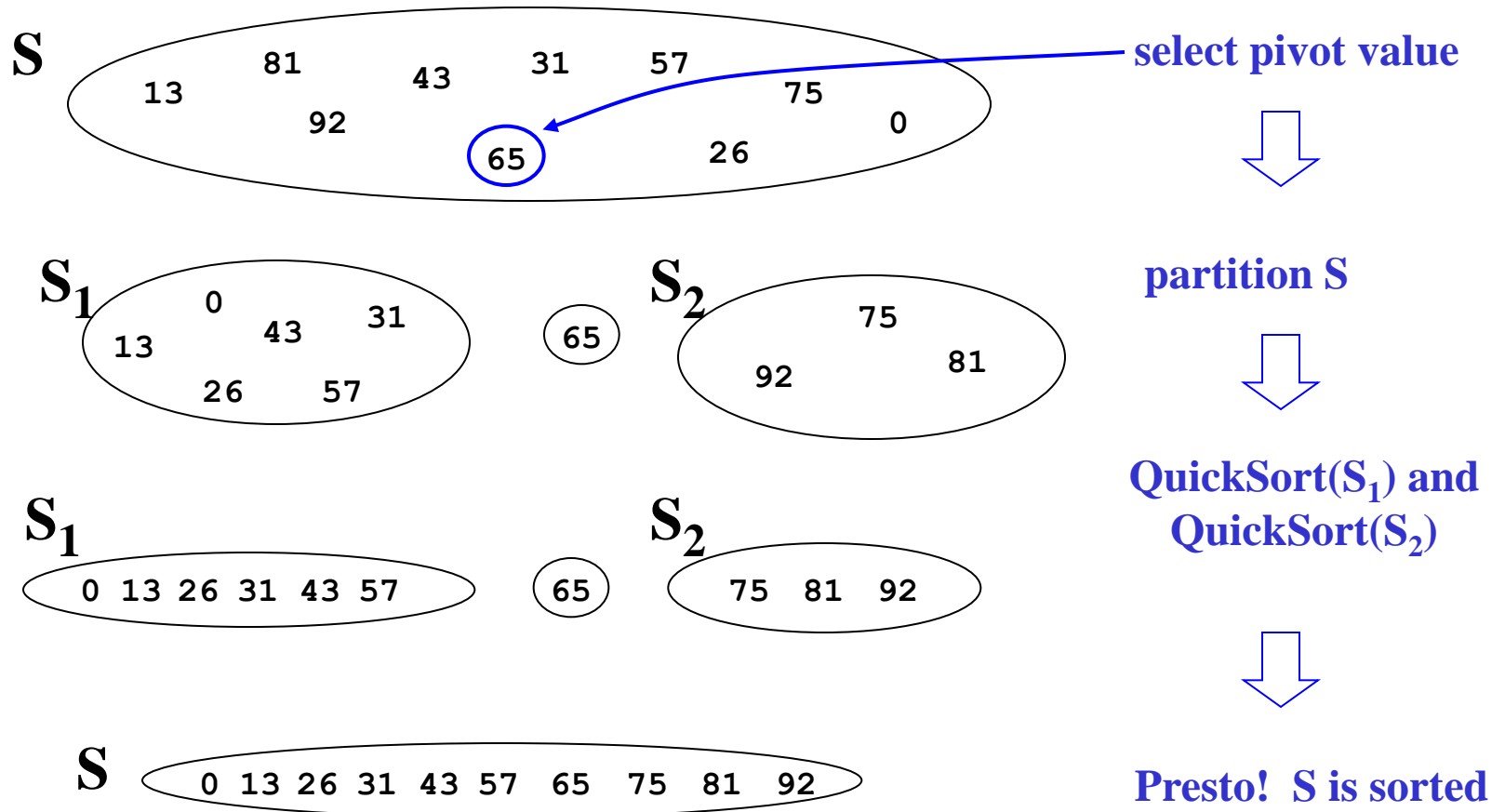
- Also uses divide-and-conquer
  - Recursively chop into halves
  - Instead of doing all the work as we merge together, we will do all the work as we recursively split into halves
  - Unlike MergeSort, does not need auxiliary space
- $O(n \log n)$  on average, but  $O(n^2)$  worst-case
  - MergeSort is always  $O(n \log n)$
  - So why use QuickSort at all?
- Can be faster than Mergesort
  - Believed by many to be faster
  - Quicksort does fewer copies and more comparisons, so it depends on the relative cost of these two operations!

# *Quicksort Overview*

1. Pick a pivot element
2. Partition all the data into:
  - A. The elements less than the pivot
  - B. The pivot
  - C. The elements greater than the pivot
3. Recursively sort A and C
4. The answer is as simple as “A, B, C”

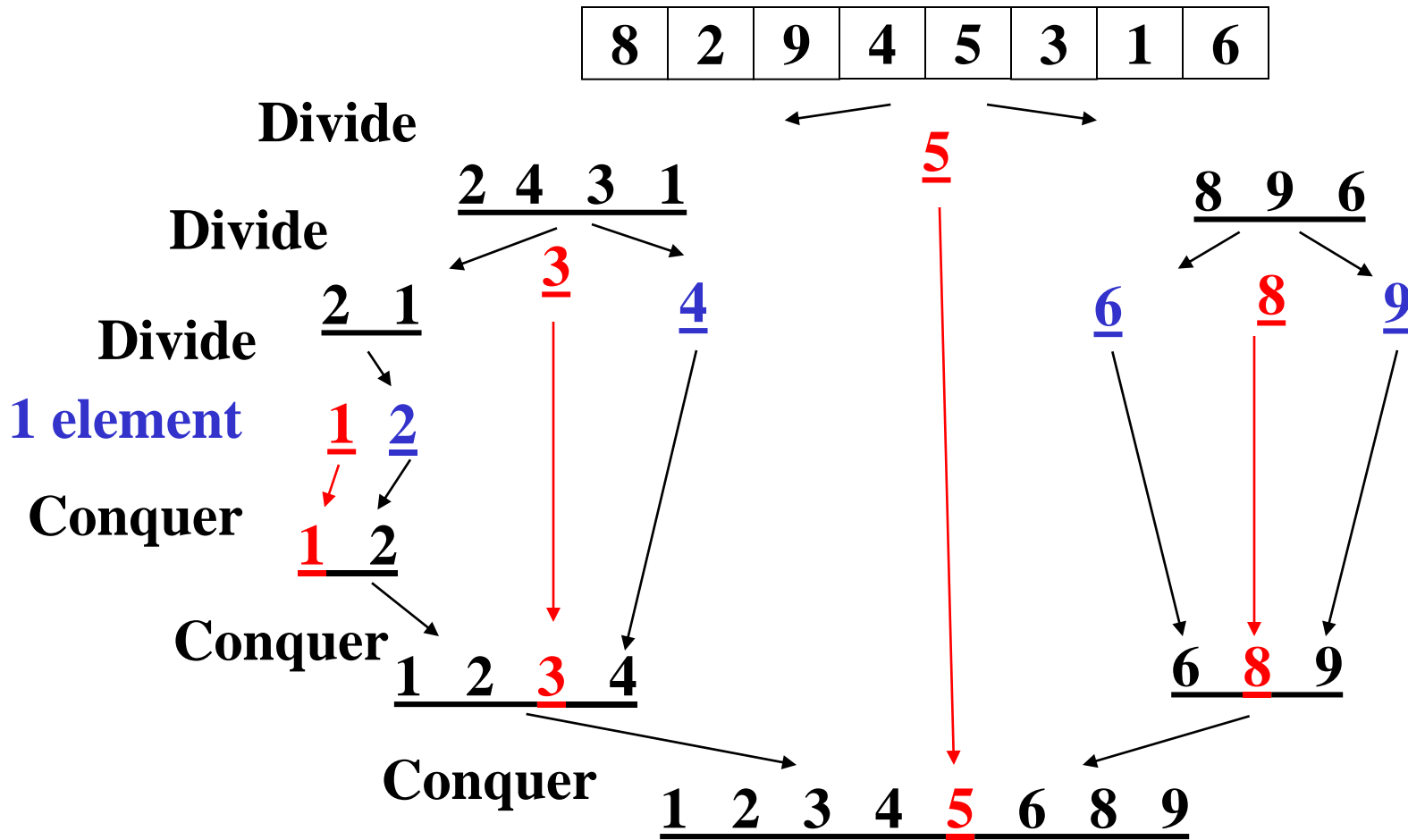
Alas, there are some details lurking in this algorithm

# Quicksort: Think in Terms of Sets





# Example: Quicksort Recursion



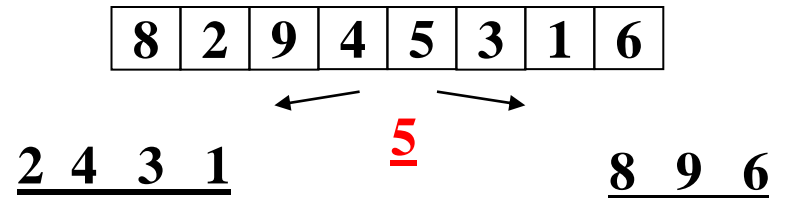
# *Quicksort Details*

We have not explained:

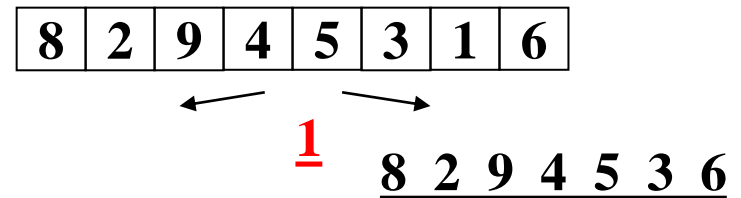
- How to pick the pivot element
  - Any choice is correct: data will end up sorted
  - But we want the two partitions to be about equal in size
- How to implement partitioning
  - In linear time
  - In place

# Pivots

- Best pivot?
  - Median
  - Halve each time



- Worst pivot?
  - Greatest/least element
  - Problem of size  $n - 1$
  - $O(n^2)$



# *Quicksort: Potential Pivot Rules*

While sorting `arr` from `lo` (inclusive) to `hi` (exclusive):

- Pick `arr[lo]` or `arr[hi-1]`
  - Fast, but worst-case occurs with approximately sorted input
- Pick random element in the range
  - Does as well as any technique
    - But random number generation can be slow
    - Still probably the most elegant approach
- Median of 3, (e.g., `arr[lo]`, `arr[hi-1]`, `arr[(hi+lo)/2]`)
  - Common heuristic that tends to work well

# *Partitioning*

- Conceptually simple, but hardest part to code up correctly
  - After picking pivot, need to partition in linear time in place
- One approach (there are slightly fancier ones):
  1. Swap pivot with `arr[lo]`
  2. Use two fingers `i` and `j`, starting at `lo+1` and `hi-1`
  3. `while (i < j)`
    - `if (arr[j] >= pivot) j--`
    - `else if (arr[i] =< pivot) i++`
    - `else swap arr[i] with arr[j]`
  4. Swap pivot with `arr[i]`

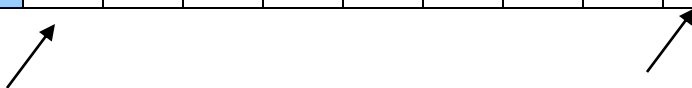
# Quicksort Example

- Step One: Pick Pivot as Median of 3
  - $lo = 0, hi = 10$

0	1	2	3	4	5	6	7	8	9
8	1	4	9	0	3	5	2	7	6

- Step Two: Move Pivot to the  $lo$  Position

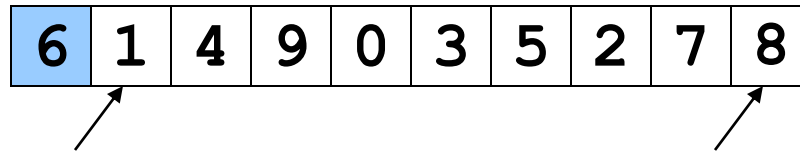
0	1	2	3	4	5	6	7	8	9
6	1	4	9	0	3	5	2	7	8



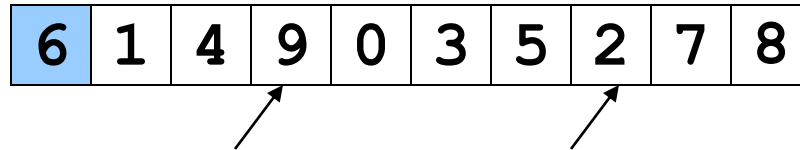
# Quicksort Example

Often have more than one swap during partition – this is a short example

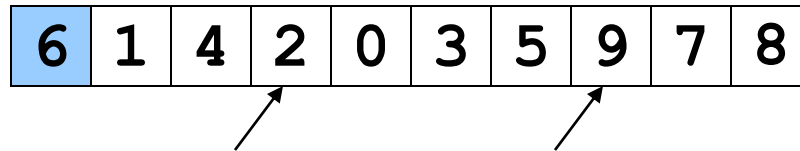
Now partition in place



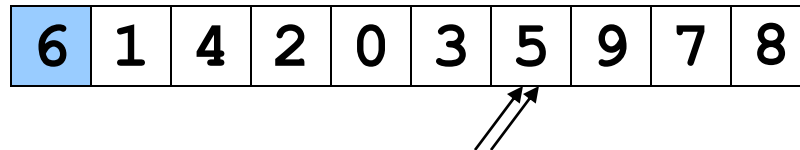
Move fingers



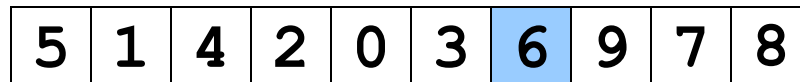
Swap



Move fingers



Move pivot



# Quicksort Analysis

- Best-case: Pivot is always the median

$$T(0)=T(1)=1$$

$$T(n)=2T(n/2) + n \quad \text{-- linear-time partition}$$

Same recurrence as mergesort:  $O(n \log n)$

- Worst-case: Pivot is always smallest or largest element

$$T(0)=T(1)=1$$

$$T(n) = 1T(n-1) + n$$

Basically same recurrence as selection sort:  $O(n^2)$

- Average-case (e.g., with random pivot)
  - $O(n \log n)$  (see text)